Singular value decomposition (SVD)

Zecheng Zhang

February 10, 2023

This section will discuss singular value decomposition (SVD) of a matrix $A \in \mathbb{R}^{m \times n}$.

1 Construction

Step 1. The first singular value is defined as:

$$\sigma_1 = \sup_{\|v\|=1} \|Av\|.$$

Remark 1. The first singular value is well defined, i.e., such a $v_1 \in \mathbb{R}^n$ always exists. Nonrigorous argument: the function $: v \to ||Av||$ is continuous and with a compact domain.

Now one can find $u_1 \in \mathbb{R}^m$ with $||u_1|| = 1$ such that $Av_1 = \sigma_1 u_1$.

One can follow the definition of the first singular value and define the second singular value as,

$$\sigma_2 = \sup_{\|v\|=1, v \perp v_1} \|Av\|.$$

The remark 1 implies that such a v_2 always exists and let us denote it as v_2 . In addition, we can find $u_2 \in \mathbb{R}^m$ with $||u_2|| = 1$ such that $Av_2 = \sigma_2 u_2$.

Remark 2. $\sigma_2 \leq \sigma_1$ because v_2 is taken from a smaller subspace $\{v_1\}^{\perp} \subset \mathbb{R}^n$.

Theorem 1.1. u_1 and u_2 which are defined above are orthogonal.

The theorem implies that $u_1 \perp u_2$. Repeat the process, one can find a unit vector $v_3 \in W_2 = \{v_1, v_2\}^{\perp}$ such that it admits

$$\sigma_3 = \sup_{\|v\|=1, v \in V_2} \|Av\|.$$

In addition, one can find a unit vector u_3 such that $Av_3 = \sigma_3 u_3$. One can show that $\{u_1, u_2, u_3\}$ are orthogonal.

Remark 3. Let us define $W_p = \{v_1, v_2, ..., v_p\}^{\perp}$. If $\sup_{v \in W_p} ||Av|| = 0$, or, $Av_{p+1} = 0$, we can make u_{p+1} (nonzero if possible) to be any vector which is orthogonal to $\{u_1, ..., u_p\}$. If u_{p+1} has to be zero, $span\{u_1, ..., u_p\} = \mathbb{R}^m$

Repeat the process for *n* times (why is *n* the maximum step of the process?), we then can construct an orthonormal matrix $V = [v_1, ..., v_n] \in \mathbb{R}^{n \times n}$, another matrix with orthonormal columns $U = [u_1, ..., u_n] \in \mathbb{R}^{m \times n}$ up to some 0 columns, and a diagonal matrix $\Sigma \in \mathbb{R}^{n \times n}$ with diagonal entries being $\sigma_1, ..., \sigma_n$ (up to some 0). Recall the matrix multiplication we have,

$$AV = U\Sigma.$$

$$\begin{aligned} step 1, \qquad G_{1} &= sup || A V || \\ & velp'' \\ & uvl = 1. \end{aligned}$$

$$\begin{aligned} F_{1mk} U_{1} &= I_{1}, \\ A V_{1} &= G_{1} U_{1}, \\ U_{1} &= G_{1} U_{1}, \\ U_{1} &= \frac{A V_{1}}{G_{1}}, \\ u_{1} &= \frac{A V_{1}}{G_{1}}, \\ u_{1} &= \frac{A V_{1}}{G_{1}} = 1. \end{aligned}$$

$$\begin{aligned} step 2. \qquad G_{2} &= sup || A V || \\ & velp'' \\ & velp'' \\ & velp'' \\ & velp'' \\ & uvl = 1. \end{aligned}$$

Find
$$v_2 \in [k^m]$$
, $||v_2|| = 1$,

 $Av_2 = 62 U_2$,
 $||Av_2|| = 6_2$, $||v_2|| = 1$, $v_2 \in [v_1]^d$
 $Av_2 = 62 U_2$,
 $||Av_2|| = 6_2$, $||v_2|| = 1$, $v_2 \in [v_1]^d$
 $U_1 \otimes U_2$ are
 $U_1 \otimes U_2$ are

 $Step 3.$
 $G_3 = \sup_{v \in [k^m]} ||Av||$,
 $Ov \text{thogonal}$
 $VL \text{ five} v_2$
 $Thm 1.1.$

$$A v_{3} = G_{3} v_{3}$$
, $(A v_{3} | l = G_{3}, |(v_{3} | l = 1), v_{3} \perp \int v_{1} v_{2} \int$

	U, U2 UZ CNE
Pausanh	orthogonal
R Ewdurk.	Thm I.I.

