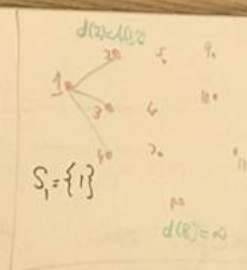


$$d(i) = \min_{j \in S_{k-1}} d(i, j)$$

Add $i: S_k = S_{k-1} \cup \{i\}$

$d(i) = \text{min length path } 1 \rightarrow \dots \rightarrow i$
 $\in S_{k-1}$

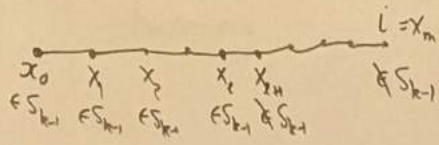


Dijkstra produces $d(1), d(2), \dots, d(n)$

$P = \{x_0=1, x_1, \dots, x_m=i\}$ be a path from 1 to i

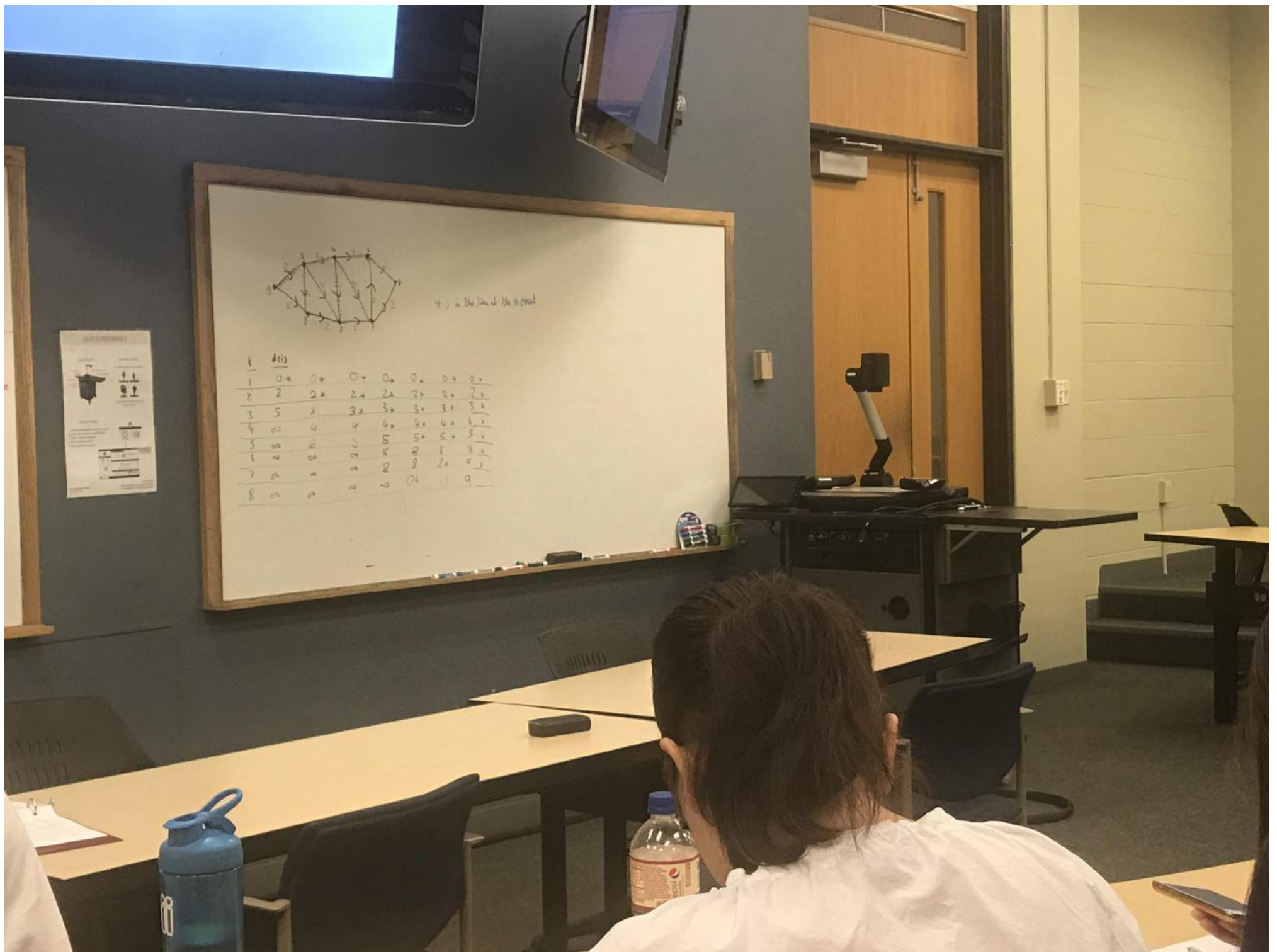
Want to show $l(P) \geq d(i)$.

Suppose i is added at round k .



$$\begin{aligned} l(P) &\geq l(P[1, x_{k-1}]) && \leftarrow \text{because arc lengths are non-negative} \\ &\geq d(x_{k-1}) \\ &\geq d(i) \end{aligned}$$





$\pm$ in the line of the record

i	d(i)						
1	0	0	0	0	0	0	0
2	2	2	2	2	2	2	2
3	5	3	3	3	3	3	3
4	0	4	4	4	4	4	4
5	0	0	5	5	5	5	5
6	0	0	0	0	0	0	0
7	0	0	0	0	0	0	0
8	0	0	0	0	0	0	0

Instead of assuming $\ell(e) \geq 0, \forall e \in E$ and $\ell(P) = \ell_{\text{reg}}(P) = \sum_{e \in P} \ell(e)$
assume

$$P = (P_1, P_2) \Rightarrow \ell(P_1) \leq \ell(P).$$

Dijkstra proof is still valid

① Time dependent path length.

If $e = (x, y)$ then we have $a_x, b_x \geq 0$

such that if a path arrives at x at time t

then the length of e is $a_x + b_x t$

If $P = (x_0, x_1, x_2, \dots, x_m)$

$P_i = (x_0, \dots, x_i)$

$$\ell(P_{i+1}) = \ell(P_i) + a_{x_i} + b_{x_i} \ell(P_i)$$



(ii) Avoid S : penalty $f(k)$ for visiting S , k times.

$$l(P) = l_{\text{reg}}(P) + f(|P \cap S|) \quad \& \quad l(e) \geq 0, \forall e$$

(iii) Visit S in some fixed order.

$$l(P) = \begin{cases} l_{\text{reg}}(P) & : \text{visits } S \text{ in order} \\ \infty & : \text{otherwise} \end{cases}$$

Ford's Algorithm

Suppose we allow $l(e) < 0$.

Electric car: $l(e)$ = decrease in battery energy.

$l(e) < 0$ if e goes down hill.

but

$l(C) \geq 0$ for all directed cycles.

