# Iterative methdos 

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## 1 Eigenvalue problem

We will consider symmetric matrix $A \in \mathbb{R}^{m \times m}$. We define the Rayleigh Quotient,

$$
\begin{equation*}
r(x)=\frac{x^{t} A x}{x^{t} x} . \tag{1}
\end{equation*}
$$

Note that if $x$ is an eigenvector of $A, r(x)=\lambda$ is its eigenvalue.
One way to understand this formula is: given $x$, what is the scale $\alpha$ which acts almost like an eigenvalue of $x$ in the sense that $A x-\alpha x$ is minimized? This is a least square problem, but $x$ is the matrix $\alpha$ is the unknown vector, and $A x$ is the right-hand side $b$ vector. We can see that $\alpha=r(x)$ if we consider the normal equation.
Take the derivative of $r(x)$ with respect to all component $x_{j}$ of $x$, we can easily derive that,

$$
\begin{equation*}
\nabla r(x)=\frac{2}{x^{t} x}(A x-r(x) x) \tag{2}
\end{equation*}
$$

We can see that when $x$ is the eigenvector, the gradient vanishes. Conversely, if the gradient is trivial with $x \neq 0, x$ is an eigenvector with eigenvalue $r(x)$.
Theorem 1.1. Let $q_{j}$ be an eigenvector of $A$, we have

$$
\begin{equation*}
r(x)-q_{j}=\mathcal{O}\left(\left\|x-q_{j}\right\|^{2}\right) \tag{3}
\end{equation*}
$$

as $x \rightarrow q_{j}$.
The Power iteration is expected to return an eigenvector corresponding to the largest eigenvalues.

```
Algorithm 1: Power Iteration
Set \(v_{0}\) with \(\left\|v_{0}\right\|=1\).
for \(k=1\) to ... do
    \(w=A v^{k}\)
    \(v^{k}=w /\|w\|\)
    \(\lambda^{k}=\left(v^{k}\right)^{T} A v^{k}\)
```

Theorem 1.2. Suppose $\left|\lambda_{1}\right|>\left|\lambda_{2}\right| \geq \ldots \geq\left|\lambda_{m}\right| \geq 0$ and $q_{1}^{T} v^{0} \neq 0$. Then the algorithm satisfies,

$$
\begin{align*}
& \left\|v^{k}-q_{1}\right\|=\mathcal{O}\left(\left|\frac{\lambda_{2}}{\lambda_{1}}\right|^{k}\right),  \tag{4}\\
& \left|\lambda^{k}-\lambda_{1}\right|=\mathcal{O}\left(\left|\frac{\lambda_{2}}{\lambda_{1}}\right|^{2 k}\right) \tag{5}
\end{align*}
$$

as $k \rightarrow \infty$

Remark 1. Power iteration has some limitations.

1. It can only find the largest eigenvectors corresponding to the largest eigenvalues.
2. The convergence is linear, i.e., the algorithm reduces the error by a factor $\left.\left\lvert\, \frac{\lambda_{2}}{\lambda_{1}}\right.\right)$ in every iteration.
3. The quality of the convergence depends on the quotient. If there is no huge eigen-gap, the convergence is slow.

### 1.1 Inverse Iteration

Let $\mu$ be a number which is not an eigenvalue of $A$, the eigenvectors of $(A-\mu I)^{-1}$ are the same as the eigenvectors of $A$, and the coresponding eigenvalues are $\left(\lambda_{j}-\mu\right)^{-1}$, where $\left\{\lambda_{j}\right\}$ are the eigenvalues of $A$.
This motivates us to design an algorithm to identify $\lambda_{j}$ and the corresponding eigenvectors of $A$. Suppose we know any estimate of $\lambda_{j}$ and denote it as $\mu .\left(\mu-\lambda_{j}\right)^{-1}$ will be very large. According to the Remark, the power iteration can identify $q_{j}$, which are the eigenvectors of $(A-\mu I)^{-1}$ (also the eigenvectors of $A$ ). This idea is called the inverse iteration.

```
Algorithm 2: Inverse iteration
\(v^{0}=\) some vectors with norm 1
for \(k=1\) to ... do
    Solve \((A-\mu I) w=v^{k-1}\) for \(w\)
    \(v^{k}=w /\|w\|\)
    \(\lambda^{k}=\left(v^{k}\right)^{T} A v^{k}\).
```

Rayleigh quotient is one method to estimate eigenvalues from an eigenvector estimation. Inverse iteration is an estimate of the eigenvector from the eigenvalues.

```
Algorithm 3: RQ iteration
\(v^{0}=\) some vectors with norm 1
\(\lambda^{0}=v^{0} A v^{0}=\) coresponding Rayleigh quotient.
for \(k=1\) to ... do
    Solve \(\left(A-\lambda^{k-1} I\right) w=v^{k-1}\) for \(w\)
    \(v^{k}=w /\|w\|\)
    \(\lambda^{k}=\left(v^{k}\right)^{T} A v^{k}\).
```

Without proof, the Rayleigh Quotient iteration has cubic convergence.

