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Introduction

Model under study :

$$\frac{\partial_t u - D\partial_{xx}^2 u = v(t, x, 0) - \mu u}{d\partial_v v = \mu u - v}$$

$$\partial_t v - d\Delta v = f(v)$$



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$$\frac{\partial_t u - D\partial_{xx}^2 u = v(t, x, 0) - \mu u}{d\partial_v v = \mu u - v}$$

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 Model proposed by Berestycki, Roquejoffre, Rossi to describe the effect of a line of fast diffusion.



Ecological motivation : transportation networks increase the speed of biological invasions (Siegfried).



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• Ex. 1 : pandemics. The 1347 black plague spread from major roads to inland areas.



Figure: Source : Wikipédia



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 Ex. 2 : the pine processionary moth. Thought to move northwards because of climate change, but roads also thought to play a role.



Figure: Pine processionary from Auray (Britain). Source : Wikipédia



Introduction

Fisher-KPP propagation



Theorem (Berestycki, Roquejoffre, Rossi 2012)

There is an asymptotic speed of spreading $c^*(D) > 0$ s.t. :

• If
$$D \leq 2d$$
, $c^* = c_{KPP} = 2\sqrt{df'(0)}$.



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Fisher-KPP propagation



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• If
$$D \le 2d$$
, $c^* = c_{KPP} = 2\sqrt{df'(0)}$.

If D > 2d, $c^* > c_{KPP}$ and $\frac{c^*(D)}{\sqrt{D}}$ has a finite limit as $D \to +\infty$.

Remark : $2\sqrt{df'(0)}$ is the classical spreading speed in $u_t - du_{xx} = f(u)$, $x \in \mathbb{R}^N$.



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Introduction

Issues

Does acceleration still occure in presence of a treshold phenomenon ?



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Figure: Example $f = \mathbf{1}_{u>\theta}(u-\theta)^2(1-u)$



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Introduction

Travelling waves to the full model in a strip $c > 0, u(t, x) = \phi(x + ct), v(t, x, y) = \psi(x + ct, y)$



Introduction

Travelling waves to the full model in a strip

$$c > 0, u(t, x) = \phi(x + ct), v(t, x, y) = \psi(x + ct, y)$$

$$\begin{array}{ccc} \mathbf{0} \leftarrow \phi & & -D\phi'' + \mathbf{c}\phi' = \psi(\mathbf{x},\mathbf{0}) - \mu\phi & & \phi \rightarrow 1/\mu \\ \\ & & \\ d\partial_y \psi = \mu\phi - \psi(\mathbf{x},\mathbf{0}) \end{array}$$

$$0 \leftarrow \psi \qquad -d\Delta \psi + c\partial_x \psi = f(\psi) \qquad \psi
ightarrow 1$$

$$\partial_y \psi = 0 \tag{1}$$

with uniform limits.



Introduction

Results

Assumption A

 $f \in \mathcal{C}^{1,\alpha}([0,1])$ is a non-negative function, f = 0 on $[0,\theta] \cup \{1\}$ for some $\theta > 0$, f(0) = f(1) = 0, and f'(1) < 0.



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Main result

There exists (c, φ, ψ) ∈ ℝ^{*}₊ × C^{2,α}(ℝ) × C^{2,α}(Ω_L) a solution of (1) obtained by continuation from the classical 1D problem −dψ^{''}₀ + c₀ψ[']₀ = f(ψ₀).



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$$0 < \phi < \frac{1}{\mu}$$
, $0 < \psi < 1$, and $\partial_x \phi, \partial_x \psi > 0$.



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$$0 < \phi < \frac{1}{\mu}$$
, $0 < \psi < 1$, and $\partial_x \phi, \partial_x \psi > 0$.

If $(\underline{c}, \overline{\phi}, \overline{\psi})$ is a classical solution of (1), $\underline{c} = c$ and there exists $r \in \mathbb{R}$ such that $\overline{\phi}(\cdot + r) = \phi(\cdot)$ and $\overline{\psi}(\cdot + r) = \psi(\cdot)$.



