Last time:

 $\tilde{P} \longrightarrow \tilde{E}_{n}(D_{n} S_{n+1}) = D_{n} S_{n}$ (Disconted stork is a Mg under P) Risk neutral Mecane.

**Theorem 4.57.** Let  $X_n$  represent the wealth of a portfolio at time n. The portfolio is self-financing portfolio if and only if the discounted wealth  $D_nX_n$  is a martingale under the risk neutral measure  $\tilde{P}$ .

Remark 4.58. Recall a portfolio is self financing if  $X_{n+1} = \Delta_n S_{n+1} + (1+r)(X_n - \Delta_n S_n)$  for some adapted process  $\Delta_n$ .

- (1) That is, self-financing portfolios use only tradable assets when trading, and don't look into the future.
- (2) All replication has to be done using self-financing portfolios.

Proof of Proposition (4.1.) ~~ Security by & V at the N Then AFP at time  $n \leq N$  is  $V_{n} = \frac{1}{D_{n}} \left( \tilde{E}_{n} \left( D_{N} V_{N} \right) \right)$ Pf & Price by replication. Pind a self fin fant or ? Want XN = VN. Nealth at time Kn -> Xn ? Want XN = N.

Thus we know  $\chi_n = A F P$ . () Chane  $X_N = V_N$ (2) Define  $X_n = \int_{D_n} \tilde{E}_n(D_N X_N) = \int_{D_m} \tilde{E}_n(D_N V_N)$ D<sub>n</sub>X<sub>n</sub> is a Mg mole P 3) (loim:  $P_{lo} = E_{n}(D_{n+1}X_{n+1}) \xrightarrow{W_{aut}} D_{n}X_{n}$ 

Know  $\widetilde{E}_{N}(D_{n+1}X_{n+1}) = \widetilde{E}_{N}(\widetilde{E}_{N+1}(D_{N}X_{N}))$  $\begin{array}{l} \overbrace{}^{t_{0}}\underset{}{}^{t_{0}}$ Knows  $X_N = V_N \implies \text{Replication} \implies \forall u \leq N, X_u = AFP.$ 

*Example* 4.59. Consider two stocks  $\underline{\underline{S}}^1$  and  $\underline{\underline{S}}^2$ ,  $\underline{\underline{u}} = 2$ ,  $\underline{\underline{d}} = 1/2$ .

- ▷ The coin flips for  $S^1$  are heads with probability 90%, and tails with probability 10%. || ▷ The coin flips for  $S^2$  are heads with probability 99%, and tails with probability 1%.
  - ▷ Which stock do you like more?
  - $\triangleright$  Amongst a call option for the two stocks with strike <u>K</u> and maturity <u>N</u>, which one will be priced higher?

Samp!  
Founda for 
$$\hat{f} = \frac{1+r-d}{r-d} \in \text{doesn't defaul on } \hat{f}$$
?

Remark 4.60. Even though the stock price changes according to a coin that flips heads with probability  $p_1$ , the arbitrage free price is computed using conditional expectations using the risk neutral probability. So when computing  $\tilde{E}_n V_N$ , we use our new invented "risk neutral" coin that flips heads with probability  $\tilde{p}_1$  and tails with probability  $\tilde{q}_1$ .

## Concepts that will be generalized to continuous time.

- Probability measure: Lebesgue\_integral, and not a finite sum. Same properties.
- Filtration: Same intuition. No easy description.
- Conditional expectation: Same properties, no formula.
- Risk neutral measure: Formula for  $\tilde{\boldsymbol{P}}$  is complicated (Girsanov theorem.)
- Everything still works because of of Theorem 4.57. Understanding why is harder.

5. Stochastic Processes

# 5.1. Brownian motion.

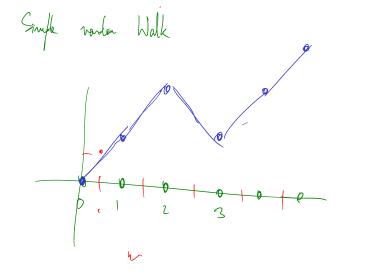
- Discrete time: Simple Random Walk.
  - $\triangleright X_n = \sum_{i=1}^{n} \xi_i$ , where  $\underline{\xi_i}$ 's are i.i.d.  $\underline{E}\xi_i = 0$ , and Range $(\xi_i) = \{\pm 1\}$ .
- Continuous time: Brownian motion.
  - $\begin{array}{l} \triangleright \ \underbrace{Y_t}_t = X_n + (\underline{t} n)\xi_{n+1} \ \text{if} \ t \in [n, n+1). \\ \triangleright \ \Bar{Rescale:} \ Y_t^\varepsilon = \sqrt{\varepsilon}Y_{t/\varepsilon}. \ (\text{Chose} \ \sqrt{\varepsilon} \ \text{factor to ensure Var}(Y_t^\varepsilon) \approx t.) \\ \triangleright \ \Let \ \underbrace{W_t}_t = \lim_{\varepsilon \to 0} Y_t^\varepsilon. \end{array}$

**Definition 5.1** (Brownian motion). The process W above is called a Brownian motion.

- ▷ Named after Robert Brown (a botanist).
- ▷ Definition is intuitive, but not as convenient to work with.