1111=1

2. Q: How many steps can use do?
A:
$$N - steps$$
.
3. Q.: suppose $V_p = spear \{V_1 - V_p\}$
with $G_1 - G_p \neq 0$, but.
 $G_{pq1} = \sup_{V \in IR} II \land VII = 0$
 $V \perp V_p$
 $II \land VII = 1$
 $II \land VII \neq 0$ (c) $\land V = 0$, $V \in mult(A)$
 $Or ull conditates [V_p^{\perp}] \subseteq mult(A)$
 $G_r ull conditates [V_p^{\perp}] \subseteq mult(A)$
 $II \land VII \neq 0$, $h = 0$, $h = 10$ find V_{pH}
A: construct a U_{pH} which is orthogonal to $[U_1 - U_p]$
 $Eg. U_1 = {0 \choose p}$ $V_2 = {0 \choose p}$
 $U_3 = {0 \choose p}$ (rematricet V_3)

5: Q:
$$u_{1} = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \quad u_{2} = \begin{pmatrix} 0 \\ 1 \end{pmatrix}, \quad G_{5} = 0$$

 $u_{5} = 0$
6. Q: $u_{1}u_{1}$ $u_{n+1}u_{n+5}t \quad b = 0$?
A: $p_{1} > u = fin (R^{n}), \quad Ui \in R^{m}$
 $\begin{cases} A \quad v_{1} = & G_{1} \ u_{1} \\ A \quad v_{2} = & G_{2} \ u_{2} \\ \dots & \dots \\ A \quad u_{n} = & G_{n} \ u_{n} \end{cases}$
Denote $V = [\quad v_{1} \ v_{2} \dots \ v_{n}] \in R^{n, n}, \quad V \text{ is contregendent metrics}$
 $U = [\quad u_{1} \ \dots \ u_{n}] \in R^{m, n}, \quad V \text{ is contregendent metrics}$
 $U = [\quad u_{1} \ \dots \ u_{n}] \in R^{m, n}, \quad V \text{ is contregendent metrics}$
 $A \quad v = U \equiv \int U^{1} \ v_{n} = \int U^{1} A \quad v_{n} = \int U = \int U^{1} \ v_{n} = \int U = \int U = \int U^{1} \ v_{n} = \int U = \int U^{1} \ v_{n} = \int U = \int$



Theorem 1.2. rank(A) equals to the number of nonzero singular values.

Proof. Let us assume $\{\sigma_1, ..., \sigma_p\}$ are all nonzero singular values but $\sigma_{p+1} = 0$. Let $V_p =$ $\{v_1, ..., v_p\}$ be the singular vector corresponding to $\sigma_1, ..., \sigma_p$. We claim that $V_p \subset row(A)$. We have $AV = U\Sigma$, or $U^T A = \Sigma V^T$. The i - th row $(i \leq p)$ of the right-hand side is $\sigma_i v_i^t$. The i-th row on the left-hand side is $(u_i)^t A$, it follows that $v_i^t = \frac{1}{\sigma_i} (u_i)^t A$. This implies that $V_p \subset row(A)$.

By theorem in the last section (Complement theorem), $null(A) = row(A)^{\perp} \subset V_p^{\perp}$. Now, for $v \in V_p^{\perp}$, we have Av = 0, otherwise contradicts with the definition of V_p . As a result, $V_p^{\perp} \subset null(A)$, i.e., $V_p^{\perp} = null(A)$. By the rank theorem, $dim(V_p) = rank(A)$.