- Introduction

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Ongoing work : $D \to +\infty$

Probable outcome : $m\sqrt{D} \le c(D) \le M\sqrt{D}$

Existence of travelling waves

└─ Strategy of proof

1 Introduction

2 Existence of travelling waves

Strategy of proof

Outline of the main steps

3 The limit $D \to +\infty$



Existence of travelling waves

Idea

Continuation from the full model to

$$-d\psi^{\prime\prime}+c\psi^{\prime}=f(\psi),\ \psi(-\infty)=0,\psi(+\infty)=1$$

$$0 \leftarrow \psi \qquad -d\Delta \psi + c\partial_x \psi = f(\psi) \qquad \psi
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 $\partial_{\mathbf{y}}\psi = \mathbf{0}$



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$$0 \leftarrow \psi \qquad -d\Delta \psi + c\partial_x \psi = f(\psi) \qquad \psi
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 $\partial_{y}\psi = 0$

Step 1 : force $\phi = \psi$ on the road with ε , parameter in (0, 1).



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Existence of travelling waves

└─ Strategy of proof

Idea

$$egin{aligned} d\partial_y\psi&=rac{D}{\mu}\partial_{xx}\psi-rac{c}{\mu}\partial_x\psi\ 0\leftarrow\psi&-d\Delta\psi+c\partial_x\psi=f(\psi)&\psi
ightarrow 1\ \partial_y\psi&=0 \end{aligned}$$



Existence of travelling waves

└─ Strategy of proof

Idea

$$d\partial_y \psi = rac{sD}{\mu} \partial_{xx} \psi - rac{c}{\mu} \partial_x \psi$$

$$0 \leftarrow \psi$$
 $-d\Delta \psi + c\partial_x \psi = f(\psi)$ $\psi \rightarrow 1$

$$\partial_y \psi = 0$$

Step 2 : vary D with s, parameter in (0, 1).



Existence of travelling waves

Strategy of proof

Idea

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$$0 \leftarrow \psi$$
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$\partial_{\mathbf{y}}\psi = \mathbf{0}$

Interpretation : ψ on the road adjusts to ψ in the field with some delay.



Existence of travelling waves

Strategy of proof

Idea

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Interpretation : ψ on the road adjusts to ψ in the field with some delay.

Step 3 : vary $\frac{1}{u}$ with t, parameter in (0, 1).



Existence of travelling waves

Strategy of proof

Idea

 $d\partial_y \psi = 0$

$$0 \leftarrow \psi \qquad -d\Delta \psi + c\partial_x \psi = f(\psi) \qquad \psi
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Existence of travelling waves

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Biological interpretation : the road becomes a fence.



Existence of travelling waves

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Biological interpretation : the road becomes a fence.

Theorem : Kanel '69, Berestycki-Nirenberg '90

This problem has a unique solution up to translations, the planar wave.



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Existence of travelling waves

Strategy of proof

Strategy

Go from step 3 to step 1.



Existence of travelling waves

Strategy of proof

- Go from step 3 to step 1.
- For each step, prove that the set of parameters for which the problem has a solution is open and closed in [0, 1].



Existence of travelling waves

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 - Closedness : a priori estimates, upper and lower bounds on *c*, exponential estimates.



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 - Openness : relies on a more or less sophisticated application of the implicit function theorem.



Existence of travelling waves

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- Go from step 3 to step 1.
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 - Closedness : a priori estimates, upper and lower bounds on *c*, exponential estimates.
 - Openness : relies on a more or less sophisticated application of the implicit function theorem.
- The case $\varepsilon \simeq 0$ is non trivial and is treated separately.



Existence of travelling waves

Outline of the main steps

1 Introduction

Existence of travelling wavesStrategy of proof

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3 The limit $D \to +\infty$



Existence of travelling waves

└─ Outline of the main steps

Exp. sols. for the full model with parameter ε

We search for $\phi(x) = e^{\lambda x}$, $\psi(x, y) = e^{\lambda x}h(y)$ and we get, depending on the comparison between d and D:



Existence of travelling waves

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■ *D* < *d* :

$$\begin{cases} \psi(x,y) = \frac{\mu e^{\lambda x} \cos\left(\sqrt{\lambda\left(\lambda - \frac{c}{d}\right)}(y+L)\right)}{\cos\left(\sqrt{\lambda\left(\lambda - \frac{c}{d}\right)}L\right) - \varepsilon d\sqrt{\lambda\left(\lambda - \frac{c}{d}\right)} \sin\left(\sqrt{\lambda\left(\lambda - \frac{c}{d}\right)}L\right)} \\ \phi(x) = e^{\lambda x} \end{cases}$$



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Existence of travelling waves

- Outline of the main steps



Figure: Equation on λ , D < d.



