

**HOMOGENIZATION
OF FULLY NONLINEAR FIRST & SECOND ORDER PDE IN
STATIONARY ERGODIC MEDIA**

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- medium with self-averaging properties
periodic, almost periodic, random (stationary ergodic)
- phenomenon/law described by a spatially inhomogeneous equation

$$F[u, x] = 0$$

- look from far away — scale ε

$$F\left[u^\varepsilon, \frac{x}{\varepsilon}\right] = 0$$

- microscopic properties average out in the limit $\varepsilon \rightarrow 0$

$$u^\varepsilon \rightarrow \bar{u}$$

and

$$\bar{F}[\bar{u}] = 0$$

spatially homogeneous, translation invariant equation

PROBABILISTIC SETTING

$\Omega = \{\text{“all equations”}\}$ P probability on Ω frequency to have certain equation

$F_\omega(\cdot, \cdot) = F(\cdot, \cdot, \omega)$ element of Ω

- at position x we observe $F(\cdot, x, \omega)$

at position $x + y$ we observe same configuration labeled by different ω but with the same frequency

$$F(\cdot, x + y, \omega) = F(\cdot, x, \tau_y \omega) \quad \text{and } \tau_y \text{ is measure preserving (stationarity)}$$

- at large scale “media averages”

under translations operators “repeat each other”

$$A \subset \Omega, P(A) > 0 \implies P\left(\underbrace{\bigcup_{y \in \mathbb{R}^n} \tau_y A}_{\text{translation invariant}}\right) = 1 \quad (\text{ergodicity})$$

GENERAL PROBLEM

$$(\text{BVP})_\varepsilon \quad \begin{cases} F(D^2u_\varepsilon, \varepsilon D^2u_\varepsilon, Du_\varepsilon, u_\varepsilon, x, \frac{x}{\varepsilon}, \omega) = 0 & \text{in } U \subset \mathbb{R}^N \\ u_\varepsilon = g & \text{on } \partial U \end{cases}$$

ASSUMPTION

F stationary ergodic wrt $(x/\varepsilon, \omega)$

CONCLUSION

$$u_\varepsilon(\cdot, \omega) \xrightarrow[\varepsilon \rightarrow 0]{} \bar{u} \quad \text{in } C(\bar{U}) \text{ and a.s. in } \omega$$

$$\overline{(\text{BVP})} \quad \begin{cases} \bar{F}(D^2\bar{u}, D\bar{u}, \bar{u}, x) = 0 & \text{in } U \\ \bar{u} = g & \text{on } \partial U \end{cases}$$

HISTORY

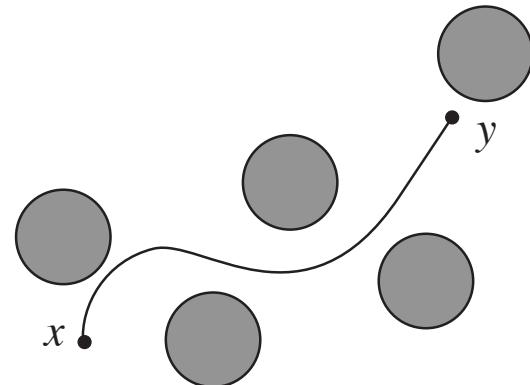
- periodic
 - almost periodic
- stationary ergodic
 - linear theory Papanicolaou-Varadhan; Kozlov; Jikov; Yurinskii;...
 - variational nonlinear Dal Masso-Modica
 - nonvariational nonlinear Souganidis; Rezankhanlou-Tarver
 - viscous Hamilton-Jacobi Lions-Souganidis
Kosygina-Rezankhanlou-Varadhan
Freidlin ($N=1$); Sznitman;...
 - fully nonlinear second-order Caffarelli-Souganidis-Wang; Caffarelli-Souganidis

HAMILTON-JACOBI EQUATIONS

$$H\left(Du^\varepsilon, u_\varepsilon, \frac{x}{\varepsilon}\right) = 0$$

- effective geodesics

random medium



$$|Du^\varepsilon| - V\left(\frac{x}{\varepsilon}, \omega\right) = 0$$

$$u^\varepsilon(x, \omega) = \inf \left\{ \int_0^1 V\left(\frac{x(s)}{\varepsilon}, \omega\right) ds : x(0) = 0, \ x(1) = x, \ |\dot{x}| \leqq 1 \right\}$$

$$u^\varepsilon(\cdot, \omega) \rightarrow \bar{u} \quad \text{as } \varepsilon \rightarrow 0$$

$$\bar{H}(D\bar{u}) = 0$$

$$\bar{u}(x) = \inf \left\{ \int_0^1 \bar{H}^*(x(s)) ds : x(0) = 0, \ x(1) = x, \ |\dot{x}| \leqq 1 \right\}$$

(\bar{H}^* convex dual of \bar{H})

recall H convex

$$H^*(q) = \sup\{q \cdot p - H(p)\}$$

$$H(p) = \sup\{p \cdot q - H^*(q)\}$$

“VISCOUS” HAMILTON-JACOBI (BELLMAN EQUATIONS)

$$-\varepsilon \operatorname{tr} A(x, \frac{x}{\varepsilon}, \omega) D^2 u_\varepsilon + H(Du_\varepsilon, u_\varepsilon, x, \frac{x}{\varepsilon}, \omega) = 0$$

- large deviations of Brownian motions in random environments

$$\begin{cases} dX_t^\varepsilon = \sqrt{2\varepsilon} \sigma(X_t^\varepsilon, \varepsilon^{-1} X_t^\varepsilon, \omega) dB_t \\ X_0^\varepsilon = x \in U \end{cases} \quad \tau_x^\varepsilon \text{ exit time from } U \subset \mathbb{R}^N$$



“effective” asymptotics of $P(X_{\tau_x^\varepsilon}^\varepsilon \in \Gamma)$ ($\Gamma \subset \partial U$)

$$u_\varepsilon = P(X_{\tau_x^\varepsilon}^\varepsilon \in \Gamma) = \exp(-\frac{1}{\varepsilon} I^\varepsilon)$$

$$-\varepsilon \operatorname{tr}[(\sigma \sigma^T)(x, \frac{x}{\varepsilon}, \omega) D^2 I^\varepsilon] + ((\sigma \sigma^T)(x, \frac{x}{\varepsilon}, \omega) D I^\varepsilon, D I^\varepsilon) = 1 \text{ in } U$$

$$I^\varepsilon = \exp[-\frac{1}{\varepsilon}(\bar{I} + o(1))]$$

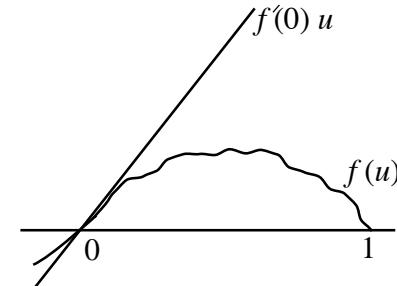
$$\begin{cases} ((\bar{\sigma} \bar{\sigma}^T)(x) D \bar{I}, D \bar{I}) = 1 \text{ in } U \\ \bar{I} = \begin{cases} 0 & \text{on } \Gamma \\ +\infty & \text{on } \partial U \setminus \Gamma \end{cases} \end{cases}$$

\bar{I} “effective” rate for large deviations

- premixed turbulent combustion with separated scales in random environments

$$\begin{cases} u_{\varepsilon t} - \varepsilon \Delta u_{\varepsilon} + a(x, \frac{x}{\varepsilon^\alpha}, \omega) \cdot Du_{\varepsilon} = \frac{1}{\varepsilon} f(u_{\varepsilon}, x, \frac{x}{\varepsilon^\alpha}, \omega) & \text{in } \mathbb{R}^N \times (0, \infty) \\ u_{\varepsilon}(\cdot, 0) = 0 \text{ off } G_0 \subset \mathbb{R}^N \end{cases}$$

f KPP-type with equilibria at 0 and 1



$$u_{\varepsilon} \rightarrow \begin{cases} 0 & \text{in } \{\bar{v} > 0\} \\ 1 & \text{in } \text{int } \{\bar{v} = 0\} \end{cases}$$

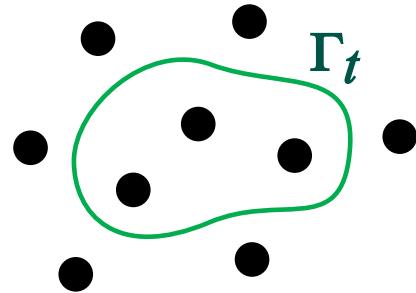
$$\begin{cases} \max[\bar{v}_t + \bar{H}(D\bar{v}, x), \bar{v}] = 0 & \text{in } \mathbb{R}^N \times (0, \infty) \\ \bar{v}(\cdot, 0) = \begin{cases} 0 & \text{in } G_0 \\ -\infty & \text{off } \overline{G_0} \end{cases} & \text{interface } \partial\{\bar{v} > 0\} \end{cases}$$

effective Hamiltonian \bar{H} is identified at the limit, as $\varepsilon \rightarrow 0$, of

$$v_{\varepsilon t} - \varepsilon^{1-\alpha} \Delta v_{\varepsilon} + a(x, \frac{x}{\varepsilon^\alpha}, \omega) \cdot Dv_{\varepsilon} - |Dv_{\varepsilon}|^2 - f_u(0, x, \frac{x}{\varepsilon^\alpha}, \omega) = 0$$

- OPEN for other f (bistable)
- random travelling waves

- front propagation



$$V = -\delta \operatorname{tr} Dn + a(n, x, \omega)$$

$$u_t - \delta M(D^2 u, Du) + H(Du, x, \omega) = 0$$

$$\begin{aligned} M(X, p) &= \operatorname{tr}(I - \hat{p} \otimes \hat{p})X \\ H(p, x, \omega) &= a(-\hat{p}, x, \omega)|p| \\ (\hat{p} &= p/|p|) \end{aligned}$$

