

# Application of Optimal Transport to Evolutionary PDEs

## *5 -Applications*

Giuseppe Savaré

<http://www.imati.cnr.it/~savare>

Department of Mathematics, University of Pavia, Italy



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# Outline

- 1 Thin film equation as the gradient flow of the Dirichlet functional
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## Starting point: a family of 4th order equations in $\mathbb{R}^d$

We look for **non-negative** solutions to the nonlinear 4th order evolution PDEs

$$\partial_t \mathbf{u} + \operatorname{div} \left( \mathbf{u} \operatorname{D}(\mathbf{u}^{\alpha-1} \Delta \mathbf{u}^\alpha) \right) = 0 \quad \text{in } (0, +\infty) \times \mathbb{R}^d, \quad \alpha \in [1/2, 1],$$

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$$\partial_t u + \operatorname{div}(\mathbf{m}(u) \mathbf{D}(\Delta u)) = 0, \quad \text{where, e.g. } \mathbf{m}(u) = u^m$$

has been studied (mainly in dimension  $d = 1, 2, 3$ ) by many authors:

[BERNIS-FRIEDMAN '90, BERTSCH-DAL PASSO-GARCKE-GRÜN '98-'04; review: BECKER-GRÜN '05.; asymptotic behaviour: CARRILLO-TOSCANI '02, CARLEN-ULUSOY '07]



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**drift-diffusion** equation has been introduced by

DERRIDA-LEBOWITZ-SPEER-SPOHN '91 [and studied by BLEHER-LEBOWITZ-SPEER '94, JÜNGEL with PINNAU '00 and MATTHES '08]



## Structure of the equation

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The generating functional is

$$\Phi(\mathbf{u}) := \frac{1}{2} \int_{\mathbb{R}^d} |\mathbf{D}\mathbf{u}|^2 \, dx$$



## The “Wasserstein gradient” of the Dirichlet functional

Standard technique: choose a vector field  $\xi \in C_c^\infty(\mathbb{R}^d; \mathbb{R}^d)$  and the flow  $X$

$$\frac{d}{dt} X_t(x) = \xi(X_t(x)), \quad X_0(x) = x; \quad M_\varepsilon := (X_\varepsilon)_\# M; \quad \rightsquigarrow \quad \boxed{\frac{d}{d\varepsilon} \Phi(M_\varepsilon)|_{\varepsilon=0}}$$

Wasserstein gradient  $g = -v$ :  $\int_{\mathbb{R}^d} \langle g, \xi \rangle dM = \frac{d}{d\varepsilon} \Phi(M_\varepsilon)|_{\varepsilon=0}$ .

As usual  $M \leftrightarrow u$ ,  $M_\varepsilon \leftrightarrow u_\varepsilon$ . In view of the continuity equation, we choose directly  $\xi = \nabla \zeta$ :



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It corresponds to the **weak formulation of the thin film equation**

$$\boxed{\partial_t \mathbf{u} + \frac{1}{2} \Delta^2 (\mathbf{u}^2) - \partial_{x_i}^2 (\partial_{x_i} \mathbf{u} \partial_{x_j} \mathbf{u}) - \frac{1}{2} \Delta |D \mathbf{u}|^2 = 0} \quad \Leftrightarrow \quad \partial_t \mathbf{u} + \operatorname{div}(\mathbf{u} D \Delta \mathbf{u}) = 0$$



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**Discrete equation:**  $M_\tau^n \leftrightarrow U_\tau^n$

$$\int_{\mathbb{R}^d} \zeta (U_\tau^n - U_\tau^{n-1}) dx + \frac{\tau}{2} \int_{\mathbb{R}^d} \Delta^2 \zeta (U_\tau^n)^2 - 2D^2 \zeta D U_\tau^n \cdot D U_\tau^n - \Delta \zeta |D U_\tau^n|^2 dx = o(\tau)$$



# Main problem

Discrete equation:

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Strong compactness in  $W^{1,2}$  in order to pass to the limit in the quadratic term

$$\int_{\mathbb{R}^d} 2D^2 \zeta D\mathbf{U}_\tau^n \cdot D\mathbf{U}_\tau^n \, dx$$



## First variation along auxiliary flows

**MAIN IDEA:** take the first variation of the minimum problem

$$U_\tau^n \in \operatorname{argmin}_V \frac{W^2(V, U_\tau^{n-1})}{2\tau} + \Phi(V)$$

along the (Wasserstein) gradient flow  $\mathbf{S}^\Psi$  generated by other “good” auxiliary functionals  $\Psi$ .



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Look for good flows  $\mathbf{S}^\Psi$  having  $\Phi$  as Lyapunov functional



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## A Lyapunov-type estimate at the discrete level in the Wasserstein space

Suppose that  $\Psi$  generates a good flow  $w_t = S_t^\Psi(w)$  satisfying the EVI:

$$\frac{d}{dt} \frac{1}{2} W^2(S_t^\Psi(w), z) \leq \Psi(z) - \Psi(S_t^\Psi(w)) \quad (\text{EVI})$$



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$$\frac{d}{dt} \frac{1}{2} W^2(S_t^\Psi(w), z) \leq \Psi(z) - \Psi(S_t^\Psi(w)) \quad (\text{EVI})$$

We call  $\mathcal{D}$  the dissipation of  $\Phi$  along  $S^\Psi$

$$\mathcal{D}(w) := \boxed{-} \frac{d}{d\varepsilon} \Phi(S_\varepsilon^\Psi(w)) \Big|_{\varepsilon=0^+} = \limsup_{\varepsilon \downarrow 0} \frac{\Phi(w) - \Phi(S_\varepsilon^\Psi(w))}{\varepsilon}$$



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### Theorem (Discrete flow-interchange estimate)

If  $U_\tau^n$  is a minimizer of  $V \mapsto \frac{W^2(V, U_\tau^{n-1})}{2\tau} + \Phi(V)$  then

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**PROOF:**

$$0 \leq \frac{d}{d\varepsilon} \frac{W^2(\mathbf{S}_\varepsilon^\Psi(U_\tau^n), U_\tau^{n-1})}{2\tau} + \Phi(\mathbf{S}_\varepsilon^\Psi(U_\tau^n)) \Big|_{\varepsilon=0^+} \quad (\text{by the minimality of } U_\tau^n)$$



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## Auxiliary flows for the thin film equation (II)

