Coherent structures, turbulent cascades and regularity theory

Zoran Grujić University of Virginia

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*Energy cascades and flux locality in physical scales of the 3D NSE* (with R. Dascaliuc), Commun. Math. Phys. **305** (2011), 199–220.

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A geometric measure-type regularity criterion for solutions to the 3D Navier-Stokes equations (submitted to Arch. Rational Mech. Anal.) http://arxiv.org/abs/1111.0217

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"Half a century after Kolmogorov's work on the statistical theory of fully developed turbulence, we still wonder how his work can be reconciled with Leonardo's half a millennium old drawings of eddy motion in the study for the elimination of rapids in the river Arno."

- U. Frisch, Turbulence, The Legacy of A.N. Kolmogorov, 1994

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zero-step = finding a mathematical framework suitable for*encoding geometric information on the flow*in the theory of turbulent cascades

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 $R_0=$  the macro scale associated with the flow;  $B(0,2R_0)$  contained in  $\Omega$  (the global spatial domain)

 $x_0 \text{ in } B(0, R_0)$ 

 $0 < R \leq R_0$ 

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f = a locally integrable function (density) on  $B(x_0, 2R)$ 

a local physical scale R – associated to the point  $x_0$  – is realized via bounds on distributional derivatives of f,

$$|(D^{\alpha}f,\psi)| \leq \int_{B(x_{0},2R)} |f| |D^{\alpha}\psi| \leq \left(c(\alpha)\frac{1}{R^{|\alpha|}} |f|,\psi^{\delta(\alpha)}\right)$$

for some  $c(\alpha) > 0$  and  $\delta(\alpha)$  in (0,1)

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spatiotemporal cut-offs

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## spatiotemporal cut-offs

$$\begin{split} \phi &= \phi_{x_0,R,T} = \psi \,\eta \text{ on } B(x_0,2R) \times (0,T) \\ \text{where } \eta &= \eta_T(t) \in C^{\infty}(0,T) \text{ and } \psi = \psi_{x_0,R}(x) \in \mathcal{D}(B(x_0,2R)) \text{ satisfying} \\ 0 &\leq \eta \leq 1, \quad \eta = 0 \text{ on } (0,T/3), \quad \eta = 1 \text{ on } (2T/3,T), \quad \frac{|\eta'|}{\eta^{\rho_1}} \leq \frac{C}{T} \end{split}$$
(1)

and

$$0 \le \psi \le 1, \quad \psi = 1 \text{ on } B(x_0, R), \quad \frac{|\nabla \psi|}{\psi^{\rho_2}} \le \frac{C}{R}, \quad \frac{|\Delta \psi|}{\psi^{2\rho_2 - 1}} \le \frac{C}{R^2}, \quad (2)$$

$$\text{me } \frac{1}{2} \le \rho_1 \le \rho_2 \le 1$$

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for some  $\frac{1}{2} < \rho_1, \rho_2 < 1$ 

the case  $x_0 = 0$  and  $R = R_0$  corresponds to the macro scale domain cut-off  $\phi_0$ ,  $\phi_0 = \eta \psi_0$ 

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## ensemble averages; physical scales

for  $x_0$  near the boundary of the macro scale domain,  $S(0,R_0),$  assume additional conditions,

$$0 \le \psi \le \psi_0 \tag{3}$$

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and, if  $B(x_0, R)$  is not included in  $B(0, R_0)$ , then  $\psi \in \mathcal{D}(B(0, 2R_0))$  with  $\psi = 1$  on  $B(x_0, R) \cap B(0, R_0)$  satisfying, in addition to (2), the following:

 $\psi = \psi_0$  on the part of the cone centered at zero and passing through  $S(0, R_0) \cap B(x_0, R)$  between  $S(0, R_0)$  and  $S(0, 2R_0)$  (4)

and

 $\psi = 0$  on  $B(0, R_0) \setminus B(x_0, 2R)$  and outside the part of the cone centered at zero and passing through  $S(0, R_0) \cap B(x_0, 2R)$  (5) between  $S(0, R_0)$  and  $S(0, 2R_0)$  a physical scale R – associated to the macro scale domain  $B(0,R_0)$  – is realized via suitable ensemble-averaging of the localized quantities with respect to '( $K_1,K_2$ )-covers at scale R'

