

Fennel: Streaming Graph Partitioning for Massive Scale Graphs

Charalampos E. Tsourakakis ¹ Christos Gkantsidis ²
Bozidar Radunovic ² Milan Vojnovic ²

¹Aalto University, Finland

²Microsoft Research, Cambridge UK

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Slides available

<http://www.math.cmu.edu/~ctsourak/>

Motivation

- **Big data** is data that is too **large**, **complex** and **dynamic** for any conventional data tools to **capture**, **store**, **manage** and **analyze**.
- The right use of big data allows analysis to spot trends and gives niche insights that help create value and innovation much faster than conventional methods.



Source visual.ly

Motivation

- We need to handle datasets with **billions** of vertices and edges
 - Facebook: \sim 1 billion users with avg degree 130
 - Twitter: \geq 1.5 billion social relations
 - Google: web graph more than a trillion edges (2011)
- We need algorithms for **dynamic** graph datasets
 - real-time story identification using twitter posts
 - election trends, twitter as election barometer

Motivation

flickr from YAHOO!

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Signed in as [Arts Gonis](#) Help Sign Out

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Rosenborg, Copenhagen

19,365

Rosenborg Castle - where we keep the Kingdoms crown jewels.

This beautiful spot is in the heart of Copenhagen, at the Kings Garden. The photograph was shot on a nice spring day, with wonderful flickr friends on a Copenhagen walk.

Comments and faves

By [michael.dreves](#)
Michael Dreves Baier + Add Contact

This photo was taken on April 7, 2010 in Tornebuskagade, Copenhagen, Hovedstaden, DK, using a Canon EOS 5D Mark II.



This photo belongs to

[michael dreves' photostream](#) (454)



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- [FlickrToday \(only 1 pic per day\)](#) (group)
- ...and 63 more groups

People in this photo [\(add a person\)](#)

Adding people will share who is in this photo

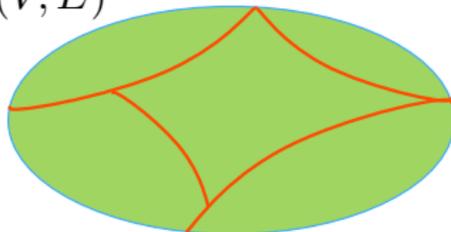
Motivation

- Big graph datasets created from social media data.
 - **vertices**: photos, tags, users, groups, albums, sets, collections, geo, query, ...
 - **edges**: upload, belong, tag, create, join, contact, friend, family, comment, fave, search, click, ...
 - also many interesting induced graphs
- What is the underlying graph?
 - **tag graph**: based on photos
 - **tag graph**: based on users
 - **user graph**: based on favorites
 - **user graph**: based on groups

Balanced graph partitioning

- Graph has to be distributed across a cluster of machines

$$G = (V, E)$$



- graph partitioning is a way to **split** the graph vertices in **multiple machines**
- graph partitioning objectives guarantee **low communication overhead** among different machines
- additionally **balanced partitioning** is desirable
- each partition contains $\approx n/k$ vertices, where n, k are the total number of vertices and machines respectively

Off-line k -way graph partitioning

METIS algorithm [Karypis and Kumar, 1998]

- popular family of algorithms and software
- multilevel algorithm
- **coarsening** phase in which the size of the graph is successively decreased
- followed by **bisection** (based on spectral or KL method)
- followed by **uncoarsening** phase in which the bisection is successively refined and projected to larger graphs

METIS is **not** well understood, i.e., from a theoretical perspective.

Off-line k -way graph partitioning

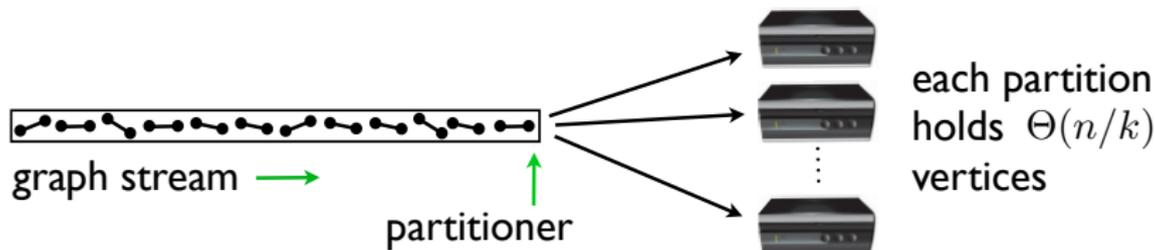
problem: minimize **number of edges cut**, subject to cluster sizes being at most $\nu n/k$ (bi-criteria approximations)

