



# Large Graph Mining: Power Tools and a Practitioner's guide

Task 3: Recommendations & proximity

*Faloutsos, Miller & Tsourakakis*

CMU



# Outline

- Introduction – Motivation
- Task 1: Node importance
- Task 2: Community detection
- ➔ • **Task 3: Recommendations**
- Task 4: Connection sub-graphs
- Task 5: Mining graphs over time
- Task 6: Virus/influence propagation
- Task 7: Spectral graph theory
- Task 8: Tera/peta graph mining: hadoop
- Observations – patterns of real graphs
- Conclusions



# Acknowledgement:

Most of the foils in ‘Task 3’ are by



**Hanghang TONG**

[www.cs.cmu.edu/~htong](http://www.cs.cmu.edu/~htong)

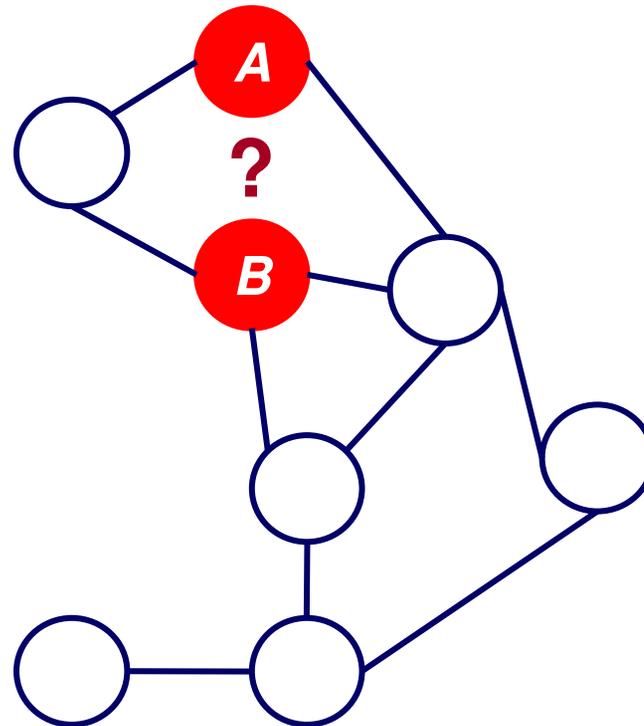


## Detailed outline

- ➔ • Problem defn and motivation
- Solution: Random walk with restarts
- Efficient computation
- Case study: image auto-captioning
- Extensions: bi-partite graphs; tracking
- Conclusions



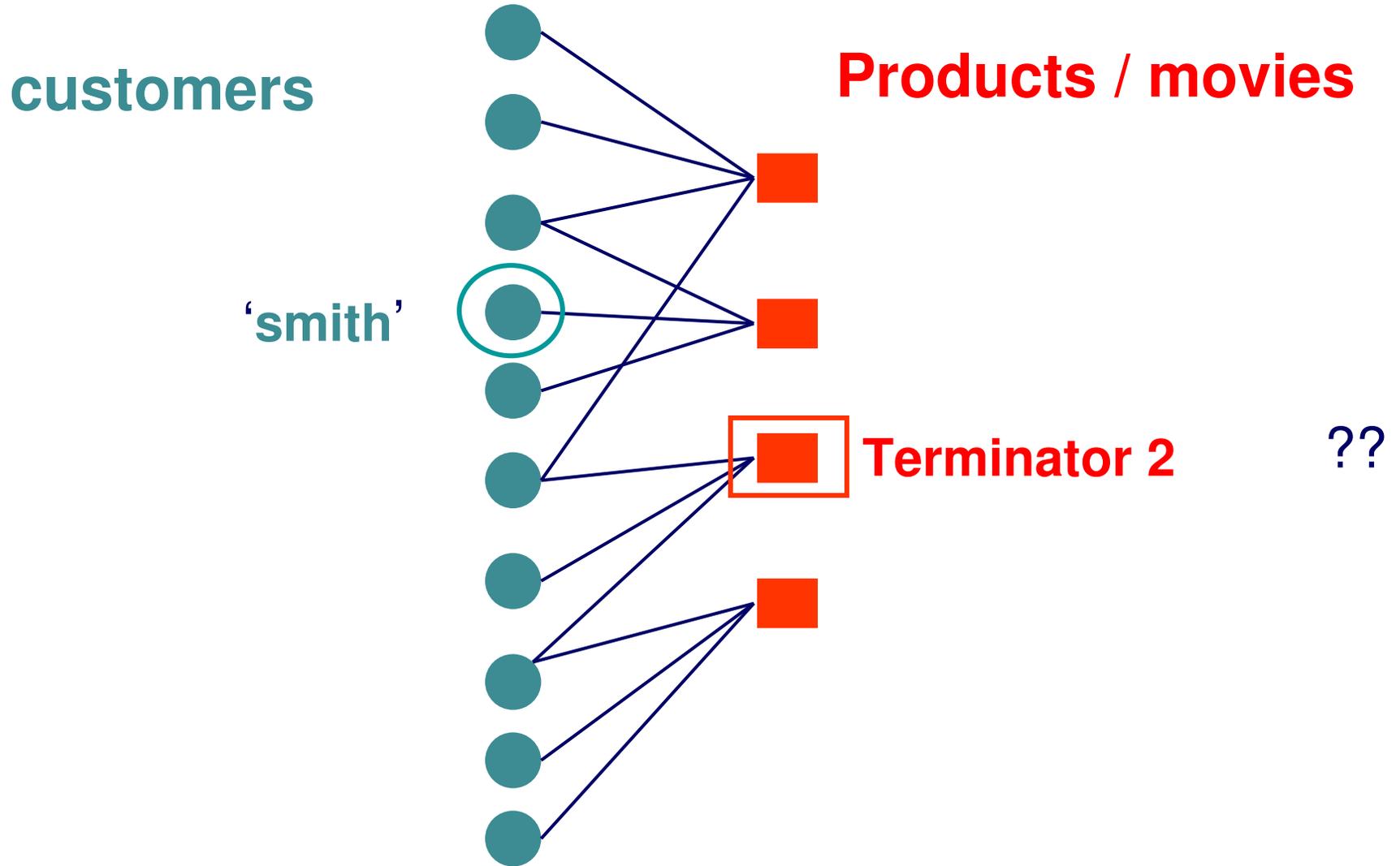
# Motivation: Link Prediction



Should we introduce  
Mr. A to Mr. B?



# Motivation - recommendations





## Answer: proximity

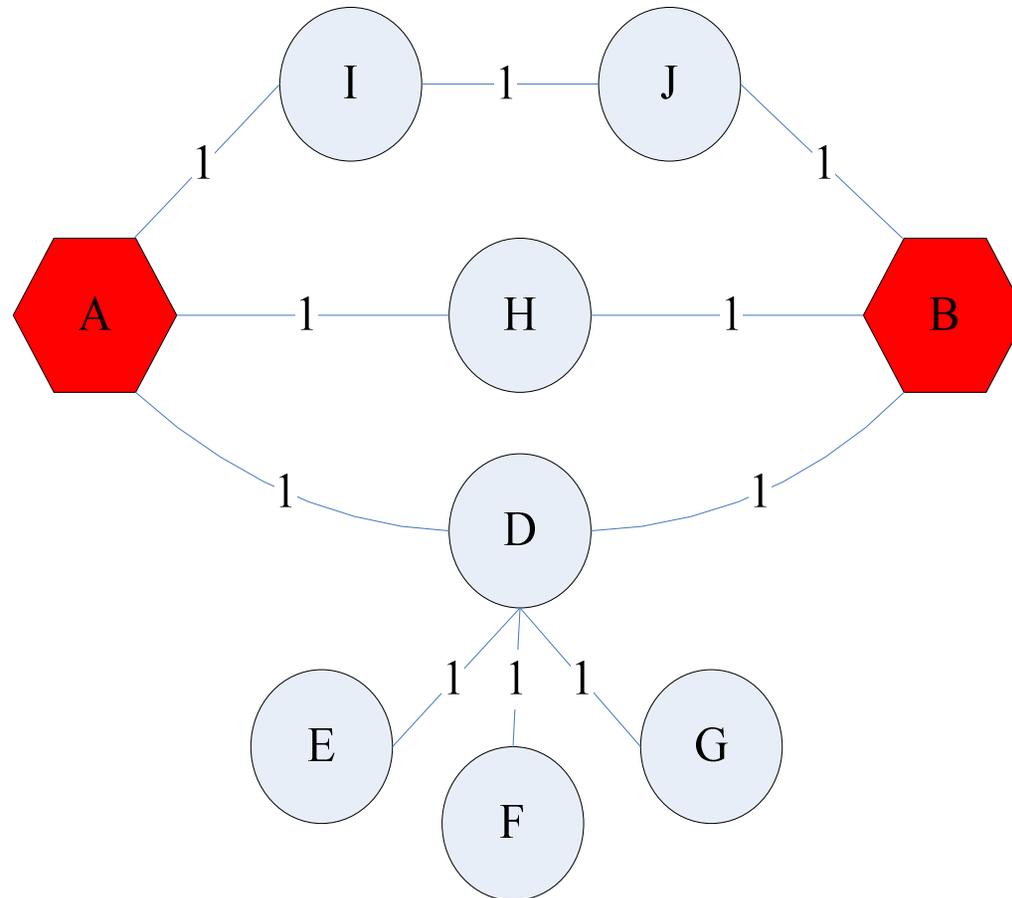
- ‘yes’, if ‘A’ and ‘B’ are ‘close’
- ‘yes’, if ‘smith’ and ‘terminator 2’ are ‘close’

QUESTIONS in this part:

- How to measure ‘closeness’/proximity?
- How to do it quickly?
- What else can we do, given proximity scores?



# How close is 'A' to 'B'?



**a.k.a Relevance, Closeness, 'Similarity'...**



## Why is it useful?

- Recommendation

And many more

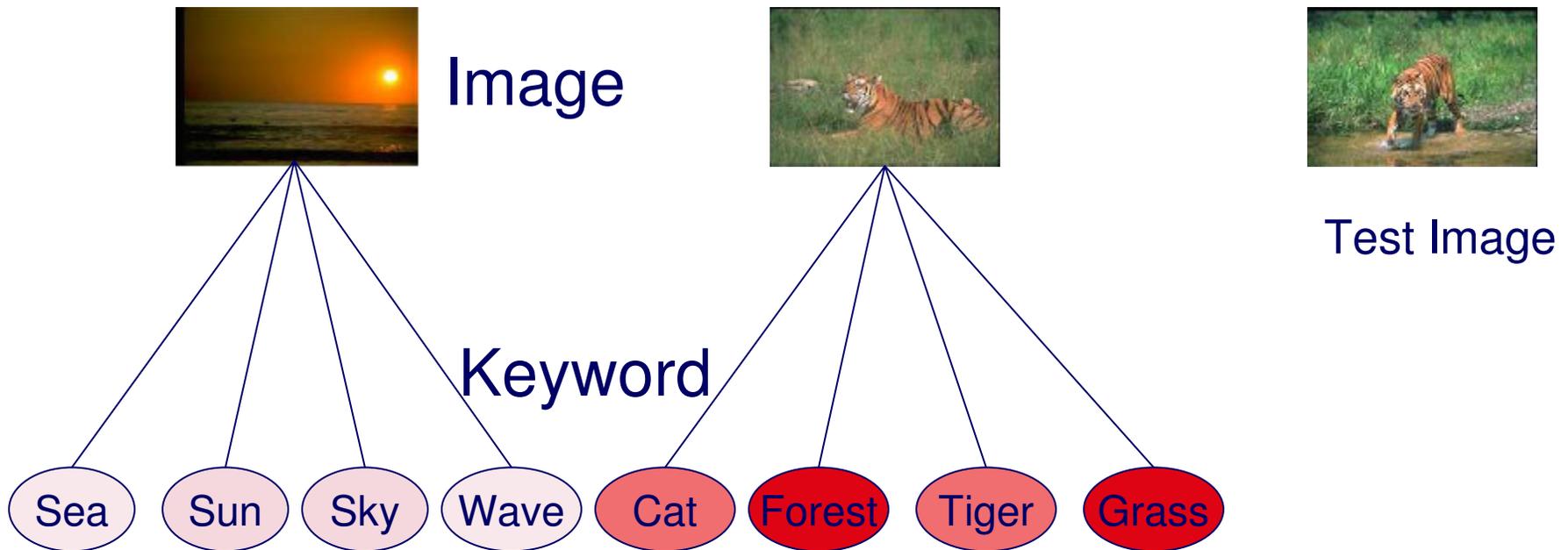
- **Image captioning** [Pan+]
- **Conn. / CenterPiece subgraphs** [Faloutsos+], [Tong+], [Koren+]

and

- Link prediction [Liben-Nowell+], [Tong+]
- Ranking [Haveliwala], [Chakrabarti+]
- Email Management [Minkov+]
- Neighborhood Formulation [Sun+]
- Pattern matching [Tong+]
- Collaborative Filtering [Fouss+]
- ...