As a corollary, $V_p = row(A)$. We summarize the results in the following theorem.

Theorem 1.3. Assume $\{\sigma_1, ..., \sigma_p\}$ are all nonzero singular values, $\{v_1, ..., v_p\}$ and $\{u_1, ..., u_p\}$ are right and left singular vectors respectively, we denote the space spanned by them as V_p and U_p . The followings are true: This imply

claim =rou(A) *Proof.* The first one is/proved in the last theorem and let us prove $U_p = col(A)$. We claim that for any $y \in \mathbb{R}^n$, there exists $x \in row(A)$ such that Ax = Ay. When $y \in row(A)$, it is true. When $y \notin row(A)$, assume not, i.e., for all $x \in row(A)$, A(x-y) = 0. This implies that $x - y \in null(A)^{\bullet}$. It follows from the theorem we discussed in the last section that $\exists X \in V \land A$ $x - y \in row(A)$. However, this is the contradiction. The claim is proved. シメーロ

Now for any $y \in \mathbb{R}^n$, let $y_x \in row(A)$ such that $Ay_x = Ay$. Since $V_p = row(A)$, $y_x = \sum_{i=1}^p c_i^y v_i$ for some constants c_i . It follows that $Ay = \sum_i \sigma_i c_i^y u_i$. The other direction is also true, this implies that $col(A) = U_p$.

Full SVD: make U matrix orthonormal when m > n. One can append an additional m - northonormal columns to fulfill this goal. Σ should change as well so that the product $AV = U\Sigma$ still holds. To do this, one can append m - n zero rows to the bottom of Σ . As a result, we have $AV = U\Sigma$ where $V \in \mathbb{R}^{n \times n}$, $U \in \mathbb{R}^{m \times m}$ and $\Sigma \in \mathbb{R}^{m \times n}$. Since V is orthonormal, we have: $A = U\Sigma V^{-1}. \qquad \forall y \qquad co((A) \equiv \langle A y, y \in h^{n} \rangle)$ $vat \qquad y = \sum_{r=1}^{n} c_{r} v_{r}, \quad \sqrt{2} \langle v_{1} - \sqrt{n} \rangle$

2 Revisit SVD

From SVD 2.1

6

Let $A \in \mathbb{R}^{m \times n}$. Suppose A admits an SVD $A = U\Sigma V^t$, where $U \in \mathbb{R}^{m \times m}$, $V \in \mathbb{R}^{n \times n}$ are () ION orthogonal matrices and $\Sigma \in \mathbb{R}^{m \times n}$ is a diagonal matrix. Let us so consider $AA^t \in \mathbb{R}^m \setminus M$ and = zpan (apr. Ap) $A^t A \in \mathbb{R}^{n \times n}$, which are symmetric matrices.

$$A^{t}A = V\Sigma^{t}U^{t}U\Sigma V^{t} = V\Sigma^{t}\Sigma V^{t},$$

$$AA^{t} = U\Sigma V^{t}V\Sigma^{t}U^{t} = U\Sigma\Sigma^{t}U^{t}.$$

01 Y -D

this is

the contradict

 $A_{j} = \sum_{i=1}^{\infty} (iA_{i}) = \sum_{i=1}^{p} (iG_{i})$

 $\Sigma\Sigma^2$ and $\Sigma^2\Sigma$ are still diagonal, and nonzero entries of these two matrices are indeed singular - k and Up - +values squared. They we dre

In addition, since U and V are orthogonal (hence invertible), this implies that $V\Sigma^t\Sigma V^t$ and $U\Sigma\Sigma^t U^t$ are the eigenvalue decomposition (diagonalization) of $A^t A$ and AA^t (theorem 4.1 in diagonalization section).