## 2 Reduction to Hessenberg form

Schur factorization returns $A=Q T Q^{*}$, where $T$ is a triangular matrix, i.e., we would like to apply unitary similarity transformation to introduce zeros below the diagonal. The natural first idea is to use the Householder.

The first Householder reflector $Q_{1}^{*}$ multiplied on the left of $A$ would introduce zeros below the diagonal in the first column, and the Householder reflector will change all rows of $A$. This is good up to now; however, if we complete the process of multiplying $Q_{1}$ on the right, all zeros previously introduced are destroyed. We will verify this in class.
The good idea in step 1 is to choose a unitary matrix $Q_{1}^{*}$ that will leave the first row unchanged. It will change the second row to the last row and introduce zeros below the second entry in the first column. It can be verified that the right multiplication by $Q_{1}$ will not change the zeros introduced by $Q_{1}^{*}$. After repeating this process for $m-2$ times, the resulting matrix is in the Hessenberg form, denoted as $H$.

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Algorithm 4: Reduction to Hessenberg
for \(k=1\) to \(m-2\) do
    \(x=A_{k+1: m, k}\)
    \(v_{k}=\left(\operatorname{sign}\left(x_{1}\right)\right)\|x\|_{2} e_{1}+x\)
    \(v_{k}=v_{k} /\left\|v_{k}\right\|\)
    \(A_{k+1: m, k: m}=A_{k+1: m, k: m}-2 v_{k} v_{k}^{*} A_{k+1: m, k: m}\)
    \(A_{1: m, k+1: m}=A_{1: m, k+1: m}-2 A_{1: m, k+1: m} v_{k} v_{k}^{*}\)
```

When $A$ is Hermitian, $H$ is symmetric, then $H$ is a tridiagonal matrix.

## 3 QR Algorithm

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Algorithm 5: QR Algorithm for \(e^{\text {'igenvalue. }}\)
\(A_{1}=A\)
for \(k=1\) to ... do
    \(Q_{k} R_{k}=A_{k}\)
    \(A_{k+1}=R_{k} Q_{k}\).
```

The algorithm converges to the Schur form of the matrix $A$. Specifically, suppose $A$ admits the Schur decomposition $A=U T U^{T}$, then $A_{k}$ converges to $T$.

Remark 2. Some properties regarding the algorithm.

1. $A_{k+1}=R_{k} Q_{k}$, since $A_{k}=Q_{k} R_{k}, R_{k}=Q_{k}^{t} A_{k}$, this implies that $A_{k+1}=Q_{k}^{t} A_{k} Q_{k}$. That is, all $A_{k}$ are unitarily similar to each other, i.e., eigenvalues of all $A_{k}$ and $A$ are the same. Since $A^{k}$ converges to $T$, we have the eigenvalues of $A$.
2. Let us define $Q^{(k)}=Q_{1} Q_{2} \ldots Q_{k}$ and $R^{(k)}=R_{k} R_{k-1} \ldots R_{1}$, we have the following theorem.

Property 3.0.1. (a) $A_{k+1}=\left(Q^{(k)}\right)^{t} A Q^{(k)}$.
(b) $A^{k}=Q^{(k)} R^{(k)}$.

Proof. The property (a) is trivial to prove and let us the property (b). Let us prove by induction. $k=1$ case is trivial. Suppose $A^{k-1}=Q^{(k-1)} R^{(k-1)}$ is true. By the property (a) and the algorithm definition, we have,

$$
\begin{equation*}
A_{k}=\left(Q^{(k-1)}\right)^{t} A Q^{(k-1)}=Q_{k} R_{k} . \tag{6}
\end{equation*}
$$

Algorithm 4 Reduction to Hessenkerg $A \in \mathbb{R}^{\text {mam }}$

$$
\begin{aligned}
& \text { For } k=1 \text { to } m-2 \\
& x=A_{k+1!w, k} \\
& v_{k}=-\|x\| e_{1}+x \\
& V_{k}=V_{k} /\left\|V_{k}\right\| \\
& Q_{k}^{*} A \rightharpoondown A_{k+1: m, k: m}=A_{k+1: m, k: m} \sim 2 V_{k} \cup_{k}^{t} A_{k+1: m, k: m} \\
& Q_{k}^{*} A Q_{k} A_{1: m, k+1: m}=A_{1: m, k+1: m}-2 A_{1: m, n+1: m} V_{k} V_{k}^{A} \\
& Q_{k}^{*}\left[\left(Q_{k}^{*} A\right)^{*}\right]
\end{aligned}
$$