- scale in space-time Γ_t^ε

identify effective front $\bar{\Gamma}_t$

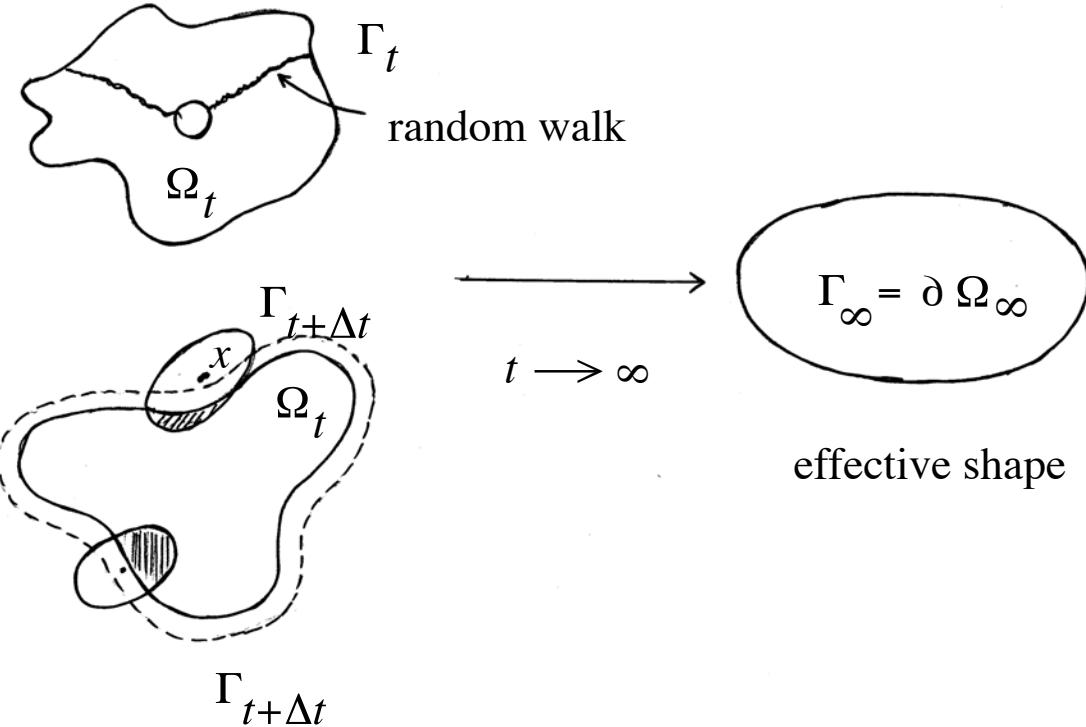
$$\Gamma_t^\varepsilon \xrightarrow[\varepsilon \rightarrow 0]{} \Gamma_t \text{ a.s.}$$

- long time behavior (percolation)

identify effective shape

$$\frac{1}{t} \Gamma_t \xrightarrow[t \rightarrow \infty]{} \bar{\Gamma} \text{ a.s.}$$

percolation



voter model

$$V = -\delta \operatorname{tr} Dn - a(n, x, \omega) \quad u_t - \delta M(D^2u, Du) + H(Du, x, \omega) = 0$$

different scalings – different effects of heterogeneity

- $(x, t) \rightarrow \left(\frac{x}{\varepsilon}, \frac{t}{\varepsilon}\right)$

$$V = -\varepsilon\delta \operatorname{tr} Dn - a\left(n, \frac{x}{\varepsilon}, \omega\right) \quad u_t^\varepsilon - \varepsilon\delta M(D^2u^\varepsilon, Du^\varepsilon) + H\left(Du^\varepsilon, \frac{x}{\varepsilon}, \omega\right) = 0$$

OPEN  δ = 0 and H not convex unless medium is almost periodic
δ ≠ 0 unless medium is almost periodic

- $(x, t) \rightarrow \left(\frac{x}{\varepsilon}, \frac{t}{\varepsilon^2}\right)$

$$V = -\delta \operatorname{tr} Dn - \frac{1}{\varepsilon}a\left(a, \frac{x}{\varepsilon}, \omega\right) \quad u_t^\varepsilon - \delta M(D^2u^\varepsilon, Du^\varepsilon) + \frac{1}{\varepsilon}H\left(Du^\varepsilon, \frac{x}{\varepsilon}, \omega\right) = 0$$

OPEN in all settings (including periodic)

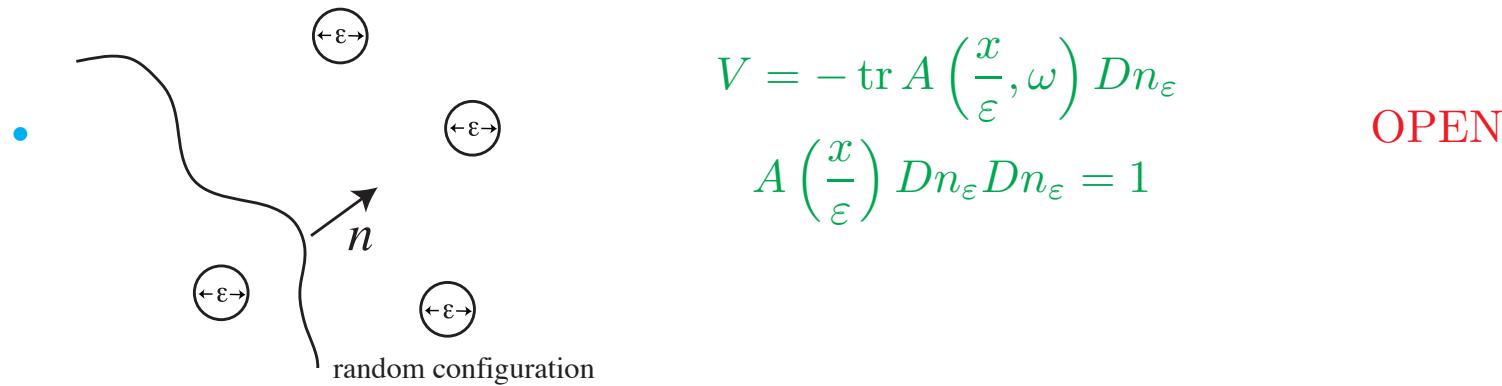
FULLY NONLINEAR, SECOND-ORDER, UNIFORMLY ELLIPTIC EQUATIONS

$$F(D^2u_\varepsilon, Du_\varepsilon, u_\varepsilon, x, \frac{x}{\varepsilon}, \omega) = 0$$

- Monge-Ampère $\det D^2u_\varepsilon = f(\frac{x}{\varepsilon}, \omega)$

- minimal surface

$$-\operatorname{tr} \left[A\left(\frac{x}{\varepsilon}, \omega\right) \left(I - \frac{Du_\varepsilon \otimes Du_\varepsilon}{1 + |Du_\varepsilon|^2} \right) D^2u_\varepsilon \right] = f\left(\frac{x}{\varepsilon}, \omega\right)$$



$$\begin{aligned} & u_{\varepsilon t} - \operatorname{tr} \left\{ A\left(\frac{x}{\varepsilon}, \omega\right) [I - (A\left(\frac{x}{\varepsilon}, \omega\right) Du_\varepsilon Du_\varepsilon)^{-1} A\left(\frac{x}{\varepsilon}, \omega\right) Du_\varepsilon Du_\varepsilon] D^2u_\varepsilon \right\} \\ & + \frac{2}{\varepsilon} (A\left(\frac{x}{\varepsilon}, \omega\right) Du_\varepsilon Du_\varepsilon)^{-1} \operatorname{tr} A\left(\frac{x}{\varepsilon}, \omega\right) Du^\varepsilon \otimes D_y A\left(\frac{x}{\varepsilon}, \omega\right) Du_\varepsilon Du_\varepsilon = 0 \end{aligned}$$

GENERAL PROBLEM

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PROBABILISTIC SETTING

(Ω, \mathcal{F}, P) probability space

- $f : \mathbb{R}^N \times \Omega \rightarrow \mathbb{R}$ stationary iff $P(\{\omega : f(x, \omega) > \alpha\})$ independent of x

$\tau_x : \Omega \rightarrow \Omega$ measure preserving group

$$f : \mathbb{R}^N \times \Omega \rightarrow \mathbb{R} \text{ stationary} \quad \text{iff} \quad f(x + y, \omega) = f(x, \tau_y \omega)$$

$$f(x, \omega) = f(0, \tau_x \omega) = \tilde{f}(\tau_x \omega) \quad \tilde{f} : \Omega \rightarrow \mathbb{R}$$

- τ_x ergodic iff $\tau_x A = A$ for all $x \in \mathbb{R}^N \Rightarrow P(A) = 0$ or 1

τ_x ergodic \implies all translation invariant quantities are non-random

EXAMPLES

- periodic functions

$\tilde{f} : \mathbb{R} \rightarrow \mathbb{R}$ 1-periodic; $\Omega \equiv S^1$, $\mathcal{F} \equiv$ Borel sets, $P \equiv$ Lebesgue measure, $\tau_x \omega = x + \omega \bmod 1$

$$f(x, \omega) = \tilde{f}(x + \omega) \quad \text{stationary}$$

- quasi-periodic functions

$\Omega \equiv$ torus T^N , $\mathcal{F} \equiv$ Borel sets, $P \equiv$ Lebesgue measure

$\tilde{f}(x) = F(\alpha_1 x, \dots, \alpha_N x)$; $F : \mathbb{R}^N \rightarrow \mathbb{R}$ T^N -periodic, $\alpha_1, \dots, \alpha_N$ rationally independent

$$f(x, \omega) = F(\alpha_1 x + \omega_1, \dots, \alpha_N x + \omega_N) \quad \text{stationary}$$

- almost periodic functions

Ω compact subset of $C(\mathbb{R}^N)$ wrt $\| \cdot \|_\infty$ -topology, P normalized Haar measure

- regular random chessboard structure

(Ω, \mathcal{F}, P) probability space

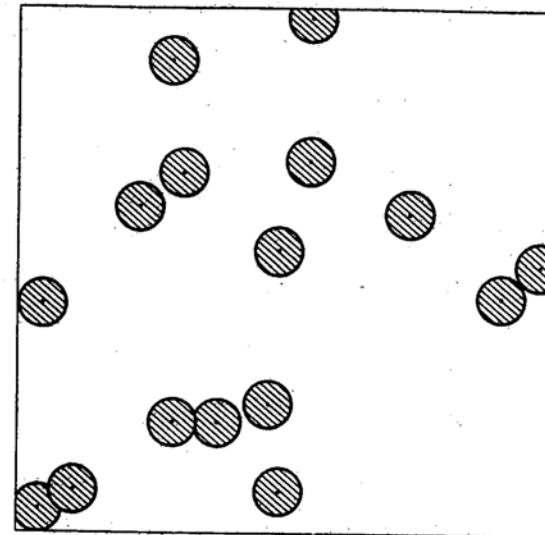
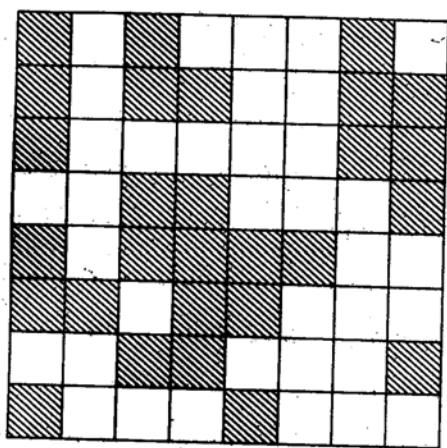
$(X_k)_{k \in \mathbb{Z}^N}$ independent rv taking values λ and $\Lambda > 0$ with prob r and $1 - r$

$Q_k = \{x \in \mathbb{R}^N : k_i \leq x_i \leq k_i + 1, i = 1, \dots, N\}$ cube in \mathbb{R}^N

$$V(x, \omega) = \sum_{k \in \mathbb{Z}^N} X_k(\omega) \mathbf{1}_{Q_k}(x) \quad \text{stationary}$$

cubic lattice with cells occupied by two different materials with densities λ and Λ chosen independently by Bernoulli's law

λ	λ	Λ	Λ
λ	λ	Λ	Λ
λ	λ	λ	λ



- material with random spherical inclusions

X_A Poisson process counting process for a uniform random distribution of points

$$V(x, \omega) = c_1 + (c_2 - c_1) \min\{1, X_{B(x,r)}(\omega)\}$$

$V \equiv c_2$ in union of balls of radius r associated to (X_A) and c_1 elsewhere