From eigenvalue decomposition 2.2

 $A^{t}A$ is symmetric and by the Spectral theorem, let $\{v_{i}\}_{i=1}^{n}$ be the orthonormal eigenvectors of $A^{t}A$ corresponding to eigenvalue $\lambda_{1} \geq \lambda_{2} \dots \geq \lambda_{n}$ We first claim that $\lambda_{1} \geq \lambda_{2} \dots \geq \lambda_{n} \geq 0$. We 11×11,1,- (Vr, 4r)> have, real

$$\|Av_{i}\|^{2} = (Av_{i})^{t}Av_{i} = v_{i}^{t}A^{t}Av_{i} = \lambda_{i}\|v\|^{2} \ge 0, \quad \forall AV_{i}\|^{2} = (Av_{i})^{t}A^{v}(Av_{i})^{t} = (Av_{i})^{t}A^{v}(Av_{i})^{t}$$

 $= \mathcal{N} || \mathcal{N}_{i}^{\prime}(|)$

AtAN: - NiVi

it implies that $\lambda_i \geq 0$.

Let $\sigma_1 = \sqrt{\lambda_1}$ for all *i*. We want to find $\{u_k\}_k$, which are orthonormal, such that,

$$Av_k = \sigma_k u_k.$$

 $z v_i^{\dagger} \lambda v_i^{\prime}$ When $\sigma_k \neq 0$, one can define $u_k = \frac{1}{\sigma_k} A v_k$. Let us claim all u_k are orthonormal. Let u_i, u_j be nonzero and defined as before. We have,

$$u_i^t u_j = \frac{1}{\sigma_i \sigma_j} v_i^t A^t A v_j = v_i^t v_j = \delta_{ij}.$$

The claim is proved. When $\lambda_p = 0$, for some $1 \le p \le n$, we can construct u_p which is orthogonal to u_1, u_2, \dots, u_{p-1} . If $\{u_1, \dots, u_{p-1}\}$ have formed a basis for \mathbb{R}^m , then set $u_p = 0$. Now we can construct an orthonormal matrix $V = [v_1, ..., v_n] \in \mathbb{R}^{n \times n}$, another matrix with orthonormal columns $U = [u_1, ..., u_n] \in \mathbb{R}^{m \times n}$ up to some 0 columns, and a diagonal matrix $\Sigma \in \mathbb{R}^{n \times n}$ with diagonal entries being $\sigma_1, ..., \sigma_n$. The SVD follows: $AV = U\Sigma$. One can apply the same trick as before to make U a square matrix and obtain the full SVD.

Remark 4. Nonzero u_k constructed before are eigenvectors of AA^t . The proof is simple.

$$AA^{t}u_{k} = AA^{t}\frac{1}{\sigma_{k}}Av_{k} = A\frac{1}{\sigma_{k}}A^{t}Av_{k} = A\sigma_{k}v_{k} = \sigma_{k}^{2}u_{k}.$$

Remark 5. If $S = S^t$ is symmetric and assumes all eigenvalues are non-negative, then the eigenvalue decomposition is the SVD (as long as the eigenvalues are in descending order).

3 **Rank** k approximation

Let us consider the SVD of $A \in \mathbb{R}^{m \times n}$, i.e., $A = U\Sigma V^t$. Recall the matrix multiplication, we have a decomposition for A as,

$$A = \sum_{i=1}^{n} \sigma_i u_i v_i^t = \sum_{i=1}^{r} \sigma_i u_i v_i^t,$$

where $\{\sigma_i\}_{i=1}^r$ are all nonzero singular values of A. Let us define an approximation A_k to A as:

$$A_k = \sum_{i=1}^k \sigma_i u_i v_i^t,$$

where $k \leq r$. It is easy to check $rank(A_k) = k$. We then can show A_k is the best approximation to A; the result is summarized in the following theorem.

3.1 Preliminaries

Definition 3.1. L^2 norm of a matrix $A \in \mathbb{R}^{m \times n}$ is defined as:

$$||A||_2 = \max_{x \in \mathbb{R}^n, ||x||=1} ||Ax|| = \max_{x \in \mathbb{R}^n, x \neq 0} \frac{||Ax||}{||x||} = \sigma_1.$$

In the rest of the notes, we sometimes write $\|\cdot\|_2$ as $\|\cdot\|$ for simplicity.