Existence of travelling waves

Outline of the main steps



Figure: Equation on λ , D < d.

Figure: Equation on λ , D > d.

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- Existence of travelling waves
 - Outline of the main steps



Figure: Level lines for ψ with D < d

Interpretation :

- D < d: the field drives the road.
- D > d: the road drives the field.



Figure: Level lines for ψ with D > d

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Existence of travelling waves

Outline of the main steps



Figure: Level lines for ψ with D < d

Figure: Level lines for ψ with D > d

Interpretation :

- D < d: the field drives the road.
- D > d: the road drives the field.
- In BRR : comparison between 2d and D but here f'(0) = 0.



Existence of travelling waves

└─ Outline of the main steps

Remark

In a similar fashion, the reduced models have exp. sols. $p(x, y) = e^{\lambda x} \phi(y)$, and in the Wentzell case there is a comparison between d and sD.



Existence of travelling waves

Untline of the main steps

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- As $\varepsilon \to 0$, everything goes smoothly to the Wentzell case.



Existence of travelling waves

Outline of the main steps

Remark

- In a similar fashion, the reduced models have exp. sols. $p(x, y) = e^{\lambda x} \phi(y)$, and in the Wentzell case there is a comparison between d and sD.
- As $\varepsilon \to 0$, everything goes smoothly to the Wentzell case.
- Provided uniform (on t, s or ε) bounds on c, we have a uniform positive lower bound for λ and uniform bounds on φ (or h). This will be necessary for comparison purposes.



Existence of travelling waves

└─ Outline of the main steps

Closedness : some hints

These properties are valid for the three models.

Lemma : a priori bounds

 $0 \leq \inf \psi \leq \mu \phi \leq \sup \psi \leq 1$



Existence of travelling waves

└─ Outline of the main steps

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Prop. : uniqueness and monotonicity

• (c, ϕ, ψ) is unique up to translations.



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Existence of travelling waves

Untine of the main steps

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Prop. : *c_{min}* provided *c_{max}*

$$\begin{split} \mathsf{IBP}: c &= \frac{1}{L + t/\mu} \int_{\Omega_L} f(\psi). \text{ This gives that if there exists } c_{max} > 0 \text{ s.t. any sol.} \\ \mathsf{satisfies} \ c &< c_{max}, \text{ then there exists } c_{min} = \frac{M_0}{L + 1/\mu} f(\frac{1 + \theta}{2}). \end{split}$$



Existence of travelling waves

└─ Outline of the main steps

Prop. : existence of c_{max}

There exists $c_{max} > 0$ s.t. any solution satisfies $c < c_{max}$.



Existence of travelling waves

Untine of the main steps

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Figure: Graph of $\overline{\psi}$ for some arbitrary values of the parameters



Existence of travelling waves

Untine of the main steps

Prop. : existence of c_{max}

There exists $c_{max} > 0$ s.t. any solution satisfies $c < c_{max}$.



Figure: Graph of $\overline{\psi}$ for some arbitrary values of the parameters

Proof.

Glue a positive exponential solution with a linear solution of the problem with f replaced by $||f||_{\infty}$. If c is large enough, contact points only occur at salient angles, contradiction.

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Existence of travelling waves

Outline of the main steps

Prop. : limiting conditions

• Comparison with the exponential solutions give the uniform limit to the left.



Existence of travelling waves

Outline of the main steps

Prop. : limiting conditions

- Comparison with the exponential solutions give the uniform limit to the left.
- Classical computations from Berestycki, Larrouturou, Lions gives the uniform limit to the right.



Existence of travelling waves

└─ Outline of the main steps

Openness : ideas of the proof

 Linearise the problem around a solution for some value of the parameter (e.g. s₀). Construct an auxiliary function to reduce the problem to a homogeneous boundary value problem.



Existence of travelling waves

└─ Outline of the main steps

Openness : ideas of the proof

- Linearise the problem around a solution for some value of the parameter (e.g. s₀). Construct an auxiliary function to reduce the problem to a homogeneous boundary value problem.
- In a suitable Hölder space weighted by exponential decay at x → -∞, the linearised have the Fredholm property of index 0 : Lyapunov-Schmidt reduction is possible.