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a physical scale R – associated to the macro scale domain  $B(0,R_0)$  – is realized via suitable ensemble-averaging of the localized quantities with respect to '( $K_1,K_2$ )-covers at scale R'

let  $K_1$  and  $K_2$  be two positive integers, and  $0 < R \le R_0$ . a cover  $\{B(x_i, R)\}_{i=1}^n$  of  $B(0, R_0)$  is a  $(K_1, K_2)$ -cover at scale R if

$$\left(\frac{R_0}{R}\right)^3 \le n \le K_1 \left(\frac{R_0}{R}\right)^3,$$

and any point x in  $B(0, R_0)$  is covered by at most  $K_2$  balls  $B(x_i, 2R)$ 

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the parameters  $K_1 \mbox{ and } K_2$  represent the maximal global and local multiplicities, respectively

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for a physical density of interest f, consider time-averaged, per unit mass – spatially localized to the cover elements  $B(x_i, R)$  – local quantities  $\hat{f}_{x_i,R,T}$ ,

$$\hat{f}_{x_i,R,T} = \frac{1}{T} \int_0^T \frac{1}{R^3} \int_{B(x_i,2R)} f(x,t) \phi_{x_i,R,T}^{\delta}(x,t) \, dx \, dt$$

for some  $0 < \delta \leq 1$ , and denote by  $\langle F \rangle_R$  the *ensemble average* given by

$$\langle F \rangle_R = \frac{1}{n} \sum_{i=1}^n \hat{f}_{x_i,R,T}$$

the key feature of the ensemble averages  $\{\langle F\rangle_R\}_{0< R\leq R_0}$  is that  $\langle F\rangle_R$  being stable, i.e., nearly independent on a particular choice of the cover – with the fixed parameters  $K_1$  and  $K_2$  – indicates there are no significant sign-fluctuations of the density f at scales comparable or greater than R

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on the other hand, if f does exhibit significant sign-fluctuations at scales comparable or greater than R, suitable rearrangements of the cover elements up to the maximal multiplicities will result in the range of  $\langle F\rangle_R$  containing an interval of the form (-M,M) for a large M

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on the other hand, if f does exhibit significant sign-fluctuations at scales comparable or greater than  $R_{\rm r}$  suitable rearrangements of the cover elements up to the maximal multiplicities will result in the range of  $\langle F \rangle_R$  containing an interval of the form (-M,M) for a large M

consequently, for an *a priori* sign-varying density, the ensemble averaging process acts as a *coarse detector of the sign-fluctuations at scale* R (the larger the maximal multiplicities  $K_1$  and  $K_2$ , the finer detection)

as expected, for a non-negative density f, all the averages are comparable to each other throughout the full range of scales R,  $0 < R \leq R_0$ ; in particular, they are all comparable to the simple average over the macro scale domain

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$$\frac{1}{K_*}F_0 \le \langle F \rangle_R \le K_*F_0 \tag{6}$$

for all  $0 < R \leq R_0$ , where

$$F_0 = \frac{1}{T} \int \frac{1}{R_0^3} \int f(x,t) \phi_0^{\delta}(x,t) \, dx \, dt,$$

and  $K_* = K_*(K_1, K_2) > 1$ 

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more generally, the bound (6) holds for any non-negative distribution (integration replaced by duality); in fact, this was a key technical ingredient in the proof of existence of 3D inviscid cascade presented in [Dascaliuc and G., 2011]

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## geometric depletion of nonlinearity

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$$(\partial_t + u \cdot \nabla - \triangle)|\omega|^2 + |\nabla \omega|^2 = \alpha |\omega|^2$$

$$\alpha(x) = \frac{3}{4\pi} P.V. \int D\left(\hat{y}, \xi(x+y), \xi(x)\right) |\omega(x+y)| \frac{1}{|y|^3} \, dy,$$

where  $\hat{y}$  is the unit vector in the *y*-direction,  $\xi$  is the vorticity direction and the *geometric* kernel *D* is defined by

$$D(e_1, e_2, e_3) = (e_1 \cdot e_3) (e_1 \cdot (e_2 \times e_3))$$

for any triple of unit vectors  $e_1, e_2$  and  $e_3$ 

note that

$$|D\left(\hat{y},\xi(x+y),\xi(x)\right)| \le |\sin\varphi\big(\xi(x+y),\xi(x)\big)|$$

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and later in [Beirao da Veiga and Berselli, 2002] where the Lipschitz condition was replaced by  $\frac{1}{2}\text{-H\"older}$ 

