

9/9/13

Infinite time horizon

Production problem going on indefinitely.

Consider some cost sequences

A	5	5	5	5	5	...
B	4	4	4	4	4	...
C	3	5	3	5	3	...

B is better than A

C is better than B
with inflation

Discounted Cash Flow or Net Present Value.

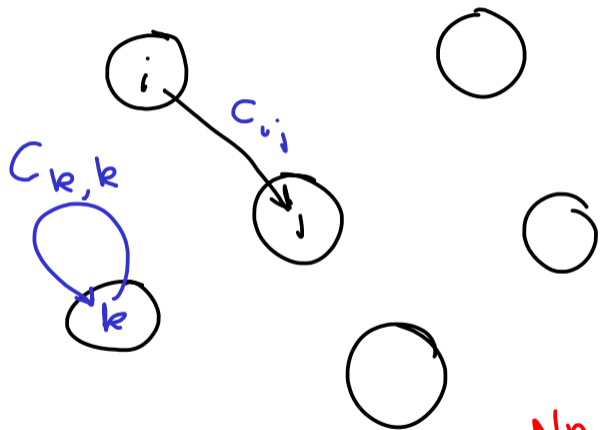
We assume a discount rate of $0 < \alpha < 1$

C_1, C_2, C_3, \dots

gives

NPV of $C_1 + \alpha C_2 + \alpha^2 C_3 + \dots$

System of n states:



$C_{i,j}$ = cost of going from state i to state j

If you through states $i_1, i_2, i_3, i_4, \dots$

$$NPV = C(i_1, i_2) + \alpha C(i_2, i_3) + \alpha^2 C(i_3, i_4)$$

So, $\exists \pi : [n] \rightarrow [n]$

so that when a_i go next to $\pi(i)$,

There are n^n choices for π .

Evaluating π .

$y_i = \text{NPV of following } \pi \text{ indefinitely}$

$$= c_{i, \pi(i)} + \alpha y_{\pi(i)}$$

$$c_{i, \pi(i)} + \alpha c_{\pi(i), \pi^2(i)} + \alpha^2 c_{\pi^2(i), \pi^3(i)} + \dots$$

$$C = \begin{bmatrix} 3 & 2 & 1 & 5 \\ 4 & 3 & 4 & 1 \\ 2 & 4 & 1 & 3 \\ 5 & 4 & 3 & 4 \end{bmatrix}$$

$$\alpha = 1/2$$

Start with

i	1	2	3	4
$\pi(i)$	4	3	2	1

Algorithm

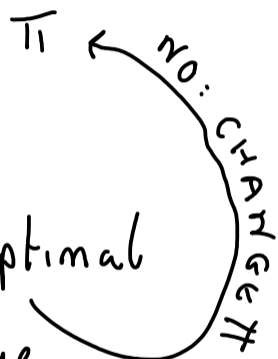
Current π

Evaluate

Check for optimal

yes
↓

DONE



$$C = \begin{bmatrix} 3 & 2 & 1 & 5 \\ 4 & 3 & 4 & 1 \\ 2 & 4 & 1 & 3 \\ 5 & 4 & 3 & 4 \end{bmatrix}$$

$$y_1 = 5 + \frac{1}{2} y_4 = 10$$

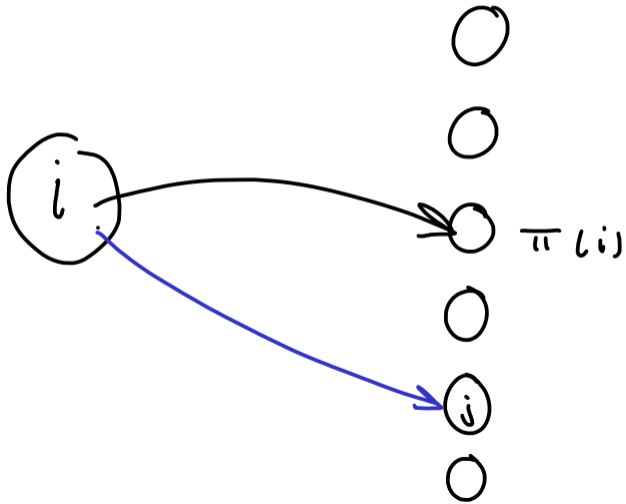
$$y_2 = 4 + \frac{1}{2} y_3 = 8$$

$$y_3 = 4 + \frac{1}{2} y_2 = 8$$

$$y_4 = 5 + \frac{1}{2} y_1 = 10$$

We can find a Π that simultaneously
 minimizes y_1, y_2, \dots

Optimality condition



$$C_{i, \pi(i)} + \alpha Y_{\pi(i)}$$

$$C_{i, j} + \alpha Y_j$$

$i \rightarrow j$ then follow π .

Check

$$y_i = \min_j [C_{ij} + \alpha y_j]$$

Claim: true iff π simultaneously
minimizes y_1, y_2, \dots, y_n .

Check:

$$\underline{i = 1}$$

$$\begin{array}{cccc} & y_1 & y_2 & y_3 & y_4 \\ & 10 & 8 & 8 & 10 \\ 3 + \frac{1}{2} y_1 & = & 8 \\ 2 + \frac{1}{2} y_2 & = & 6 \\ 1 + \frac{1}{2} y_3 & = & 5^* \\ 5 + \frac{1}{2} y_4 & = & 10 \end{array}$$

$$C = \begin{bmatrix} 3 & 2 & 1 & 5 \\ 4 & 3 & 4 & 1 \\ 2 & 4 & 1 & 3 \\ 5 & 4 & 3 & 4 \end{bmatrix}$$