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- Write the equation as some $F(s, c_1, v_R, v_N) = 0$. For $s = s_0$ the equation is linear and solved step by step. For $s > s_0$ close to s_0 use the implicit function theorem.



Existence of travelling waves

└─ Outline of the main steps

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- Linearise the problem around a solution for some value of the parameter (e.g. s₀). Construct an auxiliary function to reduce the problem to a homogeneous boundary value problem.
- In a suitable Hölder space weighted by exponential decay at x → -∞, the linearised have the Fredholm property of index 0 : Lyapunov-Schmidt reduction is possible.
- Write the equation as some $F(s, c_1, v_R, v_N) = 0$. For $s = s_0$ the equation is linear and solved step by step. For $s > s_0$ close to s_0 use the implicit function theorem.
- Limiting conditions are obtained thanks to exponential solutions.



Existence of travelling waves

└─ Outline of the main steps

Step 2 to step 1 : the singular perturbation $arepsilon \sim 0$

Here, the existence of the auxiliary function becomes totally unclear since the exchange condition $d\partial_y \psi = \mu \phi - \psi$ degenerates into the Wentzell condition



Existence of travelling waves

└─ Outline of the main steps

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$$W\psi_{1} + \varepsilon \frac{c_{1}}{\mu} \partial_{x} \psi_{1} + \left(-\frac{\varepsilon D}{\mu} \partial_{xx} + \varepsilon \frac{c_{0} + c_{1}\varepsilon}{\mu} \partial_{x} \right) d\partial_{y} \psi_{1}$$

$$= -\frac{c_{1}}{\mu} \partial_{x} \psi_{0} - \left(-\frac{D}{\mu} \partial_{xx} + \frac{c_{0} + c_{1}\varepsilon}{\mu} \partial_{x} \right) d\partial_{y} \psi_{0}$$
(2)



Existence of travelling waves

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$$= -\frac{c_{1}}{\mu} \partial_{x} \psi_{0} - \left(-\frac{D}{\mu} \partial_{xx} + \frac{c_{0} + c_{1}\varepsilon}{\mu} \partial_{x} \right) d\partial_{y} \psi_{0}$$
(2)

Key lemma : construction of an auxiliary function

Compute $\tilde{\psi}$ not for the linearised operator but for the simpler problem $-d\Delta u + u = 0$ by a partial Fourier transform.



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Existence of travelling waves

Untine of the main steps

By taking a small enough exponent in the weight, there exists $u = \tilde{\psi}(\varepsilon, c_1, v)$ in $C^{2,\alpha}$ that solves for $v \in C^{3,\alpha}$

$$Wu + \varepsilon \frac{c_1}{\mu} \partial_X u + \left(-\frac{\varepsilon D}{\mu} \partial_{XX} + \varepsilon \frac{c_0 + c_1 \varepsilon}{\mu} \partial_X \right) d\partial_y u = h_0 - \varepsilon \frac{c_1}{\mu} \partial_X v - \left(-\frac{\varepsilon D}{\mu} \partial_{XX} + \varepsilon \frac{c_0 + c_1 \varepsilon}{\mu} \partial_X \right) d\partial_y v$$

 $-d\Delta u + u = 0$

 $\partial_y u = 0$



Existence of travelling waves

Outline of the main steps

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 $-d\Delta u + u = 0$

 $\partial_y u = 0$

and $|u|_{\mathcal{C}^{2,\alpha}} \leq C_1 |h_0|_{\infty} + C_2 \left| \frac{1}{\varepsilon} \mathcal{K}_0\left(\frac{|x|}{d\varepsilon} \right) * (h_0 + \varepsilon h(v)) \right|_{\alpha} + C_3 |h_0 + \varepsilon h(v)|_{\alpha}$



Existence of travelling waves

Outline of the main steps

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$$-d\Delta u + u = 0$$

$$\partial_y u = 0$$

and $|u|_{\mathcal{C}^{2,\alpha}} \leq C_1 |h_0|_{\infty} + C_2 \left| \frac{1}{\varepsilon} \mathcal{K}_0\left(\frac{|x|}{d\varepsilon} \right) * (h_0 + \varepsilon h(v)) \right|_{\alpha} + C_3 |h_0 + \varepsilon h(v)|_{\alpha}$ where \mathcal{K}_0 denotes the 0-th modified Bessel function of the second kind $(\mathcal{K}_0 \in L^1, \hat{\mathcal{K}}_0 = \frac{\pi}{\sqrt{1+\varepsilon^2}})$. Moreover, the weighted spaces are stable.