$\Phi(\mathbf{u}) = \frac{1}{2} \int_{\mathbb{R}^d} |\mathbf{D}\mathbf{u}|^2 \, d\mathbf{x}$  decays on the heat flow

$$\partial_t \mathbf{w} - \Delta \mathbf{w} = 0$$

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In term of  $U_\tau$  it corresponds to

$$\int_0^T \int_{\mathbb{R}^d} |D^2 U_\tau|^2 dx dt \leq C.$$



## Main result

Assume that the non-negative initial condition  $u_0 \in L^1(\mathbb{R}^d)$  satisfies

$$\int_{\mathbb{R}^d} |x|^2 u_0(x) dx < +\infty, \quad \mathcal{H}(u_0) = \int_{\mathbb{R}^d} u_0 \log u_0 dx < +\infty.$$



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### Theorem

There exists an infinitesimal subsequence of time steps  $\tau_k \downarrow 0$  such that

$$U_{\tau_k} \rightarrow \mathbf{u} \quad \text{pointwise in } L^1(\mathbb{R}^d) \text{ and in } L^2(0, T; W^{1,2}(\mathbb{R}^d)) \quad \text{as } k \uparrow \infty$$



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$\mathbf{u} \in C^0([0, +\infty); L^1(\mathbb{R}^d)) \cap L^2_{\text{loc}}([0, +\infty); W^{2,2}(\mathbb{R}^d))$  is a non-negative global solution of the weak formulation of thin film equation

$$\partial_t \mathbf{u} + \frac{1}{2} \Delta^2(\mathbf{u}^2) - \partial_{x_i x_j}^2 (\partial_{x_i} \mathbf{u} \partial_{x_j} \mathbf{u}) - \frac{1}{2} \Delta |\mathbf{D}\mathbf{u}|^2 = 0$$



# Outline

- 1 Thin film equation as the gradient flow of the Dirichlet functional
  - in collaboration with U. Gianazza, G. Toscani, D. Matthes, R. McCann
- 2 The  $L^2$ -gradient flow of the simplest polyconvex functional
  - in collaboration with L. Ambrosio, S. Lisini
- 3 The sticky particle system
  - in collaboration with L. Natile



# Polyconvex functionals

$$\mathcal{F}(\mathbf{u}) = \int_{\Omega} F(D\mathbf{u}) dx$$

where

$$F(A) = \Phi(A, M_2(A), \dots, M_{d-1}(A), \det A), \quad \text{and } \Phi \text{ is convex;}$$
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If  $\Phi$  is superlinear then the functional  $\mathcal{F}$  is lower semicontinuous in  $L^2(\Omega; \mathbb{R}^d)$  [J. BALL].

### Well posedness of the variational problems

$$\min_{\mathbf{U}} \frac{1}{2\tau} \int_{\Omega} |\mathbf{U} - \mathbf{U}_{\tau}^{n-1}|^2 dx + \mathcal{F}(\mathbf{U})$$



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Nevertheless, **no general results** are known for gradient flows of polyconvex functionals and for their variational approximation



# The “simplest” polyconvex functional

$$F(A) := \Phi(\det A), \quad \mathcal{F}(\mathbf{u}) := \int_{\Omega} \Phi(\det D\mathbf{u}(x)) dx$$

under the additional constraint that

$\mathbf{u}$  is a **diffeomorphism** between  $\Omega$  and  $\mathbf{u}(\Omega)$ ,  $\det D\mathbf{u}(x) > 0$ ,  
 $\mathbf{u}(\Omega)$  is contained in a target open set  $\mathcal{U}$ .

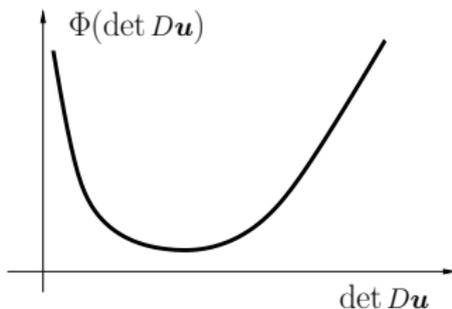


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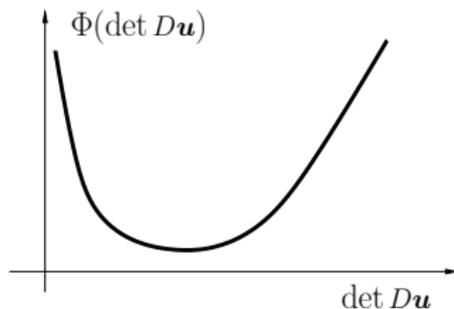


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## Difficulties (besides polyconvexity):

**lack of coercivity** ( $\mathcal{F}$  controls only  $\det D\mathbf{u}$ )

**lack of lower semicontinuity** in  $L^2(\Omega; \mathcal{U})$ .



## The form of the PDE

$$F(A) = \Phi(\det A), \quad DF(A) = (\operatorname{cof} A)^T \Phi'(\det A),$$

since

$$\frac{\partial \det A}{\partial A_{\alpha}^i} = (\operatorname{cof} A)_{\alpha}^i \quad \text{where} \quad \sum_{\alpha} A_{\alpha}^i (\operatorname{cof} A)_{\alpha}^j = \det A \delta_{ij} \quad \forall i, j.$$

$$\delta \mathcal{F}(\mathbf{u}, \boldsymbol{\xi}) = \int_{\Omega} \Phi'(\det D\mathbf{u}) \operatorname{cof} D\mathbf{u} \cdot D\boldsymbol{\xi} \, dx$$



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### Gradient flow

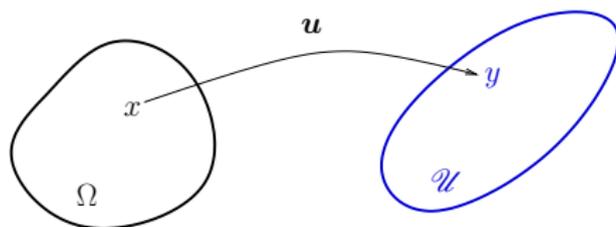
$$\partial_t \mathbf{u} - \operatorname{div} \left( \Phi'(\det D\mathbf{u}) \operatorname{cof} D\mathbf{u} \right) = 0$$