Better way: E3; = 1 n vat essential.

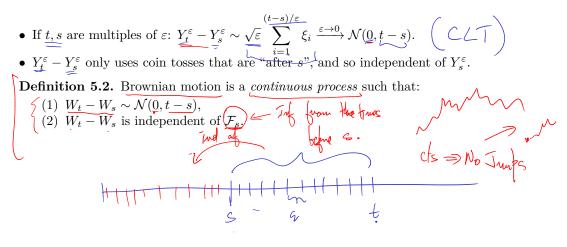


() Flip every 2 seconds DRechne step size lim 3 22 32 9.

-> Converto a "ets time RW" (Brownian motion) и

 $Y \quad (say \quad t/c \in \mathbb{N})$   $\frac{1}{4c} \quad \frac{1}{4c} \quad \frac{1}{4$ (Sun 'af t iid RV's mean D & Var 1)  $V_{av}(Y_{t_{a}}) \approx = \frac{t}{\epsilon}$ 

 $\Rightarrow V_{av}\left(\sqrt{z} \quad \frac{Y_{av}}{Y_{c}}\right) = \left(\sqrt{z}\right)^{2} \quad \frac{t}{z} = t$ 



#### 5.2. Sample space, measure, and filtration.

- Discrete time: Sample space Ω = {(ω<sub>1</sub>,..., ω<sub>N</sub>), ω<sub>1</sub> = outcome of the comtoss }
  View (ω<sub>1</sub>,..., ω<sub>N</sub>) as the trajectory of a random walk.
- Continuous time: Sample space  $\Omega = C([0, \infty))$  (space of continuous functions). ▷ It's infinite. No probability mass function!

to is.

 $\triangleright$  Mathematically impossible to define P(A) for all  $A \subseteq \Omega$ .

• Restrict our attention to 
$$\underline{\mathcal{G}}$$
, a subset of some sets  $A \subseteq \Omega$ , on which  $\underline{P}$  can be defined.  
 $\triangleright \ \overline{\mathcal{G}}$  is a  $\sigma$ -algebra. (Closed countable under unions, complements, intersections.)  
•  $P$  is called a *probability measure* on  $(\Omega, \overline{\mathcal{G}})$  if:  
 $\triangleright P: \underline{\mathcal{G}} \to [0, 1], P(\emptyset) = 0, P(\Omega) = 1,$   
 $\triangleright P(\underline{A} \cup \underline{B}) = P(A) + P(B)$  if  $\underline{A}, B \in \mathcal{G}$  are disjoint.  
 $\triangleright If \underline{A}_n \in \mathcal{G}, P(\bigcup_1 A_n) = \lim_{n \to \infty} P(A_n).$ 

Random variables are *measurable* functions of the sample space:
▷ Require {X ∈ A} ∈ G for every "nice" A ⊆ ℝ.
▷ E.g. {X = 1} ∈ G, {X > 5} ∈ G, {X ∈ [3,4]} ∈ G, etc.
▷ Recall {X ∈ A} = {ω ∈ Ω | X(ω) ∈ A}.

$$\frac{1}{2} \exp\left[\chi(\omega) > 0\right] = \frac{1}{2} \times \frac{1}{2} + \frac{1}{2} \times \frac{1}{2} + \frac{1}{2} \times \frac{1}{2} + \frac{1}{2} \times \frac{1}{2} \times \frac{1}{2} + \frac{1}{2} \times \frac{1}{2} \times \frac{1}{2} \times \frac{1}{2} + \frac{1}{2} \times \frac{1}{2} \times$$

-

• Expectation is a Lebesgue Integral: Notation 
$$\underline{EX} = \int_{\Omega} X(\omega) dP(\omega)$$
.  
 $\triangleright$  No simple formula.  
 $\triangleright$  If  $\underline{X} = \sum_{a_i \mid A_i}$ , then  $\underline{EX} = \sum_{a_i \mid P(A_i)} A_i \in \mathbb{R}$  Are distington  $A_i \in \mathbb{R}$  and  $A_i \in \mathbb{R}$ .  
 $\models \mathbf{1}_A$  is the indicator function of A:  $\mathbf{1}_A(\omega) = \begin{cases} 1 & \omega \in A \\ 0 & \omega \notin A \end{cases}$   
 $\models X = \mathbb{Z} \land_0 P(X = \alpha_i)$   
 $P_i \in \mathbb{R}$  is the indicator function  $A_i = \mathbf{1}_A(\omega) = \begin{cases} 1 & \omega \in A \\ 0 & \omega \notin A \end{cases}$   
 $\downarrow X = \alpha_i$   
 $\downarrow X = \alpha$ 

#### **Proposition 5.3** (Useful properties of expectation).

(hazy

- (Linearity)  $\alpha, \beta \in \mathbb{R}, X, Y$  random variables,  $E(\alpha X + \beta Y) = \alpha E X + \beta E Y$ . (Positivity) If  $X \ge 0$  then  $EX \ge 0$ . If  $X \ge 0$  and EX = 0 then X = 0 almost surely.
- (3) (Layer Cake) If  $X \ge 0$ ,  $EX = \int_0^\infty P(X \ge t) dt$ .  $(P(\chi = 0) = 1)$ .

