

9/23/13

Shortest Paths

Directed graph $D = (V, A)$ and every arc a has a length $l(a)$.

Length of path $P = (x_0, x_1, \dots, x_k)$
is $l(x_0, x_1) + l(x_1, x_2) + \dots + l(x_{k-1}, x_k)$

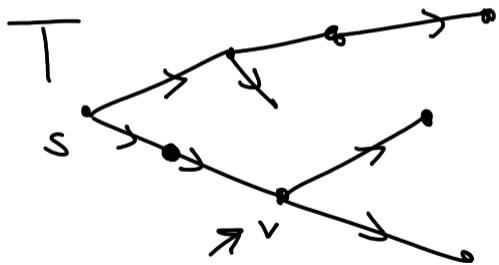
Problem: given vertices x, y find shortest path from x to y .

Case 1: $l(a) \geq 0$.

Dijkstra's algorithm.

Fixed vertex s - find shortest path s to all other vertices.

At some stage we have a tree T



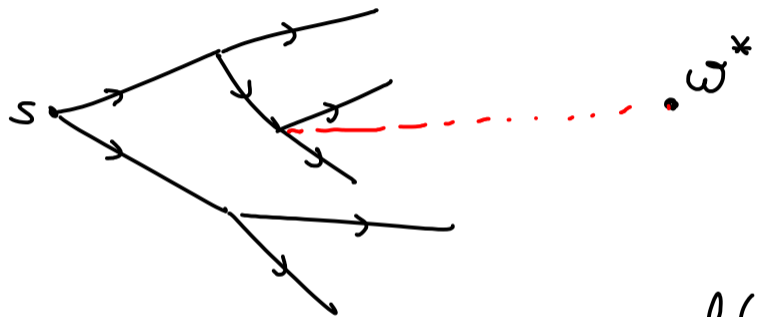
$d(v)$ = length of the T -path $s \rightarrow v$.

Claim: $d(v)$ = length of shortest

$d(w)$ = min. length path $s \rightarrow w$ that goes $\underbrace{s \rightarrow v \rightarrow w}_{\subseteq T}$

$d(w^*) = \min_{w \in T} d(w)$

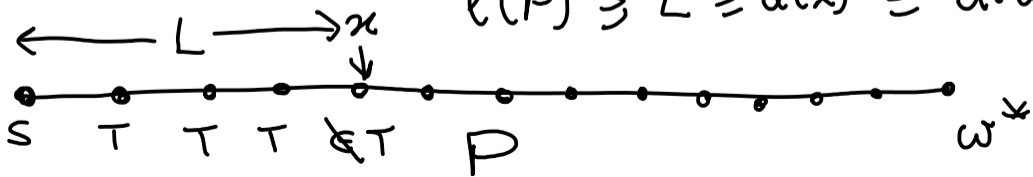
Claim: $d(w^*) = \text{length of shortest path to } w^*$



Dijkstra works for any definition of length for which $l(P) \geq l(Q)$ where $\leftarrow Q \rightarrow$

only place where non-negativity is used.

$$l(P) \geq L \geq d(x) \geq d(w^*)$$



Time dependent air length.

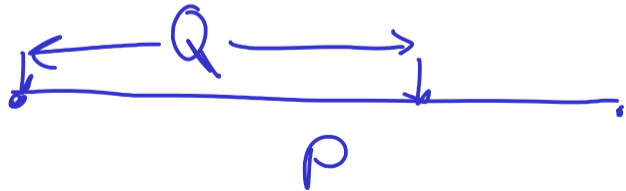
Suppose length of a depends on time of arrival at x .

