## Summary of Day 17

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## 1 Objectives

- Begin the discussion of similarity and diagonalization.
- Explore a few more properties of eigenvalues/eigenvectors to aid in exploration of diagonalization.
- Get necessary and sufficent conditions for a matrix to be diagonalized.

## 2 Summary

• For now though, we will explore another equivalence relation on matrices. We have explored one already: having the same reduced row echelon form. This preserves lots of nice properties, like invertibility, rank, nullity, and even the row space and the null space (but *not* the column space, although it will preserve the dimension of this space, which is exactly the rank).

The bad thing of this equivalence relation is it does *not* preserve most spectral properties. That is, elementary row operations in general do change the spectrum or eigenvectors (although it does preserve some properties of the spectrum; for example elementary row operations will never introduce/eliminate a 0 eigenvalue). It also does not preserve the determinant (although it does preserve the nonzero-ness of it).

• We say a matrix B is **similar to** (or **conjugate to**) matrix A if there is some invertible matrix P such that:

 $B = P^{-1}AP$ 

We notate this as  $A \sim B$ .

Example

**Theorem** For any A, B square matrices:

- $-A \sim A.$
- If  $A \sim B$  then  $B \sim A$ .
- If  $A \sim B$  and  $B \sim C$  then  $A \sim C$ .
- Like the equivalence relation of row equivalence, similarity preserves lots of properties of a matrix. Let's write them down:

**<u>Theorem</u>** If A and B are  $n \times n$  matrices where  $A \sim B$  then:

- $-\det(A) = \det(B)$
- -A is invertible if and only if B is.
- -A and B have the same rank.
- -A and B have the same characteristic polynomial.
- -A and B have the same eigenvalues.

Proof.

• This theorem gives us some easy ways to determine that matrices are not similar. **Example** The following matrices are not similar:

$$\begin{pmatrix} 1 & 2 \\ 2 & 1 \end{pmatrix} \qquad \begin{pmatrix} 2 & 1 \\ 1 & 2 \end{pmatrix}$$

- We have seen that having upper triangular and diagonal matrices helps a lot with computations. To that end we make the following definition: a matrix A is **diagonalizable** if there is some diagonal matrix B such that  $A \sim B$ .
- This might seem artificial, but it is of computational significance. For example, suppose A was diagonalizable, and we wanted to calculate  $A^{100}$  (which is actually not the most uncommon thing to do. We might even want to look at  $\lim A^n$  as  $n \to \infty$ !). Well, if A is diagonalizable by B then there is P such that  $A = P^{-1}BP$ . Then:

$$A^{100} = \underbrace{(P^{-1}BP)(P^{-1}BP)\cdots(P^{-1}BP)}_{100}$$

But, this is just:

$$A^{100} = P^{-1}B^{100}P$$

But raising a diagonal matrix to the 100 power is just raising the diagonal entries by that power!

• If A is diagonalizable, then the matrix B must have the eigenvalues of A in its diagonal entries. Can you see why?

<u>**Theorem</u>** If a matrix A is diagonalizable then it's determinant is the product of its eigenvalues.</u>

• We will explore when matrices are diagonalizable. This is related to properties regarding the spectrum of a matrix. Here's a helpful property:

<u>**Theorem</u>** Let  $\mathbf{x}_1, \ldots, \mathbf{x}_m$  be eigenvectors corresponding to eigenvalues  $\lambda_1, \ldots, \lambda_m$ . Then  $\mathbf{x}_1, \ldots, \mathbf{x}_m$  is linearly independent.</u>

*Proof.* Omitted for class. It's in the book at the end of 4.3.

So, the big takeaway here is that eigenvectors that come from different eigenvalues are linearly independent. So the eigenspaces corresponding to each of these are these disjoint (except for **0**) subspaces of  $\mathbb{R}^n$ .

<u>**Theorem</u>** If A has n distinct eigenvalues then there is a basis for  $\mathbb{R}^n$  from the eigenvectors of A.</u>

Proof.

**<u>Remark</u>** This is not an if and only if. The converse is false because there still could be a basis. We can strengthen the two previous theorems:

**<u>Theorem</u>** Let A be an  $n \times n$  matrix. Let  $\lambda_1, \ldots, \lambda_m$  be eigenvalues, and like  $B_m$  be bases, where basis  $B_i$  is a basis for the eigenspace of  $\lambda_i$ . Then  $\bigcup B_1, \ldots, B_i$  is linearly independent.

*Proof.* Omitted for class. It is 4.24 in the book.

**<u>Theorem</u>** Let A be a  $n \times n$  matrix with k many distinct eigenvalues. There is a basis for eigenvectors of  $\mathbb{R}^n$  if and only if the sum of the geometric multiplicity of each eigenvalue is n.

*Proof.* The proof is really rather the same. Each eigenvalue comes as associated with some *l*-dimensional subspace (the eigenspace). This has a basis of *l* eigenvectors. If the sum of the geometric multiplicity is *n* then the sum of the dimensions of all of these vector spaces is *n*. Therefore we can choose a basis of eigenvectors by choosing a basis for each eigenspace and then putting them together. By the above theorem, they are linearly independent. As there are *n* of them, they must span the entire space of  $\mathbb{R}^n$ .

• The purpose for all this exploration is currently unclear, but here is a theorem that will relate what we have just discovered to diagonalizability:

<u>**Theorem</u>** A matrix A is diagonalizable if and only if it has n linearly independent eigenvectors. Moreover, if  $P^{-1}AP = D$  then</u>

- The diagonal of A is just the eigenvalues of A
- P is the collection of eigenvectors in the same order.

**<u>Theorem</u>** If A is a  $n \times n$  matrix with n eigenvalues with multiplicity, then the following are equivalent:

- 1. A is diagonalizable
- 2.  $\mathbb{R}^n$  has a basis of eigenvectors of A.
- 3. Each eigenvalue of  ${\cal A}$  has algebraic multiplicity equal to its geometric multiplicity.