Existence of travelling waves

Outline of the main steps

By taking a small enough exponent in the weight, there exists $u = \tilde{\psi}(\varepsilon, c_1, v)$ in $C^{2,\alpha}$ that solves for $v \in C^{3,\alpha}$

$$Wu + \varepsilon \frac{c_1}{\mu} \partial_X u + \left(-\frac{\varepsilon D}{\mu} \partial_{XX} + \varepsilon \frac{c_0 + c_1 \varepsilon}{\mu} \partial_X \right) d\partial_y u = h_0 - \varepsilon \frac{c_1}{\mu} \partial_X v - \left(-\frac{\varepsilon D}{\mu} \partial_{XX} + \varepsilon \frac{c_0 + c_1 \varepsilon}{\mu} \partial_X \right) d\partial_y v$$

$$-d\Delta u + u = 0$$

$$\partial_y u = 0$$

and $|u|_{\mathcal{C}^{2,\alpha}} \leq C_1 |h_0|_{\infty} + C_2 \left| \frac{1}{\varepsilon} \mathcal{K}_0\left(\frac{|x|}{d\varepsilon} \right) * (h_0 + \varepsilon h(v)) \right|_{\alpha} + C_3 |h_0 + \varepsilon h(v)|_{\alpha}$ where \mathcal{K}_0 denotes the 0-th modified Bessel function of the second kind $(\mathcal{K}_0 \in L^1, \hat{\mathcal{K}}_0 = \frac{\pi}{\sqrt{1+\varepsilon^2}})$. Moreover, the weighted spaces are stable.

Proof.

Uses explicit (heavy) computations by partial Fourier transform, and a Paley-Wiener type theorem.



1 Introduction

Existence of travelling wavesStrategy of proof

Outline of the main steps

3 The limit $D \to +\infty$



 $L _{\text{The limit } D} \rightarrow +\infty$

Rescaled problem

Set $u_D(x) = \phi(\sqrt{D}x)$, $v_D(x, y) = \psi(\sqrt{D}x, y)$, $c_D = \frac{c}{\sqrt{D}}$. Equation on (c, u, v)



 $\Box_{\mathsf{The limit } D} \to +\infty$

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$$0 \leftarrow u \qquad -u'' + cu' = v(x, 0) - \mu u \qquad u \to 1/\mu$$
$$d\partial_y v = \mu u - v(x, 0)$$
$$0 \leftarrow v \qquad -\frac{d}{D}\partial_{xx}v - d\partial_{yy}v + c\partial_x v = f(v) \qquad v \to 1$$
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- Upper bound : $c_D \leq M$ (the exp. sols. pass to the limit $D \rightarrow +\infty$)
- Lower bound : needs a uniform local $C^{1,\alpha}$ estimate on v_D (true when $D = +\infty$).



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 $\Box_{\text{The limit } D \to +\infty }$

Thank you for your attention.





 $L _{\text{The limit } D} \rightarrow +\infty$

Oblique case

Search for $p(x, y) = e^{\lambda x} \phi(y)$ zero of $-d\Delta + c\partial_x$ with $(Ob)_s$ boundary condition.



 $\Box_{\text{The limit } D} \to +\infty$

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$$\begin{cases} -\phi'' + \lambda(\frac{c}{d} - \lambda)\phi = 0 \text{ on } (-L, 0) \\ d\phi'(0) + \frac{c}{\mu}s\lambda\phi(0) = 0 \\ \phi'(-L) = 0 \\ \phi > 0 \end{cases}$$


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We get $\phi(y) = \cos\left(\sqrt{\lambda(\lambda - \frac{c}{d})}(y + L)\right)$, and we are left with $\lambda > \frac{c}{d}$ solving

$$\tan\left(\sqrt{\lambda\left(\lambda-\frac{c}{d}\right)}L\right) = \frac{cs\lambda}{\mu d\sqrt{\lambda\left(\lambda-\frac{c}{d}\right)}}$$
(3)



Front propagation directed by a line of fast diffusion : existence of travelling waves.

 \Box The limit $D \to +\infty$



Figure: Equation (3) on λ , oblique case.