- $\nu = 2$: Krauthgamer, Naor and Schwartz [Krauthgamer et al., 2009] provide $O(\sqrt{\log k \log n})$ approximation ratio based on the work of Arora-Rao-Vazirani for the **sparsest-cut problem** ($k = 2$) [Arora et al., 2009]
- $\nu = 1 + \epsilon$: Andreev and Räcke [Andreev and Räcke, 2006] combine recursive partitioning and dynamic programming to obtain $O(\epsilon^{-2} \log^{1.5} n)$ approximation ratio.

There exists a lot of related work, e.g., [Feldmann et al., 2012], [Feige and Krauthgamer, 2002], [Feige et al., 2000] etc.

streaming k -way graph partitioning

- input is a **data stream**
- graph is ordered
 - arbitrarily
 - breadth-first search
 - depth-first search
- generate an **approximately** balanced graph partitioning



Graph representations

- incidence stream
 - at time t , a vertex arrives with its neighbors
- adjacency stream
 - at time t , an edge arrives

Partitioning strategies

- **hashing**: place a new vertex to a cluster/machine chosen **uniformly at random**
- **neighbors heuristic**: place a new vertex to the cluster/machine with the **maximum number of neighbors**
- **non-neighbors heuristic**: place a new vertex to the cluster/machine with the **minimum number of non-neighbors**

Partitioning strategies

[Stanton and Kliot, 2012]

- $d_c(v)$: neighbors of v in cluster c
- $t_c(v)$: number of triangles that v participates in cluster c
- **balanced**: vertex v goes to cluster with least number of vertices
- **hashing**: random assignment
- **weighted degree**: v goes to cluster c that maximizes $d_c(v) \cdot w(c)$
- **weighted triangles**: v goes to cluster j that maximizes $t_c(v) / \binom{d_c(v)}{2} \cdot w(c)$

Weight functions

- s_c : number of vertices in cluster c
- unweighted: $w(c) = 1$
- linearly weighted: $w(c) = 1 - s_c(k/n)$
- exponentially weighted: $w(c) = 1 - e^{(s_c - n/k)}$

FENNEL algorithm

The standard formulation hits the ARV barrier

$$\begin{aligned} \text{minimize}_{\mathcal{P}=(S_1, \dots, S_k)} \quad & |\partial e(\mathcal{P})| \\ \text{subject to} \quad & |S_i| \leq \nu \frac{n}{k}, \text{ for all } 1 \leq i \leq k \end{aligned}$$

- We **relax** the hard cardinality constraints

$$\text{minimize}_{\mathcal{P}=(S_1, \dots, S_k)} \quad |\partial E(\mathcal{P})| + c_{\text{IN}}(\mathcal{P})$$

where $c_{\text{IN}}(\mathcal{P}) = \sum_i s(|S_i|)$, so that objective self-balances

FENNEL algorithm

- for $S \subseteq V$, $f(S) = e[S] - \alpha|S|^\gamma$, with $\gamma \geq 1$
- given partition $\mathcal{P} = (S_1, \dots, S_k)$ of V in k parts define

$$g(\mathcal{P}) = f(S_1) + \dots + f(S_k)$$

- **the goal:** maximize $g(\mathcal{P})$ over all possible k -partitions
- notice:

$$g(\mathcal{P}) = \underbrace{\sum_i e[S_i]}_{m\text{-number of edges cut}} - \underbrace{\alpha \sum_i |S_i|^\gamma}_{\text{minimized for balanced partition!}}$$

Connection

notice

$$f(S) = e[S] - \alpha \binom{|S|}{2}$$

- related to **modularity**
- related to **optimal quasCliques** [Tsourakakis et al., 2013]