# Automatic Image Captioning



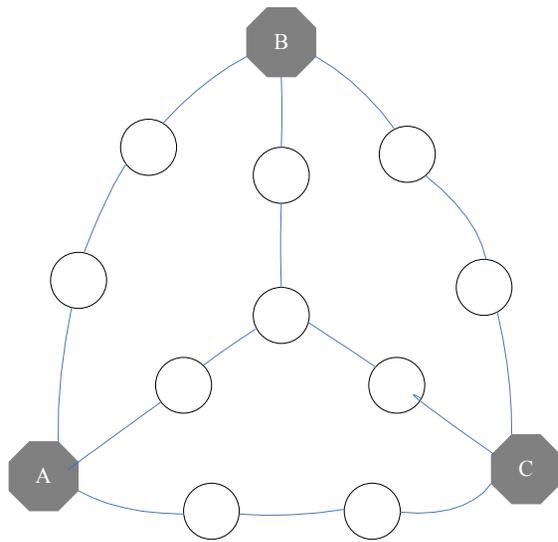
Q: How to assign keywords to the test image?

A: **Proximity!** [Pan+ 2004]

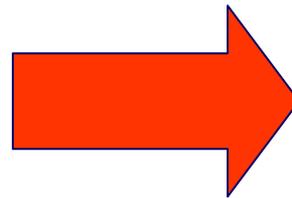


# Center-Piece Subgraph(CePS)

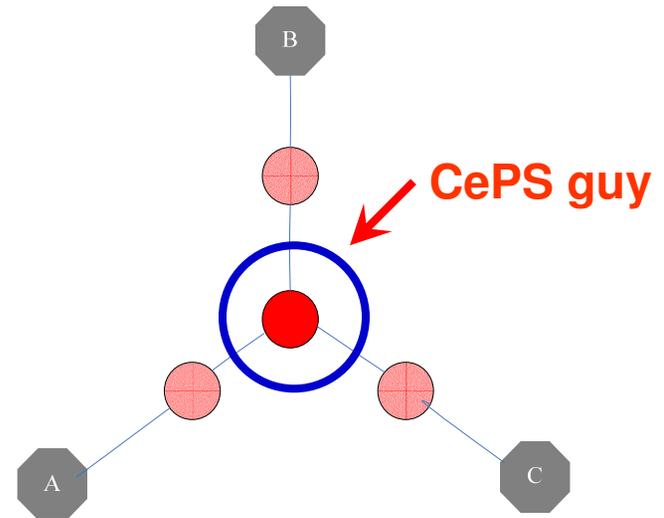
Input



Original Graph



Output



CePS

Q: How to find hub for the black nodes?

A: Proximity! [Tong+ KDD 2006]



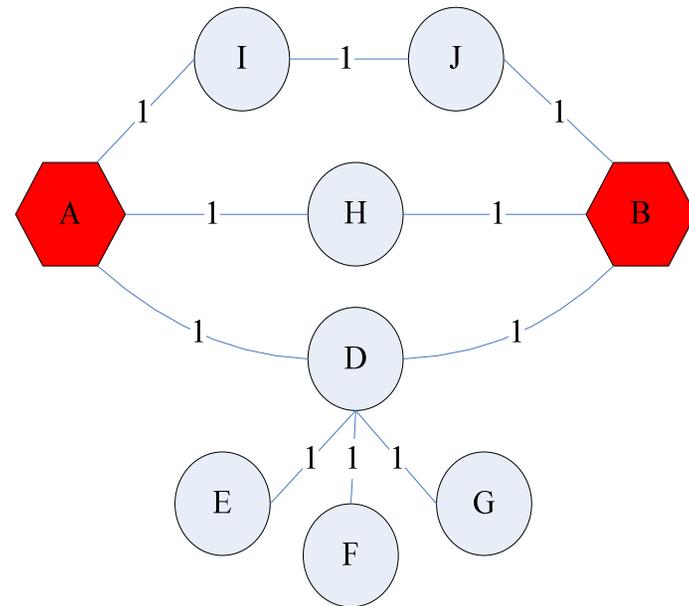
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# How close is 'A' to 'B'?

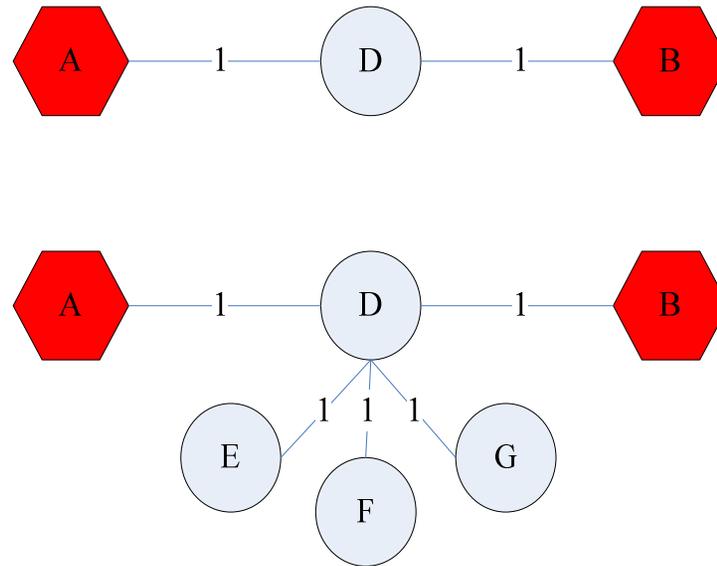
Should be close, if they have

- many,
- short
- 'heavy' paths





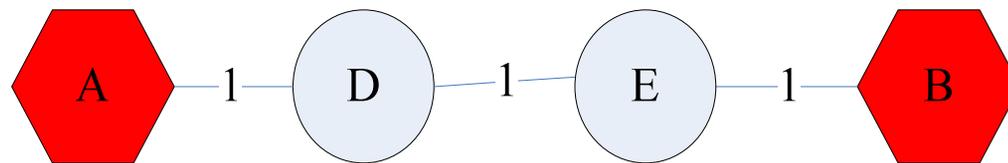
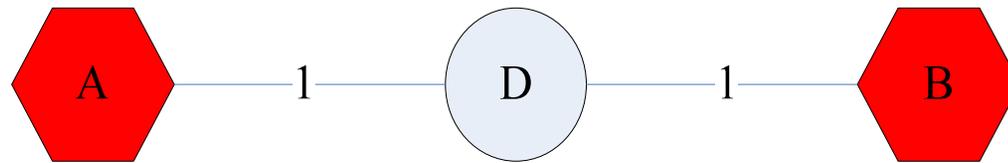
# Why not shortest path?



A: 'pizza delivery guy' problem



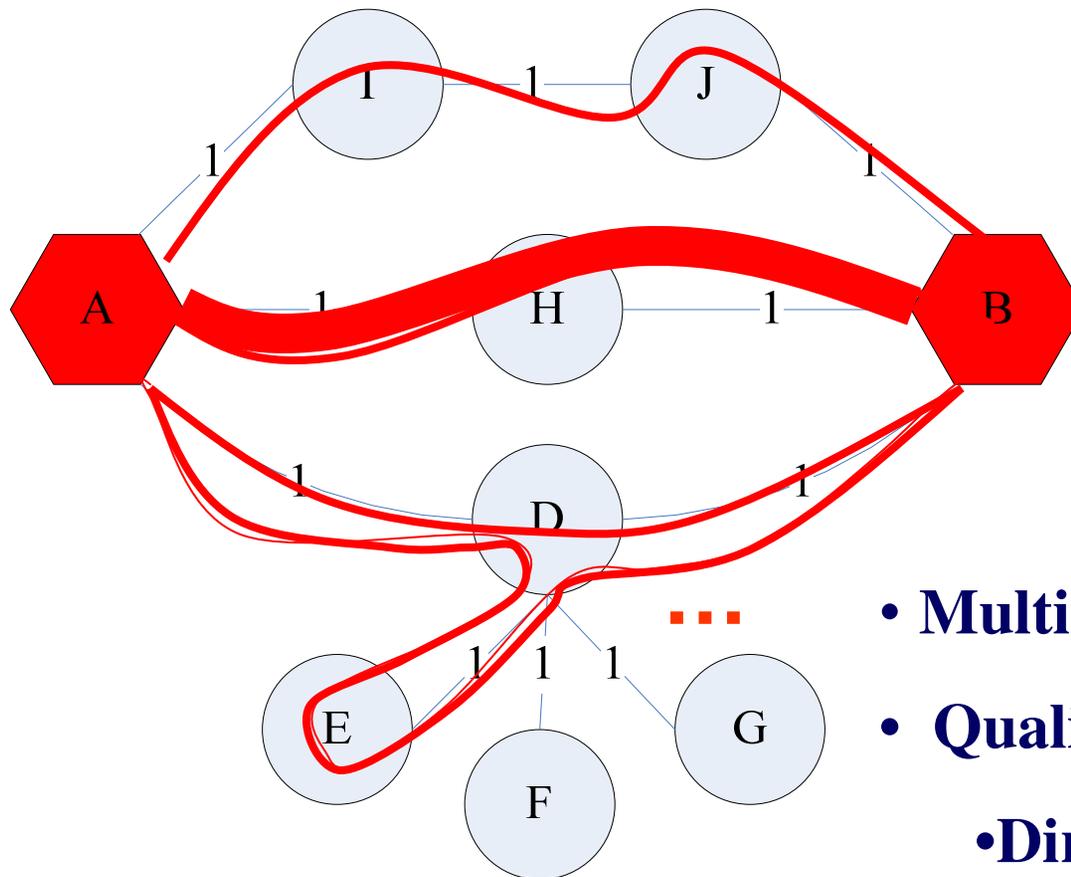
# Why not max. netflow?



A: No penalty for long paths



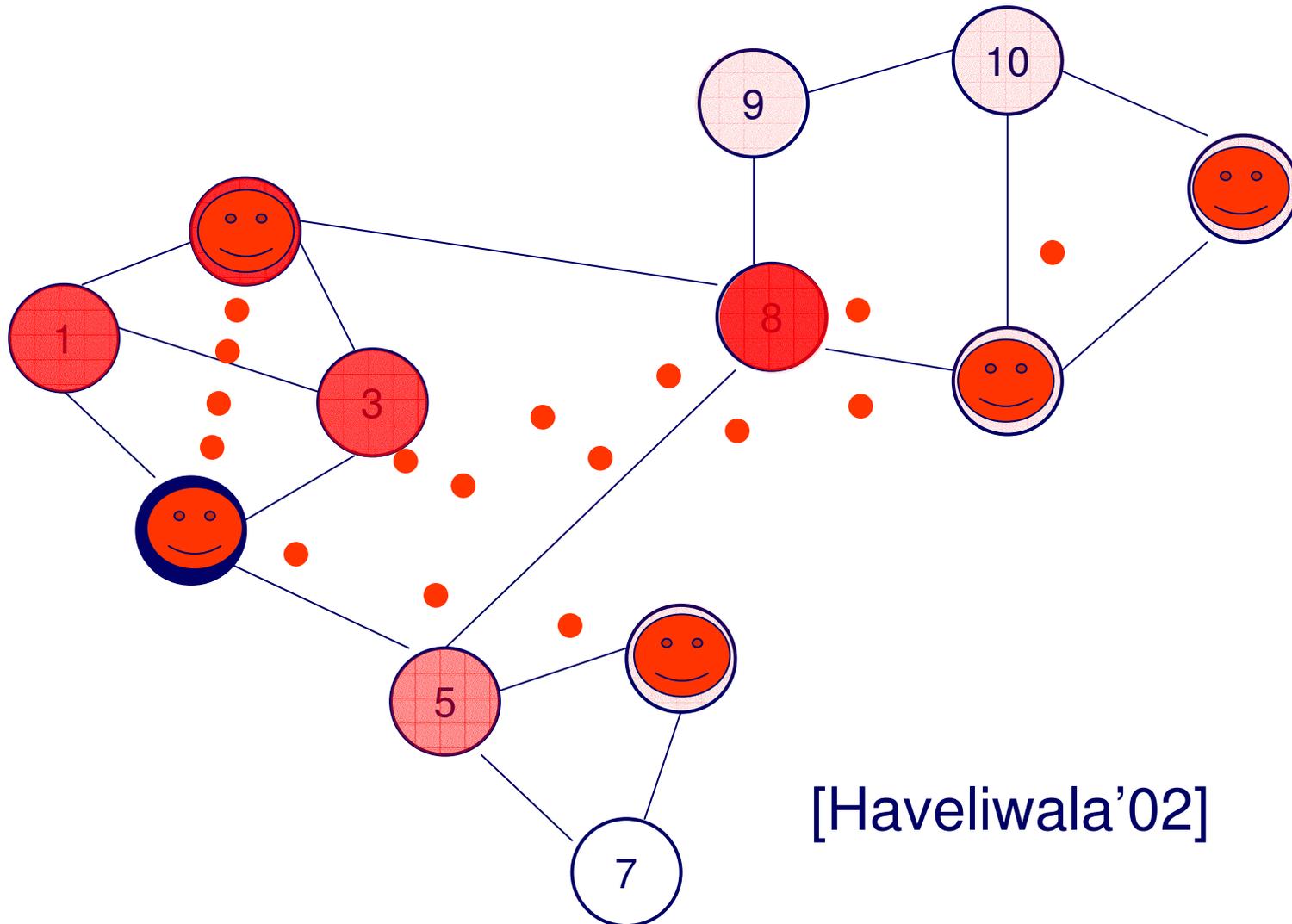
# What is a ``good'' Proximity?



