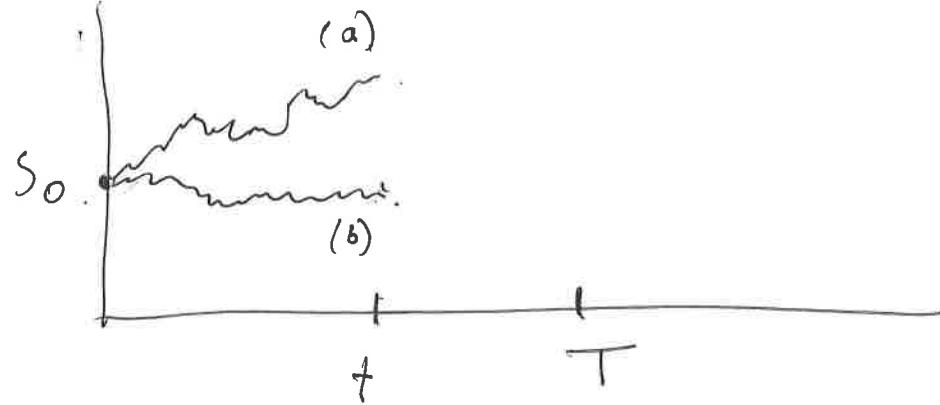


Today : — Conditioned EXP.

— Brownian Motion

— Martingales.

(2) intuitively means the conditional expectation  $\mathbb{E}[X|\mathcal{F}]$  is on average our best estimate of  $X$  incorporating only the information given by  $\mathcal{F}_t(1)$ .



$\{S_T > K\}$ .  
event of interest.

$X_T \rightarrow$  payoff value  
some derivative that  
expires at call  $T$ .

clearly at time  $t$  the ~~the~~ value of  $X_T$   
will be different than  $X_0$ .

Ex  $(\Omega, \mathcal{G}, \mathbb{P})$ .  $A, B \in \mathcal{G}$   $\mathbb{P}(B) > 0$ .

$$\mathcal{F} = \sigma(\mathbb{I}_B) = \{\emptyset, B, B^c, \Omega\}.$$

Claim  $\mathbb{E}[\mathbb{I}_A | \sigma(\mathbb{I}_B)] = \underbrace{\mathbb{P}(A|B)\mathbb{I}_B + \mathbb{P}(A|B^c)\mathbb{I}_{B^c}}_{X}.$

$$\left( \mathbb{P}(A|B) = \frac{\mathbb{P}(A \cap B)}{\mathbb{P}(B)} \right).$$

Verification (1) Need  $X$  to be  $\sigma(\mathbb{I}_B)$  meas.

$$X(w) = \begin{cases} \mathbb{P}(A|B) ; w \in B \\ \mathbb{P}(A|B^c) ; w \notin B \end{cases}.$$

Look at sets of the form  $\{w : X(w) < a\}$ .

$$c = \min \{ \text{IP}(A|B), \text{IP}(A|B^c) \}, d = \max \{ \text{IP}(A|B), \text{IP}(A|B^c) \}$$

if  $a \leq c$  :

$$\{ \omega : X(\omega) \geq a \} = \emptyset \in \mathcal{F}.$$

$$\cdot \text{IP}(A|B) = c.$$

if  $c < a \leq d$   $\{ \omega : X(\omega) \geq a \} = \begin{cases} B & : \text{IP}(A|B) < \text{IP}(A|B^c) \\ B^c & : \text{IP}(A|B^c) = c. \end{cases} \in \mathcal{F}.$

if  $a > d$   $\{ \omega : X(\omega) \geq a \} = \mathcal{N} \in \mathcal{F}.$

$\therefore X$  is  $\mathcal{F}$ -meas  $\checkmark$ .

we will want later to write.

$$X_+ = \mathbb{E}[X_T | \mathcal{F}_+],$$

↳ this will typically depend on ~~on~~  $S_+$

and even it may depend on  $\{S_s : 0 \leq s \leq +\}$ .

so we see that  $X_+$  is a RV.

(2) We need to check that

$$\textcircled{*} \quad \mathbb{E}[\mathbb{1}_A \mathbb{1}_F] = \mathbb{E}[X \mathbb{1}_F] \quad \text{for every } F \in \mathcal{F}.$$

$$= \mathbb{E}[\mathbb{E}[\mathbb{1}_A \mathbb{1}_F] \mathbb{1}_F]. \quad \text{by } \mathbb{E}[\mathbb{1}_F]$$

$\{\emptyset, B, B^c, \Omega\}$

(i)  $F = \emptyset$  in  $\textcircled{*}$ .  $\checkmark$

$$\text{LHS} = 0 = \text{RHS.} \quad (\text{since } \mathbb{1}_{\emptyset} = 0)$$

