

Local Time of Brownian Motion

- Definition
- Tanaka's formula
- Itô's formula for convex functions.

Intro and Definition.

W : Brownian Motion (1 dim)

We are interested in the amount of time W spends near x .

Now, with

$$L_w(x) \triangleq \text{leb} [t \geq 0 \mid W_t(\omega) = x]$$

we have $L_w(x)$ is $\mathbb{F}$ mbl and

$$E[L_w(x)] = E\left[\int_0^\infty 1_{W_t=x} dt\right]$$

$$= \int_0^\infty P(W_t=x) dt$$

$$= 0$$

$$\Rightarrow L_w(x) = 0 \quad \text{a.s.} \quad \forall x \in \mathbb{R}^d$$

- 0 time spent at any particular point.

(2)

But, to get a more useful measure of how long W spends near x , Lévy introduced the ~~good~~ quantity

$$L_x(x)(w) = \lim_{\epsilon \downarrow 0} \frac{1}{2\epsilon} \text{Prob}[0 \leq \Delta \leq \epsilon \mid |W_\Delta - x| \leq \epsilon]$$

$\epsilon > 0, x \in \mathbb{R}$.

- $L_x(w)$ is the normalized percent of time W spends near x on $[0, \epsilon]$
- either $L_x(x)$ or $\frac{1}{2} L_x(x)$ is called the local time of W near x .

We use this definition and prove the following result, known as Tanaka's formula.

Thm (Tanaka)

$$L_x(a) = |W_x - a| - |z - a| - \int_0^x \text{sign}(w_s - a) dw_s$$

a.s. on $(0, \infty)$ where the measure is P^z , i.e. the B.M. starts at z .

3

We want to formally apply Itô's rule to the function $f(x) = |x-a|$

If we could

$$\hat{f}(x) = \begin{cases} 1 & x > 0 \\ -1 & x < 0 \end{cases} = \text{sign}(x-a) \quad \text{if we ignore } a \text{ and set } f'(a) = -1.$$

$$\ddot{f}(x) = \delta_0 = \text{dirac at } 0.$$

Then, under P^z

$$|W_t - a| = |z - a| + \int_0^t \text{sign}(W_s - a) dW_s + \frac{1}{2} \text{Lab}[0 \leq s \leq t \mid W_s = a]$$

well defined b/c $\text{sign}^2 = 1$
↓

Making the approximation

$$\begin{aligned} \frac{1}{2} \text{Lab}[0 \leq s \leq t \mid W_s = a] \\ \approx \frac{1}{2\epsilon} \text{Lab}[0 \leq s \leq t \mid |W_s - a| \leq \epsilon] \end{aligned}$$

small ϵ

we get.

④

$$|W_t - a| = |Z - a| + \int_0^t \text{sign}(W_s - a) dW_s + L_t(a)$$

- desired result.

Workaround

$$\text{Set } g_\varepsilon(x) = \begin{cases} |x - a| & |x - a| > \varepsilon \\ \frac{1}{2} \left(\varepsilon + \frac{(x-a)^2}{\varepsilon} \right) & |x - a| \leq \varepsilon. \end{cases}$$

Then, $g_\varepsilon \in C^1(\mathbb{R})$ with

$$g'_\varepsilon(x) = \begin{cases} 1 & x > a + \varepsilon \\ -1 & x < a - \varepsilon \\ \frac{(x-a)}{\varepsilon} & a - \varepsilon \leq x \leq a + \varepsilon. \end{cases}$$

Also, $g_\varepsilon \in C^2(\mathbb{R} \setminus \{a\})$ with

$$g''_\varepsilon(x) = \begin{cases} 0 & x > a + \varepsilon, x < a - \varepsilon \\ \frac{1}{\varepsilon} & a - \varepsilon < x < a + \varepsilon. \end{cases}$$

Now, using mollification, we have the following:

- Oksendal Exercise 4.8b), Appendix D.

⑤

If $g \in C'$, $\tilde{g}$ exists and is continuous
for all but finitely many x and

$|\tilde{g}(x)| \leq M \quad \forall x$ then we can use Ito:

$$g(w_t) = g(w_0) + \int_0^t g'(w_s) dw_s + \frac{1}{2} \int_0^t \tilde{g}(w_s) ds$$

So, for any g

$$g(w_t) = g(z) + \int_0^t g'(w_s) dw_s$$

$$+ \frac{1}{2\epsilon} \mathbb{P}[0 \leq s \leq t \mid |w_s - z| > \epsilon]$$

||

$$\mathbb{P}[0 \leq s \leq t \mid |w_s - z| \leq \epsilon]$$

$$= g(z) + \int_0^t \tilde{g}(w_s) dw_s$$

$$+ \frac{1}{2\epsilon} \mathbb{P}[0 \leq s \leq t, |w_s - z| \leq \epsilon]$$

Now, as $\epsilon \rightarrow 0$

$$1) g(z) = \begin{cases} |z - z_0| & \text{if } |z - z_0| > \epsilon \\ \frac{1}{2} \left(\epsilon + \frac{(z - z_0)^2}{\epsilon} \right) & \text{if } |z - z_0| \leq \epsilon \end{cases} \rightarrow |z - z_0|$$

⑥

Similarly, a.s. $g_\varepsilon(w_t) \rightarrow |w_t - a|$.