- **Multiple Connections**
- **Quality of connection**
  - **Direct & In-directed Conns**
  - **Length, Degree, Weight...**

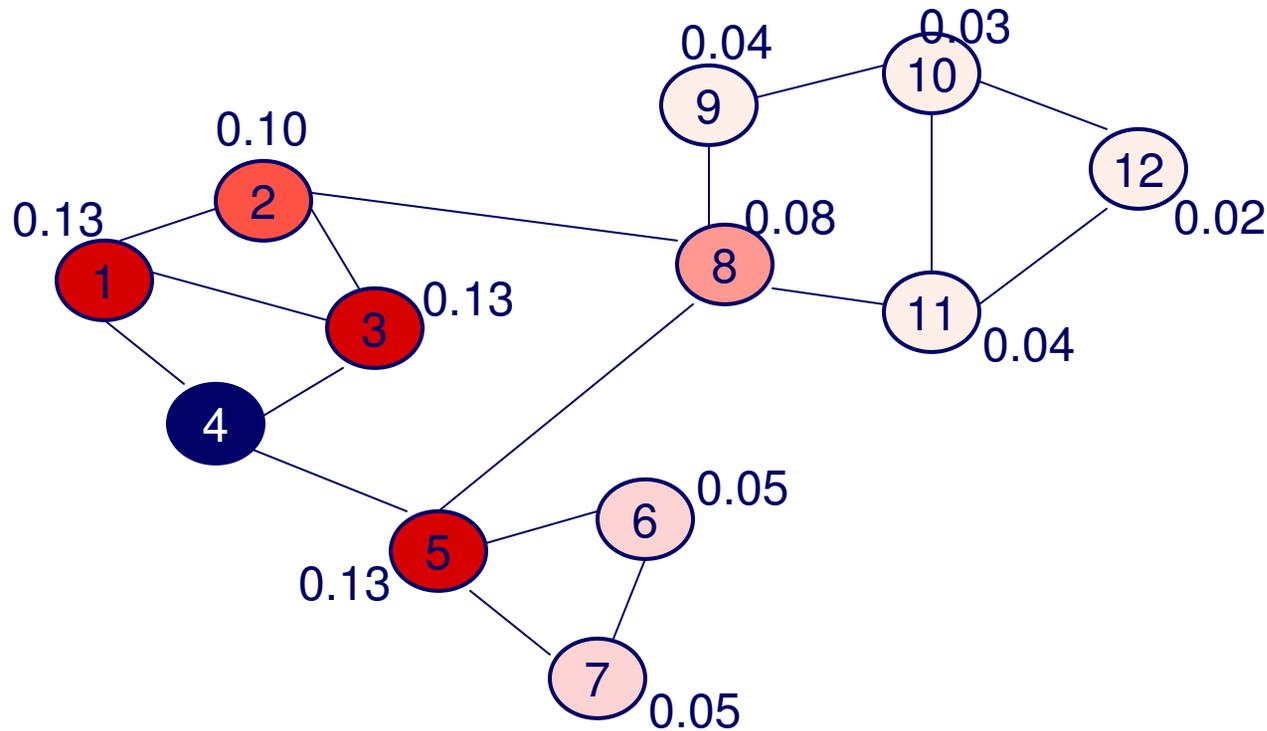


# Random walk with restart





# Random walk with restart



	Node 4
Node 1	0.13
Node 2	0.10
Node 3	0.13
Node 4	0.22
Node 5	0.13
Node 6	0.05
Node 7	0.05
Node 8	0.08
Node 9	0.04
Node 10	0.03
Node 11	0.04
Node 12	0.02

Nearby nodes, higher scores

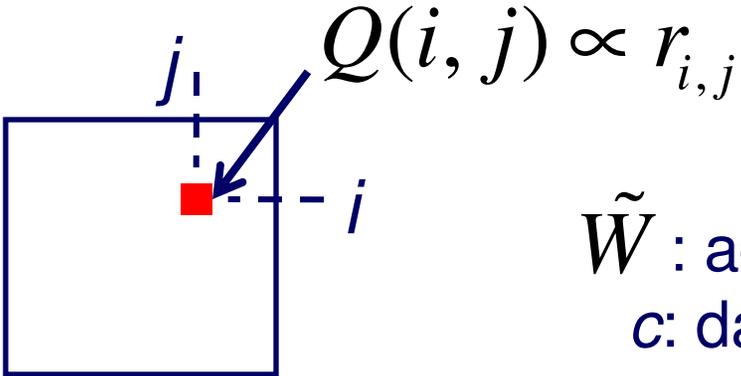
More red, more relevant

Ranking vector

$$\vec{r}_4$$

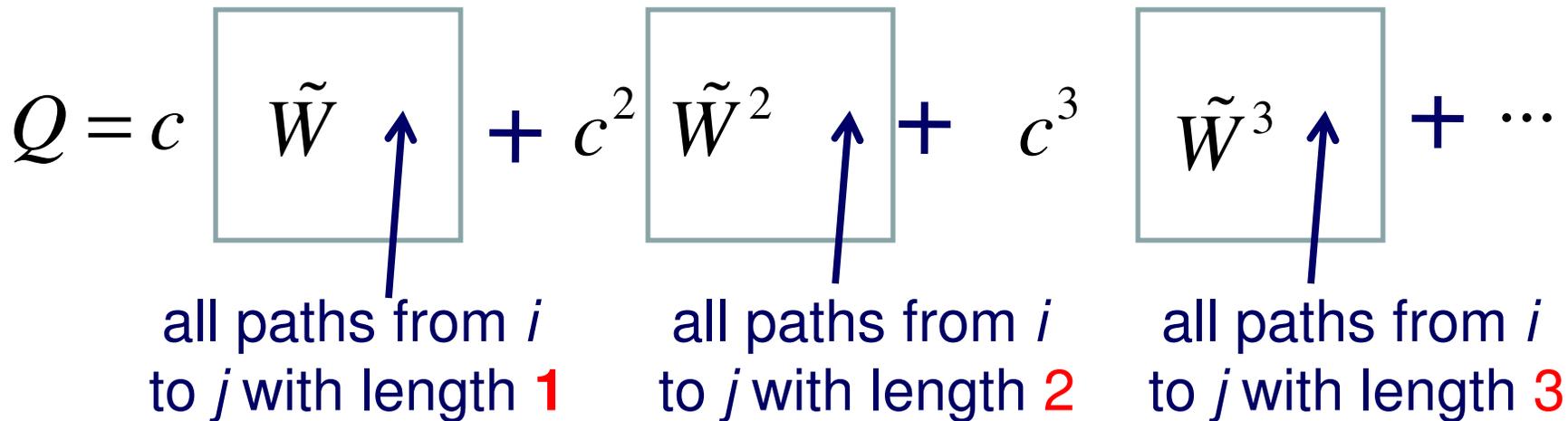


# Why RWR is a good score?

$$Q = (I - c\tilde{W})^{-1} =$$


$Q(i, j) \propto r_{i,j}$

$\tilde{W}$  : adjacency matrix.  
 c: damping factor

$$Q = c \tilde{W} + c^2 \tilde{W}^2 + c^3 \tilde{W}^3 + \dots$$


all paths from  $i$  to  $j$  with length **1**

all paths from  $i$  to  $j$  with length **2**

all paths from  $i$  to  $j$  with length **3**



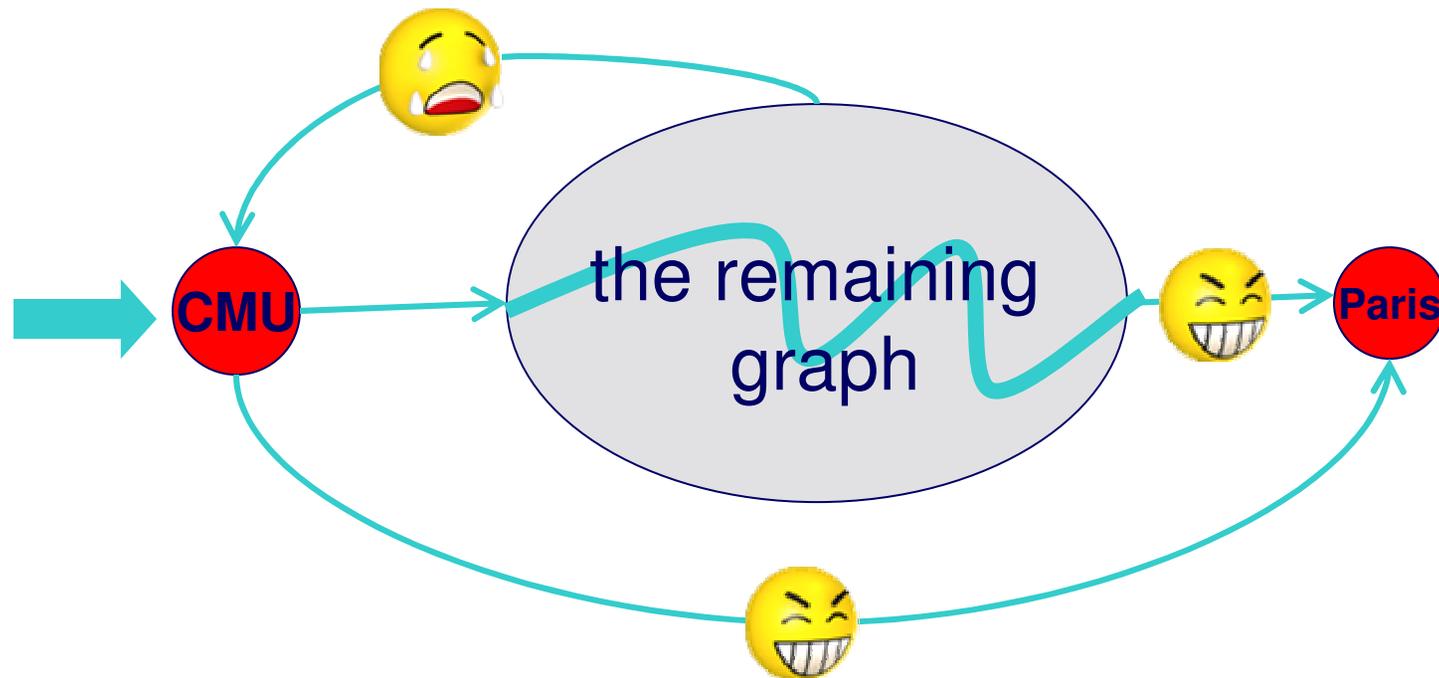
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  - ➔ – variants
- Efficient computation
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# Variant: escape probability

- Define Random Walk (RW) on the graph
- $\text{Esc\_Prob}(\text{CMU} \rightarrow \text{Paris})$ 
  - Prob (starting at CMU, reaches Paris before returning to CMU)





# Other Variants

- Other measure by RWs
  - Community Time/Hitting Time [Fouss+]
  - SimRank [Jeh+]
- Equivalence of Random Walks
  - Electric Networks:
    - EC [Doyle+]; SAEC[Faloutsos+]; CFEC[Koren+]
  - Spring Systems
- Katz [Katz], [Huang+], [Scholkopf+]
- Matrix-Forest-based Alg [Chobotarev+]



# Other Variants

- Other measure by RWs
  - Community Time/Hitting Time [Fouss+]
  - SimRank [Jeh+]

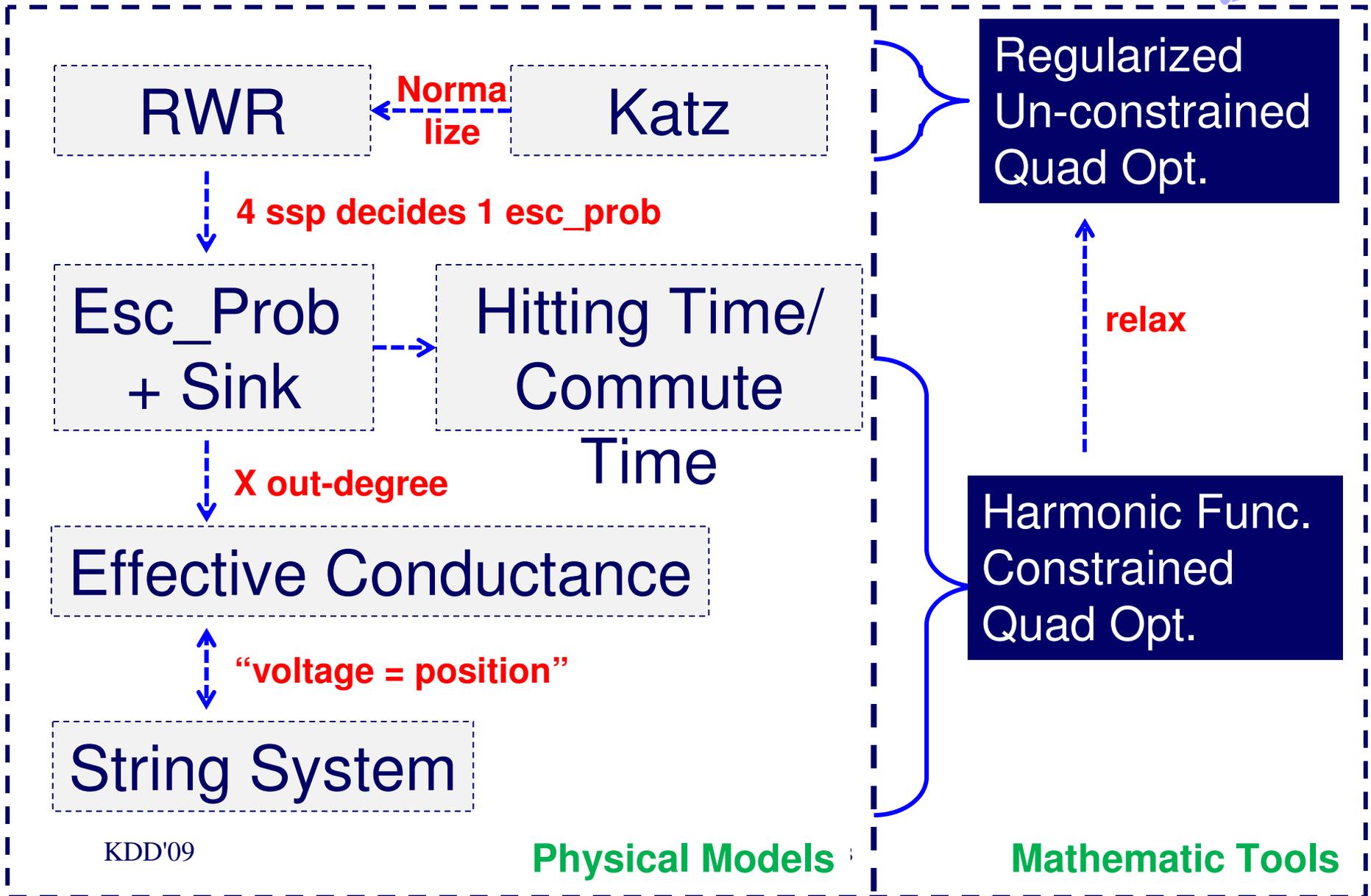
All are “related to” or “similar to”  
random walk with restart!