\mathcal{B}_N bdd Borel subsets of \mathbb{R}^N

$(X_A)_{A \in \mathcal{B}_N}$ Poisson process with parameter λ : family of rv on (Ω, \mathcal{F}, P)

with nonnegative integer values such that

- (a) $X_{A \cup B}(\omega) = X_A(\omega) + X_B(\omega)$, if $A \cap B = \emptyset$
- (b) (A_k) finite, disjoint family $\implies X_{A_k}$ are independent
- (c) $P(X_A = m) = e^{-\lambda|A|} \frac{\lambda^m |A|^m}{m!}$

- random chessboard structures with cells of arbitrary size

$$N = 2$$

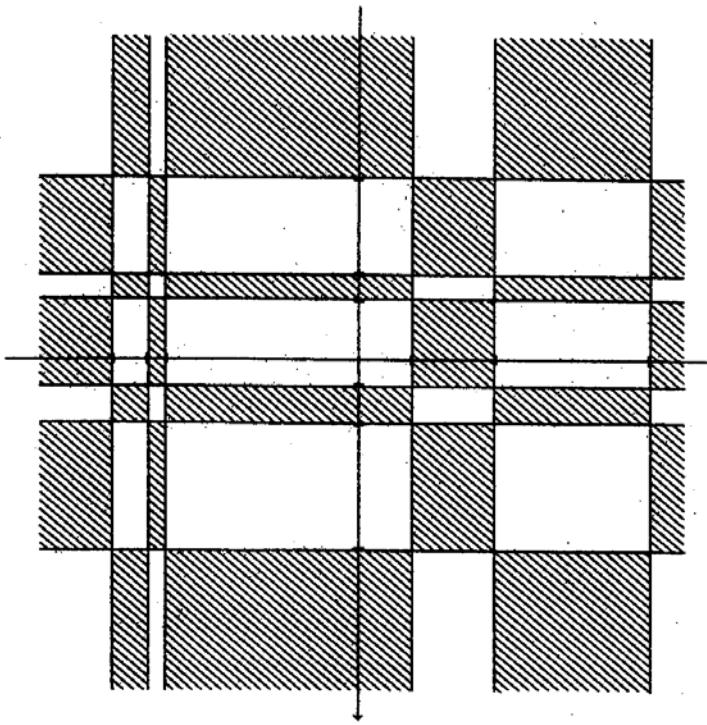
X_A, Y_A independent one-dimensional Poisson processes

V rv independent of X_A and Y_A taking the values c_1, c_2 with prob. $1/2$

$$A(t) = \begin{cases} [0, t) & t > 0 \\ [t, 0) & t < 0 \\ \emptyset & t = 0 \end{cases}$$

$$V(x, \omega) = \begin{cases} V(\omega) & \text{if } X_{A(x_1)}(\omega) + Y_{A(x_2)}(\omega) \text{ is even} \\ c_1 + c_2 - V(\omega) & \text{if } X_{A(x_1)}(\omega) + Y_{A(x_2)}(\omega) \text{ is odd} \end{cases}$$

For fixed $\omega \in \Omega$, $V(x, \omega)$ is constant on each cell of the chessboard with alternated values c_1 and c_2 (the value at the origin is given by $V(\omega)$)



Review (formal) of linear homogenization for uniformly elliptic equations

- nondivergence form

$$-a_{ij}\left(\frac{x}{\varepsilon}\right)u_{x_i x_j}^\varepsilon = f\left(x, \frac{x}{\varepsilon}\right) \quad a_{ij} \text{ uniformly elliptic}$$

- formal expansion

$$u^\varepsilon(x) = u(x) + \varepsilon w\left(x, \frac{x}{\varepsilon}\right) + \varepsilon^2 v\left(x, \frac{x}{\varepsilon}\right) + h.o.t. \quad (y = x/\varepsilon)$$

$$Du^\varepsilon = Du + D_y w + \varepsilon D_x w + \varepsilon D_y v + \varepsilon^2 D_x v + h.o.t.$$

$$D^2 u^\varepsilon = \mathcal{D}^2 u + \frac{1}{\varepsilon} \mathcal{D}_y^2 w + 2 \mathcal{D}_{x,y}^2 w + \varepsilon D_x^2 w + \mathcal{D}_y^2 v + \varepsilon D_{x,y}^2 v + \varepsilon^2 D_x^2 v + h.o.t.$$

- substitute in equation

$$\varepsilon^{-1} \quad a_{ij} w_{y_i y_j} = 0 \quad \stackrel{\text{ellipticity}}{\implies} \quad w(y, x) \equiv w(x) \quad (\equiv 0)$$

$$\varepsilon^0 \quad -a_{ij}(u_{x_i x_j} + v_{y_i y_j}) = f(x, y)$$

$$Lv = -a_{ij}(y)v_{y_i y_j} = f(x, y) + a_{ij}(y)u_{x_i x_j}$$

- $m > 0$ st $L^*m = -(a_{ij}m)_{y_i y_j} = 0$ (invariant measure)

Fredholm's alternative \implies

$$Lv = f(x, y) + a_{ij}u_{x_i x_j} \text{ has a solution} \quad (\text{corrector})$$

iff

$$f(x, \cdot) + a_{ij}(\cdot)u_{x_i x_j} \perp m$$

$$-\bar{a}_{ij}u_{x_i x_j} = \bar{f}$$

$$\bar{a}_{ij} = -\left(\int a_{ij}(y)m(y)dy \right) \quad \text{and} \quad \bar{f} = \int f(x, y)m(y)dy$$

- divergence form

$$L^\varepsilon u^\varepsilon = -\partial_{x_i} \left(a_{ij} \left(\frac{x}{\varepsilon} \right) \partial_{x_j} u^\varepsilon \right) = f \left(x, \frac{x}{\varepsilon} \right) \quad a_{ij} \text{ uniformly elliptic}$$

- notation $\Phi(x) = \phi \left(x, \frac{x}{\varepsilon} \right)$ $\partial_{x_i} \Phi = \partial_{x_i} \phi + \frac{1}{\varepsilon} \partial_{y_i} \phi$

$$L^\varepsilon \Phi = - \left(\partial_{x_i} + \frac{1}{\varepsilon} \partial_{y_i} \right) \left(a_{ij} \left(\partial_{x_j} + \frac{1}{\varepsilon} \partial_{y_j} \right) \phi \right) = (\varepsilon^{-2} L_1 + \varepsilon^{-1} L_1 + \varepsilon^0 L_0) \phi$$

$$L_1 = -\partial_{y_i} (a_{ij}(y) \partial_{y_j})$$

$$L_2 = -\partial_{y_i} (a_{ij}(y) \partial_{x_j}) - \partial_{x_i} (a_{ij}(y) \partial_{y_j})$$

$$L_3 = -\partial_{x_i} (a_{ij}(y) \partial_{x_j})$$

- formal expansion

$$u^\varepsilon(x) = u \left(x, \frac{x}{\varepsilon} \right) + \varepsilon w \left(x, \frac{x}{\varepsilon} \right) + \varepsilon^2 v \left(x, \frac{x}{\varepsilon} \right) + h.o.t.$$

$$L_1 u = 0$$

- $L^\varepsilon u^\varepsilon = 0 \implies L_1 w + L_2 u = 0$

$$L_1 v + L_2 w + L_3 u = f$$

- $L_1 u = 0 \quad \xrightarrow{\text{ellipticity}} \quad u(x, y) \equiv u(x)$
- $L_1 w + L_2 u = 0 \quad \implies \quad L_1 w = \partial_{y_i} a_{ij}(y) \partial_{x_j} u$
 $w(x, y) = -X(y) \cdot Du(x)$
 $L_1 X^i = -\partial_{y_i} a_{ij}$
 Fredholm's alternative $\implies \exists \quad X$
- $L_1 v + L_2 w + L_3 u = f \quad \implies \quad L_1 v = f - L_2 w + L_3 u$
 Fredholm's alternative $\implies v \text{ exists iff rhs } \perp 1$

$$\int (L_2 w + L_3 u) dy = \int f dy$$

$$\int L_2 w = - \int \partial_{y_i} (a_{ij}(y) \partial_{x_j} w) + \partial_{x_i} (a_{ij}(y) \partial_{y_j} w) = -\partial_{x_j} \int a_{ij} \partial_{y_j} w$$

$$= \dots = \partial_{x_i} \left[\left(\int a_{ij} \partial_{y_j} X^i \right) \partial_{x_j} u \right] \quad \implies$$

$$-\bar{a}_{ij} u_{x_i x_j} = \bar{f}$$

$$\bar{a}_{ij} = \int (a_{ij} - a_{ik} \partial_{y_k} X^j) dy \quad \text{and} \quad \bar{f} = \int f(x, y) dy$$

$$H(Du_\varepsilon, \frac{x}{\varepsilon}, \omega) = 0$$

formal expansion

$$u_\varepsilon(x) = \bar{u}(x) + \varepsilon \underbrace{v(\frac{x}{\varepsilon}, \omega)}_{\text{corrector}} + O(\varepsilon^2)$$

$$H(D\bar{u} + D_y v, \frac{x}{\varepsilon}, \omega) = 0$$

macroscopic (cell) problem (nonlinear eigenvalue)

$$\left\{ \begin{array}{l} \text{for each } p \quad \exists! \bar{H}(p) \text{ such that} \\ \qquad H(Dv + p, y, \omega) = \bar{H}(p) \text{ in } \mathbb{R}^N \\ \text{has a solution (corrector) } v \text{ satisfying} \\ \qquad |y|^{-1}v(y, \omega) \rightarrow 0 \text{ as } |y| \rightarrow \infty \text{ a.s. in } \omega \end{array} \right.$$

why the decay?