Remark 6. For any $x \in \mathbb{R}^n$ and $x \neq 0$, we have, $\frac{\|Ax\|}{\|x\|} \leq \|A\|_2$. This implies that $\|Ax\| \leq \|A\| \|x\|$.

3.2 Eckart-Young theorem

Theorem 3.2 (Eckart-Young). Suppose $A, B \in \mathbb{R}^{m \times n}$ and $rank(B) = k \leq rank(A) = r$. We then have:

$$||A - B|| \ge ||A - A_k|| = \sigma_{k+1}$$

That is A_k is the best rank k approximation to A in the L^2 sense.

Proof. We first prove that $||A - A_k|| = \sigma_{k+1}$. We have,

$$A - A_k = \sum_{i=k+1}^n \sigma_i u_i v_i^t = \sum_{i=1}^{n-k} \sigma_{i+k} u_{i+k} v_{i+k}^t + \sum_{i=n-k+1}^n \tilde{\sigma}_i \tilde{u}_i \tilde{v}_i^t,$$

where $\tilde{\sigma}_i = 0$, \tilde{u}_i are orthonormal to all u_{i+k} , and \tilde{v}_i are also orthonormal to all v_{i+k} . The summation is then an SVD of $A - A_k$. Since $||A - A_k||$ is equal to the first singular value of its SVD, we have $||A - A_k|| = \sigma_{k+1}$.

Assume not, i.e., assume there is $B \in \mathbb{R}^{m \times n}$ with rank(B) = k such that $||A - B|| < ||A - A_k|| = \sigma_{k+1}$. For any $w \in \mathbb{R}^n$, we have $||(A - B)w|| < \sigma_{k+1}||w||$. It follows that, for any $w \in null(B)$, we have,

$$\|(A - B)w\| = \|Aw\| < \sigma_{k+1} \|w\|.$$
(1)

Now for any $w \in V_{k+1} = span\{v_1, v_2, ..., v_{k+1}\}$, we claim that $||Aw|| \ge \sigma_{k+1}||w||$. Since $w \in V_{k+1}$, there exist $c_1, ..., c_{k+1}$, such that $w = \sum_{i=1}^{k+1} c_i v_i$. It follows that

$$\|Aw\| = \|\sum_{i=1}^{k+1} c_i Av_i\| = \sum_{i=1}^{k+1} |c_i|\sigma_i \ge \sigma_{k+1} \|w\|,$$
(2)

where the last inequality is due to the orthogonality of v_i and $\sigma_1 \ge ... \ge \sigma_{k+1}$.

The Rank theorem indicates that dim(null(B)) = n - k, however $dim(V_{k+1}) = k + 1$. We then have $dim(null(B)) + dim(V_{k+1}) > n$. Since null(B) and V_{k+1} both are subspace of \mathbb{R}^n , this implies that there exists $w \neq 0$ such that $w \in null(B) \cap V_{k+1}$. However, 1 and 2 cannot hold simultaneously, which is the contradiction.

Corollary 3.2.1. Suppose $A, B \in \mathbb{R}^{m \times n}$ and $rank(B) \le k \le rank(A) = r$. We then have:

$$||A - B|| \ge ||A - A_k|| = \sigma_{k+1}$$

Proof. Let rank(B) = k - j, $0 \le j \le k$, by Eckart-Young, we have $||A - B|| \ge ||A - A_{k-j}|| = \sigma_{k-j+1} \ge \sigma_{k+1} = ||A - A_k||$.