- Spring Systems
- Katz [Katz], [Huang+], [Scholkopf+]
- Matrix-Forest-based Alg [Chobotarev+]



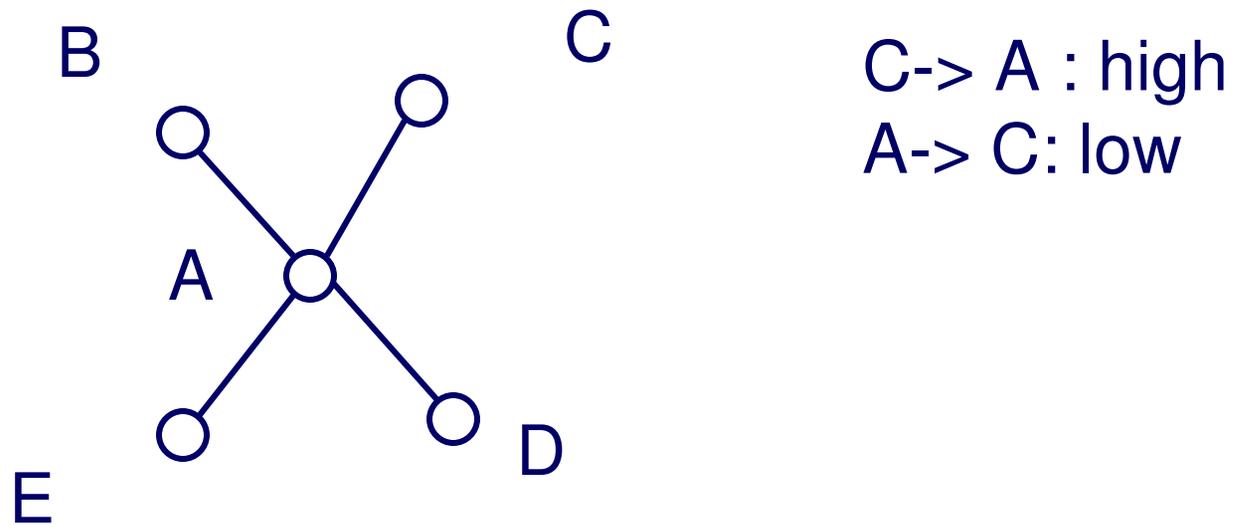
# Map of proximity measurements

details





# Notice: Asymmetry (even in undirected graphs)





# Summary of Proximity Definitions

- Goal: Summarize multiple relationships
- Solutions
  - **Basic**: Random Walk with Restarts
    - [Haweliwala'02] [Pan+ 2004][Sun+ 2006][Tong+ 2006]
  - **Properties**: Asymmetry
    - [Koren+ 2006][Tong+ 2007] [Tong+ 2008]
  - **Variants**: Esc\_Prob and many others.
    - [Faloutsos+ 2004] [Koren+ 2006][Tong+ 2007]



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# Preliminary: Sherman–Morrison Lemma

details

If:

$$\tilde{A} = A + u v^T$$

$$\tilde{A} = A + \begin{matrix} & & & \\ & & & \\ & & +3 & \\ & & & \end{matrix}$$



# Preliminary: Sherman–Morrison Lemma

details

If:

$$\tilde{A} = A + u \cdot v^T$$

Then:

$$\tilde{A}^{-1} = (A + u \cdot v^T)^{-1} = A^{-1} - \frac{A^{-1} \cdot u \cdot v^T A^{-1}}{1 + v^T \cdot A^{-1} \cdot u}$$



# Sherman – Morrison Lemma – intuition:

- Given a small perturbation on a matrix  
 $A \rightarrow A'$
- We can quickly update its inverse



# SM: The block-form

*details*

<b>A</b>	<b>B</b>
<b>C</b>	<b>D</b>

$$\begin{bmatrix} A & B \\ C & D \end{bmatrix}^{-1} = \begin{bmatrix} A^{-1} + A^{-1}B(D - CA^{-1}B)^{-1}CA^{-1} & -A^{-1}B(D - CA^{-1}B)^{-1} \\ -(D - CA^{-1}B)^{-1}CA^{-1} & (D - CA^{-1}B)^{-1} \end{bmatrix}$$

Or...

$$\begin{bmatrix} A & B \\ C & D \end{bmatrix}^{-1} = \begin{bmatrix} (A - BD^{-1}C)^{-1} & -A^{-1}B(D - CA^{-1}B)^{-1} \\ -D^{-1}C(A - BD^{-1}C)^{-1} & (D - CA^{-1}B)^{-1} \end{bmatrix}$$

And many other variants...

Also known as Woodbury Identity



# SM Lemma: Applications

- RLS (Recursive least squares)
  - and almost any algorithm in time series!
- Kalman filtering
- Incremental matrix decomposition
- ...
- ... and all the fast solutions we will introduce!

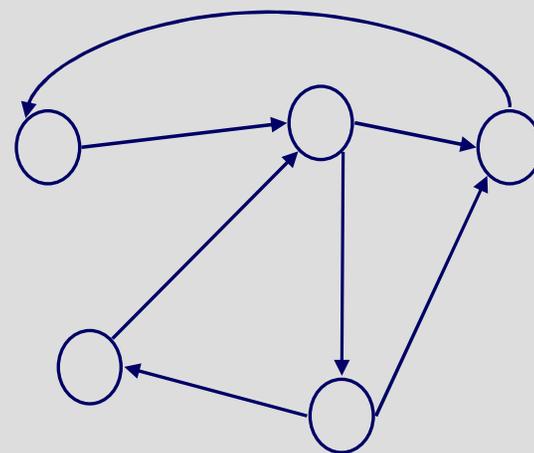
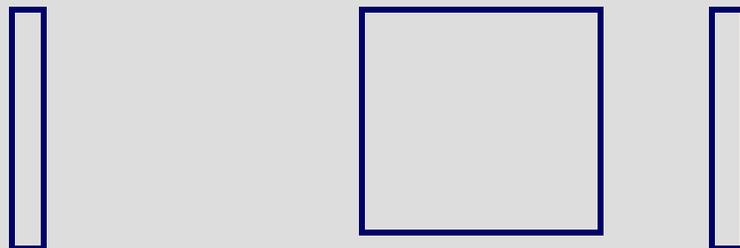


# Reminder: PageRank

- With probability  $1-c$ , fly-out to a random node
- Then, we have

$$\mathbf{p} = c \mathbf{B} \mathbf{p} + (1-c)/n \mathbf{1} \Rightarrow$$

$$\mathbf{p} = (1-c)/n [\mathbf{I} - c \mathbf{B}]^{-1} \mathbf{1}$$





$$\mathbf{p} = c \mathbf{B} \mathbf{p} + (1-c)/n \mathbf{1}$$

$$\vec{r}_i = c \tilde{W} \vec{r}_i + (1-c) \vec{e}_i$$

**The only  
difference**

Ranking vector

Adjacency matrix

Restart p

Starting vector



# Computing RWR

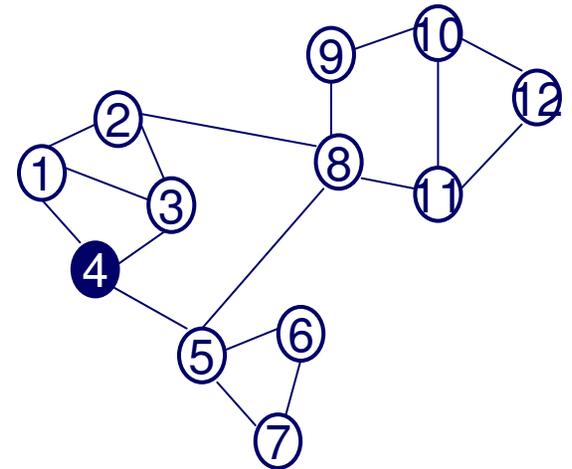
$$\mathbf{p} = c \mathbf{B} \mathbf{p} + (1-c)/n \mathbf{1}$$

$$\vec{r}_i = c \tilde{W} \vec{r}_i + (1-c) \vec{e}_i$$

Ranking vector      Adjacency matrix      Restart p      Starting vector

$$\begin{pmatrix} 0.13 \\ 0.10 \\ 0.13 \\ 0.22 \\ 0.13 \\ 0.05 \\ 0.05 \\ 0.08 \\ 0.04 \\ 0.03 \\ 0.04 \\ 0.02 \end{pmatrix} = 0.9 \times \begin{pmatrix} 0 & 1/3 & 1/3 & 1/3 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 1/3 & 0 & 1/3 & 0 & 0 & 0 & 0 & 1/4 & 0 & 0 & 0 & 0 \\ 1/3 & 1/3 & 0 & 1/3 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 1/3 & 0 & 1/3 & 0 & 1/4 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1/3 & 0 & 1/2 & 1/2 & 1/4 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1/4 & 0 & 1/2 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1/4 & 1/2 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1/3 & 0 & 0 & 1/4 & 0 & 0 & 0 & 1/2 & 0 & 1/3 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1/4 & 0 & 1/3 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1/2 & 0 & 1/3 & 1/2 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1/4 & 0 & 1/3 & 0 & 1/2 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1/3 & 1/3 & 0 \end{pmatrix} + 0.1 \times \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

$n \times 1$                        $n \times n$                        $n \times 1$





# Q: Given query $i$ , how to solve it?

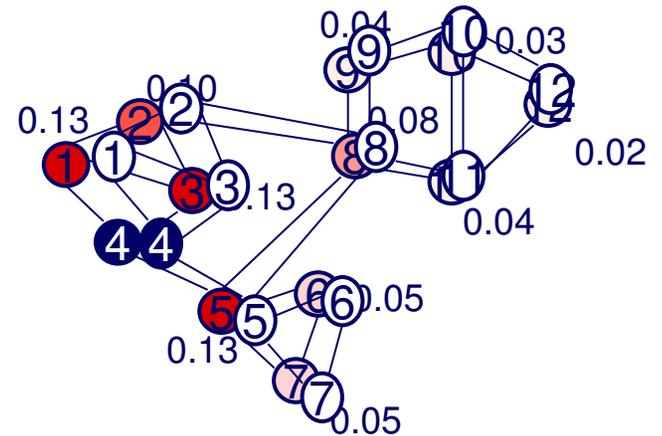
$$\begin{array}{c} \left. \begin{array}{c} \text{?} \\ \text{?} \end{array} \right\} \\ \text{Ranking vector} \end{array} = 0.9 \times \begin{array}{c} \left( \begin{array}{cccccccccccc} 0 & 1/3 & 1/3 & 1/3 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 1/3 & 0 & 1/3 & 0 & 0 & 0 & 0 & 1/4 & 0 & 0 & 0 & 0 \\ 1/3 & 1/3 & 0 & 1/3 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 1/3 & 0 & 1/3 & 0 & 1/4 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1/3 & 0 & 1/2 & 1/2 & 1/4 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1/4 & 0 & 1/2 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1/4 & 1/2 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1/3 & 0 & 0 & 1/4 & 0 & 0 & 0 & 1/2 & 0 & 1/3 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1/4 & 0 & 1/3 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1/2 & 0 & 1/3 & 1/2 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1/4 & 0 & 1/3 & 0 & 1/2 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1/3 & 1/3 & 0 \end{array} \right) \\ \text{Adjacency matrix} \end{array} \begin{array}{c} \left. \begin{array}{c} \text{?} \\ \text{?} \end{array} \right\} \\ \text{Ranking vector} \end{array} + 0.1 \times \begin{array}{c} \left( \begin{array}{c} 0 \\ 0 \\ 0 \\ 0 \\ 1 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{array} \right) \\ \text{Starting vector} \end{array} \quad \begin{array}{c} \leftarrow \text{Query} \\ \leftarrow \end{array}
 \end{array}$$