• note: $\int_0^t |g_\varepsilon(w_s)|^2 ds \leq t$

Now, for $t \leq T$

$$\int_0^t |g_\varepsilon(w_s) - \text{sign}(w_s - a)|^2 ds$$

$$\leq \int_0^T \mathbb{1}_{|w_s - a| \leq \varepsilon} \left(\frac{w_s - a}{\varepsilon} - \text{sign}(w_s - a) \right)^2 ds$$

$$\leq 4 \int_0^T \mathbb{1}_{|w_s - a| \leq \varepsilon} ds.$$

so

$$E \left[\int_0^t |g_\varepsilon(w_s) - \text{sign}(w_s - a)|^2 ds \right]$$

$$\leq 4 \int_0^T P(|w_s - a| \leq \varepsilon) ds \rightarrow 0 \text{ (easy to check).}$$

so $\int_0^{\cdot} g_\varepsilon(w_s) dw_s \xrightarrow{L^2[0, \infty[\times [0, T]]} \int_0^{\cdot} \text{sign}(w_s - a) dw_s$

and $\exists$ a sub-sequence s.t. this convergence holds a.s. $P \times \text{Leb}[0, T]$.

⑦

Thus, along this subsequence, a.s. P^Z

$$\lim_{\epsilon \rightarrow 0} \frac{1}{\epsilon} \mathbb{P}^b[0 \leq \tau \leq \epsilon \mid |W_\tau - a| \leq \epsilon]$$

exists and the limit $L_\epsilon(a)$ satisfies

$$L_\epsilon(a) = |W_\epsilon - a| - |Z - a| - \int_0^\epsilon \text{sign}(W_s - a) dW_s$$

- note: we also have that $L_\epsilon(a)$ is $\mathbb{F}_\epsilon$ mbl.

Next, let $\epsilon, \tau \geq 0$, $a, b \in \mathbb{R}$. Under P^Z , a.s.

$$\begin{aligned} & |L_\epsilon(a) - L_\tau(b)| \\ & \leq ||W_\epsilon - a| - |W_\tau - b|| + ||Z - a| - |Z - b|| \\ & \quad + \left| \int_0^\epsilon \text{sign}(W_s - a) dW_s - \int_0^\tau \text{sign}(W_s - b) dW_s \right| \end{aligned}$$

Using this, one can show (Kolmogorov-Centsov, K+S pg 207-209) that $\exists$ a modification

of $L_\epsilon(a)$ which is a.s. (P^Z) jointly continuous in (ϵ, a) and still satisfies

⑧ Tanaka's equation (which we now use to define the local time). In fact we can define it in such a way that it is jointly continuous in (t, ω) a.s. (single Ω^*)
 $\forall p^z, z \in \mathbb{R}$.

The local time can ~~be~~ be used to evaluate functionals of the Brownian Path, as the following shows.

Thm.

For all Borel mbl $f: \mathbb{R} \rightarrow [0, \infty)$ we have a.s. $p^z \forall z$ and $t \geq 0$

$$\int_0^t f(W_s) ds = \int_{\mathbb{R}} f(x) L_t(x) dx.$$

Pf.

We will consider $f(x) = 1_{(a,b)}(x)$ $a < b \in \mathbb{Q}$ as the rest will follow ~~by~~ via an approximation.

9

Now, set

$$h(x) = \frac{x - a_1}{a_2 - a_1}$$

1

$$\frac{a_2 - x}{a_2 - b}$$

0

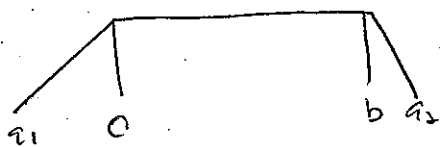
$$x \leq a_1 < 0$$

$$a_1 \leq x \leq 0$$

$$0 \leq x \leq b$$

$$b \leq x \leq a_2 \quad a_2 > b$$

$$x > a_2$$



and

$$H(x) = \int_{\mathbb{R}} h(u)(x-u)^+ du = \int_{-\infty}^x \int_{-\infty}^y h(u) du dy$$