(ii)  $F = \Omega$  in  $\textcircled{*}$ .  $\mathbb{1}_\Omega = 1. \quad \checkmark$

$$\text{LHS} \quad \mathbb{E}[\mathbb{1}_A] = \mathbb{P}(A).$$

$$\text{RHS} \quad \mathbb{E}[X] = \mathbb{E}[\mathbb{1}_A + \mathbb{P}(A|B) \mathbb{1}_B + \mathbb{E}[\mathbb{P}(A|B^c)] \mathbb{1}_{B^c}].$$

$$= \mathbb{P}(A|B) \mathbb{P}(B) + \mathbb{P}(A|B^c) \mathbb{P}(B^c) = \mathbb{P}(A).$$

(iii)  $F = B$ :

$$\text{LHS} : \mathbb{E}[I_A \cdot I_B] = \mathbb{E}[I_{\{A \cap B\}}] = \mathbb{P}(A \cap B). \quad \checkmark$$

$$\text{RHS} \quad \mathbb{E}[X I_B] = \mathbb{E}\left[\mathbb{P}(A|B) I_B I_B + \cancel{\mathbb{P}(A|B^c)} \cdot \mathbb{P}(A|B^c) I_{B^c} I_B\right] \\ = 0.$$

$$= \mathbb{P}(A|B) \mathbb{E}[I_B] = \mathbb{P}(A|B) \mathbb{P}(B) \\ = \mathbb{P}(A \cap B).$$

(iv)  $F = B^c$

$$\text{LHS} : \mathbb{E}[I_A I_{B^c}] = \mathbb{P}(A \cap B^c). \quad \checkmark$$

$$\text{RHS} : \mathbb{E}[X I_{B^c}] = \mathbb{E}\left[\mathbb{P}(A|B^c) I_{B^c}\right] \\ = \mathbb{P}(A \cap B^c)$$

$$\therefore X = \mathbb{E}[I_A | \sigma(I_B)].$$

$$X = \underbrace{\mathbb{P}(A|B) I_B}_{\frac{\mathbb{P}(A \cap B)}{\mathbb{P}(B)}} + \mathbb{P}(A|B^c) I_{B^c}.$$

Even in this case where  $\mathbb{I}_A, \mathbb{I}_B$  each take on only 2 values this is tedious.

We want rules to compute these!

$X, Y$  are RV's.,  $\lambda \in \mathbb{R}$ .

### 1) Linearity

$$\mathbb{E}[X + \lambda Y | \mathcal{F}] = \mathbb{E}[X | \mathcal{F}] + \lambda \cdot \mathbb{E}[Y | \mathcal{F}].$$

### Positivity

If  $X \leq Y$

$$\mathbb{E}[X | \mathcal{F}] \leq \mathbb{E}[Y | \mathcal{F}].$$

2. If  $X$  is  $\mathcal{F}$ -meas then

$$\mathbb{E}[X | \mathcal{F}] = X.$$

if  $X$  is independent of  $\mathcal{F}$ , then

$$\mathbb{E}[X | \mathcal{F}] = \mathbb{E}[X].$$

(3) (TOWER) If  $X$  is  $\mathcal{F}$ -meas and  $Y$  is any RV.

$$\text{then } \mathbb{E}[X|Y|\mathcal{F}] = X\mathbb{E}[Y|\mathcal{F}].$$

(4) (Tower).  $\mathcal{E} \subseteq \mathcal{F} \subseteq \mathcal{G}$ .  $\sigma$ -algebras.

$$\mathbb{E}[\mathbb{E}[X|\mathcal{F}]|\mathcal{E}] = \mathbb{E}[X|\mathcal{E}].$$

(5). Indep Lemma.  $X, Y$  RV.  
 $X$  is indep of  $\mathcal{F}$  ( $X \perp\!\!\!\perp \mathcal{F}$ )  
 $Y$  is  $\mathcal{F}$ -meas.

$$f: \mathbb{R}^2 \rightarrow \mathbb{R}.$$

$$\mathbb{E}[f(X, Y)|\mathcal{F}] = \mathbb{E}^X[f(x, Y)] = g(Y).$$

If  $X$  has density  $p_x$  then .. integrating over  $\text{RV } Y$ .

$$E[f(X, Y) | \mathcal{F}] = \int_{-\infty}^{\infty} f(x, Y) p_x(x) dx$$

Ex:  $X, Y$  are independent RV's.

$X \sim \exp(\lambda)$ ,  $Y \sim \text{unif}[0, \lambda]$ .

$$Z = f(X, Y) = e^{-XY^2}$$

$$\text{Find } E[Z | \sigma(Y)] =: E[Z | Y].$$

$$\text{solt'n. } E[e^{-XY^2} | Y] = \int_{-\infty}^{\infty} e^{-XY^2} p_x(x) dx$$

$$= \int_0^{\infty} \cancel{xe^{-\lambda x}} e^{-XY^2} \lambda e^{-\lambda x} dx.$$

$$= \int_0^\infty \lambda e^{-x(\lambda + Y^2)} dx = \left. -\frac{\lambda}{\lambda + Y^2} e^{-x(\lambda + Y^2)} \right|_{x=0}^{x=\infty}$$

$$= \frac{\lambda}{\lambda + Y^2} = g(Y) \text{ is a RV.}$$

(6) Law of total Expectation:

$$\mathbb{E}[X] = \mathbb{E}[\mathbb{E}[X|F]]$$

Example of two Normal's. <sup>on Wikipedia</sup> where you draw first one value and use that the mean of the ~~and~~ <sup>other</sup> Normal.