(4) More generally, if  $\varphi$  is increasing,  $\varphi(0) = 0$  then  $E\varphi(X) = \int_0^\infty \varphi'(t) P(X \ge t) dt$ . (5) (Unconscious Statistician Formula) If PDF of X is p, then  $Ef(X) = \int_0^\infty f(x)p(x) dx$ .

almost mely: even of prob 1.

- Filtrations:
  - $\triangleright$  Discrete time:  $\mathcal{F}_n$  events described using the first *n* coin tosses.
  - $\triangleright$  Coin tosses doesn't translate well to continuous time.
  - $\triangleright \text{ Discrete time } \underbrace{\text{try } \#2:}_{n.} \underbrace{\mathcal{F}_n}_{=} \text{ events described using the } \underbrace{trajectory}_{=} \text{ of the SRW up to time}$
  - $\triangleright$  Continuous time:  $F_t$  = events described using the *trajectory* of the *Brownian motion* up to time t.

  - ▷ Discrete time:  $\mathcal{F}_0 = \{\emptyset, \Omega\}$ . Continuous time:  $\mathcal{F}_0 = \{A \in \mathcal{G} \mid \mathbf{P}(A) \in \{0, 1\}\}$ .

fix t E R. A = (0, 0)AGR mice al set { W EAL  $\{W_s \ge 0\} \in \{F_1, F_2, F_3\} \leftarrow Y_{es}$ 

### 5.3. Conditional expectation.

- Notation  $\underline{E_t(X)} = \underline{E(X \mid \mathcal{F}_t)}$  (read as conditional expectation of X given  $\underline{\mathcal{F}_t}$ )
- No formula! But same intuition as discrete time.
- $\underline{E}_t X(\omega) =$  "average of  $\underline{X}$  over  $\Pi_t(\underline{\omega})$ ", where  $\Pi_t(\omega) = \{\omega' \in \Omega \mid \omega'(s) = \omega(s) \; \forall s \leq t\}.$
- Mathematically problematic:  $P(\Pi_t(\omega)) = 0$  (but it still works out.)

(1)  $\underline{E}_{t}X$  is  $\underline{\mathcal{F}}_{t}$ -measurable. (2) For every  $\underline{A} \in \underline{\mathcal{F}}_{t}$ ,  $\int_{A} \underline{E}_{t}X dP = \int_{A} X dP$  (Ref.  $\underline{X} \in A \in \mathcal{E}_{t}$ ) (2) For every  $\underline{A} \in \underline{\mathcal{F}}_{t}$ ,  $\int_{A} \underline{E}_{t}X dP = \int_{A} X dP$  (Ref.  $\underline{A} \in \mathcal{E}_{t}X(\omega) \phi(\omega)$ ) nark 5.5. Choosing  $\underline{A} = \Omega$  implies  $\underline{E}(\underline{E}_{t}X) = \underline{E}X$ . position 5.6 (Useful properties of conditional exact time) =  $\underline{\sum} X(\omega) \phi(\omega)$ **Definition 5.4.**  $E_t X$  is the unique random variable such that: Remark 5.5. Choosing  $\underline{A} = \underline{\Omega}$  implies  $\underline{E}(\underline{E}_t X) = \underline{E} X$ . **Proposition 5.6** (Useful properties of conditional expectation). (1) If  $\alpha, \beta \in \mathbb{R}$  are constants, X, Y, random variables  $E_t(\alpha X + \alpha Y) = \alpha E_t X + \beta E_t Y$ . (2) If  $X \ge 0$ , then  $E_t X \ge 0$ . Equality holds if and only if X = 0 almost surely. (3) (Tower property) If  $0 \leq s \leq t$ , then  $\mathbf{E}_s(\mathbf{E}_t X) = \mathbf{E}_s X$ . (4) If X is  $\mathcal{F}_t$  measurable, and Y is any random variable, then  $E_t(XY) = XE_tY$ . (5) If X is  $\mathcal{F}_t$  measurable, then  $\mathbf{E}_t X = X$  (follows by choosing Y = 1 above). (6) If Y is independent of  $\mathcal{F}_t$ , then  $\mathbf{E}_t Y = \mathbf{E} Y$ .

*Remark* 5.7. These properties are exactly the same as in discrete time.