- expansion
- uniqueness of \bar{H}

$$H(q, y, \omega) = H(q)$$

macroscopic problem

$$H(Dv + p) = \bar{H}(p)$$

$$v = q \cdot y$$

$$\bar{H}(p) = H(q + p) \text{ not unique !}$$

proof of homogenization when correctors exist

$$u_\varepsilon + H(Du_\varepsilon, \frac{x}{\varepsilon}) = 0 \quad \text{in } \mathbb{R}^N$$

- assume $u_\varepsilon \rightarrow \bar{u}$ in $C(\mathbb{R}^N)$
- need to show $\begin{cases} \text{if } \phi \text{ smooth and } x_0 \text{ local max of } u - \phi, \text{ then} \\ \bar{u}(x_0) + \bar{H}(D\phi(x_0)) \leq 0 \end{cases}$
- ψ corrector for $p = D\phi(x_0)$

$$H(D\phi(x_0) + D\psi, y) = \bar{H}(D\phi(x_0))$$

- $u_\varepsilon - (\phi + \underbrace{\varepsilon \psi(\frac{x}{\varepsilon})}_{\longrightarrow 0 \text{ as } \varepsilon \rightarrow 0})$ attains a max at x_ε and $x_\varepsilon \rightarrow x_0$

$$\begin{aligned} & u_\varepsilon(x_\varepsilon) + \underbrace{H(D\phi(x_\varepsilon) + D\psi(\frac{x_\varepsilon}{\varepsilon}), \frac{x_\varepsilon}{\varepsilon})}_{= \bar{H}(D\phi(x_0)) + o(1)} \leq 0 \\ & \vdots \end{aligned}$$

“proof of existence of correctors”

$$H(Dv + p, y, \omega) = \bar{H}(p)$$

H coercive

$$H(q, y, \omega) \rightarrow +\infty \quad \text{as} \quad |q| \rightarrow \infty$$

H bounded for fixed q

$$\sup_y H(q, y, \omega) < \infty$$

- **approximate** $\alpha v_\alpha + H(Dv_\alpha + p, y, \omega) = 0 \quad \text{in } \mathbb{R}^N$
- **estimate** $\sup_{\alpha > 0} (\|\alpha v_\alpha\|_\infty + \|Dv_\alpha\|_\infty) < \infty$
- **normalize** $\hat{v}_\alpha(y) = v_\alpha(y) - v_\alpha(0) ; \quad \| |y|^{-1} \hat{v}_\alpha(y) \| + \| D\hat{v}_\alpha \| \leq C$
 $\alpha \hat{v}_\alpha + H(D\hat{v}_\alpha + p, y, \omega) = -\alpha v_\alpha(0)$
- **pass to the limit**
 $\alpha \rightarrow 0$ $\alpha_n \rightarrow 0 , \quad \hat{v}_{\alpha_n} \rightarrow \hat{v}$
 $H(D\hat{v} + p, y) = \lim_{\alpha_n \rightarrow 0} (-\alpha_n v_{\alpha_n}(0))$

Difficulties

- measurability
- growth of \hat{v} at infinity

CANNOT BE RESOLVED USING EXISTING ESTIMATES

NO CORRECTORS

$$|v'| = f(x, \omega) + \bar{H}(0)$$

$$\inf_y f(y, \omega) = 0 \implies \bar{H}(0) = 0$$

$$|v'| = \underbrace{2 - \cos(2\pi x + \omega_1) - \cos(2\pi \alpha x + \omega_2)}_{f(x, \omega)} \quad \begin{cases} (\omega_1, \omega_2) \in [0, 1] \times [0, 1] \\ \alpha \text{ irrational} \end{cases}$$

$$f(x, \omega) > 0 \text{ a.s. in } \omega = (\omega_1, \omega_2)$$

$$\begin{aligned} |w'| = F(x) \\ F > 0 \text{ for } |x| \gg 1 \end{aligned} \implies w(x) = \pm \int_{\bar{x}}^x F(y) dy$$

$$\begin{aligned} v(x, \omega) &= 2|x| - \frac{\sin(2\pi x + \omega_1)}{2\pi} - \frac{\sin(2\pi \alpha x + \omega_2)}{2\pi \alpha} \quad (|x| \gg 1) \\ \implies \frac{v(x, \omega)}{|x|} &\rightarrow 2 \text{ as } |x| \rightarrow \infty \text{ a.s. in } \omega = (\omega_1, \omega_2) \end{aligned}$$

Lions-Souganidis (2003)

MAIN TOOL

(sub-additive) ergodic theorem identifies
uniquely a.s. a (limiting) quantity controlling the behavior of u_ε as $\varepsilon \rightarrow 0$

SUB-ADDITIONAL ERGODIC THEOREM

(Ω, \mathcal{F}, P) probability space, $\mu : \mathcal{P} \times \mathbb{R} \rightarrow \mathbb{R}$ such that

- $0 \leq \mu(A, \omega) \leq c|A|$
- sub-additive $A = \cup A_k$, A_k mutually disjoint $\implies \mu(A, \omega) \leq \sum \mu(A_k, \omega)$
- stationary $\mu(z + A, \omega)$ same distribution as $\mu(A, \omega)$

$$\implies \frac{\mu(tQ, \omega)}{|tQ|} \xrightarrow{t \rightarrow \infty} \bar{\mu}(\omega) \text{ a.s.} \quad (Q \text{ "nice" subset of } \mathbb{R}^N)$$

$$\text{ergodicity} \implies \bar{\mu}(\omega) = \bar{\mu} \text{ a.s.}$$

HAMILTON-JACOBI EQUATIONS

$$\begin{cases} H(Du_\varepsilon, u_\varepsilon, x, \frac{x}{\varepsilon}, \omega) = 0 \text{ in } U \\ u_\varepsilon = g \text{ on } \partial U \end{cases} \quad \begin{matrix} u_\varepsilon(\cdot, \omega) \rightarrow \bar{u} \\ \text{in } C(\bar{U}) \text{ a.s. in } \omega \end{matrix} \quad \begin{cases} \bar{H}(D\bar{u}, \bar{u}, x) = 0 \text{ in } U \\ \bar{u} = g \text{ on } \partial U \end{cases}$$

$H(p, r, x, y, \omega)$ coercive, convex wrt p
 stationary ergodic wrt (y, ω)

- $\bar{H}(p, r, x) = \inf_{\Phi \in S} \sup_{y \in \mathbb{R}^N} H(p + D\Phi, r, x, y, \omega)$ (\bar{H} independent of ω)

$$S = \{\Phi : \mathbb{R}^N \times \Omega \rightarrow \mathbb{R} : \text{ Lip, } D\Phi \text{ stationary, } E(D\Phi) = 0\}$$

ergodic thm \implies if $\Phi \in S$, then $|y|^{-1}\Phi(y, \omega) \xrightarrow{|y| \rightarrow \infty} 0$ a.s. in ω

- $\bar{H}^*(q, r, x) = \lim_{t \rightarrow \infty} \frac{1}{t} \inf \left[\int_0^t H^*(-\dot{\gamma}(s), r, x, \gamma(s), \omega) ds : \gamma(0) = 0, \gamma(t) = tq \right]$
- no correctors (in general)

- H not convex OPEN

Souganidis (1999)

Rezankhanlou-Tarver (2000)

Lions-Souganidis (2003)

Schwab (2006) (time dependent)

VISCOUS HAMILTON-JACOBI (BELLMAN) EQUATIONS

$$\begin{cases} -\varepsilon \operatorname{tr} A(x, \frac{x}{\varepsilon}, \omega) D^2 u_\varepsilon + H(Du_\varepsilon, u_\varepsilon, x, \frac{x}{\varepsilon}, \omega) = 0 \text{ in } U \\ u_\varepsilon = g \text{ on } \partial U \end{cases} \quad \begin{cases} \bar{H}(D\bar{u}, \bar{u}, x) = 0 \text{ in } U \\ \bar{u} = g \text{ on } \partial U \end{cases}$$

$$u_\varepsilon(\cdot, \omega) \xrightarrow[\varepsilon \rightarrow 0]{} \bar{u} \quad \text{in } C(\bar{U}) \text{ a.s. in } \omega$$

$A(x, y, \omega)$ degenerate elliptic, stationary ergodic

$H(p, r, x, y, \omega)$ coercive, convex in p , stationary ergodic

- $\bar{H}(p, r, x) = \inf_{\Phi \in S} \sup_{y \in \mathbb{R}^N} [-\operatorname{tr} A(x, y, \omega) D^2 \Phi + H(p + D\Phi, r, x, y, \omega)]$ (independent of ω)

- $\bar{H}(p, r, x) = \sup_{(b, \Phi) \in \mathcal{E}} E[(\theta \cdot b(\omega) - H^*(b(\omega), x, \omega)) \Phi(\omega)]$ ($A = I$)

$$\mathcal{E} = \{(b, \Phi) : \operatorname{div}(b\Phi) = \Delta\Phi\}$$

- $\bar{H}^*(p, r, x) = \lim_{t \rightarrow \infty} \frac{1}{t} \inf E \left\{ \int_0^t H^*(\alpha(s), r, x, \gamma(s), \omega) ds : \gamma(\cdot) \in \mathcal{B}(0, t, 0, tp, \alpha) \right\}$

$\mathcal{B}(a, b, x, y, \alpha) \equiv$ “Brownian bridges” in (a, b) with drift α connecting x and y

- no correctors (in general)

- H not convex

Lions-Souganidis (2004)

A depending on p

OPEN

Kosygina-Rezankhanlou-Varadhan (2005)

Kosygina-Varadhan (2006) (time dependent, uniformly elliptic)

SKETCH OF PROOF # 1 (A deg. elliptic)

$\exists ! \ L^\varepsilon(y, \hat{y}, s, \sigma, \omega)$ st

- $$\begin{cases} L_\sigma^\varepsilon - \varepsilon \operatorname{tr} A(\varepsilon^{-1}y, \omega) D^2 L^\varepsilon + H(DL^\varepsilon, \varepsilon^{-1}y, \omega) = 0 & \text{in } \mathbb{R}^N \times (s, t) \\ L^\varepsilon(y, \hat{y}, s, s, \omega) = \begin{cases} \infty & \text{if } y \neq \hat{y} \\ 0 & \text{if } y = \hat{y} \end{cases} \end{cases}$$

• L^ε loc Lip in y, \hat{y} , Hölder in σ for $y - \hat{y}$ bdd, $L^\varepsilon(y, \hat{y}, s, \sigma, \omega) = L^\varepsilon(0, \hat{y} - y, s, \sigma, \tau_y \omega)$

uniqueness / comparison \implies

$$L^\varepsilon(y, \hat{y}, s, t, \omega) \leqq L^\varepsilon(y, z, s, \sigma, \omega) + L^\varepsilon(z, \hat{y}, \sigma, t, \omega) \quad (s < \sigma < t)$$

subadditive ergodic thm \implies

$$L^\varepsilon(y, \hat{y}, 0, t, \omega) \xrightarrow[\varepsilon \rightarrow 0]{} t\bar{L}\left(\frac{y - \hat{y}}{t}\right) \quad \text{a.s. in } \omega \quad \text{for all } y, \hat{y} \in \mathbb{R}^N \text{ with } \bar{L} \text{ convex}$$

$$u_\varepsilon(x, t, \omega) \approx \inf[g(y) + L^\varepsilon(x, y, 0, t, \omega)] \xrightarrow[\varepsilon \rightarrow 0]{} \bar{u}(x, t) = \inf[g(y) + t\bar{L}\left(\frac{x - y}{t}\right)]$$

\uparrow
needs uniform estimates

$$\begin{cases} \bar{u}_t + \bar{H}(D\bar{u}) = 0 \\ \bar{u} = g \text{ on } \mathbb{R}^N \times \{0\} \end{cases} \quad (\bar{H} = (\bar{L})^*)$$

- $A \equiv 0$

$$L^\varepsilon(y, \hat{y}, s, t, \omega) = \inf \left\{ \int_s^t H^* \left(-\dot{\gamma}(s), r, x, \frac{\gamma(s)}{\varepsilon}, \omega \right) ds : \gamma(s) = y, \gamma(t) = \hat{y} \right\}$$

- A nondegenerate, $H(p, r, x, y, \omega) = O(|p|^k)$ with $k > 2$

$$L^\varepsilon(y, \hat{y}, s, t, \omega) = \inf E \left\{ \int_s^t H^* \left(\alpha(s), r, x, \frac{\gamma(s)}{\varepsilon}, \omega \right) ds : \gamma(\cdot) \in \mathcal{B}(s, t, y, \hat{y}, \alpha) \right\}$$