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$$\int \frac{1}{2} |\omega(x,t)|^2 \psi(x) \, dx + \int_0^t \int |\nabla \omega|^2 \phi \, dx \, ds$$
$$= \int_0^t \int \frac{1}{2} |\omega|^2 (\phi_t + \Delta \phi) \, dx \, ds$$
$$+ \int_0^t \int \frac{1}{2} |\omega|^2 (u \cdot \nabla \phi) \, dx \, ds + \int_0^t \int (\omega \cdot \nabla) u \cdot \phi \omega \, dx \, ds \quad (7)$$

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suppressing the time variable, the localized vortex-stretching term can be written as

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(cf. [G., 2009])

$$\begin{split} (\omega \cdot \nabla) u \cdot \phi \omega \left( x \right) &= \phi^{\frac{1}{2}}(x) \frac{\partial}{\partial x_{i}} u_{j}(x) \phi^{\frac{1}{2}}(x) \omega_{i}(x) \omega_{j}(x) \\ &= -c \, P.V. \int_{B(x_{0}, 2r)} \epsilon_{jkl} \frac{\partial^{2}}{\partial x_{i} \partial y_{k}} \frac{1}{|x - y|} \phi^{\frac{1}{2}} \omega_{l} \, dy \, \phi^{\frac{1}{2}}(x) \, \omega_{i}(x) \, \omega_{j}(x) + \text{ LOT} \\ &= -c \, P.V. \int_{B_{(x_{0}, 2r)}} \left( \omega(x) \times \omega(y) \right) \cdot G_{\omega}(x, y) \, \phi^{\frac{1}{2}}(y) \, \phi^{\frac{1}{2}}(x) \, dy + \text{ LOT} \\ &= \text{ VST} + \text{ LOT} \end{split}$$
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(8)

where  $\epsilon_{jkl}$  is the Levi-Civita symbol,

$$\left(G_{\omega}(x,y)\right)_{k} = \frac{\partial^{2}}{\partial x_{i}\partial y_{k}} \frac{1}{|x-y|} \omega_{i}(x)$$

and LOT denotes the lower order terms

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geometric cancelations in the highest order-term VST were utilized in [G., 2009] to obtain a spatiotemporal localization of  $\frac{1}{2}$ -Hölder coherence of the vorticity direction regularity criterion

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and later in [G. and Guberović, 2010] to introduce a family of *scaling-invariant* regularity classes featuring a balance between coherence of the vorticity direction and the vorticity magnitude

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and later in [G. and Guberović, 2010] to introduce a family of *scaling-invariant* regularity classes featuring a balance between coherence of the vorticity direction and the vorticity magnitude

the following regularity class – a scaling-invariant improvement of  $\frac{1}{2}\text{-H\"older}$  coherence – is included,

$$\int_{t_0 - (2R)^2}^{t_0} \int_{B(x_0, 2R)} |\omega(x, t)|^2 \rho_{\frac{1}{2}, 2R}^2(x, t) dx \, dt < \infty; \tag{9}$$

$$\rho_{\gamma, r}(x, t) = \sup_{y \in B(x, r), y \neq x} \frac{|\sin \varphi(\xi(x, t), \xi(y, t))|}{|x - y|^{\gamma}}$$

let  $\mathcal{R}$  be a region contained in the global spatial domain  $\Omega$ . the inward enstrophy flux through the boundary of the region is given by

$$-\int_{\partial\mathcal{R}}\frac{1}{2}|\omega|^2(u\cdot n)\,d\sigma = -\int_{\mathcal{R}}(u\cdot\nabla)\omega\cdot\omega\,dx$$

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localization of evolution of the enstrophy to cylinder  $B(x_0,2R)\times(0,T)$  leads to the following version of the enstrophy flux,

$$\int \frac{1}{2} |\omega|^2 (u \cdot \nabla \phi) \, dx = -\int (u \cdot \nabla) \omega \cdot \phi \omega \, dx \tag{10}$$