# A differential approach [Evans, Gangbo, Savin]

Make the transformation

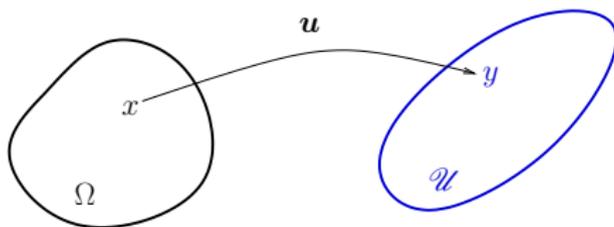
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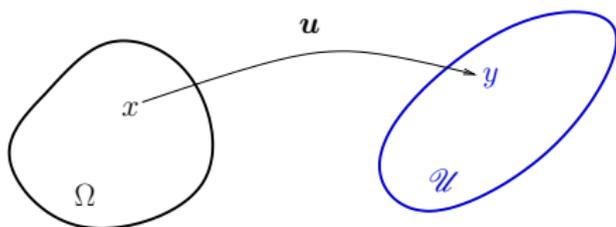
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$\rho$  solves the nonlinear diffusion PDE

$$\begin{cases} \partial_t \rho - \operatorname{div}(\rho D\phi'(\rho)) = 0 & \text{in } \mathcal{U} \times (0, +\infty), \\ \rho(x, 0) = \rho_0(x) \text{ in } \mathcal{U}; \quad \partial_n \rho = 0 & \text{on } \partial\mathcal{U} \times (0, +\infty) \end{cases}$$

where  $\phi(\rho) := \rho\Phi(1/\rho)$



# Recovering $u$

Step 1: put

$$\phi(\rho) := \rho\Phi(1/\rho)$$



# Recovering $u$

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Step 2: solve the PDE

$$\begin{cases} \phi(\rho) := \rho\Phi(1/\rho) \\ \partial_t \rho - \operatorname{div}(\rho \nabla \phi'(\rho)) = 0 & \text{in } \mathcal{U}, \\ \rho(\cdot, 0) = \rho_0, \quad \partial_n \rho = 0 & \text{on } \partial \mathcal{U} \end{cases}$$



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Step 4: Compute the flow

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# Recovering $u$

Step 1: put

Step 2: solve the PDE

Step 3:  
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Step 5

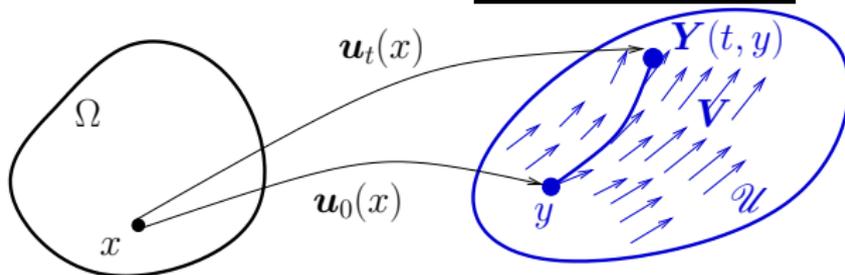
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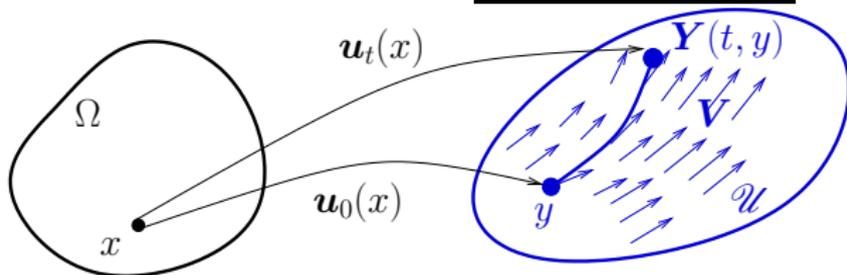
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## Main problem:

Prove that the  $L^2$ -Minimizing Movement scheme converges to this solution



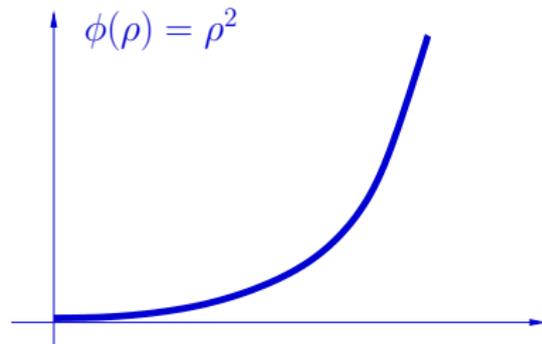
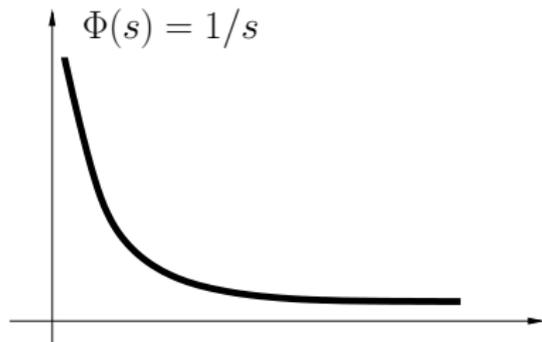
Transporting the functional  $\mathcal{F}$ 

$$\begin{aligned}\boxed{\mathcal{F}(\mathbf{u})} &= \int_{\Omega} \Phi(\det D\mathbf{u}(x)) dx = \int_{\mathcal{U}} \Phi(\det D\mathbf{u}(\mathbf{u}^{-1}(\mathbf{y}))) \rho(\mathbf{y}) d\mathbf{y} \\ &= \int_{\mathcal{U}} \Phi\left(\frac{1}{\rho(\mathbf{y})}\right) \rho(\mathbf{y}) d\mathbf{y} = \int_{\mathcal{U}} \phi(\rho(\mathbf{y})) d\mathbf{y} = \boxed{\mathcal{G}(\rho)}\end{aligned}$$