so $H \in C^1$ with

$$\hat{H}(x) = \int_{-\infty}^x h(u) 1_{(0, \infty)}(x) du = \int_{-\infty}^x h(u) du$$

$$\tilde{H}(x) = h(x).$$

Thus, under p^2

(10)

$$\frac{1}{2} \int_0^t h(w_s) ds = H(w_t) - H(z) - \int_0^t \dot{H}(w_s) dW_s.$$

$$= \int_n h(a)(w_t - a)^+ da - \int_n h(r)(z - r)^+ dr \\ - \int_0^t \left(\int_n h(a) 1_{(a, \infty)}(w_s) da \right) dW_s.$$

$$= \frac{1}{2} \int_n h(a) L_x(a) da + \int_n h(a) \left(\int_0^t 1_{(a, \infty)}(w_s) dW_s \right) da \\ - \int_0^t \left(\int_n h(r) 1_{(r, \infty)}(w_s) dr \right) dW_s.$$

- Here, we have used

$$\frac{1}{2} L_x(a) = (w_t - a)^+ - (z - a)^+ - \int_0^t 1_{(a, \infty)}(w_s) dW_s$$

which follows similarly to Tanaka's formula
using $f(x) = (x - a)^+$ which is approximated

by

$$g_\epsilon(x) = \begin{cases} (x - a) & x \geq a + \epsilon \\ \frac{1}{2} \left(\epsilon + \frac{(x - a)^2}{\epsilon} \right) & 0 \leq x \leq a + \epsilon \\ \frac{\epsilon}{2} & x < a \end{cases}$$

(11)

Now, for h continuous, compactly supported
one can show (K+S pg 209)

$$\int_0^t h(s) \left(\int_0^s 1_{(0, \infty)}(u) du \right) ds$$

$$= \int_0^t \left(\int_0^s h(s) 1_{(0, \infty)}(u) ds \right) du.$$

- consider simple process approximations for
both stochastic integrals.

$\Rightarrow$

$$\frac{1}{2} \int_0^t h(u) du = \frac{1}{2} \int_0^t L_x(s) h(s) ds$$

$$+ \int_0^t h(s) \left(\int_0^s (1_{(0, \infty)}(u) - 1_{(0, \infty)}(u)) du \right) ds \rightarrow 0$$

~~is~~.

So, we have shown

$$\int_0^t h(u) du = \int_0^t L_x(s) h(s) ds$$

$h : \text{Borel mbl, } \geq 0$

(12)

We now use this to relax the C^2 requirement in Itô's formula, replacing it with the assumption that the function is convex.

Convex Functions.

We say $f: \mathbb{R} \rightarrow \mathbb{R}$ is convex if

$$f(\lambda x + (1-\lambda)y) \leq \lambda f(x) + (1-\lambda)f(y) \quad *.$$

$$\forall x < y, 0 \leq \lambda \leq 1.$$

Setting $z = \lambda x + (1-\lambda)y$ we obtain

$$f(z) \leq \frac{z-y}{x-y} f(x) + \frac{x-z}{x-y} f(y) \quad **$$

$$y < z < x.$$

Facts

1) f convex $\Rightarrow f$ continuous

• takes $z \nearrow x, z \downarrow y, x \downarrow z$ and $y \nearrow z$
in $**$.

(13)

2) f convex implies

$$h \mapsto \frac{f(x+h) - f(x)}{h} \quad h \neq 0$$

is non-decreasing in h , bounded above by $f(x+1) - f(x)$ ($0 < h < 1$) and below by $f(x-1) - f(x)$ ($-1 < h < 0$). Thus

$$D^{\pm} f(x) = \lim_{h \rightarrow 0^{\pm}} \frac{1}{h} (f(x+h) - f(x)) \quad (A)$$

exists and is finite. Furthermore,

$$D^{+} f(x) \leq D^{-} f(y) \leq D^{+} f(y) \quad x \leq y \quad (B)$$

Lastly, $D^{+} f$ is right-continuous and $D^{-} f$ is left-continuous.

Sketch - use **

$$0 < h < 1 : \quad \text{ ~~} y = x, z = x+h, x = x+h \text{ } \rangle \quad 0 < h \leq 1~~$$

Non
-Decr.

$\varepsilon = 1$ gives band

$$-1 < h < 0 : \quad y = x, z = x-h, x = x-h, \quad -1 < h < 0$$

$\varepsilon = -1$ gives band.