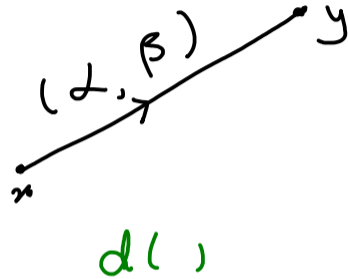
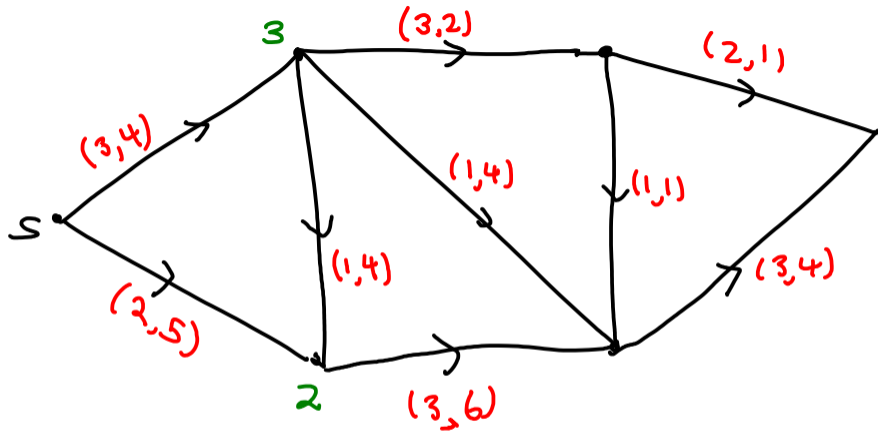
(x, y)

For example: assume $l(a, t) = \alpha_a + \beta_a t$

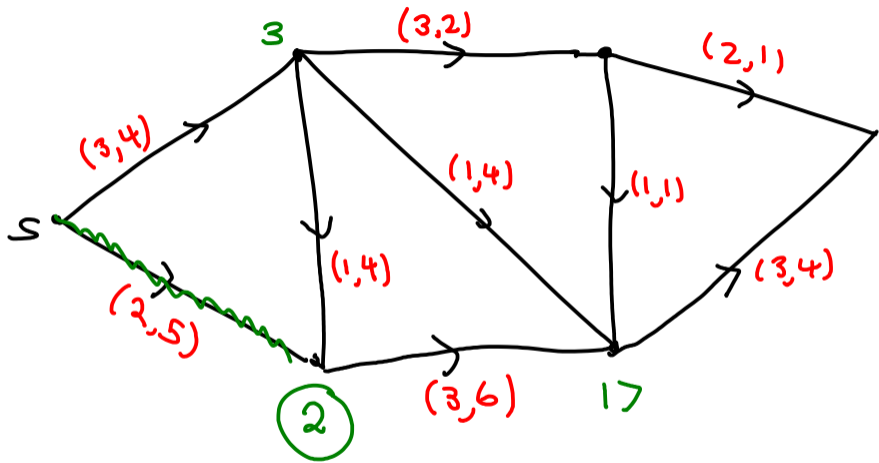
where $\alpha_a, \beta_a \geq 0$.