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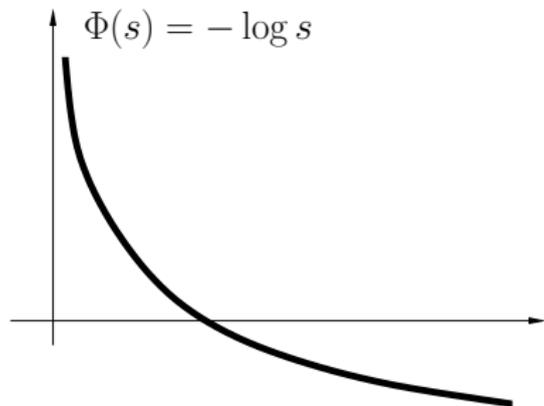


$$\partial_t \rho - \Delta \rho^2 = 0 \quad \text{Porous media equation}$$

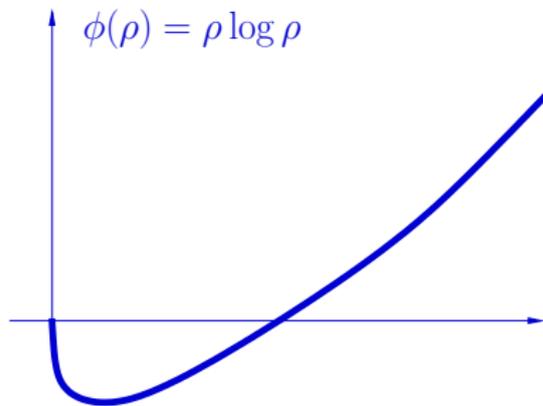


# Transporting the functional $\mathcal{F}$

$$\begin{aligned} \boxed{\mathcal{F}(\mathbf{u})} &= \int_{\Omega} \Phi(\det D\mathbf{u}(x)) dx = \int_{\mathcal{U}} \Phi(\det D\mathbf{u}(\mathbf{u}^{-1}(y))) \rho(y) dy \\ &= \int_{\mathcal{U}} \Phi\left(\frac{1}{\rho(y)}\right) \rho(y) dy = \int_{\mathcal{U}} \phi(\rho(y)) dy = \boxed{\mathcal{G}(\rho)} \end{aligned}$$



$\partial\rho - \Delta\rho = 0$

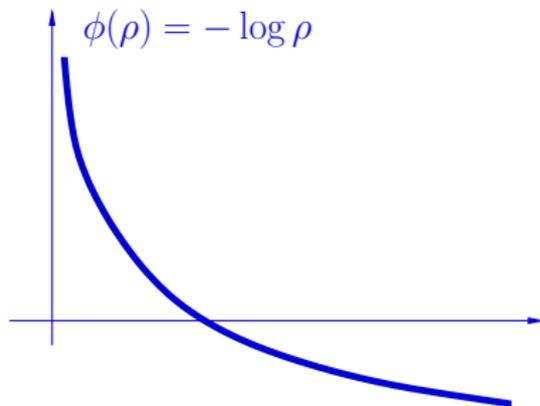
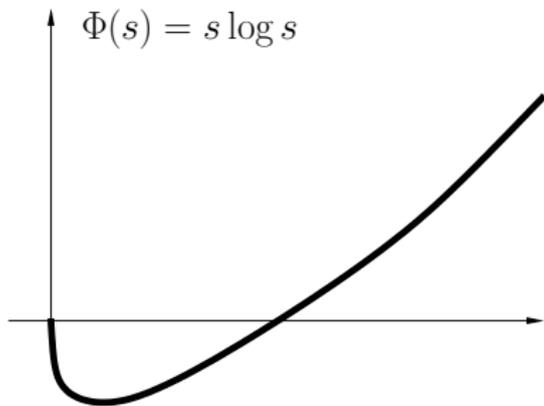


Heat equation



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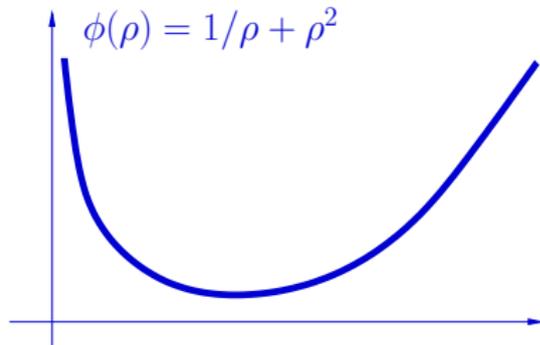
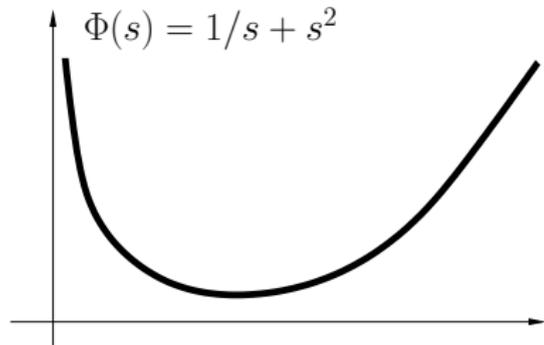


$$\partial_t \rho - \Delta \log \rho = 0$$



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## Transporting the variational problem

$$U \rightsquigarrow R = \frac{1}{\det DU} \circ U^{-1}, \quad \begin{cases} \mathcal{F}(U) = \int_{\Omega} \Phi(\det DU) dx = \\ \mathcal{G}(R) = \int_{\Omega} \phi(R) dy \end{cases}$$



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$$\min_U \mathcal{F}(U) + \frac{1}{2\tau} \|U - U_{\tau}^{n-1}\|_{L^2(\Omega; \mathbb{R}^d)}^2$$


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**Problem:** given a density  $R$  in  $\mathcal{U}$  and  $U_{\tau}^{n-1} \rightsquigarrow R_{\tau}^{n-1}$  solve

$$\min_{U \rightsquigarrow R} \|U - U_{\tau}^{n-1}\|_{L^2(\Omega; \mathbb{R}^d)}^2$$



## Optimal transportation

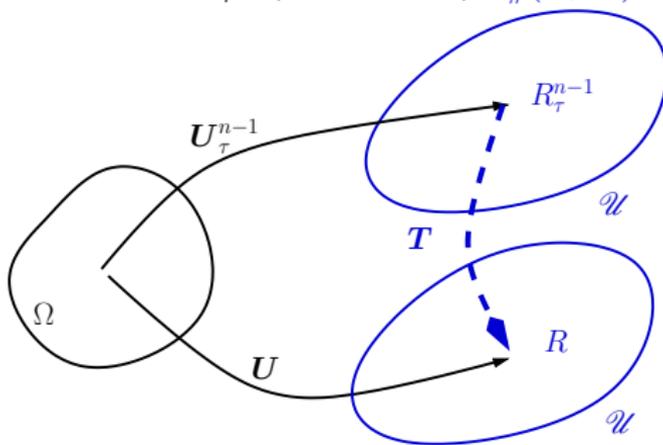
Minimize  $\int_{\Omega} |U - U_{\tau}^{n-1}|^2 dx$  under the constraint  $U \rightsquigarrow R$ .