# OntheFly: $\vec{r}_i[t+1] = c\tilde{W}\vec{r}_i[t] + (1-c)\vec{e}_i$

$$\begin{pmatrix} 0.018 \\ 0.018 \\ 0.018 \\ 0.025 \\ 0.018 \\ 0.007 \\ 0.007 \\ 0.007 \\ 0.004 \\ 0.001 \\ 0.004 \\ 0.002 \end{pmatrix} = 0.9 \times \begin{pmatrix} 0 & 1/3 & 1/3 & 1/3 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 1/3 & 0 & 1/3 & 0 & 0 & 0 & 0 & 1/4 & 0 & 0 & 0 & 0 \\ 1/3 & 1/3 & 0 & 1/3 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 1/3 & 0 & 1/3 & 0 & 1/4 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1/3 & 0 & 1/2 & 1/2 & 1/4 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1/4 & 0 & 1/2 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1/4 & 1/2 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1/3 & 0 & 0 & 1/4 & 0 & 0 & 0 & 1/2 & 0 & 1/3 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1/4 & 0 & 1/3 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1/2 & 0 & 1/3 & 1/2 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1/4 & 0 & 1/3 & 0 & 1/2 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1/3 & 1/3 & 0 & 0 \end{pmatrix} \begin{pmatrix} 0.013 \\ 0.010 \\ 0.013 \\ 0.22 \\ 0.013 \\ 0.005 \\ 0.005 \\ 0.008 \\ 0.004 \\ 0.003 \\ 0.004 \\ 0.002 \end{pmatrix} + 0.1 \times \begin{pmatrix} 0 \\ 0 \\ 0 \\ 1 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

$\vec{r}_i$   $\tilde{W}$   $\vec{r}_i$   $\vec{e}_i$



No pre-computation/ light storage

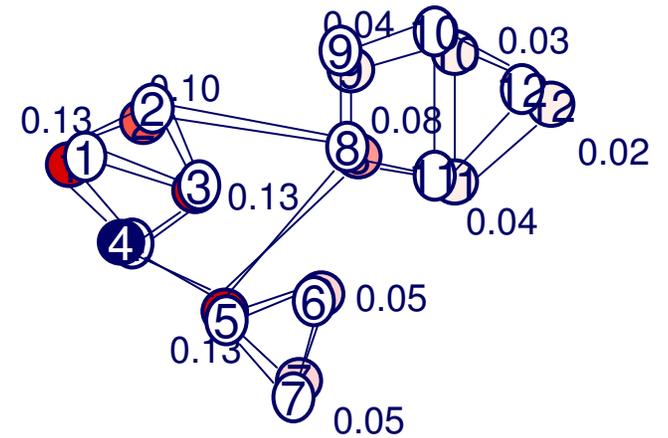


Slow on-line response  $O(mE)$



# PreCompute

**R:**



$$R = C \times Q$$

$$Q = (I - c\tilde{W})^{-1}$$

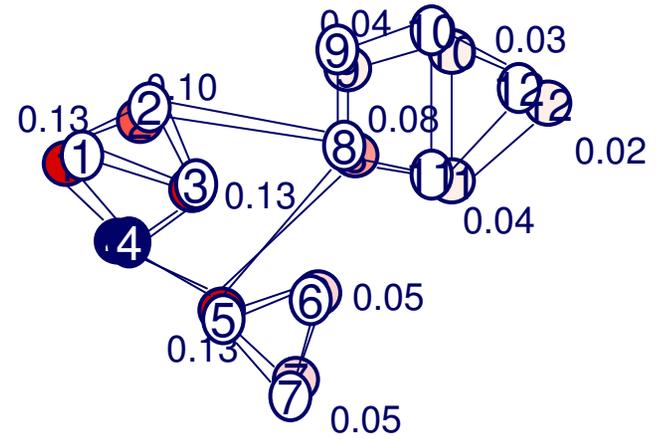
KDD 09

# PreCompute: $Q = (I - c\tilde{W})^{-1}$



$$Q = (I - c\tilde{W})^{-1}$$

0.13	1.29
0.10	0.96
0.13	1.29
0.22	2.06
0.13	1.27
0.05 ← 0.1x	0.52
0.05	0.52
0.08	0.82
0.04	0.28
0.03	0.34
0.04	0.38
0.02	0.21



Fast on-line response



Heavy pre-computation/storage cost

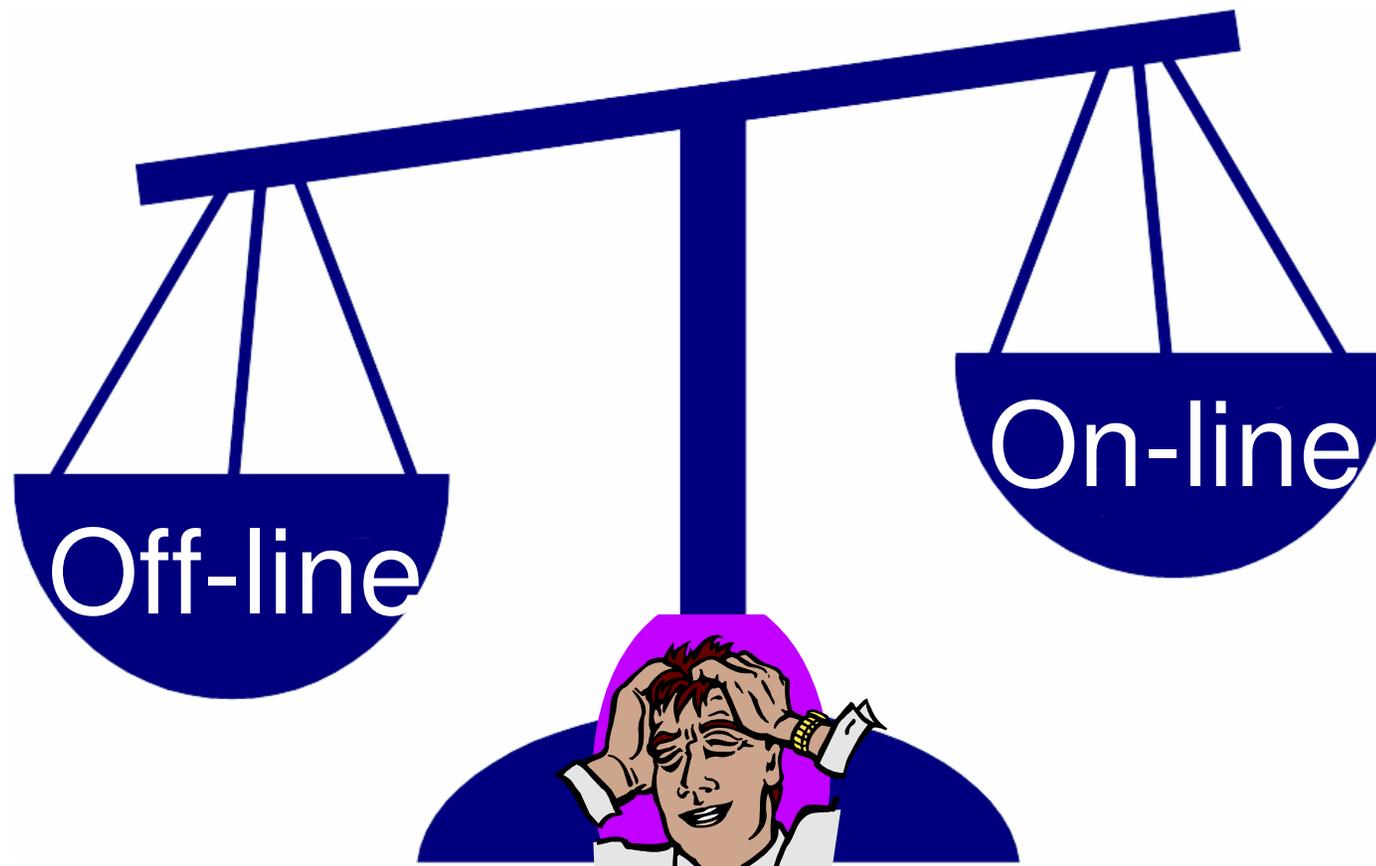
KD.

$O(n^3)$  iller, Tsourakakis

$O(n^2)$



# Q: How to Balance?





## How to balance?

### Idea ('B-Lin')

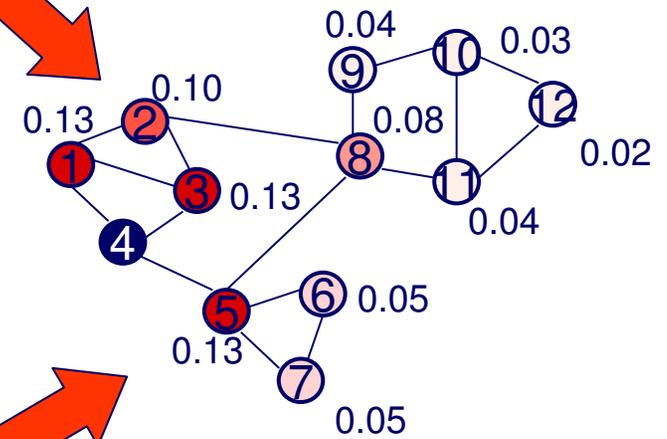
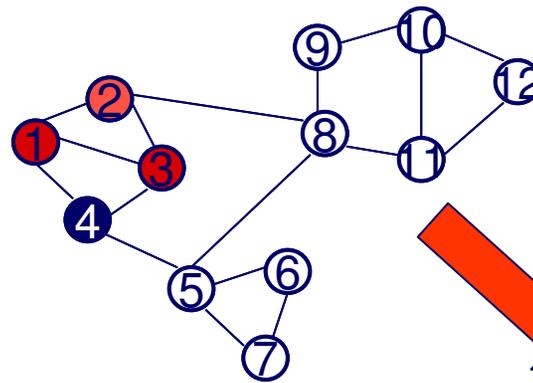
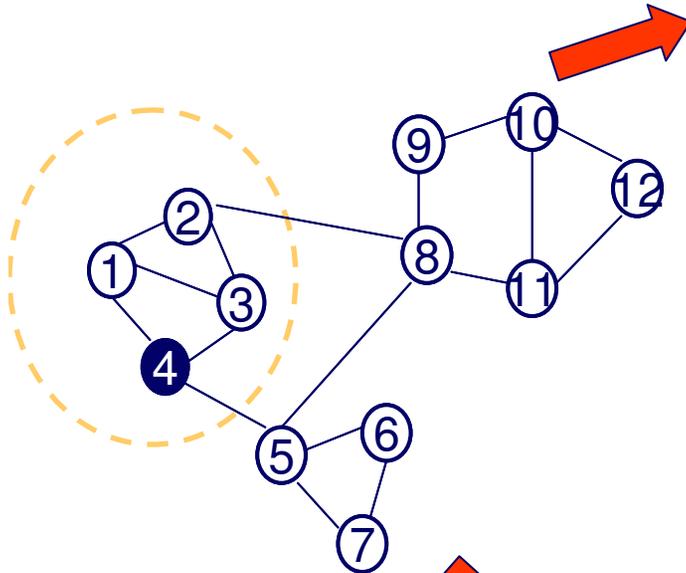
- Break into communities
- Pre-compute all, within a community
- Adjust (with S.M.) for 'bridge edges'

H. Tong, C. Faloutsos, & J.Y. Pan. *Fast Random Walk with Restart and Its Applications*. ICDM, 613-622, 2006.

# B\_Lin: Basic Idea

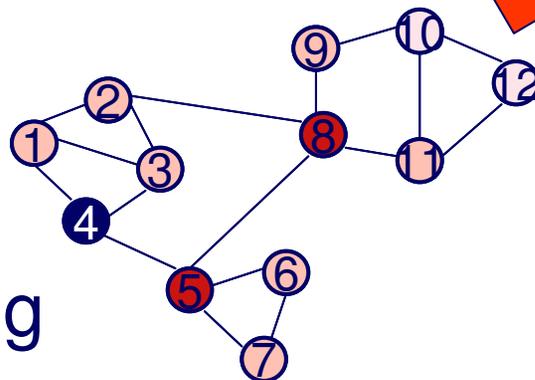
[Tong+ ICDM 2006]

