

From a Mesoscopic to a Macroscopic Description of Fluid-Particle Interaction

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Assumptions on Fluid and Particles

- Fluid is inviscid and compressible
- Only one type of particle in the fluid
- Particles are uniform spheres with density ρ_P and radius a
- Fixed spatial domain $\Omega \subseteq \mathbb{R}^3$
- System is at a fixed, constant temperature $\theta_0 > 0$.
- Fluid is described by density $\varrho(x, t) \in [0, \infty)$ and velocity field $\mathbf{u}(x, t) \in \mathbb{R}^3$.

Description of Particles

- Particle distribution in the fluid is described by density function

$$f(x, \xi, t) \in [0, \infty)$$

where ξ is the microscopic velocity fluctuation.

- Particles subject to Brownian motion, leading to diffusion in ξ , with diffusion constant

$$\frac{k\theta_0}{m_p} \frac{6\pi\mu a}{m_p} = \frac{k\theta_0}{m_p} \frac{9\mu}{2a^2\rho_P}$$

where k is the Boltzmann constant and μ the dynamic viscosity of the fluid.

- Macroscopic particle density $\eta(x, t)$ given by

$$\eta(x, t) := \int_{\mathbb{R}^3} f(x, \xi, t) d\xi. \quad (1)$$

Coupling of Fluid and Particles

Coupling of the system is due to the friction between the particles and the fluid following Stokes' Law

Definition (Stokes' Law)

Consider a uniform, spherical particle of radius a . The friction force exerted on a particle by the fluid is

$$F(x, \xi, t) = 6\pi\mu a[\mathbf{u}(x, t) - \xi] \quad (2)$$

Thus, the force exerted on the fluid by the particles is

$$6\pi\mu a \int_{\mathbb{R}^3} [\xi - \mathbf{u}(x, t)] f(x, \xi, t) d\xi$$

by Newton's Third Law.

External Force–Physical Assumptions

Both fluid and particles are influenced by an external force with a time independent potential $\Phi(x)$.

- Force exerted on a particle: $-m_P \nabla_x \Phi$.
- Force exerted per unit volume on fluid: $\alpha \rho_F \nabla_x \Phi$.
 - α : dimensionless constant measuring ratio of external force's strength on fluid and particles
 - ρ_F : typical value of fluid mass per volume
- Measures settling phenomena such as gravity, buoyancy, and centrifugal forces.

Vlasov-Euler System

$$\partial_t \varrho + \operatorname{div}_x(\varrho \mathbf{u}) = 0 \quad (3)$$

$$\begin{aligned} \partial_t(\varrho \mathbf{u}) + \operatorname{div}_x(\varrho \mathbf{u} \otimes \mathbf{u}) + \frac{1}{\varrho F} \nabla_x p(\varrho) \\ = -\alpha \varrho \nabla_x \Phi + \frac{6\pi\mu a}{\varrho F} \int_{\mathbb{R}^3} (\xi - \mathbf{u}) f \, d\xi \end{aligned} \quad (4)$$

$$\begin{aligned} \partial_t f + \xi \cdot \nabla_x f - \nabla_x \Phi \cdot \nabla_\xi f \\ = \frac{9\mu}{2a^2 \varrho_P} \operatorname{div}_\xi \left[(\xi - \mathbf{u}) f + \frac{k\theta_0}{m_P} \nabla_\xi f \right] \end{aligned} \quad (5)$$

We assume a pressure of the form $p(\varrho) = \kappa \varrho^\gamma$ where $\kappa > 0$ and $\gamma > 1$.

Unitless Parameters I

In order to find a macroscopic model, we transform (3)-(5) to a unitless model with dimensionless parameters, and scale these parameters, then take the appropriate limit.

- Stokes settling time

$$\mathcal{T}_S = \frac{m_P}{6\pi\mu a} = \frac{2\rho_P a^2}{9\mu}$$

- Thermal speed

$$\mathcal{V}_{th} = \sqrt{\frac{k\theta_0}{m_P}}$$

Unitless Parameters II

- We also define characteristic time T , length L , and velocity $U = L/T$.
- We define a pressure unit \mathcal{P} and associate a velocity \mathcal{V}_S to the external potential Φ .