-thus (A) holds

(14)

for (B) take $y = x - \epsilon$, $z = x$, $x = x + \delta$

to get
$$\frac{f(x) - f(x - \epsilon)}{\epsilon} \leq \frac{f(x + \delta) - f(x)}{\delta}$$

$\Rightarrow D^- f(x) \leq D^+ f(x).$

Also, take $\epsilon = x - y < 0$, $-\epsilon < h < 0$ for $x < y$

to get

~~$f(y) - f(x)$~~

$$\frac{f(y) - f(x)}{y - x} = \frac{f(y - \epsilon) - f(y)}{-\epsilon}$$

$$\leq \frac{f(y - h) - f(y)}{-h} \rightarrow D^- f(y)$$

$\Rightarrow f(y) - f(x) \leq (y - x) D^- f(y)$

But for $\epsilon = y - x > 0$ $0 < h < \epsilon$

$$\frac{f(x + h) - f(x)}{h} \leq \frac{f(x + \epsilon) - f(x)}{\epsilon}$$

$\downarrow$

$D^+ f(x)$

$\parallel$

$$\leq \frac{f(y) - f(x)}{y - x}$$

$\Rightarrow D^+ f(x)(y - x) \leq (y - x) D^- f(y)$

~~$(\leq f(y) - f(x))$~~ $\leq (y - x) D^- f(y)$

(15)

Now, as $y \downarrow x$ we have

$$D^+f(x) \leq \lim_{y \downarrow x} D^+f(y).$$

But for $z > x$

$$\frac{f(z) - f(x)}{z - x} = \lim_{y \rightarrow x} \frac{f(y) - f(x)}{y - x} \geq D^+f(x)$$

so $z \downarrow x$ gives result.

With all this, we define the measure on $\mathbb{R}$ via

$$\mu((a, b)) = D^-f(b) - D^-f(a) \quad -\infty < a < b < \infty.$$

By integration by ~~parts~~ parts, if $g \in C^1$ and compactly supported then

$$\int_{\mathbb{R}} g(x) \mu(dx) = - \int_{\mathbb{R}} g'(x) D^-f(x) dx.$$

-note: we use ~~$\mu((a, b))$~~ since D^- is left-continuous.

16

With all this notation, we have the following version of Itô's formula for convex functions:

Thm

If f is convex then $\forall z \in \mathbb{R}$, under P^z

$$f(w_k) = f(z) + \int_0^t D^-f(w_s) dw_s + \frac{1}{2} \int_0^t L_x(x) \mu(dx).$$

pf

By localization we can assume D^-f is uniformly bounded. With the p_n mollifier of before, set

* slight change: $p_n(x) = n p(nx)$; $p(y) = \begin{cases} \frac{1}{C(y^2-1)} & 0 < y < 1 \\ 0 & \text{else.} \end{cases}$

$$f_n(x) = \int_{-\infty}^{\infty} p_n(x-y) f(y) dy = \int_{-\infty}^{\infty} p(z) f(x - \frac{z}{n}) dz$$

to obtain

- 1) f_n is uniformly bounded (in n) on compacts
- 2) $f_n(x) \rightarrow f(x)$
- 3) $f'_n(x) \rightarrow D^-f(x)$.

17)

4) If $g \in C^1(\mathbb{R})$ with compact support

$$\int_{\mathbb{R}} g(x) f''(x) dx = - \int_{\mathbb{R}} g'(x) f'(x) dx$$

$$\xrightarrow{\text{Ito}} - \int_{\mathbb{R}} g'(x) D^- f(x) dx$$

$$= \int_{\mathbb{R}} g(x) \mu(dx).$$

5) the same calculation in 4 holds for $g \in C(\mathbb{R})$ with compact support since g can be uniformly approximated by C^1 functions.

Thus, we have

$$\begin{array}{ccccc} f_n(w_t) & = & f_n(z) & + & \int_0^t f'_n(w_s) dW_s & + & \frac{1}{2} \int_0^t f''_n(w_s) ds \\ \text{a.s.} \downarrow & & \downarrow & & \downarrow L^2 & & \\ f(w_t) & & f(z) & & \int_0^t D^- f(w_s) dW_s & & \end{array}$$

(18)

Also

$$\int_0^t f_n(w_s) dw_s = \int_R f_n(x) L_t(x) dx$$

$$\rightarrow \int_R L_t(x) \mu(dx) \quad \text{a.s.}$$

Since for each w , $x \mapsto L_t(x)$ is continuous in x and supported in $[\min_{\Delta \leq t} w_s, \max_{\Delta \leq t} w_s]$

$\therefore$ up to sub-sequences we have a.s. convergence
so for each t

$$f(w_t) = f(z) + \int_0^t D^- f(X_s) dw_s + \frac{1}{2} \int_R L_t(x) \mu(dx)$$

By a.s. continuity in t the same holds
 $\forall t$ simultaneously.