- homogenization \implies formula

- formula
$$u^\varepsilon - \Delta u^\varepsilon + H\left(Du^\varepsilon, \frac{x}{\varepsilon}, \omega\right) = 0 \text{ in } \mathbb{R}^N$$
- homogenization $\implies \begin{cases} u^\varepsilon \rightarrow \bar{u} \\ \bar{u} + \bar{H}(D\bar{u}) = 0 \text{ in } \mathbb{R}^N \end{cases} \implies \bar{u} = -\bar{H}(0)$
- viscosity proof $\implies \bar{u} + \hat{H}(D\bar{u}) \geq 0 \text{ in } \mathbb{R}^N \implies -\bar{H}(0) = \bar{u} \geq -\hat{H}(0)$

$$(\hat{H}(p) = \inf_{\phi \in S} \sup_y [-\Delta \phi + H(D\phi + p, y, \omega)])$$
- choose ϕ st
$$-\Delta \Phi + H(D\Phi, y, \omega) \leqq \bar{H}(0)$$

$$\begin{cases} u_t - \Delta u + H(Du, y, \omega) = 0 \text{ in } \mathbb{R}^N \times (0, \infty) \\ u = \phi \text{ on } \mathbb{R}^N \times (0, \infty) \end{cases}$$
- comparison $\implies u(y, t) \geqq \phi(y) - \hat{H}(0)t$

$$\implies -\bar{H}(0) \geqq -\hat{H}(0)$$

homogenization $\implies \frac{u(0, t)}{t} \rightarrow -\bar{H}(0)$

- estimate

$$\begin{cases} u_t^\varepsilon - \varepsilon \Delta u^\varepsilon + H\left(Du^\varepsilon, \frac{x}{\varepsilon}\right) = 0 \text{ in } \mathbb{R}^N \times (0, \infty) \\ u^\varepsilon = u_0 \text{ on } \mathbb{R}^N \times \{0\} \end{cases}$$

$$u_0 \in \text{Lip} \quad \implies \quad |u_t^\varepsilon| \leqq C_0$$

$$w = |Du^\varepsilon|^2$$

$$w_t - \varepsilon \Delta w + 2\varepsilon |D^2u|^2 + D_p H \cdot Dw + \frac{2}{\varepsilon} D_y H \cdot Du^\varepsilon = 0$$

at interior max

$$|D^2u|^2 + \frac{1}{\varepsilon} D_y H \cdot Du^\varepsilon \leqq 0$$

$$\text{eqn} \quad \implies \quad H - C_0 \leqq \varepsilon \Delta u \quad \implies \quad \varepsilon^2 (\Delta u)^2 \geqq (H - C_0)_+^2$$

$$(\Delta u)^2 \leqq |D^2u|^2 \quad \implies \quad (H - C_0)_+^2 \leqq \|D_y H\| |Du|$$

$$H(p, y) \geqq C_1 |p|^{1/2} - C_2, \quad C_1 > \|D_y H\|$$

- no correctors

$$\begin{cases} -\Delta u + |Du|^2 = V(y, \omega) + \bar{H}(0) \\ |y|^{-1}u(y, \omega) \rightarrow 0 \text{ as } |y| \rightarrow \infty \end{cases}$$

V potential of the Russian School

(Carmona-Lacrois)

$$V(y, \omega) = F(W_y) \quad \begin{cases} F \in C^\infty(\mathbb{T}), \inf F(y) = 0, \sup F(y) = 1, \text{ nondegenerate} \\ (Y_t)_{t \in \mathbb{R}} \text{ Brownian motion on torus } \mathbb{T} \end{cases}$$

$$L = -\Delta + V \quad \sigma(L) = [0, \infty)$$

$$\begin{aligned} w &= e^{-u} \\ -\Delta w + Vw &= -\bar{H}(0)w \end{aligned} \qquad \implies \qquad \bar{H}(0) = 0$$

if corrector exists, it is an eigenvector

but  no eigenvector for 0

SKETCH OF PROOF #2 (*A uniformly elliptic*)

$$u^\varepsilon - \varepsilon \Delta u^\varepsilon + H\left(Du^\varepsilon, \frac{x}{\varepsilon}, \omega\right) = 0 \quad \text{in } \mathbb{R}^N$$

recall

$$H(p, y, \omega) = \sup[p \cdot q - H^*(q, y, \omega)]$$

$$u^\varepsilon \rightarrow \bar{u} \quad \text{as } \varepsilon \rightarrow 0$$

assume

- $\mathcal{E} = \{(b, \Phi : b \text{ bdd, } \Phi \geqq 0, E\Phi = 1, \Delta\Phi = \operatorname{div}(b\Phi)\} \quad \bar{H}_2(p) = \sup_{(b, \Phi) \in \mathcal{E}} E[(p \cdot b - H^*(b, 0, \omega))\Phi] = 0$

Fix $(b, \Phi) \in \mathcal{E}$, write $\tilde{b}(x, \omega) = b(\tau_x \omega)$, $\tilde{\Phi}(x, \omega) = \Phi(\tau_x \omega)$

$$u^\varepsilon - \varepsilon \Delta u^\varepsilon + \tilde{b}\left(\frac{x}{\varepsilon}, \omega\right) \cdot Du^\varepsilon - H^*\left(\tilde{b}\left(\frac{x}{\varepsilon}, \omega\right), \frac{x}{\varepsilon}, \omega\right) \leq 0$$

$$\Phi \geqq 0 \implies u^\varepsilon - \varepsilon \Delta u^\varepsilon + \tilde{b}\left(\frac{x}{\varepsilon}, \omega\right) \cdot Du^\varepsilon - H^*\left(\tilde{b}\left(\frac{x}{\varepsilon}, \omega\right), \frac{x}{\varepsilon}, \omega\right) \tilde{\Phi}\left(\frac{x}{\varepsilon}, \omega\right) \leqq 0$$

$$E\left[\left(u^\varepsilon - \varepsilon \Delta u^\varepsilon + \tilde{b}\left(\frac{x}{\varepsilon}, \omega\right) \cdot Du^\varepsilon - H^*\left(\tilde{b}\left(\frac{x}{\varepsilon}, \omega\right), \frac{x}{\varepsilon}, \omega\right)\right) \tilde{\Phi}\left(\frac{x}{\varepsilon}, \omega\right)\right] \leqq 0$$

$$E\left[u^\varepsilon \tilde{\Phi} + \frac{1}{\varepsilon}(-\Delta \tilde{\Phi} + \operatorname{div}(\tilde{b}\tilde{\Phi}))u^\varepsilon - H^*\left(\tilde{b}\left(\frac{x}{\varepsilon}, \omega\right), \frac{x}{\varepsilon}, \omega\right) \tilde{\Phi}\right] \leqq 0$$

$$u^\varepsilon \rightarrow \bar{u}$$

$$-\Delta\Phi + \operatorname{div}(b\Phi) = 0 \implies \bar{u} + E[-H^*(b(\omega), 0, \omega)\Phi(\omega)] \leqq 0$$

$E\Phi = 1$, stationarity

$$(b, \Phi) \text{ arbitrary} \implies \bar{u} + \bar{H}_2(0) \leqq 0$$

$$\implies \bar{u} \leqq -\bar{H}_2(0)$$

- $S = \{\psi : D\psi \text{ stationary, } E(D\psi) = 0\}$ $\bar{H}_1(p) = \inf_{\Psi \in S} \sup_y (-\Delta\psi + H(D\psi + p, y, \omega))$

$$\phi \text{ smooth} \quad \bar{u} - \phi \text{ strict min at } x_0$$

choose $\Psi \in S$ st $\bar{H}_1(D\phi(x_0)) = \sup_y (-\Delta\psi + H(D\psi + D\phi(x_0), y, \omega))$

$$\begin{aligned} u^\varepsilon &\rightarrow \bar{u} \\ \psi \in S & \implies u^\varepsilon \left(\phi + \varepsilon \Psi \left(\frac{\cdot}{\varepsilon} \right) \right) \text{ min at } x_0 \text{ and } x_\varepsilon \rightarrow x_0 \end{aligned}$$

$$\underbrace{u^\varepsilon - \Delta\Psi + H \left(D\phi(x_\varepsilon) + \varepsilon \psi \left(\frac{x_\varepsilon}{\varepsilon} \right), \frac{x_\varepsilon}{\varepsilon}, \omega \right)}_{\leq \bar{H}_1(D\phi(x_0)) + o(1)} \geq 0$$

$$u^\varepsilon \rightarrow \bar{u} \implies \bar{u}(x_0) + \bar{H}_1(D\phi(x_0)) \geq 0$$

$$\implies \bar{u} \geq -\bar{H}_1(0)$$

- $\bar{H}_1 = \bar{H}_2$

$$\begin{aligned}
\bar{H}_1(p) &= \sup_{(b,\Phi) \in \mathcal{E}} [E(p \cdot b(\omega) - H^*(b(\omega), \omega))\Phi(\omega)] \\
&= \sup_{(b,\Phi) \in \mathcal{E}} \inf_U E[(p \cdot b(\omega) - H^*(b(\omega), \omega) + A_b U)\Phi(\omega)] \\
&= \sup_{\Phi} \sup_b \inf_U E[p \cdot b(\omega) - H^*(b(\omega), \omega) - A_b U]\Phi(\omega) \\
&\min \max \\
&= \sup_{\Phi} \inf_U \sup_b E([p \cdot b(\omega) - H^*(b(\omega), \omega) + A_b U]\Phi(\omega)) \\
&= \sup_{\Phi} \inf_U \sup_b E[(p + DU) \cdot b(\omega) - H^*(b(\omega), \omega) - \Delta U]\Phi \\
&= \sup_{\Phi} \inf_U E(H(p + DU, \omega) - \Delta U)\Phi
\end{aligned}$$

$\min \max$

$$= \inf_U \sup_{\Phi} E(H(p + DU, \omega) - \Delta U)\Phi$$

duality

$$= \inf_U \text{esssup}_{\omega} (H(p + DU, \omega) - \Delta U)$$

DU stationary

$$A_b U = -\Delta U + b \cdot DU$$

$$\inf_U E[\varphi A_b U] = -\infty$$

unless φ is invariant for A_b
(uniform ellipticity)

CORRECTORS

- periodic setting H coercive, A deg elliptic — **correctors**

$$\exists! \bar{H}(p) \text{ st } -\operatorname{tr} A(Du + p, y) D^2 u + H(Du + p, y) = \bar{H}(p)$$

Papanicolaou-Lions-Varadhan
Evans (unif. elliptic)
Lions-Souganidis (deg elliptic)

- almost periodic setting, H coercive, A deg elliptic — **approximate correctors**

$$\exists! \bar{H}(p) \text{ st } \forall \delta > 0 \ \exists v_\delta^\pm \text{ st}$$

$$-\operatorname{tr} A(Dv_\delta^\pm + p, y) D^2 v_\delta^\pm + H(Dv_\delta^\pm + p, y) \stackrel{\leq}{\geq} \bar{H}(p) \begin{cases} +\delta & \text{Ishii } (A \equiv 0) \\ -\delta & \text{Lions-Souganidis } (A \neq 0) \end{cases}$$

$$\alpha v_\alpha - \operatorname{tr} A(Dv_\alpha + p) D^2 v_\alpha + H(Dv_\alpha + p, y) = 0$$