FENNEL algorithm

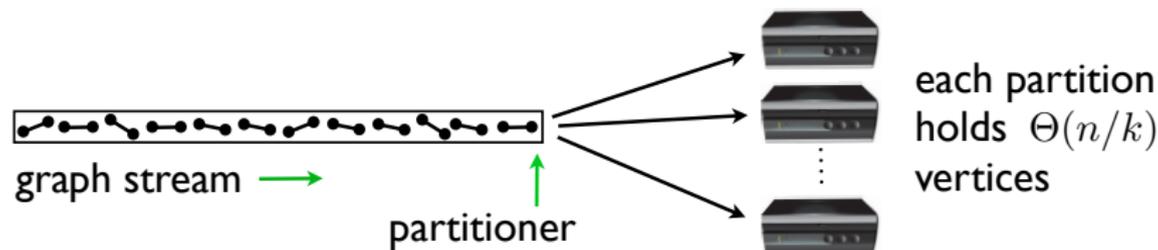
Theorem

- For $\gamma = 2$ there exists an algorithm that achieves an approximation factor $\log(k)/k$ for a shifted objective where k is the number of clusters
 - semidefinite programming algorithm
 - in the shifted objective the main term takes care of the load balancing and the second order term minimizes the number of edges cut
 - Multiplicative guarantees not the most appropriate
- random partitioning gives approximation factor $1/k$
- no dependence on n
mainly because of relaxing the hard cardinality constraints

FENNEL algorithm — greedy scheme

- $\gamma = 2$ gives non-neighbors heuristic
- $\gamma = 1$ gives neighbors heuristic
- interpolate between the two heuristics, e.g., $\gamma = 1.5$

FENNEL algorithm — greedy scheme



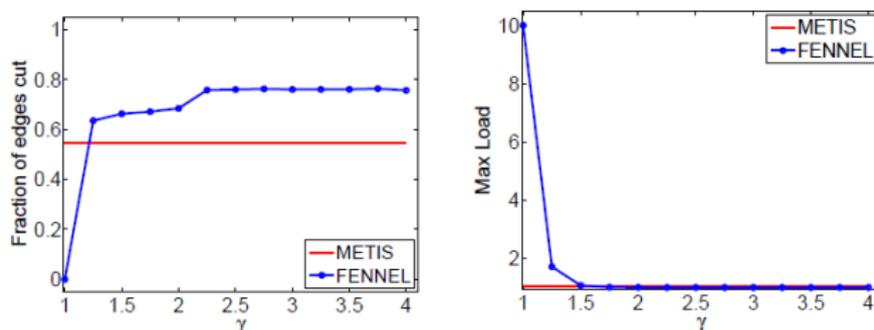
- send v to the partition / machine that maximizes

$$\begin{aligned} & f(S_i \cup \{v\}) - f(S_i) \\ &= e[S_i \cup \{v\}] - \alpha(|S_i| + 1)^\gamma - (e[S_i] - \alpha|S_i|^\gamma) \\ &= d_{S_i}(v) - \alpha\mathcal{O}(|S_i|^{\gamma-1}) \end{aligned}$$

- fast, amenable to streaming and distributed setting

FENNEL algorithm — γ

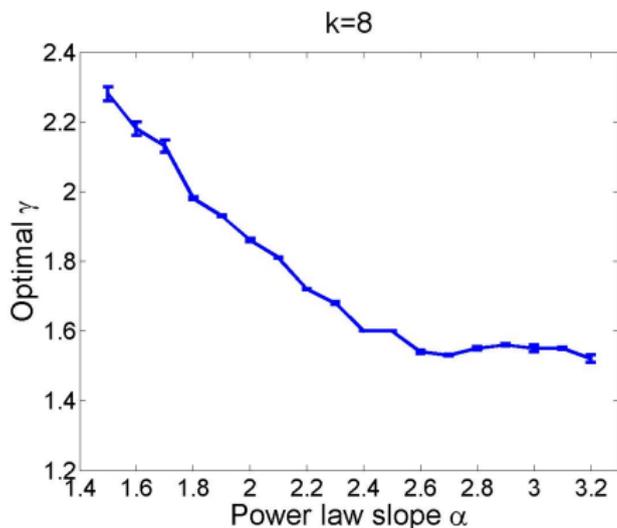
Explore the tradeoff between the number of edges cut and load balancing.