# Optimal transportation

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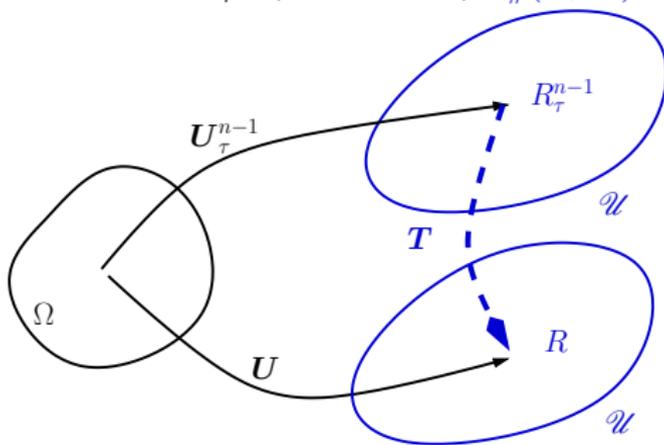
Write  $\mathbf{U} = \mathbf{T} \circ \mathbf{U}_{\tau}^{n-1}$ ,  $\mathbf{T} : \mathcal{U} \rightarrow \mathcal{U}$ ,  $\mathbf{T}_{\#}(R_{\tau}^{n-1}) = R$



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$$\begin{aligned} \int_{\Omega} |\mathbf{U} - \mathbf{U}_{\tau}^{n-1}|^2 dx &= \int_{\Omega} |\mathbf{T}(\mathbf{U}_{\tau}^{n-1}) - \mathbf{U}_{\tau}^{n-1}|^2 dx \\ &= \int_{\mathcal{U}} |\mathbf{T}(y) - y|^2 R_{\tau}^{n-1}(y) dy \end{aligned}$$



## A Wasserstein gradient flow

The piecewise constant interpolant  $R_\tau$  of the discrete solution of the variational algorithm

$$\min_U \mathcal{F}(U) + \frac{1}{2\tau} \|U - U_\tau^{n-1}\|_{L^2(\Omega; \mathbb{R}^d)}^2 = \min_R \mathcal{G}(R) + \frac{1}{2\tau} W^2(R, R_\tau^{n-1})$$



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converge to the solution of the nonlinear PDE

$$\begin{cases} \partial_t \rho + \operatorname{div}(\rho \mathbf{v}) = 0 & \text{in } \mathcal{U} \times (0, +\infty) & \text{(continuity equation)} \\ \mathbf{v} = -\nabla \phi'(\rho) & & \text{(Nonlinear condition)} \\ \rho(y, 0) = \rho_0(y), \quad \partial_n \rho = 0 & & \text{on } \partial \mathcal{U} \times (0, +\infty). \end{cases}$$



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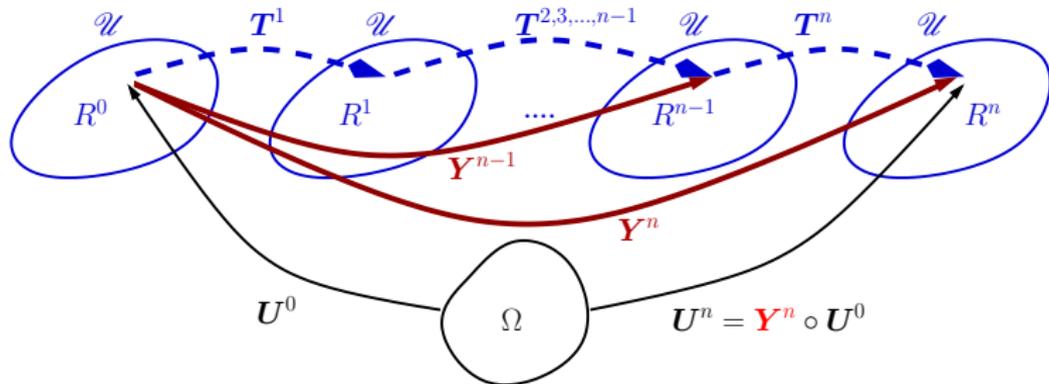
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**Optimal error estimate:**

$$\sup_t W^2(R_\tau(t), \rho(t)) \leq \tau \mathcal{G}(\rho_0)$$



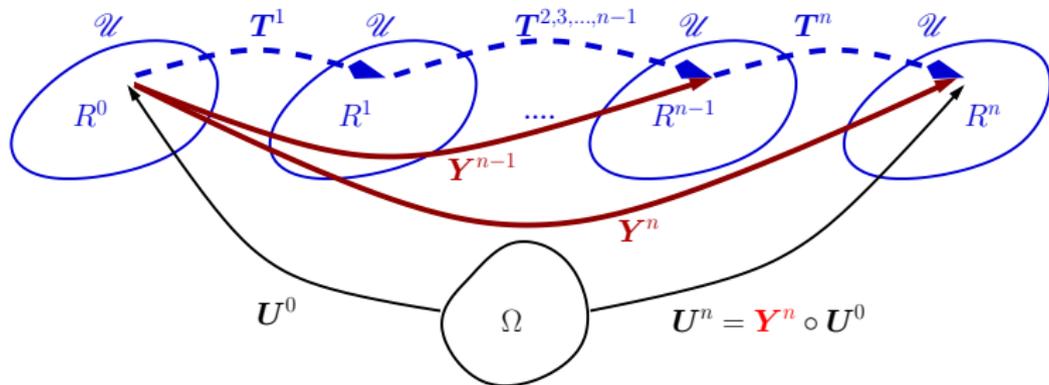
# Iterated optimal transport maps



$$\min_R \int_{\mathcal{U}} \phi(R) dy + \frac{1}{2\tau} W^2(R, R_\tau^{n-1}) \rightsquigarrow R_\tau^n$$