Wentzell case

Comparison between d and sD (in [?] : 2d and D but here f'(0) = 0) :

• sD < d : $\phi(y) = \cos\left(\sqrt{\lambda(\lambda - \frac{c}{d})}(y + L)\right)$ and $\lambda > \frac{c}{d}$ solves

$$\tan\left(\sqrt{\lambda\left(\lambda-\frac{c}{d}\right)}L\right) = \frac{c\lambda - sD\lambda^2}{\mu d\sqrt{\lambda\left(\lambda-\frac{c}{d}\right)}} \tag{4}$$



 $\Box_{\text{The limit } D} \to +\infty$

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 $\Box_{\text{The limit } D} \to +\infty$

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• sD = d : $\phi \equiv 1$ and $\lambda = \frac{c}{d}$



Front propagation directed by a line of fast diffusion : existence of travelling waves.

 \Box The limit $D \to +\infty$



Figure: Equation (4) on λ , Wentzell case with $s_1 D < d, s_2 D > d$ and $\lambda > \frac{c}{d}$.



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 $\Box_{\text{The limit } D \to +\infty}$



Figure: Equation (5) on λ , Wentzell case with sD > d and $\lambda < \frac{c}{d}$.



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 \square The limit $D \rightarrow +\infty$

P_{Ob} is open

Starting with a solution c_0, ψ_0 of some $(Ob)_{s_0}$ we set $\psi = \psi_0 + (s - s_0)\psi_1, c = c_0 + (s - s_0)c_1$ and solve the problem in c_1, ψ_1 :



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$$d\partial_y\psi^1+c^0s^0\partial_x\psi^1=-(c^0+c^1s)\partial_x\psi^0-(c^0+c^1s)(s-s^0)\partial_x\psi^1$$

$$\mathcal{L}\psi^1 + c^1\partial_x\psi^0 = R(s-s^0,c^1,\psi^1)$$

$$\partial_y \psi^1 = 0$$

with $\mathcal{L}g = -d\Delta g + c^0 \partial_x g - f'(\psi^0)$ and R being a quadratic remainder in ψ_1, c_1 that goes to 0 as $s \to s_0$.



Front propagation directed by a line of fast diffusion : existence of travelling waves.

 \square The limit $D \rightarrow +\infty$

P_{Ob} is open : functional setting

In a suitable weighted Hölder space inspired from works of [?, ?], the linearised \mathcal{L} has the Fredholm property of index 0 so that we can apply a Lyapunov-Schmidt reduction :



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$$\mathcal{C}^{lpha}_{w}(\Omega_{L}):=\{u\in\mathcal{C}^{lpha}(\Omega_{L})\mid w_{1}u\in\mathcal{C}^{lpha}(\Omega_{L})\}$$



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$$\mathcal{C}^{\alpha}_{w}(\Omega_{L}) := \{ u \in \mathcal{C}^{\alpha}(\Omega_{L}) \mid w_{1}u \in \mathcal{C}^{\alpha}(\Omega_{L}) \}$$

$$X = \{ u \in \mathcal{C}^2(\Omega_L) \mid D^{\beta} u \in \mathcal{C}^{\alpha}(\Omega_L), |\beta| = 2 \}$$

We endow X with the norm $||u||_X = ||w_1u||_{\mathcal{C}^{2,\alpha}}$.

Prop. : reduction to a homogeneous boundary problem

There exists $\tilde{\psi}(s, c^1, \cdot) : \mathcal{C}^{2,\alpha}_w(\overline{\Omega_L}) \to \mathcal{C}^{2,\alpha}_w(\overline{\Omega_L})$ a \mathcal{C}^1 function such that by writing $\psi_1 = \tilde{\psi}(s, c_1, v) + v$ we have the equivalent equation

$$\mathcal{L}\mathbf{v} + c_1 \partial_{\mathbf{x}} \psi_0 = R - \mathcal{L} \tilde{\psi}$$

on $v = v_R + v_N \partial_x \psi_0 \in X = N(\mathcal{L}) \oplus X_1$ endowed with the $(Ob)_{s_0}$ boundary condition.



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 $ilde{\psi}(s, c^1, v)$ solves for A > 0 fixed large enough

$$d\partial_y u + c^0 s^0 \partial_x u = -(c^0 + c^1 s) \partial_x \psi^0 - (c^0 + c^1 s)(s - s^0) \partial_x (u + v)$$

$$\mathcal{L}u + Au = 0$$

$$\partial_y u = 0$$