Fraction of edges cut λ and maximum load normalized ρ as a function of γ , ranging from 1 to 4 with a step of 0.25, over five randomly generated power law graphs with slope 2.5. The straight lines show the performance of METIS.

- Not the end of the story ... choose γ^* based on some “easy-to-compute” graph characteristic.

FENNEL algorithm — γ^*



y-axis Average optimal value γ^* for each power law slope in the range $[1.5, 3.2]$ using a step of 0.1 over twenty randomly generated power law graphs that results in the smallest possible fraction of edges cut λ conditioning on a maximum normalized load $\rho = 1.2$, $k = 8$. **x-axis** Power-law exponent of the degree sequence. Error bars indicate the variance around the average optimal value γ^* .

FENNEL algorithm — results

Twitter graph with approximately 1.5 billion edges, $\gamma = 1.5$

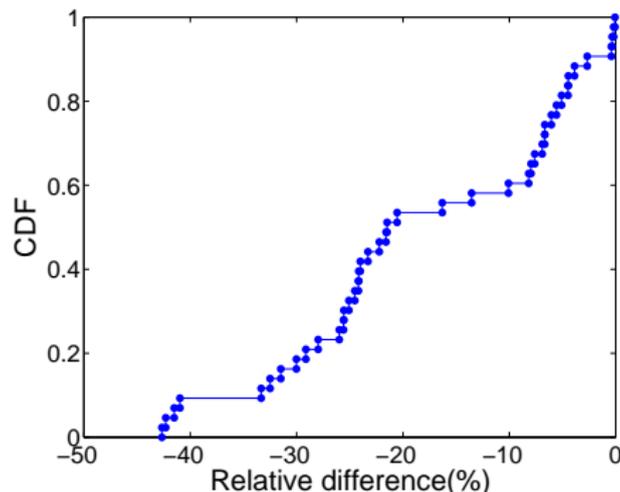
$$\lambda = \frac{\#\{\text{edges cut}\}}{m} \quad \rho = \max_{1 \leq i \leq k} \frac{|S_i|}{n/k}$$

	Fennel		Best competitor		Hash Partition		METIS	
k	λ	ρ	λ	ρ	λ	ρ	λ	ρ
2	6.8%	1.1	34.3%	1.04	50%	1	11.98%	1.02
4	29%	1.1	55.0%	1.07	75%	1	24.39%	1.03
8	48%	1.1	66.4%	1.10	87.5%	1	35.96%	1.03

Table: Fraction of edges cut λ and the normalized maximum load ρ for Fennel, the best competitor and hash partitioning of vertices for the Twitter graph. Fennel and best competitor require around 40 minutes, METIS more than $8\frac{1}{2}$ hours.

FENNEL algorithm — results

Extensive experimental evaluation over > 40 large real graphs
[Tsourakakis et al., 2012]



CDF of the relative difference $\frac{\lambda_{fennel} - \lambda_c}{\lambda_c} \times 100\%$ of percentages of edges cut of FENNEL and the best competitor (pointwise) for all graphs in our dataset.

FENNEL algorithm — “zooming in”

Performance of various existing methods on **amazon0312** for $k = 32$

Method	BFS		Random	
	λ	ρ	λ	ρ
H	96.9%	1.01	96.9%	1.01
B [Stanton and Kliot, 2012]	97.3%	1.00	96.8%	1.00
DG [Stanton and Kliot, 2012]	0%	32	43%	1.48
LDG [Stanton and Kliot, 2012]	34%	1.01	40%	1.00
EDG [Stanton and Kliot, 2012]	39%	1.04	48%	1.01
T [Stanton and Kliot, 2012]	61%	2.11	78%	1.01
LT [Stanton and Kliot, 2012]	63%	1.23	78%	1.10
ET [Stanton and Kliot, 2012]	64%	1.05	79%	1.01
NN [Prabhakaran and et al., 2012]	69%	1.00	55%	1.03
Fennel	14%	1.10	14%	1.02
METIS	8%	1.00	8%	1.02

Conclusions

summary and future directions

- cheap and efficient graph partitioning is highly desired
- new area [Stanton and Kliot, 2012],
[Tsourakakis et al., 2012],
[Nishimura and Ugander, 2013]
- average case analysis
- stratified graph partitioning
[Nishimura and Ugander, 2013]

thank you!

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