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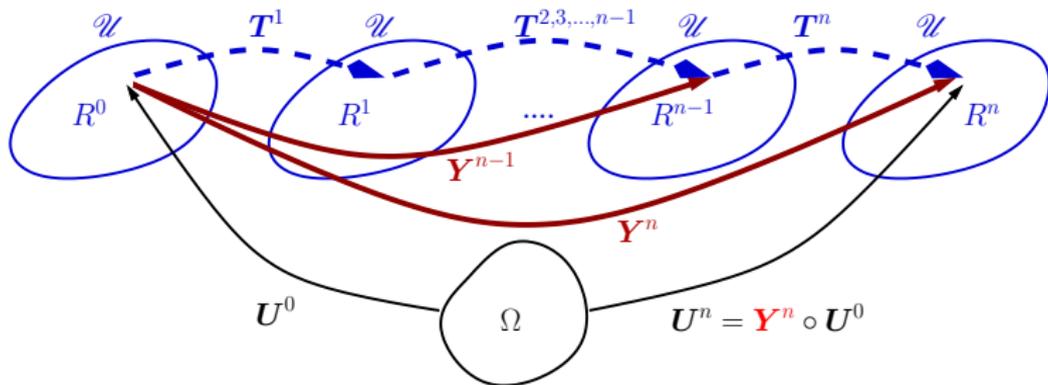
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$$\frac{Y_\tau^n - Y_\tau^{n-1}}{\tau} = V_\tau^n(Y_\tau^n), \quad V_\tau^n = -\nabla \phi'(R_\tau^n)$$



# Iterated optimal transport maps



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$R_\tau^n, Y_\tau^n$  solve the PDE. How to pass to the limit?

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# Convergence of the iterated maps

Main problem:

$$\begin{array}{ccc}
 \frac{d}{dt} \mathbf{Y}_\tau(t, y) = \mathbf{V}_\tau(t, \mathbf{Y}_\tau(t, y)), & \mathbf{V}_\tau(t, y) = -\nabla \phi'(R_\tau(t, y)) \\
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- ▶ **convergence of the energy:**

$$\lim_{\tau \downarrow 0} \int_0^T \int_{\mathcal{Q}} |\mathbf{V}_\tau(t, y)|^2 R_\tau(t, y) dy dt = \int_0^T \int_{\mathcal{Q}} |\mathbf{V}(t, y)|^2 \rho(t, y) dy dt$$



## A first result: convergence of flows

Suppose that  $\mathbf{V}_\tau, \mathbf{Y}_\tau, \mu_\tau = \rho_\tau \mathcal{L}^d$  are given with

$$\frac{d}{dt} \mathbf{Y}_\tau(t, y) = \mathbf{V}_\tau(t, \mathbf{Y}_\tau(t, y)), \quad \mu_{\tau, t} = (\mathbf{Y}_\tau(t, \cdot))_{\#} \mu_{\tau, 0}$$



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Then there exists a unique flow  $\mathbf{Y}$  solving

$$\dot{\mathbf{Y}}(t, y) = \mathbf{V}(t, \mathbf{Y}(t, y)), \quad \mathbf{Y}(0, y) = y$$

$$\lim_{\tau \downarrow 0} \int_0^T \max_t |\mathbf{Y}_\tau(t, y) - \mathbf{Y}(t, y)|^2 d\mu_0(y) = 0.$$



# Reconstruction of the gradient flow of $\mathcal{F}$

Suppose that  $\rho_0 \in C^\alpha(\overline{\mathcal{U}})$ ,  $\mathcal{G}(\rho_0) = \int_{\mathcal{U}} \phi(\rho_0) dy < +\infty$ .

- ▶ The discrete transports  $\mathbf{Y}_\tau$  converge to  $\mathbf{Y}$  in the sense of  $L^2(\mathcal{U}; L^\infty(0, T))$

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and the discrete solutions  $\mathbf{U}_\tau(t, x) = \mathbf{Y}_\tau(t, \mathbf{u}_0(x))$  converge to  $\mathbf{u}(t, x) = \mathbf{Y}(t, \mathbf{u}_0(x))$ .



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- ▶  $\rho$  is the unique solution of the nonlinear diffusion equation

$$\begin{cases} \partial_t \rho - \operatorname{div}(\rho D\phi'(\rho)) = 0 & \text{in } \mathcal{U}, \\ \rho(y, 0) = \rho_0(y), \quad \partial_n \rho = 0 & \text{on } \partial\mathcal{U} \end{cases}$$



# Outline

- 1 Thin film equation as the gradient flow of the Dirichlet functional**
  - in collaboration with U. Gianazza, G. Toscani, D. Matthes, R. McCann
  
- 2 The  $L^2$ -gradient flow of the simplest polyconvex functional**
  - in collaboration with L. Ambrosio, S. Lisini
  
- 3 The sticky particle system**
  - in collaboration with L. Natile



## Starting point: motion of a finite number of particles.

### Discrete particle model

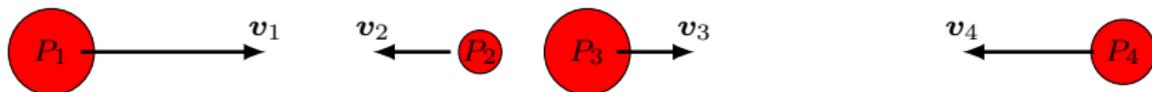
$N$  particles  $P_i := (m_i, x_i, v_i)$ ,  $i = 1, \dots, N$ ,  
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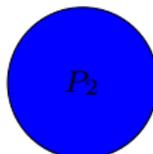
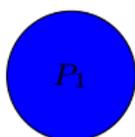
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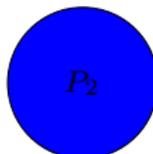
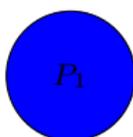
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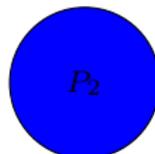
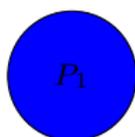
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## Measure-theoretic description

We thus have:

a **(finite) sequence of collision times**  $0 < t^1 < t^2 < \dots$

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$$v_t(x_2) - v_t(x_1) \leq \frac{1}{t}(x_2 - x_1) \quad \text{for } \rho_t\text{-a.e. } x_1, x_2 \in \mathbb{R}, \quad x_1 \leq x_2.$$



## Main problem: continuous limit

Consider a sequence of discrete initial data  $\mu_0^n := (\rho_0^n, \rho_0^n v_0^n)$  converging to  $\mu_0 = (\rho_0, \rho_0 v_0)$  in a suitable measure-theoretic sense and let  $\mu_t^n = (\rho_t^n, \rho_t^n v_t^n)$  be the (discrete) solution of SPS.



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and satisfy Oleinik entropy condition.