Clearly they are dependent.

But true independence from data can be hard to determine.

Let's compute  $E[Z]$ .

$$E[E[Z|Y]] = E\left[\frac{\lambda}{\lambda+y^2}\right] = \int_0^\lambda \frac{1}{\lambda+y^2} dy.$$

$$= \frac{\arctan\left(\frac{y}{\sqrt{\lambda}}\right)}{\sqrt{\lambda}} \Big|_{y=0}^{y=\lambda} = \frac{\arctan \sqrt{\lambda}}{\sqrt{\lambda}}$$

BM :  $\{W_t\}_{t \geq 0}$  satisfies.

(i)  $W_0 = 0.$

(ii)  $W_t \sim N(0, t)$

(iii)  $s < t < u < v$  then  $W_t - W_s \xrightarrow{\text{independent}} W_v - W_u.$

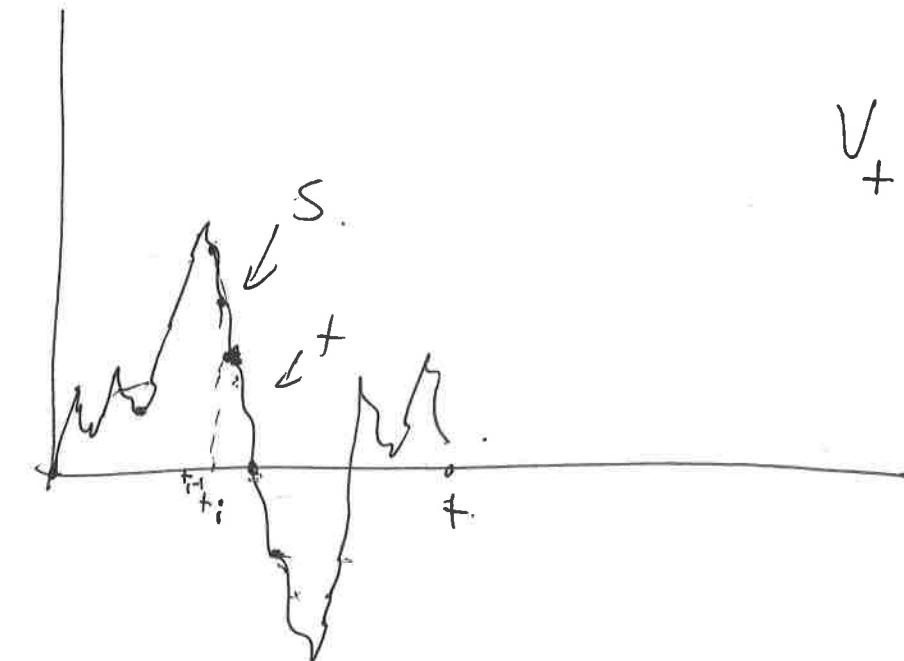
(iv). the function  $t \mapsto W_t$  is continuous.

i.e. BM has continuous paths.

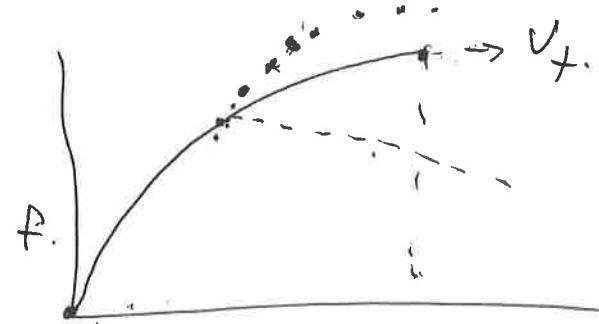
(i) - (iv) define a  $\begin{matrix} \uparrow \\ \text{standard} \end{matrix}$  Brownian motion.

BM has really "rough" or oscillatory paths.

BM.



FACT:  $V_+ = \infty$  for BM.



$$V_+ = \lim_{n \rightarrow \infty} \sum_{i=0}^{n-1} |w_{t_{i+1}} - w_{t_i}|.$$

$$0 = t_0 < t_1 < \dots < t_n = T$$

$\pi \rightarrow$  partition. of  $[0, T]$ .

$$|\pi| = \max_j |t_j - t_{j-1}|.$$

I send  $|\pi| \rightarrow 0$ .

Warning:

$$t \geq s : w_t - w_s \perp\!\!\!\perp w_s.$$

but  $w_s \cancel{\perp\!\!\!\perp} w_t$

$$\text{so } \mathbb{E}[w_t - w_s | \mathcal{F}_s] = \mathbb{E}[w_t - w_s] = 0.$$

$$\text{but } \mathbb{E}[w_t | \mathcal{F}_s] = w_s$$