αv_α converges, as $\alpha \rightarrow 0$, uniformly in \mathbb{R}^N

- random, H coercive, convex, A deg elliptic — **local approximate correctors**

$$\exists! \bar{H}(p) \text{ st } \forall R > 0 \ \exists v_R^\pm : \mathbb{R}^N \times \Omega \rightarrow \mathbb{R} \text{ st}$$

Du_R^\pm stationary with mean 0, $|Dv_R^\pm| \leq K$ and $\forall k \ \exists \varepsilon_R^k \rightarrow 0$, as $R \rightarrow \infty$, st

$$-\operatorname{tr} A(y, \omega) D^2 v_R^- + H(Dv_R^- + p, y, \omega) \leq \bar{H}(p) + \varepsilon_R^k \quad \text{in } B_{kR}$$

$$-\operatorname{tr} A(y, \omega) D^2 v_R^+ + H(Dv_R^+ + p, y, \omega) \geq \bar{H}(p) - \varepsilon_R^k$$

$$\begin{cases} u_t + H(Du, x, \omega) = 0 & \text{in } \mathbb{R}^N \times (0, \infty) \\ u = u_0 & \text{on } \mathbb{R}^N \times \{0\} \end{cases} \quad \begin{array}{l} H \text{ coercive convex, stationary ergodic} \\ S(t) \text{ solution operator} \end{array}$$

Recall

$$S = \{\Phi \in C^{0,1}(\mathbb{R}^N) \text{ a.s. in } \omega, |y|^{-1}\Phi(y, \omega) \rightarrow 0 \text{ a.s. in } \omega\}$$

\exists corrector $v \in S$

iff

for some $\Phi \in S$ st $H(p + D\phi, x) \leq \bar{H}(p)$

$$\sup_{t \geq 0} ((S(t)\Phi)(x) + t\bar{H}) < \infty$$

Lions-Souganidis

Examples

$$(*) \quad \begin{array}{ll} \text{(i)} & f : \mathbb{R}^N \times \Omega \rightarrow \mathbb{R} \text{ stationary,} \\ & \text{(ii)} \quad \inf_x f(x, \omega) = 0, \\ & \text{(iii)} \quad f(x, \omega) > 0 \end{array}$$

- $|Du^\varepsilon| + \varepsilon u^\varepsilon = f(x, \omega) \implies \varepsilon u^\varepsilon \xrightarrow[\varepsilon \rightarrow 0]{} 0$

f satisfies $(*)_{\text{(i)}}$, $(*)_{\text{(ii)}}$

$$K(\omega) = \{x : f(x, \omega) = 0\}$$

$$\text{ergodicity} \implies P(K(\omega) \neq \emptyset) = 0 \text{ or } 1$$

$$K(\omega) = \emptyset \implies \text{no correctors}$$

$$K(\omega) \neq \emptyset \implies u(x) = \inf_{\bar{x} \in K(\omega)} L(x, \bar{x}, \omega) \text{ corrector}$$

$$L(x, y, \omega) = \inf \left\{ \int_0^T f(x(s), \omega) ds : x(0) = x, \ x(T) = y, \ |\dot{x}| \leqq 1, \ T > 0 \right\}$$

- f satisfies $(*)_{(i)}$, $(*)_{(ii)}$ and $N = 1$

$$|u' + P|^2 = f(y, \omega) + \bar{H}(p) \quad \text{in } \mathbb{R}$$

$$\bar{H}(p) = \begin{cases} \inf_y f(y, \omega) & \text{if } |P| \leq E\sqrt{f(y, \omega) - \inf_y f(y, \omega)} \\ \alpha & \text{if } |P| = E\sqrt{(f(x, \omega) - \inf_y f(y, \omega)) + \alpha} \end{cases}$$

- $H(p) = bp_+ - ap_- \quad (0 < a < b)$

$$H(Du + p) = f(x, \omega) + \bar{H}(p)$$

$$\bar{H}(p) \quad \text{unique constant st} \quad E\frac{1}{b}(f + \lambda)_+ = E\frac{1}{a}(f - \lambda)_-$$

$$u_x = \frac{1}{b}(f + \lambda)_+ - \frac{1}{a}(f - \lambda)_-$$

- $H(p_1, p_2) = |p_1 + P_1|^2 + |p_2|^2 - (f_1(x, \omega) + f_2(x_2, \omega))$

$$\begin{aligned} \min f_1(\cdot, \omega) &= 0 \\ \inf f_2(\cdot, \omega) &= 0 \end{aligned} \quad ; \quad \text{and} \quad |P_1| \geq E\sqrt{f_1(x, \omega)} \quad \Rightarrow \quad \text{no corrector}$$

$$\bar{H}(P_1, 0) = \alpha \text{ where } |P_1| = E\sqrt{f_1(x, \omega) + \alpha}$$

general result

f satisfies $(*)_{(i)}$ and $(*)_{(ii)}$

$\varepsilon u^\varepsilon$ converges uniformly in \mathbb{R}^N to 0

iff

$$\sup_{x \in \mathbb{R}^N} \inf_{|y-x| \leq R} f(y, \omega) \rightarrow \infty \quad \text{as } R \rightarrow \infty$$

- true for periodic, almost periodic settings
- not true (in general) in random settings

$\xi(\cdot, \omega) \in C(\mathbb{R})$ stationary ergodic st supp of law of $\inf_{|y| \leq R} \xi(y, \omega)$ unbounded from above

$V \in C^{0,1}(\mathbb{R})$ st $V(-\infty) = 0$, $V(+\infty) = 1$, $V' \geqq 0$

$$f(x, \omega) = V(\xi(x, \omega))$$



$$\text{for all } R > 0 \quad \sup_x \inf_{|y-x| \leq R} f(y, \omega) = 1 \quad \forall R > 0 \quad \text{a.s. in } \omega$$

UNIFORMLY ELLIPTIC SECOND-ORDER PDE

$$\begin{cases} F\left(D^2u_\varepsilon, Du_\varepsilon, u_\varepsilon, x, \frac{x}{\varepsilon}, \omega\right) = 0 \text{ in } U \\ u_\varepsilon = g \text{ on } \partial U \end{cases} \quad u_\varepsilon(\cdot, \omega) \xrightarrow[\varepsilon \rightarrow 0]{} \bar{u}(\cdot) \quad \text{in } C(\bar{U}) \text{ a.s. in } \omega \quad \begin{cases} \bar{F}(D^2\bar{u}, D\bar{u}, \bar{u}, x) = 0 \text{ in } U \\ \bar{u} = g \text{ on } \partial U \end{cases}$$

F uniformly elliptic, stationary ergodic

Caffarelli-Souganidis-Wang

F uniformly elliptic, strongly mixing with power decay

$$\|u_\varepsilon(\cdot, \omega) - \bar{u}(\cdot)\|_\infty = O(\varepsilon^{-\log \varepsilon})$$

Caffarelli-Souganidis

existence of correctors OPEN even in the linear case!

$$F(D^2u_\varepsilon, Du_\varepsilon, \frac{x}{\varepsilon}, \omega) = 0$$

formal expansion

$$u_\varepsilon(x) = \bar{u}(x) + \varepsilon w\left(\frac{x}{\varepsilon}, \omega\right) + \varepsilon^2 v\left(\frac{x}{\varepsilon}, \omega\right) + O(\varepsilon^3)$$

$$F(D_y^2 v + D_x^2 \bar{u}, D_x \bar{u}, \frac{x}{\varepsilon}, \omega) = 0$$

microscopic (cell)
problem
(nonlinear eigenvalue)

$$\left\{ \begin{array}{l} \text{for each } (X, p) \quad \exists! \bar{F}(X, p) \text{ such that} \\ F(D^2 v + X, p, y, \omega) = \bar{F}(X, p) \text{ in } \mathbb{R}^N \\ \text{has a solution (corrector) } v \text{ satisfying} \\ |y|^{-2} v(y, \omega) \rightarrow 0 \text{ as } |y| \rightarrow \infty \text{ a.s. in } \omega \end{array} \right.$$

Why the decay?

- expansion
- uniqueness of \bar{F}

$$F(X, p, y, \omega) = F(X)$$

cell problem

$$F(D^2 v + X) = \bar{F}(X)$$

$$v = \frac{1}{2}(Qx, x) \quad \bar{F}(X) = F(X + Q) \text{ not unique!}$$

$$F(D^2v + X, y, \omega) = \bar{F}(X)$$

F uniformly elliptic

- approximate $\alpha v_\alpha + F(D^2v_\alpha + X, y, \omega) = 0 \text{ in } \mathbb{R}^N$
- estimate $\sup_{\alpha > 0} (\alpha \|v_\alpha\|_\infty + [v_\alpha]_{C_{\text{loc}}^{0,\gamma}}) < \infty$
- normalize $\hat{v}_\alpha(y) = v_\alpha(y) - v_\alpha(0) ; \| |y|^{-\gamma} \hat{v}(y) \|_{L_{\text{loc}}^\infty} \leq C , [\hat{v}_\alpha]_{0,\gamma} \leq C$
 $\alpha \hat{v}_\alpha + F(D_y^2 \hat{v}_\alpha + X, y) = -\alpha v_\alpha(0)$
- pass to the limit $\alpha \rightarrow 0$ $\alpha_n \rightarrow 0 , \hat{v}_{\alpha_n} \rightarrow \hat{v}$
 $F(D^2\hat{v} + X, y) = \lim_{\alpha_n \rightarrow 0} (-\alpha_n v_{\alpha_n}(0))$

Difficulties

- measurability
- growth at infinity for \hat{v}

CANNOT BE RESOLVED USING EXISTING ESTIMATES

D^2v stationary, $E(D^2v) = 0 \Rightarrow |y|^{-2}v(y, \omega) \rightarrow 0$ as $|y| \rightarrow \infty$ a.s. in ω

D^2v_α stationary, $E(D^2v_\alpha) = 0$ but \nexists estimates implying $D^2v_\alpha \rightarrow D^2v$

MOTIVATION OF NEW APPROACH

formal asymptotics

$$F\left(D^2u_\varepsilon, \frac{x}{\varepsilon}, \omega\right) = 0$$

$$u_\varepsilon(x) = \bar{u}(x) + \varepsilon^2 v\left(\frac{x}{\varepsilon}, \omega\right) + O(\varepsilon^3)$$

microscopic problem

$$\begin{cases} F(Q + D_y^2 v, y, \omega) = \bar{F}(X) \\ |y|^{-2} v(y, \omega) \rightarrow 0 \text{ as } |y| \rightarrow \infty \text{ a.s. in } \omega \end{cases}$$

- no need
 - (i) v to be independent of ε as long as $\varepsilon^2 v^\varepsilon\left(\frac{x}{\varepsilon}, \omega\right) \rightarrow 0$
 - (ii) solve cell problem in all of \mathbb{R}^N
- it suffices to find, for each Q , a unique constant $\bar{F}(Q)$ such that

if $v^\varepsilon(\cdot, \omega)$ solves $\begin{cases} F(D_y^2 v^\varepsilon, y, \omega) = \bar{F}(Q) \text{ in } B_{1/\varepsilon} \\ v^\varepsilon = Q \text{ on } \partial B_{1/\varepsilon} \end{cases}$ then $\|\varepsilon^2 v^\varepsilon(\cdot, \omega) - Q\|_{C(\bar{B}_{1/\varepsilon})} \xrightarrow[\varepsilon \rightarrow 0]{} 0$ a.s.

equivalently $(v_\varepsilon(y) = \varepsilon^2 v^\varepsilon\left(\frac{y}{\varepsilon}\right))$

if $v_\varepsilon(\cdot, \omega)$ solves $\begin{cases} F\left(D^2 v_\varepsilon, \frac{y}{\varepsilon}\right) = \bar{F}(Q) \text{ in } B_1 \\ v_\varepsilon = Q \text{ on } \partial B_1 \end{cases}$ then $\|v_\varepsilon - Q\|_{C(\bar{B}_1)} \xrightarrow[\varepsilon \rightarrow 0]{} 0$ a.s.