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  - ▶ GRENIER '95, E-RYKOV-SINAI '96: first existence and convergence result.
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- Pioneering ideas which lies (more or less explicitly) at the core of the papers by E-RYKOV-SINAI and BRENIER-GRENIER have been introduced by
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For every probability measure  $\rho \in \mathcal{P}(\mathbb{R})$  we introduce the **cumulative distribution function**

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# Monotone rearrangement

**Point of view of 1-dimensional optimal transport:** instead of using the cumulative distribution function  $M_\rho(x) = \rho((-\infty, x])$ , we

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The map  $X_\rho$  is **nondecreasing and right-continuous** and it pushes the Lebesgue measure  $\lambda := \mathcal{L}^1|_{(0,1)}$  on  $(0, 1)$  onto  $\rho$ .



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The map  $\rho \mapsto X_\rho$  is a **one-to-one correspondence** between

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In this way  $\rho \leftrightarrow X_\rho$  is an **isometry** between  $(\mathcal{P}_2(\mathbb{R}), W_2)$  and  $(\mathcal{K}, \|\cdot\|_{L^2(0,1)})$ .



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$\mu = \left( \sum_{i=1}^N m_i \delta_{x_i}, \sum_{i=1}^N m_i v_i \delta_{x_i} \right)$  is a dense subset of  $\mathcal{V}_2(\mathbb{R})$ .



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$\mu_n = (\rho_n, \rho_n v_n)$  converges to  $\mu = (\rho, \rho v)$  in  $\mathcal{V}_2(\mathbb{R})$  if and only if

$$W_2(\rho_n, \rho) \rightarrow 0, \quad \rho_n v_n \rightharpoonup \rho v \quad \text{weakly in } \mathcal{M}(\mathbb{R}), \quad \int_{\mathbb{R}} |v_n|^2 d\rho_n \rightarrow \int_{\mathbb{R}} |v|^2 d\rho.$$



## The fundamental estimate

Let  $\mathcal{V}_{\text{discr}}(\mathbb{R})$  the collection of all the discrete measures in  $\mathcal{V}_2(\mathbb{R})$  and let us denote by  $\mathcal{S}_t : \mathcal{V}_{\text{discr}}(\mathbb{R}) \rightarrow \mathcal{V}_{\text{discr}}(\mathbb{R})$  the map associating to any discrete initial datum  $(\rho_0, \rho_0 v_0) \in \mathcal{V}_{\text{discr}}$  the solution  $(\rho_t, \rho_t v_t)$  of the (discrete) sticky-particle system.  $\mathcal{S}_t$  is a **semigroup in**  $\mathcal{V}_{\text{discr}}(\mathbb{R})$ .



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for a suitable “universal” constant  $C$  independent of  $t$  and the data.



# Evolution semigroup

## Theorem (The evolution semigroup in $\mathcal{V}_2(\mathbb{R})$ )

- ▶ The semigroup  $\mathcal{S}_t$  can be uniquely extended by density to a right-continuous semigroup (still denoted  $\mathcal{S}_t$ ) of strongly-weakly continuous transformations in  $\mathcal{V}_2(\mathbb{R})$ , thus satisfying

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- ▶  $(\rho_t, \rho_t v_t) = \mathcal{S}_t[\mu]$ ,  $\mu \in \mathcal{V}_2(\mathbb{R})$ , is a distributional solution of Euler system satisfying Oleinik entropy condition.



## A gradient flow formulation in $\mathcal{P}_2(\mathbb{R})$

The semigroup  $\mathcal{S}_t$  can also be characterized by the **(metric) gradient flow  $\mathcal{G}_\tau$  of the  $(-1)$ -geodesically convex functional**

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*If  $\mu_t = (\rho_t, \rho_t v_t) = \mathcal{S}_t(\rho_0, \rho_0 v_0)$  is a solution of SPS then the rescaling  $\tau = \log t$ ,  $\hat{\mu}_\tau = \mu_t$ ,  $\hat{\rho}_\tau = \rho_t$  satisfy*

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The (rescaled) semigroup  $\mathcal{G}$  provides a **displacement extrapolation**, i.e. a canonical way to extend Wasserstein geodesics after collisions.



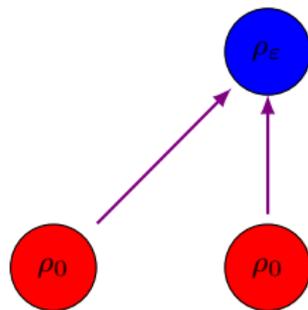
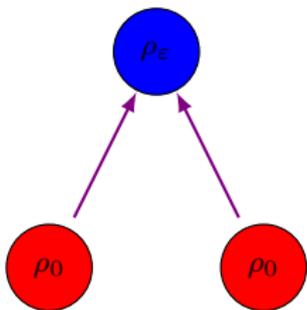
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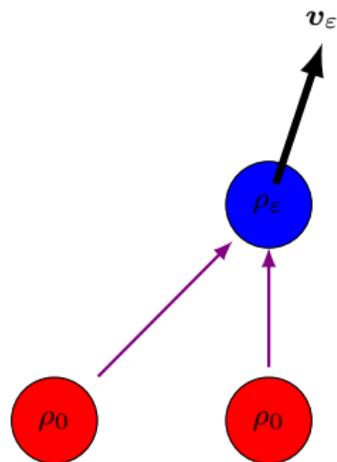
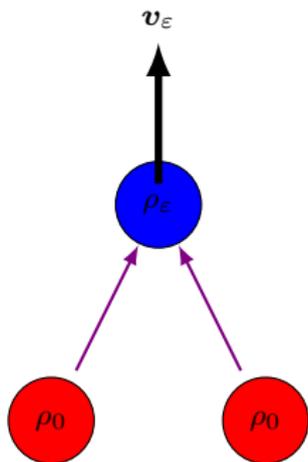
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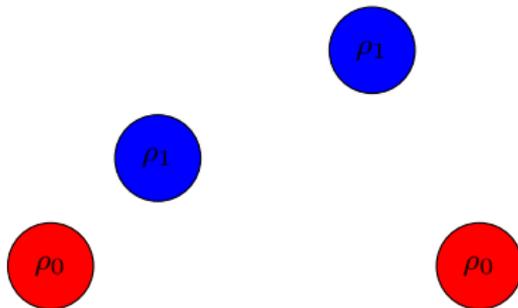
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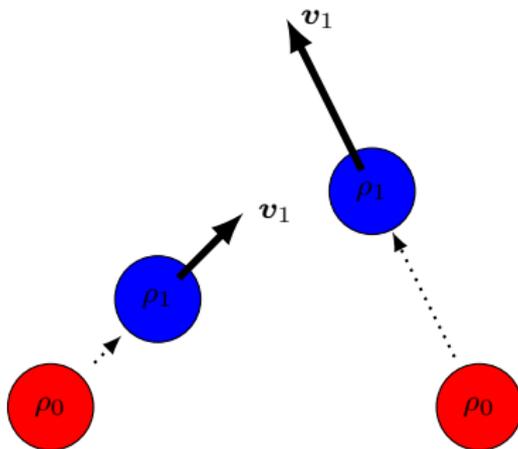
# Non-local effects in the multi-dimensional case