Q 1: What is the computational cost?
Household: $O\left(m^{3}\right)$
Total cost: $\quad 20\left(\mathrm{~m}^{3}\right)$

Q2. The algo is b/w stable.
$A=Q H Q^{*}$, Let $\tilde{C}$ \& $\tilde{H}$ be the output of the argo 4
3. QR for eiyenvalue.
$1 \quad A_{1}=A$
$A \in \mathbb{R}^{m \cdot m}$ symmetric
2 for $k=1$, to,$\ldots$

3

4

$$
\begin{aligned}
& Q_{k} R_{k}=A_{k}, \quad\left(Q R \text { of } A_{k}\right) . \\
& A_{k+1}=R_{k} Q_{k}
\end{aligned}
$$

output: $A_{p+1}$
$A_{p+1} \longrightarrow$ Schur form of $A$.
$A \in \|^{m m}, \quad A=U T U^{*}, \quad T$ : schur form of $A$. schur fuctorization.
P.P. $\quad A_{k+1}=R_{k} Q_{k} \rightarrow$ line 4 .
line 3

$$
Q_{k} R_{k}=A_{k} \quad \Rightarrow \quad R_{k}=Q_{k}^{t} A_{k}
$$

$A_{n+1}=Q_{k}^{+} A_{k} Q_{k}, \quad A_{k+1}$ is unitarily similar to $A_{k}$.
$\Rightarrow A_{k+1}$ \& $A_{k}$ heve the same e.vals.

$$
\text { p.p. (a) } Q^{\left(b_{1}\right)}=Q_{1} Q_{2} \ldots Q_{k}, R^{(k)}=R_{k} R_{k-1} \ldots R_{1}
$$

$$
A_{k+1}=\left(Q^{(k)}\right)^{+} A Q^{(k)}
$$

(b) $\quad A^{k}=C Q^{(k)} R^{(k)}$
pf: Lat us prove by the mathematical induction. step 1: This is true for $A^{2}$ step 2. Assume $A^{k-1}=Q^{(k-1)} R^{(k-1)}$

$$
\begin{aligned}
& \text { step } 3 . \\
& A_{k} \stackrel{P_{P} \cdot(a)}{=}\left(Q^{(k-1)}\right)^{t} A Q Q^{(k-1)} \stackrel{\text { line } 3}{=} Q_{k} R_{k} \\
& \Rightarrow \quad A Q^{(k-1)}=\quad Q^{(b-1)} Q_{k} R_{k} \\
& A^{k}=A \cdot A^{k-1} \stackrel{\text { arsunpton }}{=} A \cdot Q^{(b-1)} R^{(h-1)} \\
& =Q^{(k-1)} \cdot Q_{k} R_{k} R^{(k-1)} \\
& =Q^{(k)} R^{(k)} \text {. }
\end{aligned}
$$

The aldo provides us a way to calculate the $Q R$ of $A^{k}$.

Relation w/ power iteration.
the cols of $A^{k}$ are Jominanted by the Leading eigenvectors of $A$ (e:g-vector corresponding to the (algest eig_value)

Multiplying both sides by $Q^{(k-1)}$, it follows that $A Q^{(k-1)}=Q^{(k-1)} Q_{k} R_{k}$. Substitute into the assumption,

$$
\begin{equation*}
A^{k}=A A^{k-1}=A Q^{(k-1)} R^{(k-1)}=Q^{(k-1)} Q_{k} R_{k} R^{(k-1)}=Q^{(k)} R^{(k)} . \tag{7}
\end{equation*}
$$

The property provides us with one way to compute the QR factorization of matrix power. It can be shown that, this algorithm is stable.

We now intuitively explain the connection between QR and the Power iteration. It can be shown that columns of $A^{k}$ are dominated by the "leading" eigenvector $x_{1}$ of $A$, i.e., $A x_{1}=\lambda_{1} x_{1}$. Let us consider $A^{k} e_{1}=Q^{(k)} R^{(k)} e_{1}=c q_{1}$, where $q_{1}$ is the first column of $Q^{(k)}$ scaled by constant c. This implies that the leading eigenvector of $A$ is related to $q_{1}$. Property (a) shows that $A_{k+1}=\left(Q^{(k)}\right)^{t} A Q^{(k)}$ and $A_{k+1}$ is the Schur form of $A$, this indicates that $q_{1}$ is the eigenvector of $A$ and $A_{k+1}[1,1]$ is the corresponding eigenvalue.