Thus, the physical values in relation to the dimensionless parameters are (' indicates unitless quantity)

$$t = Tt'$$

$$\xi = \mathcal{V}_{th}\xi'$$

$$\mathbf{u}(Lx', Tt') = U\mathbf{u}'(x', t')$$

$$f(x', \xi', t') = \frac{4}{3}\pi a^3 \mathcal{V}_{th}^3 f(Lx', \mathcal{V}_{th}\xi', Tt')$$

$$x = Lx'$$

$$\varrho(Lx', Tt') = \varrho'(x', t')$$

$$p(Lx', Tt') = \mathcal{P}p'(x', t')$$

$$\Phi(Lx') = \frac{\mathcal{V}_S L}{T_S} \Phi'(x')$$

Unitless Parameters III

We also define the unitless constants

$$\beta = \frac{T}{L} \mathcal{V}_{th} = \frac{\mathcal{V}_{th}}{U}, \quad \frac{1}{\varepsilon} = \frac{T}{\mathcal{T}_S}, \quad n = \frac{\mathcal{V}_S T}{\mathcal{V}_{th} \mathcal{T}_S}, \quad \chi = \frac{\mathcal{P} T}{\rho_F L U} = \frac{\mathcal{P}}{\rho_F U^2}$$

Unitless Vlassov-Euler System

Using the previous relations in (3)-(5) yields after dropping primes

$$\partial_t \varrho + \operatorname{div}_x(\varrho \mathbf{u}) = 0 \quad (6)$$

$$\begin{aligned} \partial_t(\varrho \mathbf{u}) + \operatorname{div}_x(\varrho \mathbf{u} \otimes \mathbf{u}) + \nabla_x(\chi p(\varrho)) \\ = -\alpha \beta n \varrho \nabla_x \Phi + \frac{1}{\varepsilon} \frac{\varrho P}{\varrho F} \int_{\mathbb{R}^3} (\beta \xi - \mathbf{u}) f \, d\xi \end{aligned} \quad (7)$$

$$\partial_t f + \beta \xi \cdot \nabla_x f - n \nabla_x \Phi \cdot \nabla_\xi f = \frac{1}{\varepsilon} \operatorname{div}_\xi \left[\left(\xi - \frac{1}{\beta} \mathbf{u} \right) f + \nabla_\xi f \right] \quad (8)$$

Pressure and Internal Energy

- The enthalpy is defined as

$$h(\varrho) := \int_1^\varrho \frac{p'(s)}{s} ds$$

and is in $L^1_{\text{loc}}(0, \infty)$.

- The internal energy is defined as

$$\Pi(\varrho) := \int_0^\varrho h(s) ds$$

Free Energy

Assume that

$$\frac{\varrho_P}{\varrho_F} = \frac{1}{\beta^2} \text{ and } n = \beta.$$

The free energies are

- The fluid free energy

$$\mathcal{F}_F(\varrho, \mathbf{u}) = \int_{\Omega} \frac{1}{2} \varrho |\mathbf{u}|^2 + \chi \Pi(\varrho) + \alpha \beta^2 \varrho \Phi \, dx \quad (9)$$

- The particle free energy

$$\mathcal{F}_P(f) = \int_{\Omega} \int_{\mathbb{R}^3} f \ln f + \frac{|\xi|^2}{2} f + f \Phi \, d\xi \, dx \quad (10)$$

- The total free energy

$$\mathcal{F}(\varrho, \mathbf{u}, f) = \mathcal{F}_F(\varrho, \mathbf{u}) + \mathcal{F}_P(f) \quad (11)$$

Energy Dissipation

Theorem

Assuming the scaling above, we have the following dissipation.

$$\frac{d}{dt} \mathcal{F} + \frac{1}{\varepsilon} \int_{\Omega} \int_{\mathbb{R}^3} \left| (\xi - \beta^{-1} \mathbf{u}) \sqrt{f} + 2 \nabla_{\xi} \sqrt{f} \right|^2 d\xi dx \leq 0. \quad (12)$$

This result follows formally from integration by parts.

External Force–Mathematical Assumptions

- $\exp(-\Phi) \in L^1(\Omega)$, $\Phi \exp(-\Phi) \in L^1(\Omega)$.
- $\Phi \in W^{1,1}(\Omega)$ for bounded Ω ; $\Phi \in W_{loc}^{1,1}(\Omega)$ for unbounded Ω .
- $\alpha\Omega$ is bounded below on Ω .
- The sub-level sets of $\alpha\Phi$ are bounded, that is

$$\{x \in \Omega \mid \alpha\Phi \leq k\}$$

is bounded for any $k \in \mathbb{R}$.