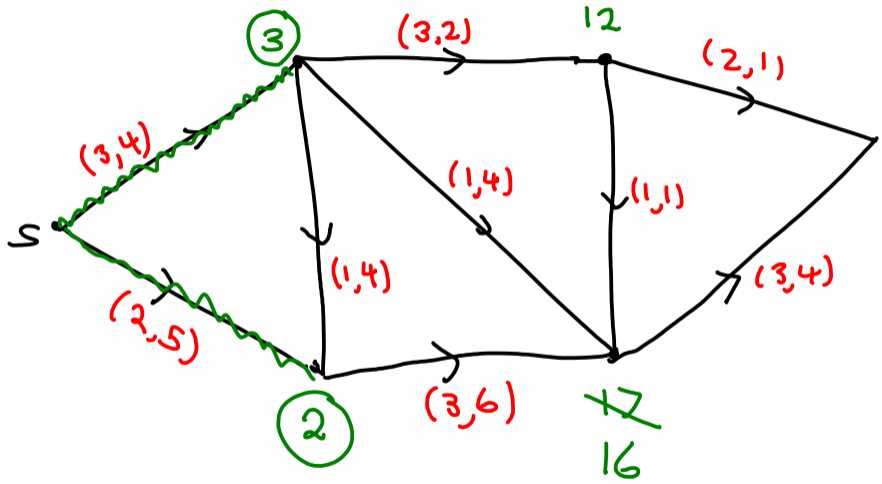
So $l(P) \geq l(Q)$

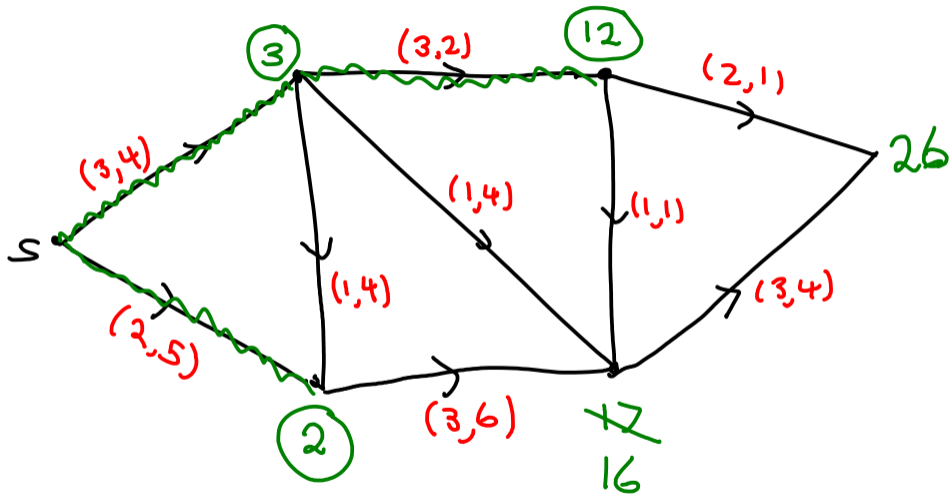


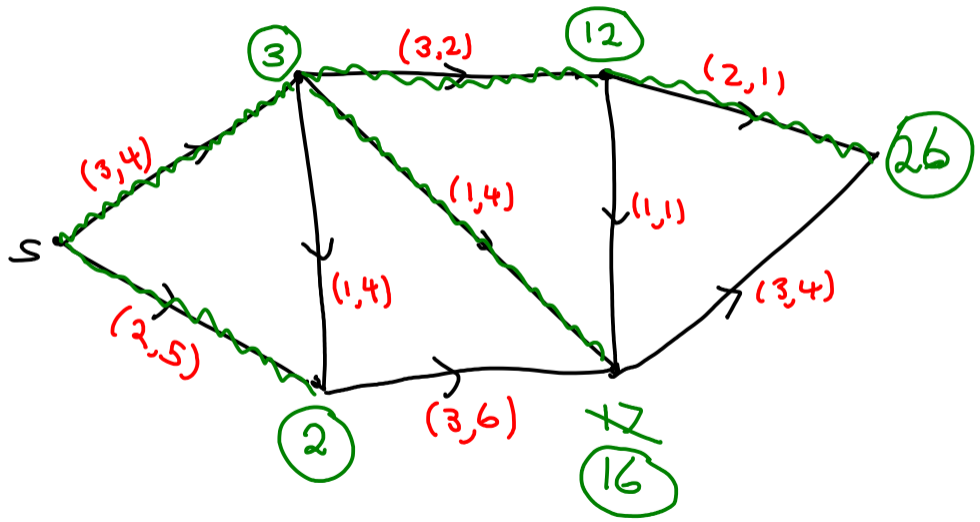


Start at $t=0$.









Now suppose that some arc lengths are negative.

Finding a shortest path from x to y , when there are negative length arcs is NP hard. — it is as hard as TSP.

Integer Programming. . . .

Hamilton Path Problem: Given x, y ; does there exist a path from x to y that goes through every vertex.

[Only visit a vertex once] NP-HARD

Suppose one can solve shortest path x to y when there are negative arc lengths in time $T(n)$ $n = \#$ of vertices
solve H-path problem

$P \equiv$ program

Hamilton Path Problem