Find Community



Combine

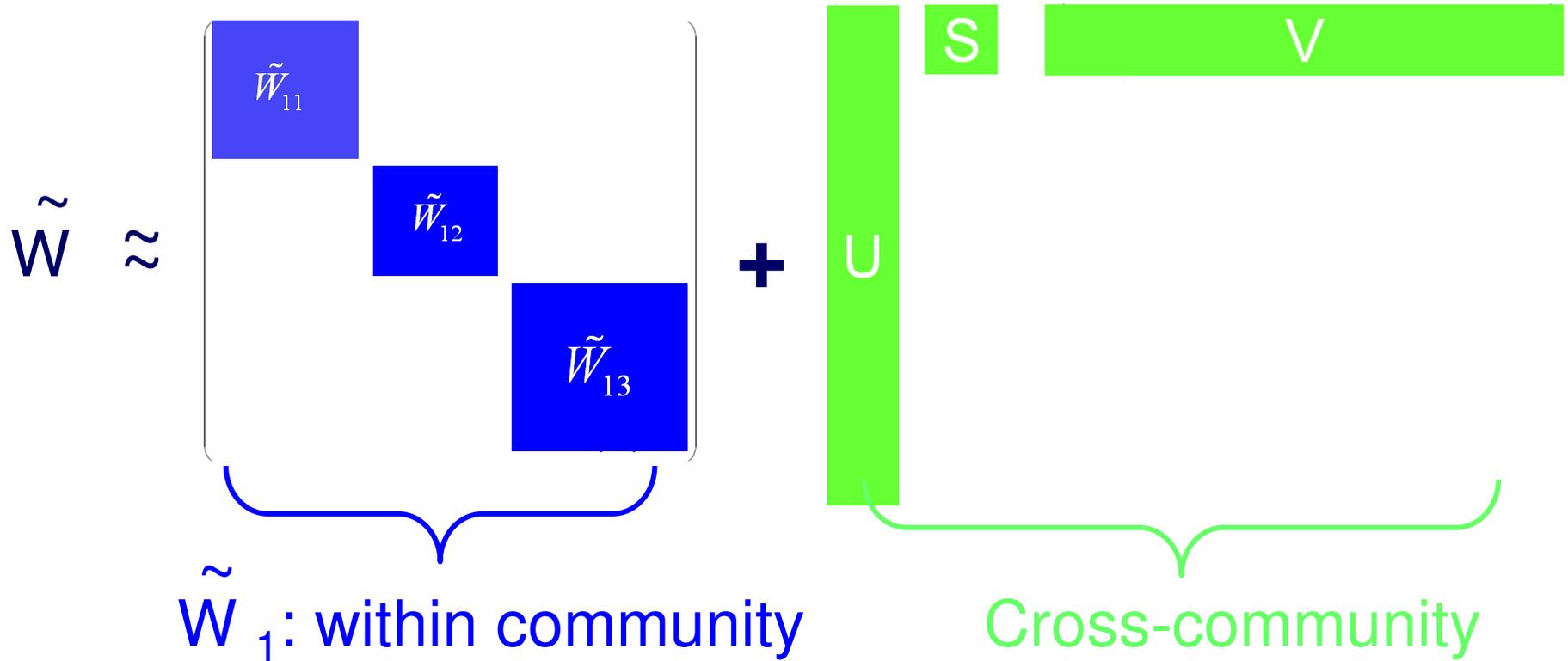
Fix the remaining





details

# B\_Lin: details



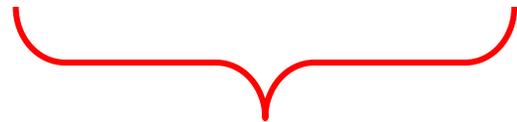


details

# B\_Lin: details

$$\left( I - c\tilde{W} \right)^{-1} \approx \left( \left[ I - c\tilde{W}_1 \right] - \left[ cUSV \right] \right)^{-1}$$

Easy to be inverted LRA difference



SM Lemma!

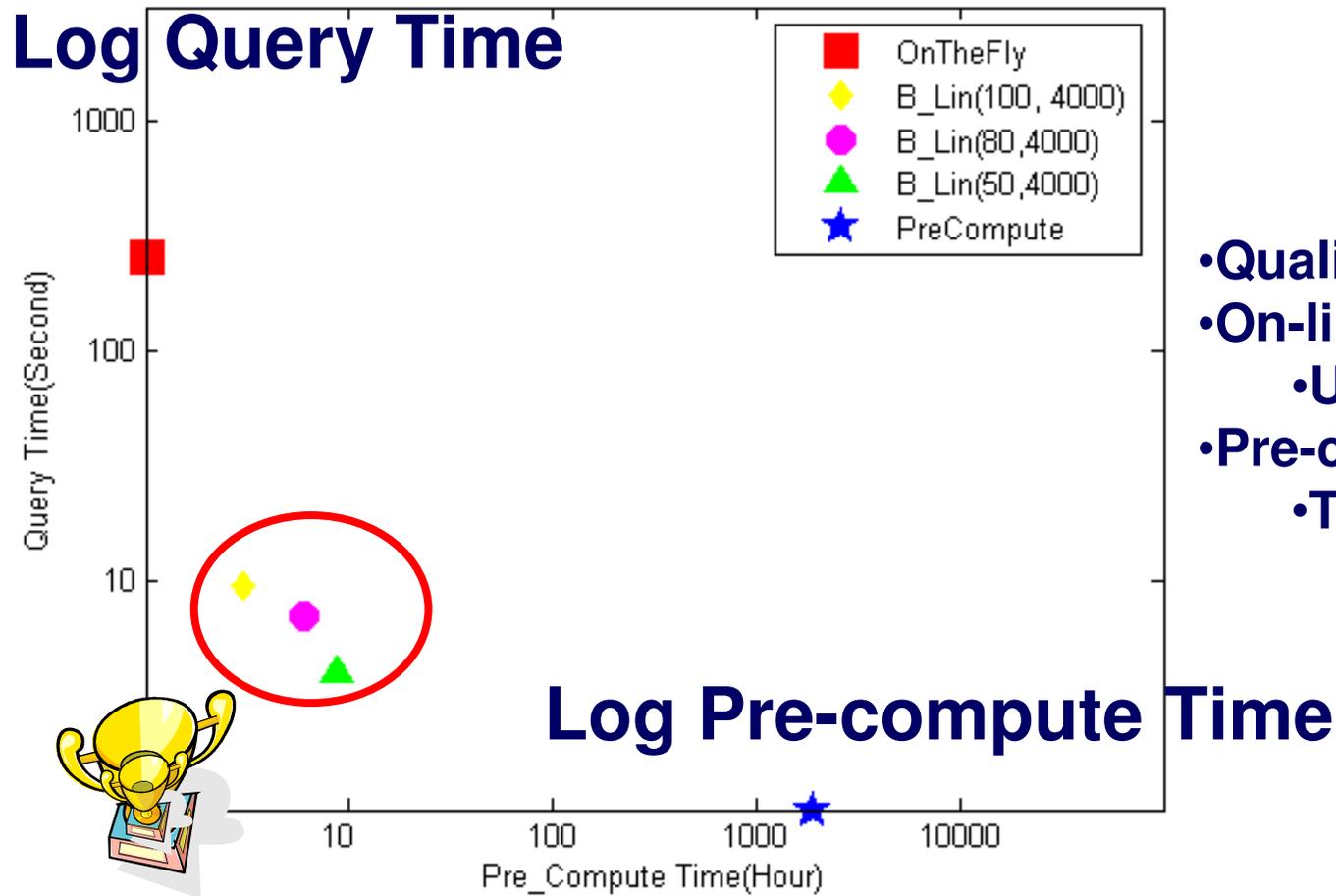


## B\_Lin: summary

- Pre-Computational Stage 
  - Q: Efficiently compute and store Q
  - A: A few small, instead of ONE BIG, matrices inversions
- On-Line Stage 
  - Q: Efficiently recover one column of Q
  - A: A few, instead of MANY, matrix-vector multiplications



# Query Time vs. Pre-Compute Time



- Quality: 90%+
- On-line:
  - Up to 150x speedup
- Pre-computation:
  - Two orders saving



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# gCaP: Automatic Image Caption

• Q



{Sea Sun Sky Wave}

...



{Cat Forest Grass Tiger}

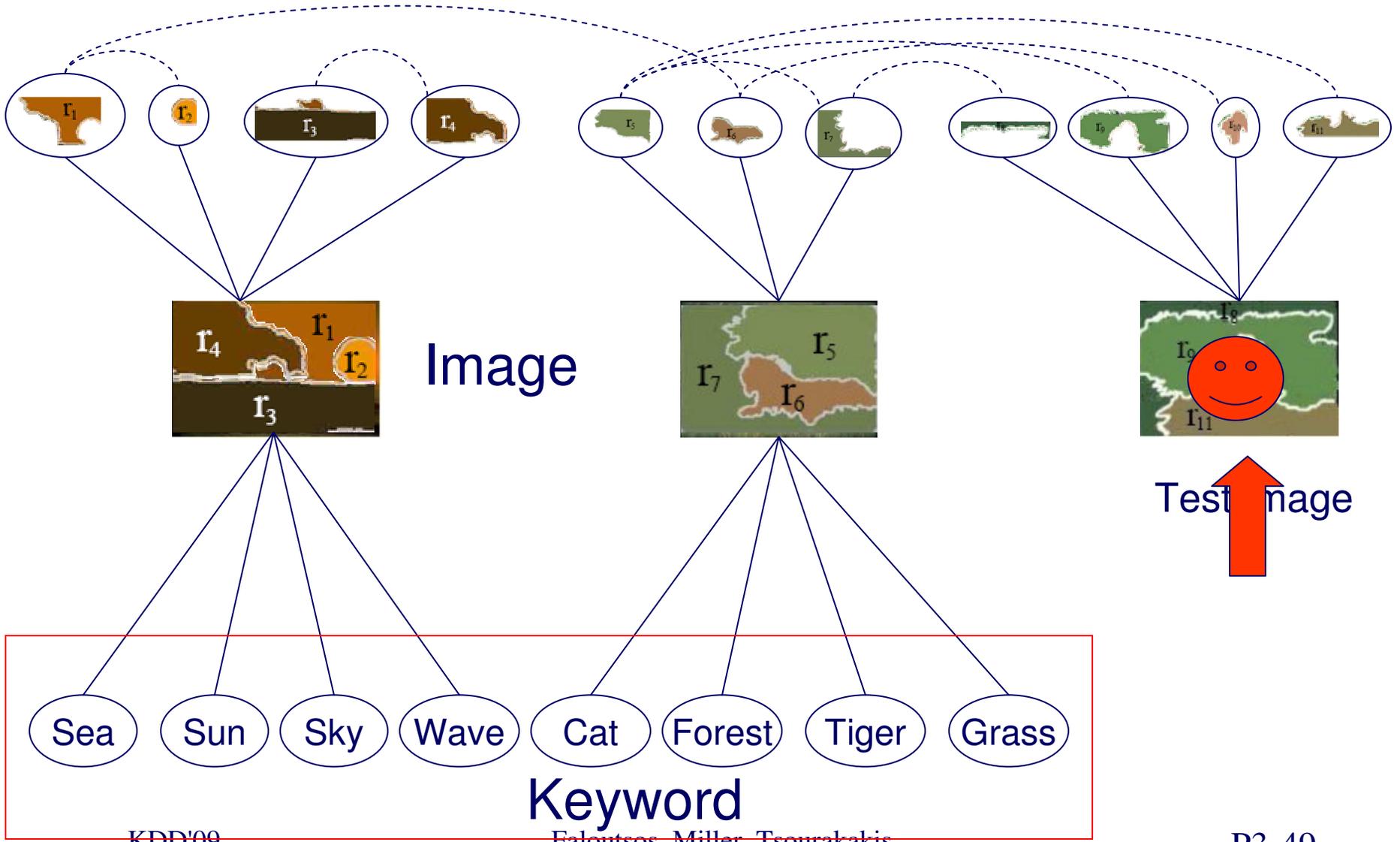


{?, ?, ?,}

A: Proximity!

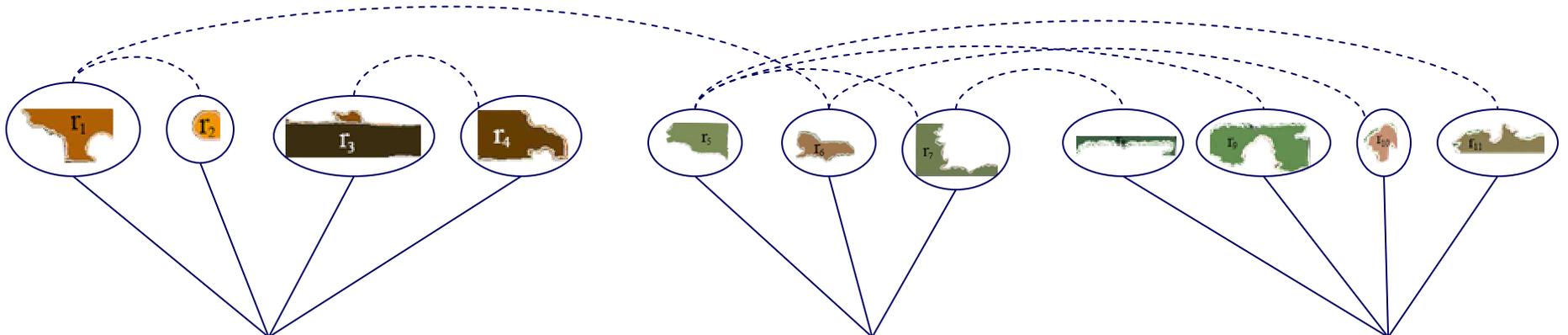
[Pan+ KDD2004]