Stationary Solutions I

Provided the total fluid mass is conserved in time and finite, the system (6)-(8) has a stationary solution $(\rho_s, \mathbf{u}_s, f_s)$ such that

- $\mathbf{u}(x) \equiv 0$
- The stationary particle density function is

$$f_s(x, \xi) = Z_P e^{-\Phi(x)} \frac{e^{-|\xi|^2/2}}{(2\pi)^{3/2}}$$

where

$$Z_P = \left(\int_{\Omega} \int_{\mathbb{R}^3} f_0 \, d\xi \, dx \right) \left(\int_{\Omega} e^{-\Phi(x)} \, dx \right)^{-1}.$$

Stationary Solutions II

- The stationary fluid density is given by

$$\varrho_s(x) = \sigma \left(Z_F - \frac{\alpha\beta n}{\chi} \Phi(x) \right)$$

where

$$Z_F = \left(\int_{\Omega} \varrho_0 \, dx \right) \left(\int_{\Omega} e^{-\Phi(x)} \, dx \right)^{-1}$$

and σ is the generalized inverse of h .

Estimates I

Assuming that

$$\int_{\Omega} \int_{\mathbb{R}^3} f_0 \left(1 + |\ln(f_0)| + \frac{|\xi|^2}{2} + |\Phi| \right) d\xi dx$$

and

$$\int_{\Omega} \varrho_0 + \varrho_0 |\mathbf{u}_0|^2 + |\Pi(\varrho_0)| + \varrho_0 \beta n |\alpha \Phi| dx$$

are both bounded, we can use the free energy inequality and the hypotheses on Φ to obtain the following uniform bounds

Estimates II

- $f(1 + |\xi|^2 + |\Phi| + |\ln f|)$ is bounded in $L^\infty(\mathbb{R}^+; L^1(\Omega \times \mathbb{R}^3))$
- ϱ , $|\Pi(\varrho)|$ and $\beta n \varrho |\alpha \Phi|$ are bounded in $L^\infty(\mathbb{R}^+; L^1(\Omega))$
- $\sqrt{\varrho} \mathbf{u}$ is bounded in $L^\infty(\mathbb{R}^+; L^2(\Omega))$
- $\frac{1}{\sqrt{\varepsilon}} \left[(\xi - \beta^{-1} \mathbf{u}) \sqrt{f} + 2 \nabla_\xi \sqrt{f} \right]$ is bounded in $L^2(\mathbb{R}^+ \times \Omega \times \mathbb{R}^3)$.

Expansions of Macroscopic Particle Quantities

We define the unitless first moment of f as

$$\mathbf{J}(x, t) = \beta \int_{\mathbb{R}^3} \xi f(x, \xi, t) d\xi$$

and unitless second moment

$$\mathbb{P}(x, t) = \int_{\mathbb{R}^3} \xi \otimes \xi f(x, \xi, t) d\xi.$$

Using the uniform bounds, these quantities can be expanded as

$$\mathbf{J} = \mathbf{u}\eta + \beta\sqrt{\varepsilon}\mathbf{K}$$

and

$$\mathbb{P} = \eta\mathbb{I} + \beta^{-2}\mathbf{J} \otimes \mathbf{u} + \sqrt{\varepsilon}\mathbb{K}$$

where the components of \mathbf{K} and \mathbb{K} are bounded in $L^2(\mathbb{R}^+; L^1(\Omega))$.

Flowing Regime Scaling

- We are interested when the settling time scale is much smaller than the observational time scale, that is

$$\mathcal{T}_S \ll T$$

so ε is small.

- We are interested then in the limit $\varepsilon \rightarrow 0$.
- We take $\beta^2 = \varrho_F / \varrho_P$ to be a constant and $n = \beta$ a fixed positive constant.
- Thus, $\mathcal{V}_S \ll U = \mathcal{V}_{th}$.
- ϱ_F and ϱ_P are of the same order.

Flowing Regime Vlassov-Euler System

$$\partial_t \varrho_\varepsilon + \operatorname{div}_x(\varrho_\varepsilon \mathbf{u}_\varepsilon) = 0 \quad (13)$$

$$\begin{aligned} \partial_t(\varrho_\varepsilon \mathbf{u}_\varepsilon) + \operatorname{div}_x(\varrho_\varepsilon \mathbf{u}_\varepsilon \otimes \mathbf{u}_\varepsilon) + \nabla_x(\chi p(\varrho_\varepsilon)) \\ = -\alpha\beta^2 \varrho_\varepsilon \nabla_x \Phi + \frac{1}{\varepsilon\beta^2} \int_{\mathbb{R}^3} (\xi - \mathbf{u}_\varepsilon) f_\varepsilon \, d\xi \end{aligned} \quad (14)$$

$$\begin{aligned} \partial_t f_\varepsilon + \beta(\xi \cdot \nabla_x f_\varepsilon - \nabla_x \Phi \cdot \nabla_\xi f_\varepsilon) \\ = \frac{1}{\varepsilon} \operatorname{div}_\xi \left[\left(\xi - \frac{1}{\beta} \mathbf{u}_\varepsilon \right) f_\varepsilon + \nabla_\xi f_\varepsilon \right] \end{aligned} \quad (15)$$