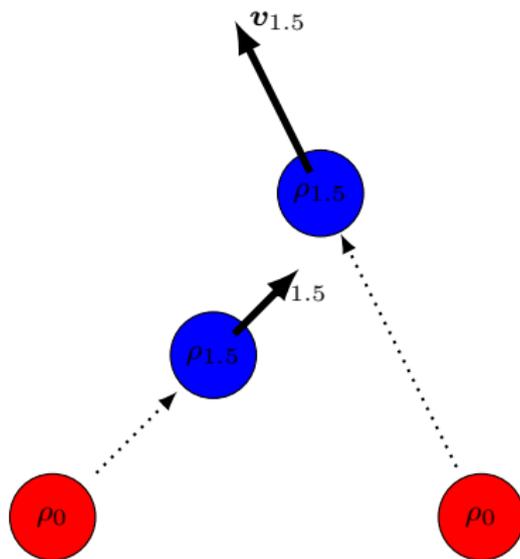
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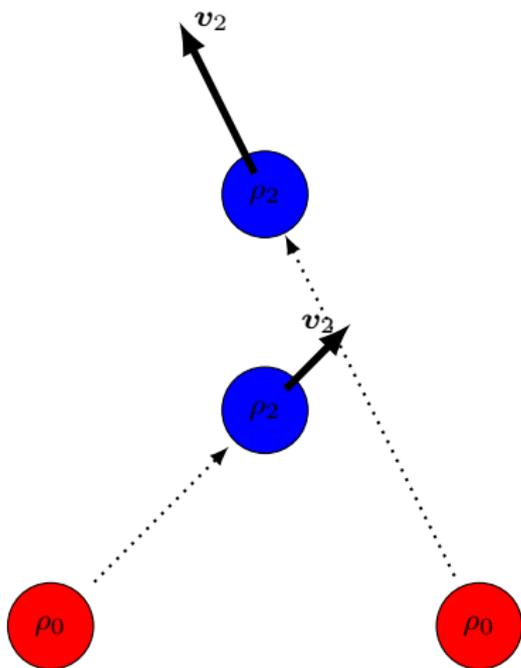
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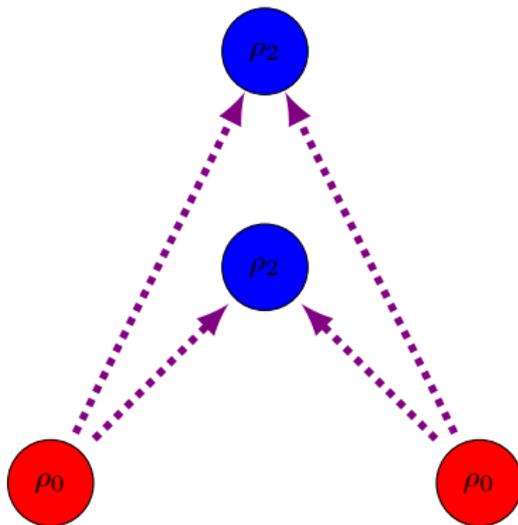
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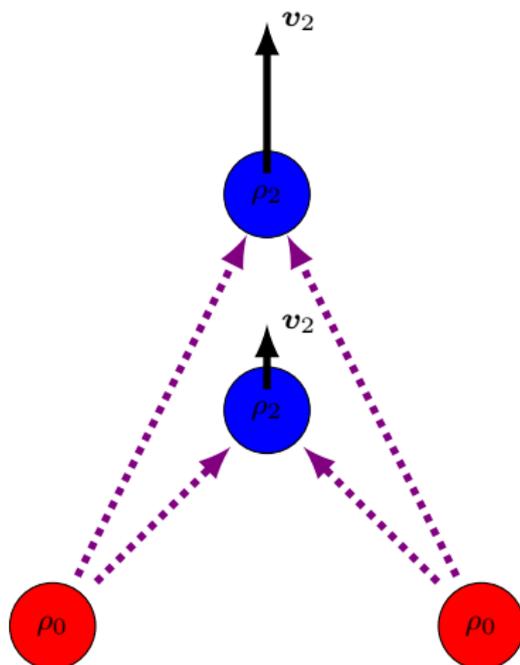
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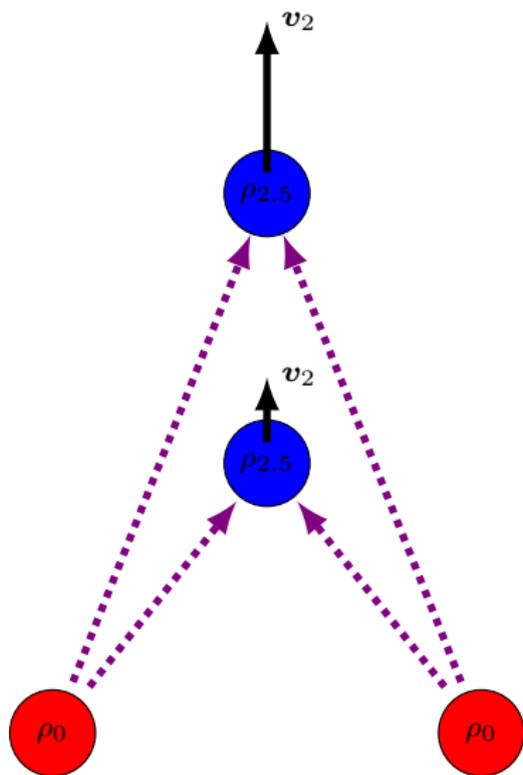
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Non-local interaction can be avoided only in the 1-dimensional case.



# Extensions

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## Open problems:

- ▶ The SPS in the multidimensional case.
- ▶ The displacement-extrapolation problem.