# Region



Test Image 

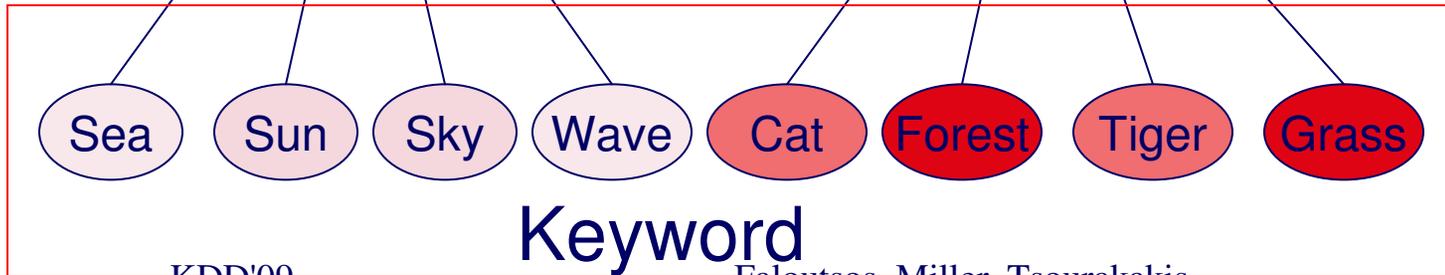
# Region



# Image



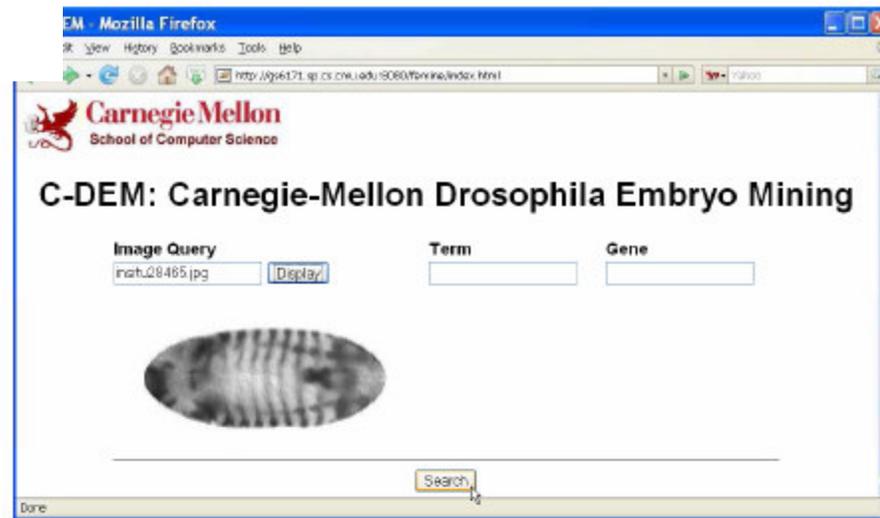
{Grass, Forest, Cage, Tiger}



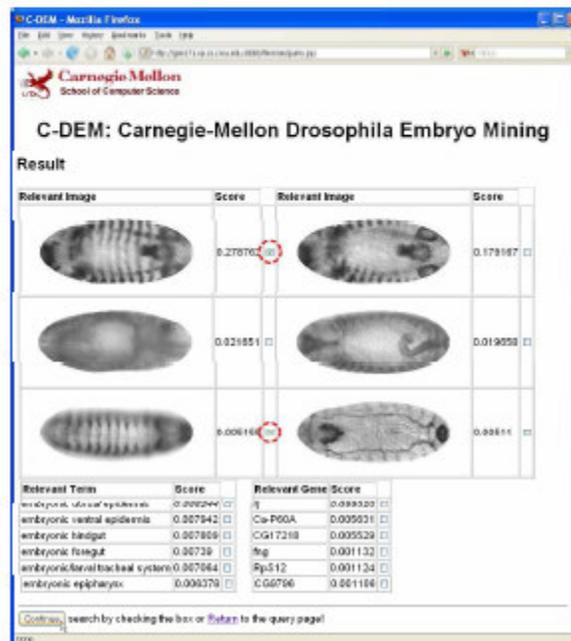
# Keyword

# C-DEM (Screen-shot)

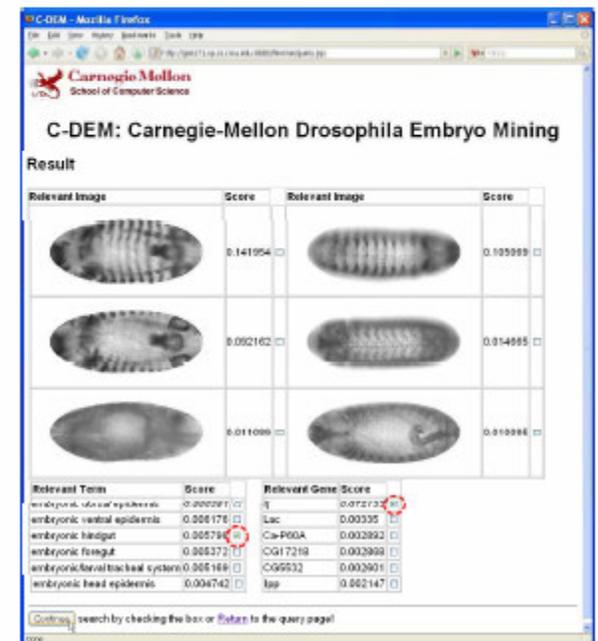
details



(a)



(b)

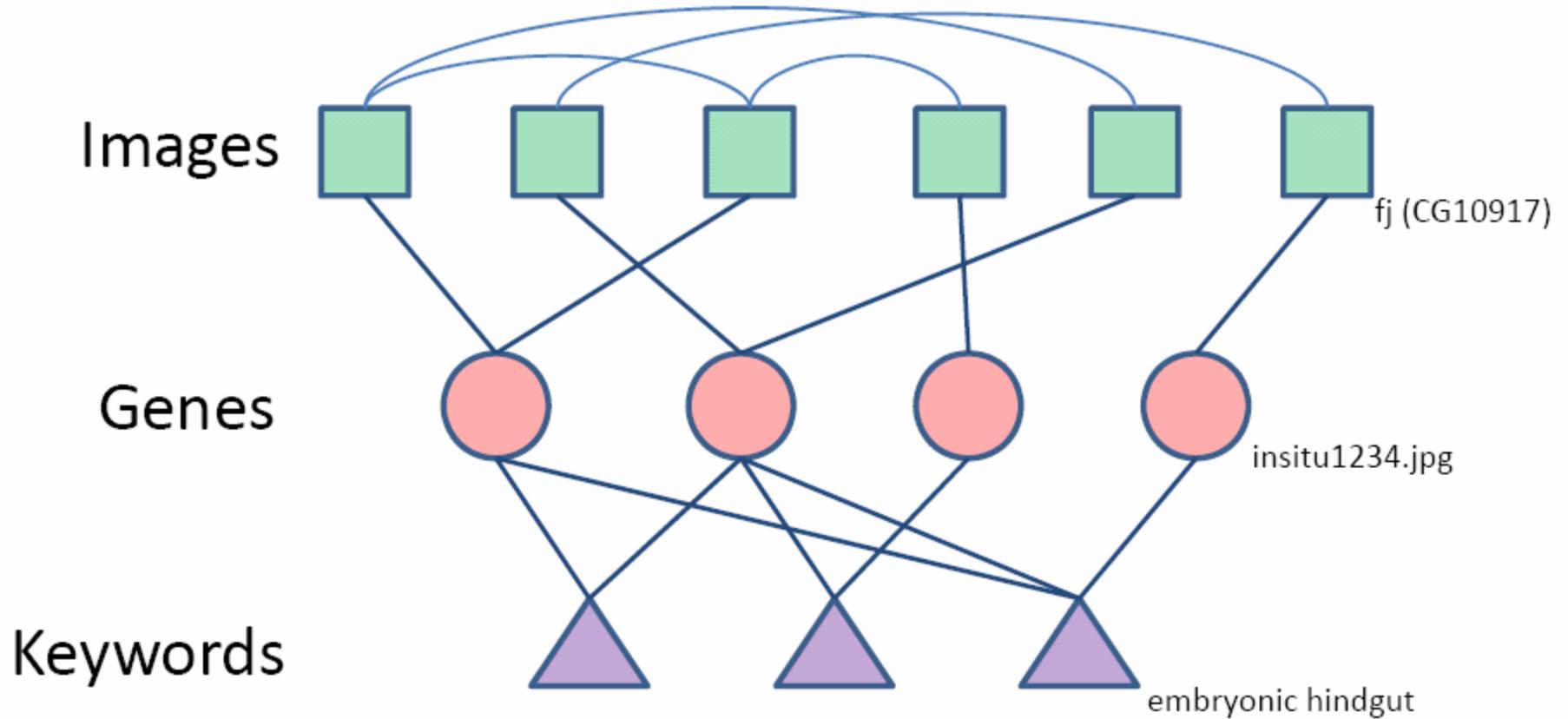


(c)



# C-DEM: Multi-Modal Query System for Drosophila Embryo Databases [Fan+ VLDB 2008]

details



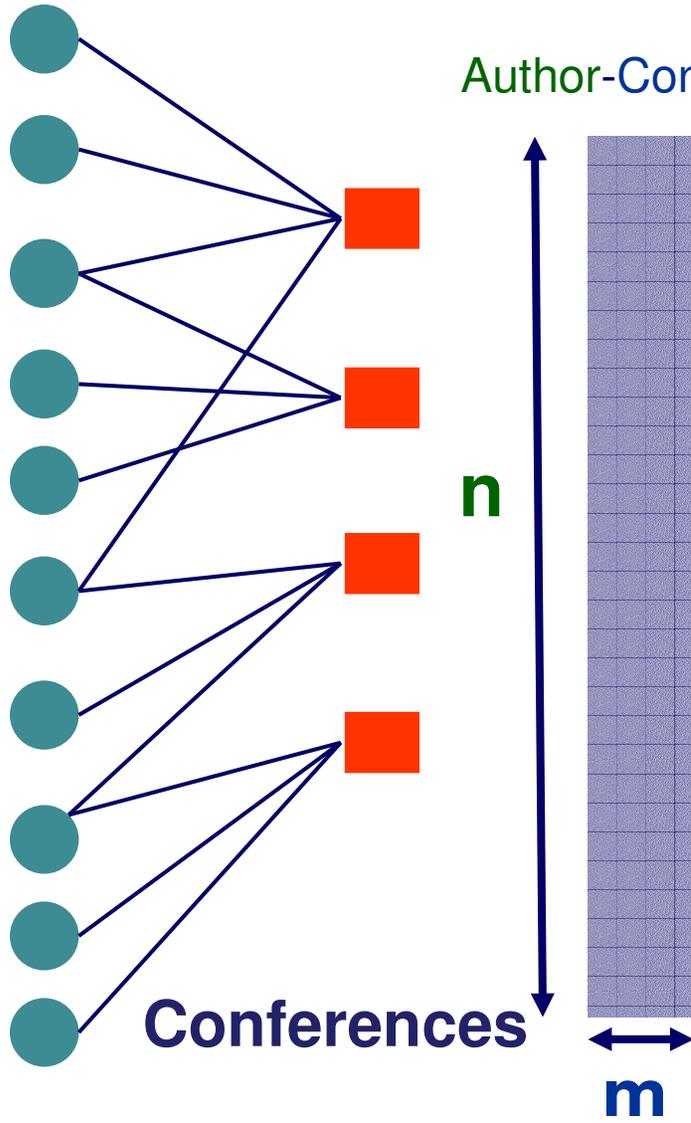


## Detailed outline

- Problem defn and motivation
- Solution: Random walk with restarts
- Efficient computation
- Case study: image auto-captioning
- ➔ • Extensions: **bi-partite graphs**; tracking
- Conclusions

# RWR on Bipartite Graph

authors



Author-Conf. Matrix

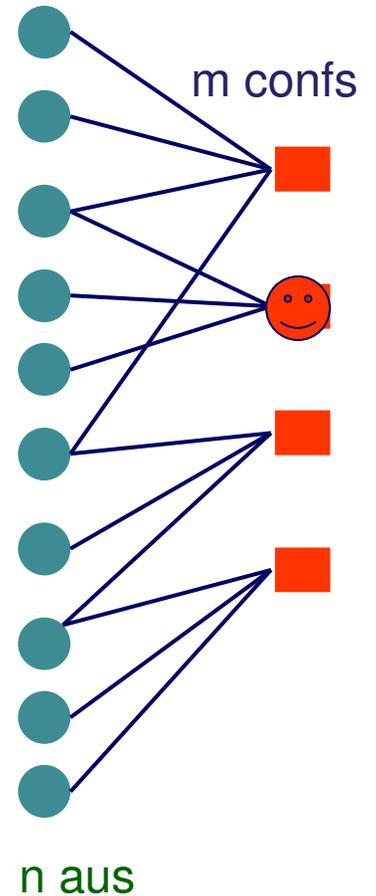
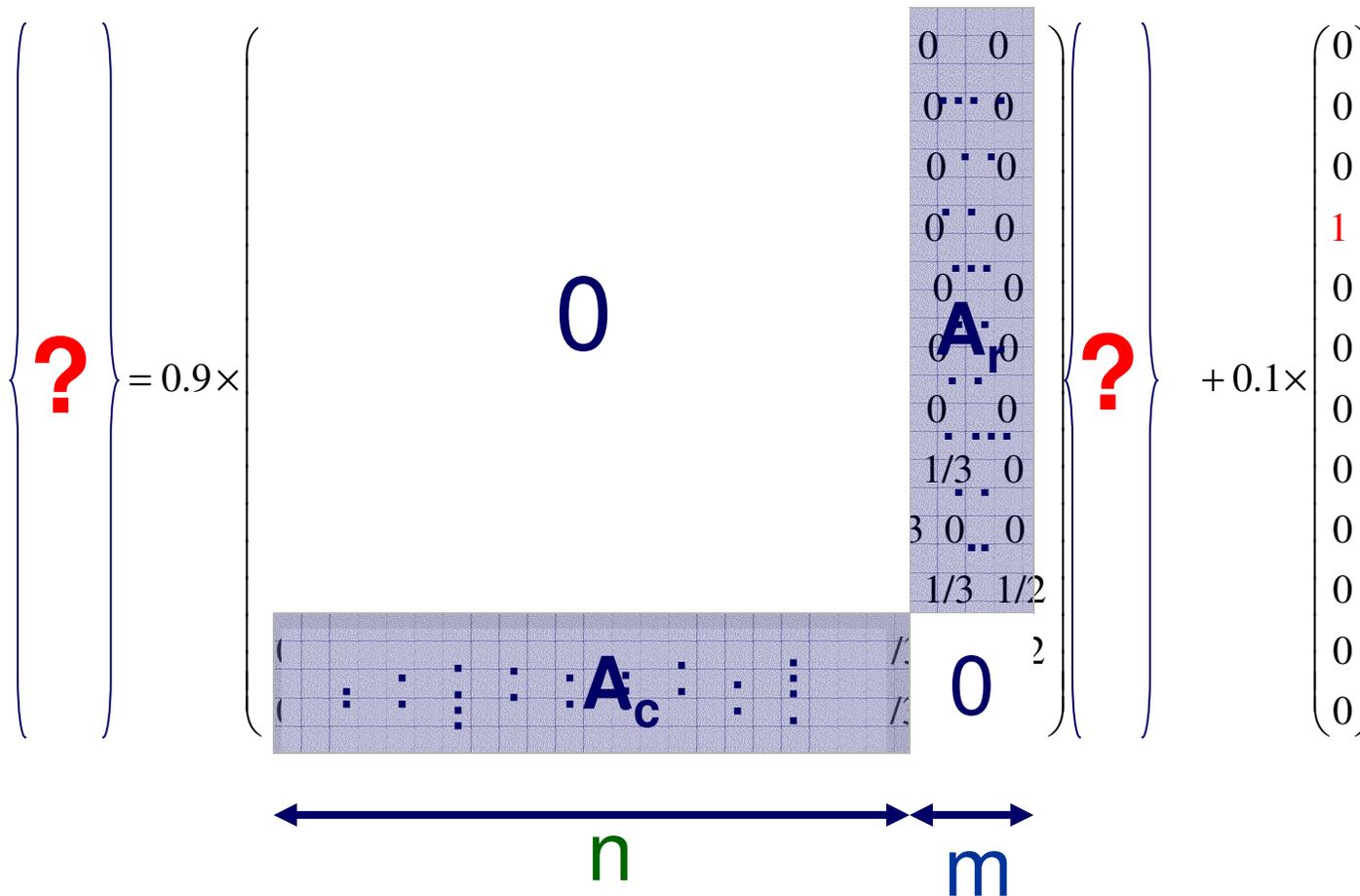
Observation:  $n \gg m!$