Macroscopic Limit of Flowing Regime

Assuming that the limits of the various unknown quantities and their non-linear combinations involved in the system exist, the limits ϱ , \mathbf{u} , and η as $\varepsilon \rightarrow 0$ are

$$\partial_t \varrho + \operatorname{div}_x(\varrho \mathbf{u}) = 0 \quad (16)$$

$$\begin{aligned} \partial_t [(\varrho + \beta^{-2} \eta) \mathbf{u}] + \operatorname{div}_x [(\varrho + \beta^{-2} \eta) \mathbf{u} \otimes \mathbf{u}] \\ + \nabla_x (\chi p(\varrho) + \eta) = -(\alpha \beta^2 \varrho + \eta) \nabla_x \Phi \end{aligned} \quad (17)$$

$$\partial_t \eta + \operatorname{div}_x(\eta \mathbf{u}) = 0 \quad (18)$$

Bubbling Regime Scaling

- Again, the settling time scale is much smaller than the observational time scale, that is

$$\mathcal{T}_S \ll T$$

so ε is small.

- We are interested then in the limit $\varepsilon \rightarrow 0$.
- Again, $\beta^2 = \rho_F / \rho_P$ and $n = \beta$, but $\beta = \varepsilon^{-1/2}$ and $\alpha = \text{sgn}(\alpha)\varepsilon$.
- Physically, $\mathcal{V}_S = U \ll \mathcal{V}_{th}$.

Bubbling Regime Vlasov-Euler System

$$\partial_t \varrho_\varepsilon + \operatorname{div}_x(\varrho_\varepsilon \mathbf{u}_\varepsilon) = 0 \quad (19)$$

$$\begin{aligned} \partial_t(\varrho_\varepsilon \mathbf{u}_\varepsilon) + \operatorname{div}_x(\varrho_\varepsilon \mathbf{u}_\varepsilon \otimes \mathbf{u}_\varepsilon) + \nabla_x(\chi p(\varrho_\varepsilon)) \\ = -\operatorname{sgn}(\alpha) \varrho_\varepsilon \nabla_x \Phi + \int_{\mathbb{R}^3} \left(\frac{\xi}{\sqrt{\varepsilon}} - \mathbf{u}_\varepsilon \right) f_\varepsilon \, d\xi \end{aligned} \quad (20)$$

$$\begin{aligned} \partial_t f_\varepsilon + \frac{1}{\sqrt{\varepsilon}} (\xi \cdot \nabla_x f_\varepsilon + \nabla_x \Phi \cdot \nabla_\xi f_\varepsilon) \\ = \frac{1}{\varepsilon} \operatorname{div}_\xi [(\xi - \sqrt{\varepsilon} \mathbf{u}_\varepsilon) f_\varepsilon + \nabla_\xi f_\varepsilon] \end{aligned} \quad (21)$$

Macroscopic Limit of Bubbling Regime

Assuming that the limits pass as $\varepsilon \rightarrow 0$,

$$\partial_t \varrho + \operatorname{div}_x(\varrho \mathbf{u}) = 0 \quad (22)$$

$$\begin{aligned} \partial_t(\varrho \mathbf{u}) + \operatorname{div}_x(\varrho \mathbf{u} \otimes \mathbf{u}) + \nabla_x(\chi \rho(\varrho) + \eta) \\ = -(\operatorname{sgn}(\alpha)\varrho + \eta)\nabla_x \Phi \end{aligned} \quad (23)$$

$$\partial_t \eta + \operatorname{div}_x(\eta \mathbf{u} - \eta \nabla_x \Phi) = \Delta_x \eta \quad (24)$$

Remarks

- We assume that f_ε , ρ_ε , and ε converge to f , ρ , and \mathbf{u} in each regime, as well as any non-linear terms converge. While we have weak compactness for the sequences (f_ε) , (ρ_ε) , (\mathbf{u}_ε) , and $(\sqrt{\rho_\varepsilon}\mathbf{u}_\varepsilon)$ from the energy inequality, this is not the case for the non-linear terms.
- Such rigor can be shown in the case of a viscous fluid.
- Even in the case of no external force, the evolution of the fluid still depends on the evolution of the particle density.

References



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