3.3 Eckart-Young theorem (Frobenius)

Definition 3.3. The Frobenius norm of $A \in \mathbb{R}^{m \times n}$ is:

$$|A||_F = \sqrt{\sum_{i=1}^m \sum_{j=1}^n a_{ij}^2}.$$

Theorem 3.4. Frobenius norm can be calculated in the following way,

$$\|A\|_F^2 = \sum_i \sigma_i^2.$$

Corollary 3.4.1. Let the SVD of A be $A = U\Sigma V^t$, and $U = [u_1, ..., u_n]$, $V = [v_1, ..., v_n]$, and the diagonal entries of Σ are $\sigma_1, ..., \sigma_n$. Let $A_k = \sum_{i=1}^k \sigma_i u_i v_i^t$, we have,

$$||A - A_k||_F^2 = \sum_{i=k+1}^n \sigma_i^2$$

Theorem 3.5 (Courant Fisher min max). For $A \in \mathbb{R}^{m \times n}$, the singular value σ_i of A satisfy:

$$\sigma_k = \max_{\substack{V \subset \mathbb{R}^n, \dim(V) = k}} \min_{\substack{v \in V, \|v\| = 1}} \|Av\|,$$

$$\sigma_{k+1} = \min_{\substack{V \subset \mathbb{R}^n, \dim V = n-k}} \max_{\substack{v \in v, \|v\| = 1}} \|Av\|.$$

Proof. Let us prove the first one first. Let V be any k- dimensional space. Since $dim(span\{v_k, ..., v_n\}) = n - k + 1$, V intersects $span\{v_k, ..., v_n\}$ nontrivially. Let v be a unit vector in the intersection, i.e., there exist $c_k, ..., c_n$ such that, $v = \sum_{i=k}^n c_i v_i$. Moreover, $\|v\| = \sum_{i=k}^n |c_i| = 1$. We have, $Av = \sum_{i=k}^n c_i \sigma_i u_i$, it follows that, $\|Av\| = \sum_{i=k}^n |c_i|\sigma_i\|u_i\| \le \sigma_k$. This implies that for any V of dimension k, there exists v such that $\|Av\| \le \sigma_k$, i.e., $\min_{v \in V, \|v\| = 1} \|Av\| \le \sigma_k$. Now we need to find a V such that the equality sign holds, i.e., $\|Av\| = \sigma_k$. We claim that V can be $span\{v_1, ..., v_k\}$, i.e., $V \cap span\{v_k, ..., v_n\} = span\{v_k\}$. Now let $v = v_k$, it follows that $\|Av\| = \sigma_k$. The claim is proved, i.e., maximizing over all V, we can obtain the equal sign.

The second one can be derived similarly. Let V be any (n-k)- dimensional subspace of \mathbb{R}^n , it intersects $V_{k+1} := span\{v_1, ..., v_{k+1}\}$ nontrivially, i.e., there exists unit vector v in the intersection. It follows that, there exist $c_1, ..., c_{k+1}$ such that $v = \sum_{i=1}^{k+1} c_i v_i$. We have $Av = \sum_{i=1}^{k+1} c_i \sigma_i u_i$, it follows that, $||Av|| \ge \sigma_{k+1}$. This implies that for any V of dimension n-k, there exists v such that $||Av|| \ge \sigma_{k+1}$, i.e., $\max_{v \in V, ||v||=1} ||Av|| \ge \sigma_{k+1}$. The equality holds when $V = span\{v_{k+1}, ..., v_n\}$ and $v = v_{k+1}$.

Theorem 3.6 (Weyl). Let $A, B \in \mathbb{R}^{m \times n}$, and denote the singular values as $\sigma_i(A)$ and $\sigma_i(B)$. We then have:

$$\sigma_{i+j-1}(A+B) \le \sigma_i(A) + \sigma_j(B). \tag{3}$$

Proof. Let V_A , and V_B be the subspace of \mathbb{R}^n of dimensions n-k and n-l, which are orthogonal to the first k and l right singular vectors of A and B respectively. Let $W = V_A \cap V_B$, we have $\dim(W) \ge n-k-l$. It follows that,

$$\max_{v \in W, \|v\|=1} \|Av + Bv\| = \max_{v \in W, \|v\|=1} \|Av\| + \|Bv\| \le \sigma_{k+1} + \sigma_{l+1}.$$

By Curant-Fisher,

$$\sigma_{k+l+1}(A+B) = \min_{V \subset \mathbb{R}^n, dim V = n-k-l} \max_{v \in v, \|v\|=1} \|Av + Bv\| \le \max_{v \in W, \|v\|=1} \|Av + Bv\| = \sigma_{k+1} + \sigma_{l+1}.$$

Weyl's inequality will help us prove the Eckart-Young for the Frobenius norm.