Examples:

1. DBLP: 400k aus, 3.5k confs
2. NetFlix: 2.7M usrs, 18k mvs

# RWR on Skewed bipartite graphs

- Q: Given query  $i$ , how to solve it?





## Idea:

- Pre-compute the smallest,  $m \times m$  matrix
- Use it to compute the rest proximities, on the fly

H. Tong, S. Papadimitriou, P.S. Yu & C. Faloutsos. *Proximity Tracking on Time-Evolving Bipartite Graphs*. SDM 2008.



# BB\_Lin: Examples

Dataset	Off-Line Cost	On-Line Cost
DBLP	a few minutes	frac. of sec.
NetFlix	1.5 hours	<0.01 sec.

400k authors  
x 3.5k conf.s

2.7m user  
x 18k movies



## Detailed outline

- Problem defn and motivation
- Solution: Random walk with restarts
- Efficient computation
- Case study: image auto-captioning
- ➔ • Extensions: bi-partite graphs; **tracking**
- Conclusions

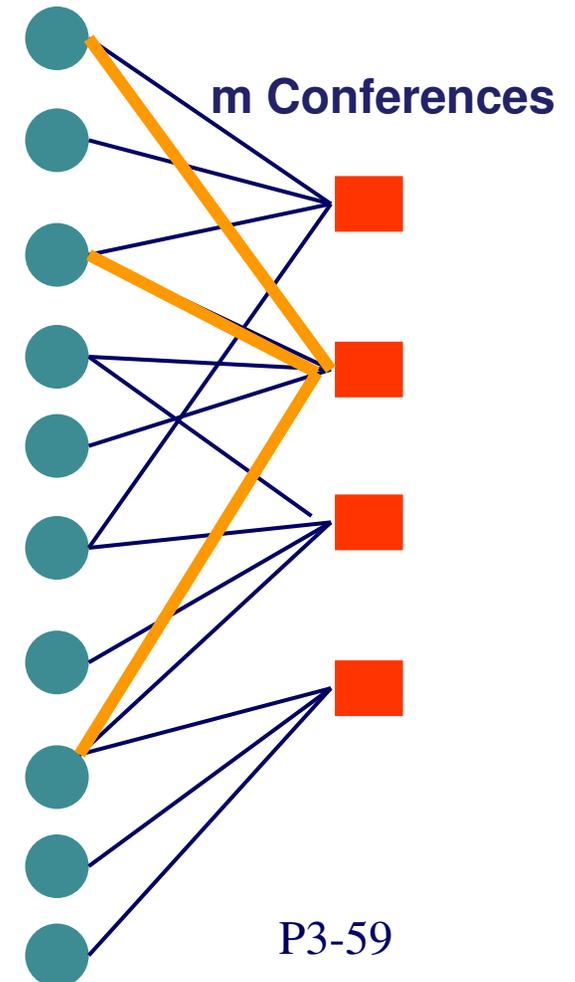


# Problem: update

**E'** edges changed

Involves  $n'$  authors,  $m'$  confs.

$n$  authors

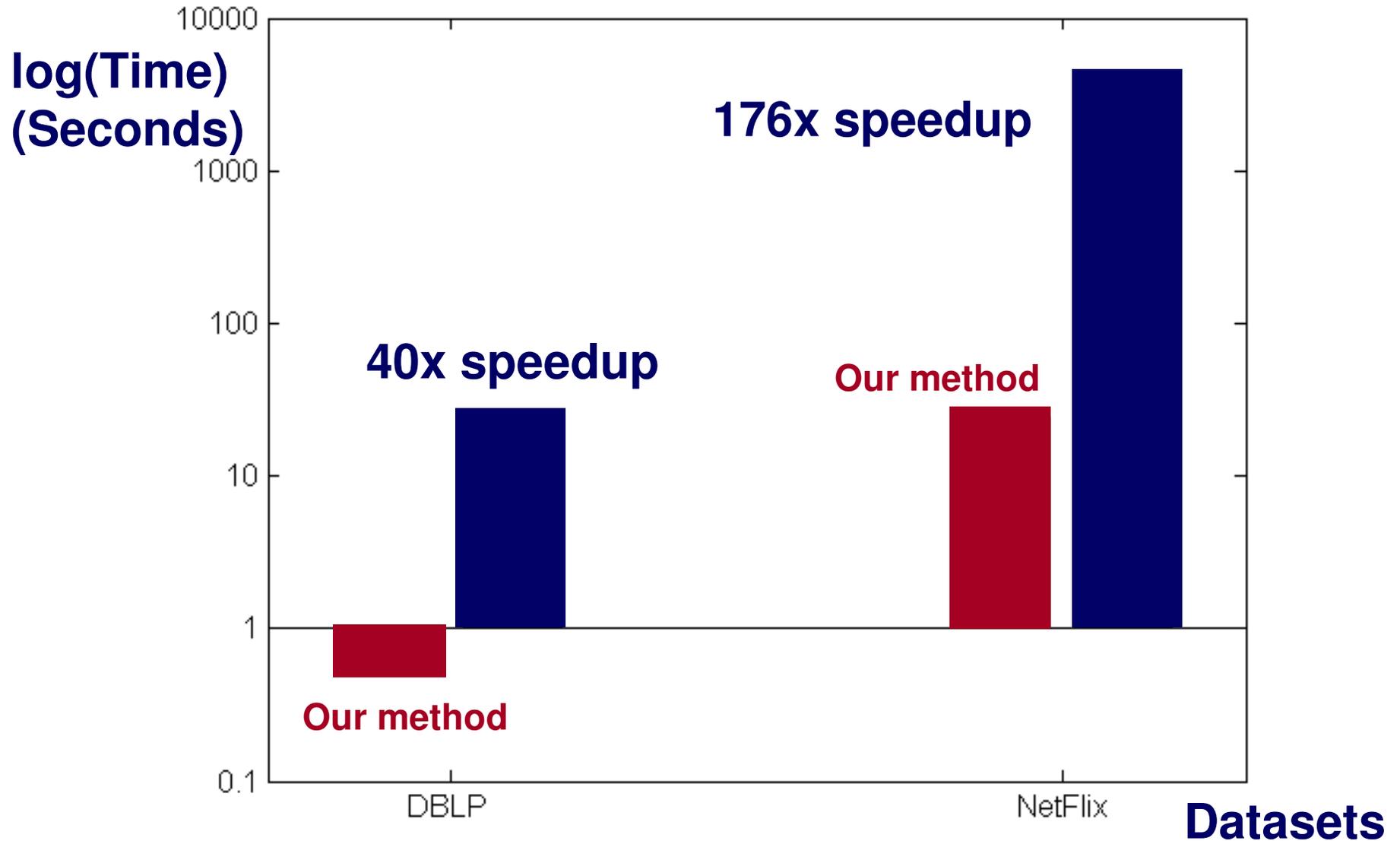




## Solution:

- Use Sherman-Morrison to quickly update the inverse matrix

# Fast-Single-Update





## pTrack: Philip S. Yu's Top 5 conferences up to each year

ICDE	CIKM	KDD	ICDM
ICDCS	ICDCS	SIGMOD	KDD
SIGMETRICS	ICDE	ICDM	ICDE
PDIS	SIGMETRICS	CIKM	SDM
VLDB	ICMCS	ICDCS	VLDB
1992	1997	2002	2007

DBLP: (Au. x Conf.)

- 400k aus,
- 3.5k confs
- 20 yrs



# pTrack: Philip S. Yu's Top 5 conferences up to each year

ICDE ICDCS SIGMETRICS PDIS VLDB	CIKM ICDCS ICDE SIGMETRICS ICMCS	KDD SIGMOD ICDM CIKM ICDCS	ICDM KDD ICDE SDM VLDB
1992	1997	2002	2007



Databases  
 Performance  
 Distributed Sys.

KDD'09

DBLP: (Au. x Conf.)  
 - 400k aus,  
 - 3.5k confs  
 - 20 yrs

Faloutsos, Miller, Tsourakakis



Databases  
 Data Mining

P3-63





# cTrack:10 most influential authors in NIPS community up to each year

## T. Sejnowski

1987	1989	1991	1993	1995	1997	1999
'Abbott_L'	'Bower_J'	'Hinton_G'	'Sejnowski_T'	'sejnowski_T'	'sejnowski_T'	'Sejnowski_T'
'Burr_D'	'Hinton_G'	'Koch_C'	'Koch_C'	'Jordan_M'	'Jordan_M'	'Koch_C'
'Denker_J'	'Tesauro_G'	'Bower_J'	'Hinton_G'	'Hinton_G'	'Koch_C'	'Jordan_M'
'Scofield_C'	'Denker_J'	'Sejnowski_T'	'Mozier_M'	'Koch_C'	'Hinton_G'	'Hinton_G'
'Bower_J'	'Mead_C'	'LeCun_Y'	'LeCun_Y'	'Mozier_M'	'Mozier_M'	'Mozier_M'
'Brown_N'	'Tenorio_M'	'Mozier_M'	'Denker_J'	'Bengio_Y'	'Dayan_P'	'Dayan_P'
'Carley_L'	'Sejnowski_T'	'Denker_J'	'Bower_J'	'Lippmann_R'	'Bengio_Y'	'Singh_S'
'Chou_P'	'Lippmann_R'	'Waibel_A'	'Kawato_M'	'LeCun_Y'	'Barto_A'	'Bengio_Y'
'Chover_J'	'Touretzky_D'	'Moody_J'	'Waibel_A'	'Waibel_A'	'Tresp_V'	'Tresp_V'
'Eeckman_F'	'Koch_C'	'Lippmann_R'	'Simard_P'	'Simard_P'	'Moody_J'	'Moody_J'

## M. Jordan

Author-paper bipartite graph from NIPS 1987-1999.

3k. 1740 papers, 2037 authors, spreading over 13 years



# Conclusions - Take-home messages

- **Proximity Definitions**

- RWR  $\vec{r}_i = c\tilde{W}\vec{r}_i + (1 - c)\vec{e}_i$
- and a lot of variants

- **Computation**

- Sherman–Morrison Lemma
- Fast Incremental Computation

- **Applications**

- Recommendations; auto-captioning; tracking
- Center-piece Subgraphs (next)
- E-mail management; anomaly detection, ...



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- H. Tong, S. Papadimitriou, P.S. Yu & C. Faloutsos. (2008) Proximity Tracking on Time-Evolving Bipartite Graphs. SDM 2008.



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- H. Tong, Y. Sakurai, T. Eliassi-Rad, and C. Faloutsos. Fast Mining of Complex Time-Stamped Events CIKM 08
- H. Tong, H. Qu, and H. Jamjoom. Measuring Proximity on Graphs with Side Information. ICDM 2008



## Resources

- [www.cs.cmu.edu/~htong/soft.htm](http://www.cs.cmu.edu/~htong/soft.htm)  
For software, papers, and ppt of presentations
- [www.cs.cmu.edu/~htong/tut/cikm2008/cikm\\_tutorial.html](http://www.cs.cmu.edu/~htong/tut/cikm2008/cikm_tutorial.html)  
For the CIKM'08 tutorial on graphs and proximity



Again, thanks to **Hanghang TONG** for permission to use his foils in this part