REVIEW OF KEY FACTS ABOUT UNIFORMLY ELLIPTIC PDE

- linearization

$$\begin{aligned} F(D^2u, x) &= 0 \\ F(D^2v, x) &= 0 \end{aligned} \quad \stackrel{\substack{\implies \\ w=u-v}}{\quad} \quad -a_{ij}(x)w_{x_i x_j} = 0 \quad a_{ij} \text{ bdd meas}$$

- Alexandrov-Bakelman-Pucci (ABP)-estimate

$$-a_{ij}w_{x_i x_j} = f \text{ in } B_1 \implies \sup_{B_1} w^+ \leq \sup_{\partial B_1} w^+ + C \|f^+\|_{L^N} \quad (C \text{ universal})$$

- Fabes-Stroock (FS)-estimate

$$\begin{cases} -a_{ij}w_{x_i x_j} = f \text{ in } B_1 \\ w = 0 \text{ on } \partial B_1 \\ 0 < f < 1 \end{cases} \implies w|_{B_{1/2}} \geq C \|f\|_{L^M} \quad (C, M \text{ universal}, M \text{ large})$$

- obstacle problem

u smallest st

$$\begin{cases} F(D^2u, x) \geq 0 \text{ in } B_1 \\ u \geqq Q \text{ in } B_1 \end{cases} \implies \begin{array}{l} \bullet \quad u = Q \text{ on } \partial B_1 \\ \bullet \quad F(D^2u, x) = 0 \text{ in } \{u > Q\} \\ \bullet \quad 0 \leqq (u - Q)(y) \leq C|x - y|^2 \quad (u(x) = Q(x)) \end{array} \quad (C \text{ universal})$$

$$\min(F(D^2u, x), u - Q) = 0 \text{ in } B_1$$

$$\bullet \quad F(D^2u, x) = \mathbf{1}_{\{u=Q\}}(F(Q, x))^+$$

NEED TO MEASURE “DISTANCE” BETWEEN SOLUTIONS AND QUADRATICS

$$\begin{cases} F(D^2v_\varepsilon, \frac{x}{\varepsilon}) = \ell \text{ in } B_1 \\ v_\varepsilon = Q \text{ on } \partial B_1 \end{cases} \xrightarrow{\text{(ABP)}} \begin{aligned} \|v_\varepsilon - Q\| &\leq C \left\| \left(F(Q, \frac{\cdot}{\varepsilon}) - \ell \right)_+ \right\|_{L^N} \\ &= C \left[\int_{B_{1/\varepsilon}} \left(F(Q, \frac{y}{\varepsilon}) - \ell \right)_+^N dy \right]^{1/N} \\ &\quad \downarrow \varepsilon \rightarrow 0 \end{aligned}$$

$$\begin{cases} F(Q, \frac{x}{\varepsilon}) = \ell + F(Q, \frac{x}{\varepsilon}) - \ell \text{ in } B_1 \\ Q = Q \text{ on } \partial B_1 \end{cases} \xrightarrow{\parallel} C [E(F(Q, \omega) - \ell)_+^N]^{1/N} \\
 O(1)$$

compare with solution of obstacle problem

$$\begin{cases} F(D^2u_\varepsilon, \frac{x}{\varepsilon}) = \ell + (F(Q, \frac{x}{\varepsilon}) - \ell)_+ \mathbf{1}_{\{u_\varepsilon = Q\}} \text{ in } B_1 \\ u_\varepsilon = Q \text{ on } \partial B_1 \end{cases} \xrightarrow{\text{(ABP)}} \|(u_\varepsilon - v_\varepsilon)_+\| \leq C \left\| \mathbf{1}_{\{u_\varepsilon = Q\}} \left(F(Q, \frac{\cdot}{\varepsilon}) - \ell \right)_+ \right\|_{L^N} \leq C |\{u_\varepsilon = Q\}|$$

after rescaling

$$h^\varepsilon(\ell, \omega) = |\{u_\varepsilon = Q\}|$$

satisfies the assumptions of the subadditive ergodic thm (subadditive wrt to domain)

$$h^\varepsilon(\ell, \omega) \xrightarrow[\varepsilon \rightarrow 0]{} h(\ell) \text{ a.s.}$$

measure of contact set is sub-additive



apply ergodic theorem



if measure of contact set is

- asymptotically 0, then v_ε and u_ε stay asymptotically close and above Q
- positive, then the contact set spreads uniformly on B_1 , u_ε converges to Q and v_ε stays asymptotically below Q

SKETCH OF THE PROOF

$$\begin{cases} F\left(D^2v_\varepsilon, \frac{x}{\varepsilon}, \omega\right) = \ell & \text{in } B_1 \\ v_\varepsilon = Q & \text{on } \partial B_1 \end{cases} \quad \begin{cases} \min\left(F\left(D^2u_\varepsilon, \frac{x}{\varepsilon}, \omega\right) - \ell, u_\varepsilon - Q\right) = 0 & \text{in } B_1 \\ u_\varepsilon = Q & \text{on } \partial B_1 \end{cases}$$

- $u_\varepsilon \geqq v_\varepsilon$
- $|\{u_\varepsilon = Q\}|$ subadditive, ergodic

ergodic thm $\implies |\{u_\varepsilon = Q\}| \xrightarrow[\varepsilon \rightarrow 0]{} h(\ell)$ a.s. in ω

- $h(\ell)$ monotone (nonincreasing) in ℓ and $h(\ell) = \begin{cases} 1 & \text{if } \ell \ll -1 \\ 0 & \text{if } \ell \gg 1 \end{cases}$

if $h(\ell) > 0$, then the contact set spreads uniformly in B_1

$$u_\varepsilon - Q = o(1) \quad \text{and} \quad v_\varepsilon - Q \leqq u_\varepsilon - Q = o(1) \quad \text{in } B_1$$

if $h(\ell) = 0$, then u_ε and v_ε stay close and above Q

$$u_\varepsilon - v_\varepsilon = o(1) \quad \text{and} \quad 0 \leqq u_\varepsilon - Q \leqq v_\varepsilon - Q + o(1) \quad \text{in } B_1$$

$$\bar{F}(Q) = \inf\{\ell \in \mathbb{R} : h(\ell) = 0\}$$

BACK TO FRONT PROPAGATION

$$u_t^\varepsilon + H\left(Du^\varepsilon, \frac{x}{\varepsilon}, \omega\right) = 0 \quad H(p, y, \omega) = a(-\hat{p}, y, \omega)|p|$$

- H periodic/almost periodic and coercive ($|a| > 0$) Lions-Papanicolaou-Varadhan; Ishii

⇒ homogenization

- H stationary ergodic, coercive, convex (concave) Souganidis; Rezankhanlou-Tarver

general coercive H

OPEN

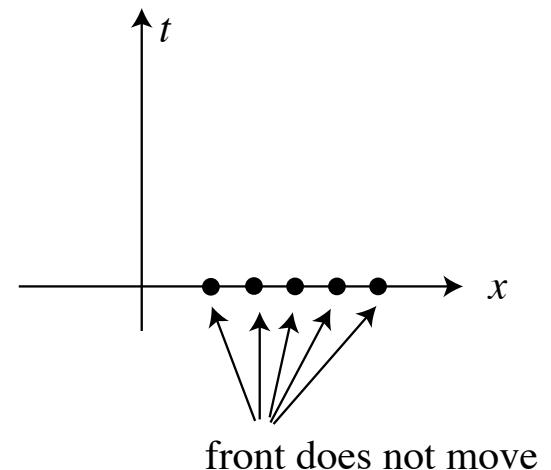
what happens if a vanishes somewhere?

H not coercive?

- trapping

$$\begin{cases} u_t^\varepsilon + \cos\left(\frac{x}{\varepsilon}\right)|u_x^\varepsilon| = 0 & \text{in } \mathbb{R} \times (0, \infty) \\ u^\varepsilon = u_0 & \text{on } \mathbb{R} \times \{0\} \end{cases}$$