Theorem 3.7 (Eckart-Young Frobenius). Suppose $A, B \in \mathbb{R}^{m \times n}$ and $rank(B) = k \leq rank(A) = r$. We then have:

$$||A - B||_F^2 \ge ||A - A_k||_F^2 = \sum_{i=k+1} \sigma_i^2.$$

That is A_k is the best rank k approximation to A in the L^2 sense.

Proof. Let X = A - B and Y = B and apply Weyl's inequality 3.6,

$$\sigma_{i+k}(A) \le \sigma_i(A-B) + \sigma_{k+1}(B) = \sigma_i(A-B),$$

where is last equal sign is due to rank(B) = k. Apply Corollary 3.4.1 it follows that,

$$\|A - A_k\|_F^2$$

= $\sum_{i=k+1}^r \sigma_i(A)^2 = \sum_{i=1}^{r-k} \sigma_{i+k}^2(A) \le \sum_{i=1}^{r-k} \sigma_i^2(A - B) \le \sum_{i=1}^{min(m,n)} \sigma_i^2(A - B) = \|A - B\|_F^2.$

A direct consequence of the Eckart-Young for the Frobenius norm is the proper orthogonal decomposition (POD).

3.4 Proper orthogonal decomposition (POD)

Given $A = [y_1, y_2, ..., y_n] \in \mathbb{R}^{m \times n}$, and a set of orthonormal vectors $Q = [x_1, ..., x_k] \in \mathbb{R}^{m \times k}$, one wants to solve the following problem:

$$\min_{Q} \sum_{i=1}^{n} \|y_i - \sum_{j=1}^{k} \langle y_i, x_j \rangle \| x_j \|^2.$$
(4)

We claim that the equation 4 is equivalent to the matrix form,

$$\sum_{i=1}^{n} \|y_i - \sum_{j=1}^{k} \langle y_i, x_j \rangle x_j \|^2 = \|A - QQ^t A\|_F.$$
(5)

Denote the matrix as columns, i.e., $||A - QQ^tA||_F = ||[y_1 - QQ^Ty_1, ..., y_n - QQ^ty_n]||_F$; and denote $y_i - QQ^Ty_i$ as $z_i \in \mathbb{R}^m$, it follows that,

$$||[y_1 - QQ^T y_1, ..., y_n - QQ^t y_n]||_F^2 = \sum_{i=1}^n \sum_{j=1}^m z_{ji}^2 = \sum_{i=1}^n ||z_i||^2 = \sum_{i=1}^n ||y_i - QQ^t y_i||^2.$$

It is not hard to see $QQ^t y_i = \sum_{j=1}^k \langle y_i, x_j \rangle x_j$. The claim is proved. Apply the Eckart-Young theorem for the Frobenius norm; we then have the POD theorem.

Theorem 3.8. Given $A = [y_1, y_2, ..., y_n] \in \mathbb{R}^{m \times n}$ with rank r. For any $k \leq r$, we consider,

$$\min_{Q} \sum_{i=1}^{n} \|y_i - \sum_{j=1}^{k} \langle y_i, x_j \rangle x_j \|^2,$$
(6)

where $Q = [x_1, ..., x_k] \in \mathbb{R}^{m \times k}$ is a set of orthonormal vectors. The minimum is given by the left singular vectors of A, which are also called proper orthogonal modes. Denote the singular values of A as σ_i , the minimum is equal to $\sum_{i=k+1}^r \sigma_i^2$.

Proof. The only statement left to prove is $QQ^T A = A_k$ if $Q = [u_1, ..., u_k]$ and u_k are the singular vectors. We have,

$$QQ^{T}A = [u_{1}, u_{2}, ..., u_{k}][u_{1}, u_{2}, ..., u_{k}]^{t}A = \sum_{i=1}^{k} u_{i}u_{i}^{t}A.$$

r	-	-	-
L			
L			
L			