

# Kolmogorov Forward Equation.

We derived the Kolmogorov backward equation in class. This short note deduces the Kolmogorov forward equation from the Kolmogorov backward equation. Let  $X$  be a diffusion satisfying the SDE

$$dX_t = b(X_t) dt + \sigma(X_t) dW_t,$$

where  $b$  and  $\sigma$  are time independent and Lipschitz. Suppose further  $X$  has a (smooth) transition density

$$p(x, s; y, t) = P(X_t^{(x,s)} \in dy).$$

We know that  $p$  satisfies the Kolmogorov backward equation in the initial variables  $x$  and  $s$ . Namely,

$$\partial_s p + L_x p = 0, \quad \text{and} \quad \lim_{s \rightarrow t^-} p(\cdot, s; y, t) = \delta_y,$$

where

$$L = \sum_i b_i \partial_i + \frac{1}{2} \sum_{i,j} a_{i,j} \partial_{i,j}$$

and

$$a_{i,j} = a_{i,j}(x) = \sum_k \sigma_{i,k}(x) \sigma_{j,k}(x).$$

The Kolmogorov forward equation says that  $p$  satisfies the dual equation in the variables  $y, t$ .

**Proposition 1** (Kolmogorov forward equation). *Let  $L^*$  be the dual of  $L$ , defined by*

$$L^* g = \sum_i -\partial_i (b_i g) + \frac{1}{2} \sum_{i,j} \partial_{i,j} (a_{i,j} g).$$

Then

$$\partial_t p - L_y^* p = 0, \quad \text{and} \quad \lim_{t \rightarrow s^+} p(x, s; \cdot, t) = \delta_x,$$

*Remark.* The operator  $L^*$  is the dual of  $L$  with respect to the  $L^2$  inner product. Namely, if  $f, g \in C_c^2(\mathbb{R}^d)$ , then

$$\int_{\mathbb{R}^d} Lf(x) g(x) dx = \int_{\mathbb{R}^d} f(x) L^*g(x) dx$$

*Proof.* Fix  $T > 0$ , and always assume  $0 \leq s < t \leq T$ . Let  $f \in C_b^2(\mathbb{R}^d)$ , and define

$$u(x, s) = E^{(x,s)} f(X_T) = \int p(x, s; y, T) f(y) dy.$$

We know that  $u$  satisfies the Kolmogorov backward equation

$$\partial_s u + L_x u = 0 \quad \text{and} \quad u(x, T) = f(x). \quad (1)$$

Also by the Markov property, it immediately follows that

$$u(x, s) = E^{(x,s)} f(X_t) = \int p(x, s; y, t) u(y, t) dy$$

for any  $t \in [s, T]$ . (Alternately, you can deduce the above equality using uniqueness of solutions to (1).) Now, differentiating both sides in  $t$ , and using (1) gives

$$\begin{aligned} 0 = \partial_t u(x, s) &= \int [\partial_t p(x, s; y, t) u(y, t) + p(x, s; y, t) \partial_t u(y, t)] dy \\ &= \int [\partial_t p(x, s; y, t) u(y, t) - p(x, s; y, t) L_y u(y, t)] dy \\ &= \int [\partial_t p(x, s; y, t) - L_y^* p(x, s; y, t)] u(y, t) dy \end{aligned}$$

Note, to obtain the last inequality we had to integrate by parts. All the boundary terms involved are 0 because one can show that  $p$  vanishes at infinity.

Now choosing  $t = T$ , we see that

$$\int [\partial_t p(x, s; y, T) - L_y^* p(x, s; y, T)] f(y) dy = 0.$$

Since  $f \in C_0^2$  is arbitrary, we are done.  $\square$