

10/3/11

$$O_x = \{ y \in X : \exists g \in G : g * x = y \}$$

orbit

Claim: the orbits partition X .

i.e. they define an equivalence relation on X .

$$x \sim y \text{ iff } \exists g \in G : g * x = y$$

$\sim$ is an equivalence relation.

Orbits will
be the
equivalence
classes of $\sim$

(a) $1_x * x = x \Rightarrow \sim$ is reflexive.

(b) $y = g * x \Rightarrow x = g^{-1} * y$ symmetric

$$\begin{aligned} g^{-1} * y &= g^{-1} * (g * x) \\ &= (g^{-1} \circ g) * x \\ &= 1_x * x \\ &= x \end{aligned}$$

(c) $y = g * x$
 $z = h * y$

$z = \underbrace{(h \circ g)}_{\in G} * x$

transitive

Claim: $|O_x| \cdot |S_x| = |G|$

Orbit-
Stabilizer
theorem

↑
Stabilizer of x
 $= \{g \in G : g * x = x\}$

S_x is a sub-group of G .

$S_x \subseteq G$ and it is a group in its own right.

Check: $1 \in G$

if $g \in S_x$ & $h \in S_x$ then $(g \circ h) * x = g * (h * x) = x$

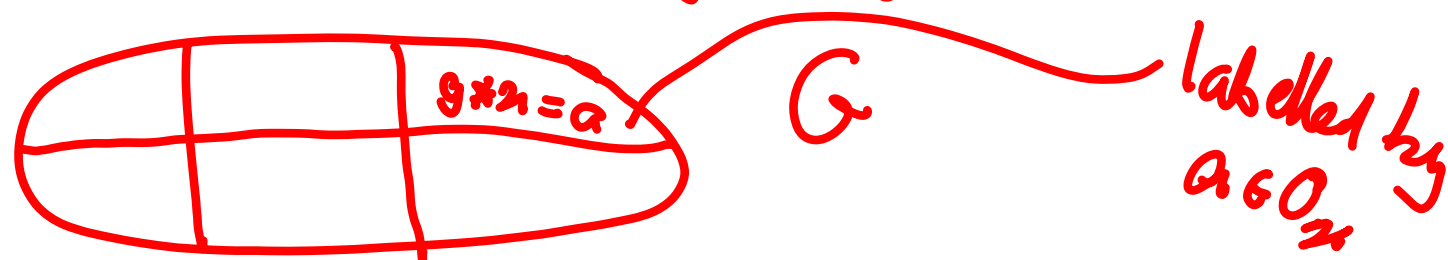
Define an equivalence relation on G .

$$g \sim h \text{ iff } g * x = h * x$$

Clearly $\sim$ is an equivalence relation

① One equivalence class for every member of O_x
#classes = # of possibilities for $g * x, g \in G$

Every class is determined by a $g * x$.



$$\begin{aligned}
 \textcircled{11} \quad g \sim h & \text{ iff } g * x = h * x \\
 & \text{ iff } x = (g^{-1} \circ h) * x \\
 & \text{ iff } g^{-1} \circ h \in S_n \\
 & \text{ iff } h \in g \circ S_n
 \end{aligned}$$

$$\begin{aligned}
 \#h &= \text{size of equivalence class of } g \\
 &= |g \circ S_n| = |S_n|
 \end{aligned}$$

$$= |g \circ S_n| = |S_n| \quad ??$$

Suppose $a, b \in S_n$ and $g \circ h_1 = g \circ h_2$

$$\Downarrow$$

$$h_1 = h_2$$



$$g \circ S_n =$$

$$\{g \circ h : h \in S_n\}$$

Example 2

b	b
r	r

$$G = \{e, a, b, c, p, q, r, s\}$$

$$x = b b r r$$

$$O_x =$$

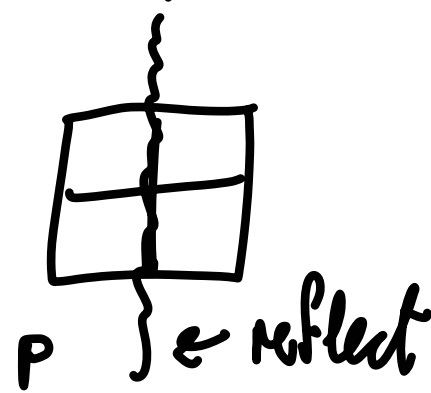
b	b
r	r

r	r
b	b

r	b
r	b

b	r
b	r

$$S_x = \{e, p\}$$



$\nu = \#$ of orbits = what we want to know

$$|O_n| |S_n| = |G|$$

each member of O_n contributes $1/|O_n|$ to the sum.

O_n contributes

$$|O_n| \times \frac{1}{|O_n|} = 1$$

to the sum.

$$= \sum_{x \in X} \frac{1}{|O_x|}$$

$$= \frac{1}{|G|} \sum_{x \in X} |S_x|$$

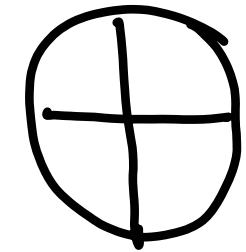
$$\{1, 2, 3, 4\} \quad \{5, 6\} \quad \{8, 9, 10\}$$

$$\frac{1}{4}, \frac{1}{4}, \frac{1}{4}, \frac{1}{4}$$

$$\frac{1}{2}, \frac{1}{2}$$

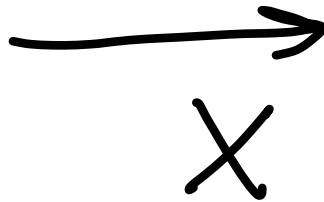
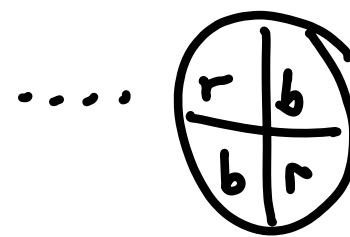
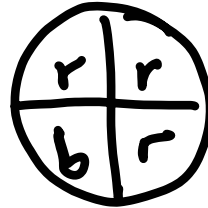
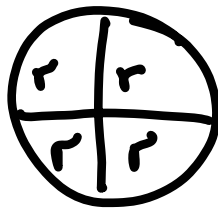
$$\frac{1}{3}, \frac{1}{3}, \frac{1}{3}$$

Example 1: $n=4$



4 rotations

$$V = \frac{1}{4} (4 + 1 + \dots + 2 + \dots) = 6$$



Tough to use if X is large.