$$u^\varepsilon \xrightarrow[\varepsilon \rightarrow 0]{} u_0$$

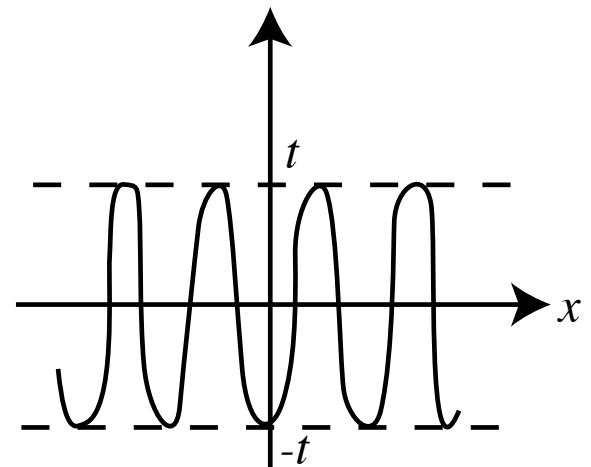


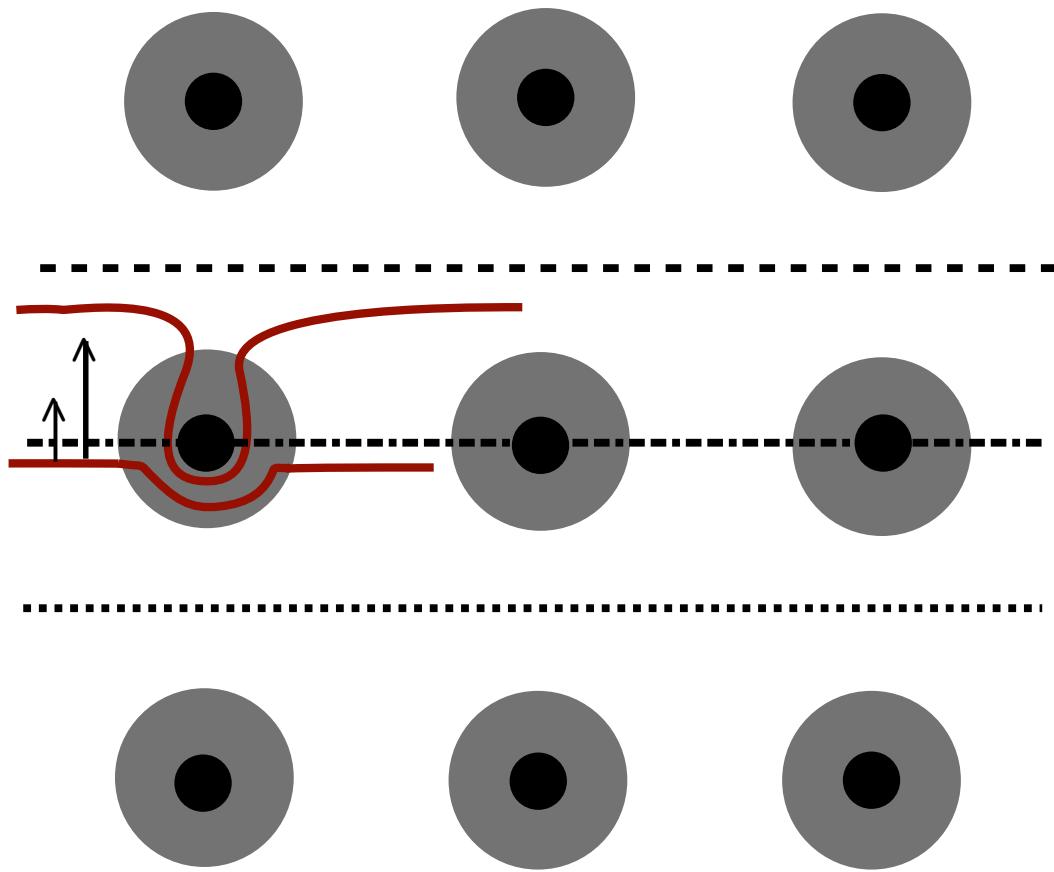
- no homogenization

$$\begin{cases} u_t^\varepsilon + \cos\left(\frac{x}{\varepsilon}\right)|Du^\varepsilon| = 0 & \text{in } \mathbb{R}^2 \times (0, \infty) \\ u^\varepsilon(x, y, 0) = y \end{cases}$$

$$\underline{\lim}_{\varepsilon \rightarrow 0} u^\varepsilon(x, y, t) = y - t$$

$$\overline{\lim}_{\varepsilon \rightarrow 0} u^\varepsilon(x, y, t) = y + t$$





- general result

$$\begin{cases} u_t^\varepsilon + a\left(\frac{x}{\varepsilon}, \omega\right)|Du^\varepsilon| = 0 & \text{in } \mathbb{R}^N \times (0, \infty) \\ u^\varepsilon = u_0 & \text{on } \mathbb{R}^N \times \{0\} \end{cases}$$

$$a(y, \omega) = \tilde{a}(\tau_y \omega) \quad (\text{stationary}) \quad P(\{\tilde{a} \leq 0\}) = \theta$$

then

$$u^\varepsilon \rightharpoonup \theta u_0 + (1 - \theta)\bar{u} \quad \text{in } L^\infty(B_R \times (0, T)) \text{ weak* a.s.}$$

where

$$\begin{cases} \bar{u}_t + \bar{H}(D\bar{u}) = 0 & \text{in } \mathbb{R}^N \times (0, \infty) \\ \bar{u} = u_0 & \text{on } \mathbb{R}^N \times \{0\} \end{cases}$$

$$\bar{H}(p) = \lim_{\delta \downarrow 0} \bar{H}_\delta(p)$$

$$\bar{H}_\delta \quad \text{effective Hamiltonian for } \max(a^+, \delta)$$

Cardaliaguet-Lions-Souganidis

$$V = -\varepsilon \delta \operatorname{div} Dn - a\left(n, \frac{x}{\varepsilon}\right)$$

- periodic / almost periodic

Lions, Souganidis

$$\min(a^2 - \delta(N-1)|D_y a|) > 0 \implies \exists \text{ effective velocity } \bar{v}$$

- stationary ergodic

OPEN

$$u_t^\varepsilon - \varepsilon \delta \operatorname{tr}(I - \widehat{Du}^\varepsilon \otimes \widehat{Du}^\varepsilon) D^2 u^\varepsilon + a\left(\widehat{Du}^\varepsilon, \frac{x}{\varepsilon}\right) |Du^\varepsilon| = 0 \text{ in } \mathbb{R}^N \times (0, \infty)$$

$$u^\varepsilon \longrightarrow \bar{u}$$

$$\bar{u}_t + \bar{v}(\widehat{Du}) |D\bar{u}| = 0 \text{ in } \mathbb{R}^N \times (0, \infty)$$

is condition necessary?

YES for Lip estimates

general v

OPEN

CELL PROBLEM

for each $p \in \mathbb{R}^N$ $\exists!$ \bar{v} st \exists bdd (periodic) solution w of

$$-\mathcal{M}(Dw + p, D^2w) + v(y)|Dw + p| = \bar{v}(\hat{p})|p| \quad \text{in } \mathbb{R}^N$$

$$\mathcal{M}(p, X) = \text{tr}(I - \hat{p} \otimes \hat{p})X$$

- approximate

$$\alpha w^\alpha - \mathcal{M}(Dw^\alpha + p, D^2w^\alpha) + v(y)|Dw^\alpha + p| = 0 \quad \text{in } \mathbb{R}^N$$

- estimate

$$\alpha|w^\alpha| + |Dw^\alpha| \leq C$$

- renormalize

$$\tilde{w}^\alpha(y) = w^\alpha(y) - w^\alpha(0)$$

$$\text{estimates} \quad \implies \quad |\tilde{w}^\alpha| + |D\tilde{w}^\alpha| \leq C$$

- pass to the limit $\alpha \rightarrow 0$

$$\tilde{w}^\alpha \rightarrow w \text{ bdd} \quad \text{and} \quad -\mathcal{M}(Dw + p, D^2w) + v(y)|Dw + p| = \lim_{\alpha \rightarrow 0} (-\alpha w_\alpha(0))$$

$$w \text{ bdd} \quad \implies \quad \text{rhs unique}$$

- $\min(u^2 - \delta_{(N-1)}|D_y v|) > 0$ sharp for Lip estimates

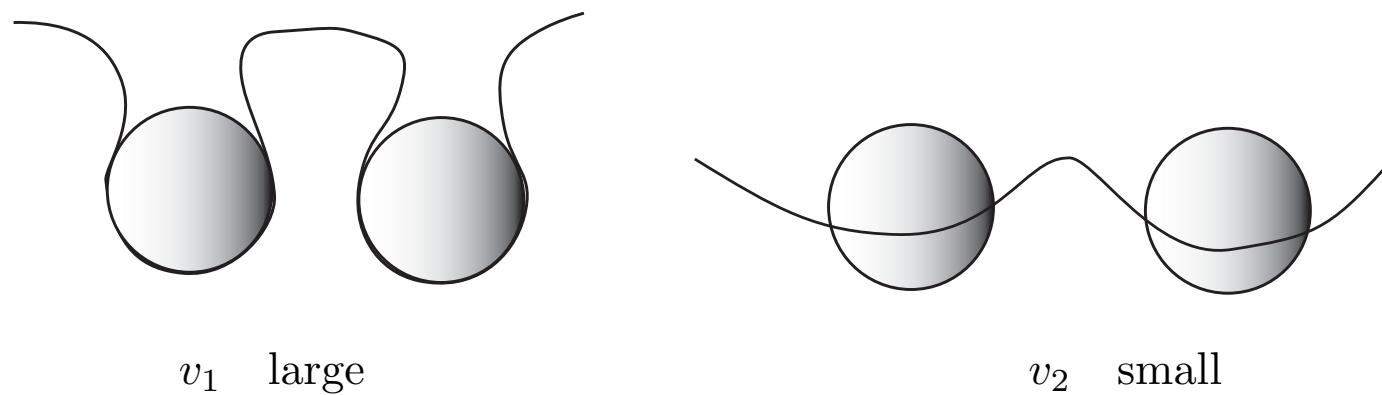
$$v(y) = \begin{cases} \frac{N-1}{\beta'} & |x| \geq \beta' \\ \frac{N-1}{|x|} & \alpha' < |x| < \beta' \quad v^2 = (N-1)|D_y v| \quad \text{in } \alpha' < |x| < \beta' \\ \frac{N-1}{\alpha'} & |x| \leq \alpha' \quad (0 < \alpha' < \alpha < \beta < \beta' < 1) \end{cases}$$

$$w(x) = \left(\frac{1}{|x|} \wedge \beta \right) \vee \alpha \quad \text{solves}$$

$$-\operatorname{tr}(I - \widehat{Dw} \otimes \widehat{Dw}) D^2 w + v(y)|Dw| = 0 \quad \text{in } \mathbb{R}^N$$

\implies no Lip estimates for w_α in general

$$V = v - \kappa$$



$$v(x_1, x_2) = \begin{cases} v_1 & \text{outside} \\ v_2 & \text{inside} \end{cases} \quad -v_2 > v_1 > 0$$

Craciun-Bhattacharya

Special case

$$\begin{cases} u_t^\varepsilon + \left(\theta \sin \left(\frac{x}{2\pi\varepsilon} \right) + \delta \right) |Du^\varepsilon| - \varepsilon \operatorname{tr}(I - \widehat{Du^\varepsilon} \otimes \widehat{Du^\varepsilon}) D^2 u^\varepsilon = 0 & \text{in } \mathbb{R}^2 \times (0, \infty) \\ u^\varepsilon = u_0 & \text{in } \mathbb{R}^2 \times \{0\} \end{cases} \quad (x, y) \in \mathbb{R}^2$$

- trapping $\delta = 0$ and $2\pi\theta < 1 \implies u^\varepsilon \rightarrow u_0$

- homogenization $\theta < 1 \implies u^\varepsilon \rightarrow \bar{u}$

$$\begin{cases} \bar{u}_t + \bar{H}(D\bar{u}) = 0 & \text{in } \mathbb{R}^2 \times (0, \infty) \\ \bar{u} = u_0 & \text{on } \mathbb{R}^2 \times \{0\} \end{cases} \quad \text{and} \quad \delta|p_y| \leq H(p, q) \leq (\theta + \delta)|p_y|$$

- no homogenization $\theta > 2\pi$ and $u_0(x, y) = -y$



$$\overline{\lim} u^\varepsilon(x, y, t) \geq -y + \alpha t$$

$\exists \alpha > 0$ st

$$\underline{\lim} u^\varepsilon(x, y, t) \leq -y - \alpha t$$

Cardaliaguet-Lions-Souganidis

OPEN PROBLEMS

- Hamilton-Jacobi, viscous Hamilton-Jacobi
non convex Hamiltonians, quasilinear equations, nonlinear equations
- uniformly elliptic
existence of correctors
- degenerate elliptic
- free boundary problems in random media
- boundary conditions
Neuman, Dirichlet, perforated domains
- error estimates
- applications
random traveling waves, mean curvature motion, minimal surfaces