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since  $\nabla \phi = (\nabla \psi)\eta$ , and  $\psi$  can be constructed such that  $\nabla \psi$  points inward, (10) represents *local inward enstrophy flux, at scale* R (more precisely, through the layer  $S(x_0, R, 2R)$ ) around the point  $x_0$ 

considering a  $(K_1, K_2)$ -cover  $\{B(x_i, R)\}_{i=1}^n$  at scale R, for some  $0 < R \le R_0$ , local inward enstrophy fluxes at scale R – associated to the cover elements  $B(x_i, R)$  – are then given by

$$\int \frac{1}{2} |\omega|^2 (u \cdot \nabla \phi_i) \, dx,\tag{11}$$

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for  $1 \leq i \leq n$ 

assuming smoothness on (0, T), the identity (7) written for  $B(x_i, R)$  yields the following expression for time-integrated local fluxes,

$$\int_0^t \int \frac{1}{2} |\omega|^2 (u \cdot \nabla \phi_i) \, dx \, ds = \int \frac{1}{2} |\omega(x,t)|^2 \psi_i(x) \, dx + \int_0^t \int |\nabla \omega|^2 \phi_i \, dx \, ds$$
$$- \int_0^t \int \frac{1}{2} |\omega|^2 ((\phi_i)_s + \Delta \phi_i) \, dx \, ds$$
$$- \int_0^t \int (\omega \cdot \nabla) u \cdot \phi_i \, \omega \, dx \, ds, \tag{12}$$

for any t in (2T/3,T) and  $1\leq i\leq n$ 

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denoting the time-averaged local fluxes per unit mass associated to the cover element  $B(x_i,R)$  by  $\hat{\Phi}_{x_i,R}\text{,}$ 

$$\hat{\Phi}_{x_i,R} = \frac{1}{t} \int_0^t \frac{1}{R^3} \int \frac{1}{2} |\omega|^2 (u \cdot \nabla \phi_i) \, dx,\tag{13}$$

the main quantity of interest is the ensemble average of  $\{\hat{\Phi}_{x_i,R}\}_{i=1}^n$  ,

$$\langle \Phi \rangle_R = \frac{1}{n} \sum_{i=1}^n \hat{\Phi}_{x_i,R} \tag{14}$$

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the goal is to formulate a set of physically reasonable conditions on the flow in  $B(0,2R_0) \times (0,T)$  implying the strict positivity and stability of  $\langle \Phi \rangle_R$  across a suitable range of scales – *existence of the enstrophy cascade* 

## (A1) Coherence Assumption

let M > 0 (large). assume that there exists a positive constant  $C_1$  such that

 $|\sin \varphi (\xi(x,t),\xi(y,t))| \le C_1 |x-y|^{\frac{1}{2}}$ 

 $\text{for any } (x,y,t) \text{ in } \left(B(0,2R_0)\times B(0,2R_0+R_0^{\frac{2}{3}})\times (0,T)\right)\cap\{|\nabla u|>M\}$ 

### (A1) Coherence Assumption

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note that the previous local regularity results [G. and Zhang, 2006, G., 2009] imply that – under (A1) – the *a priori* weak solution in view is in fact smooth inside  $B(0, 2R_0) \times (0, T)$  and can, moreover, be smoothly continued (locally-in-space) past t = T; in particular, we can write (12) with t = T

#### (A2) Modified Kraichnan Scale

denote by  $E_0$  time-averaged enstrophy per unit mass associated with the integral domain  $B(0,2R_0)\times (0,T),$ 

$$E_0 = \frac{1}{T} \int \frac{1}{R_0^3} \int \frac{1}{2} |\omega|^2 \phi_0^{2\rho-1} \, dx \, dt,$$

by  $P_0$  a modified time-averaged palinstrophy per unit mass,

$$P_0 = \frac{1}{T} \int \frac{1}{R_0^3} \int |\nabla \omega|^2 \phi_0 \, dx \, dt + \frac{1}{T} \frac{1}{R_0^3} \int \frac{1}{2} |\omega(x,T)|^2 \psi_0(x) \, dx$$

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(A2) is a requirement that the modified Kraichnan scale associated with the integral domain  $B(0,2R_0) \times (0,T)$  be dominated by the integral scale,

$$\sigma_0 < \beta R_0$$

for a suitable constant  $\beta = \beta(\rho, K_1, K_2, M, B_T)$ ,  $0 < \beta < 1$ , where  $B_T = \sup_{t \in (0,T)} \|\omega(t)\|_{L^1}$ ; this is finite provided, e.g.,  $\omega_0$  in  $L^1$  [Constantin, 1990]

# (A3) Localization of the Integral Domain and Modulation

the general set up considered is one of the Leray solutions satisfying (A1). as already mentioned, (A1) implies smoothness; however, the control on regularity-type norms is only local

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on the other hand, the energy inequality on the global spatiotemporal domain  $\mathbb{R}^3 \times (0,T)$  implies  $\int_0^T \int_{\mathbb{R}^3} |\omega|^2 \, dx \, dt < \infty$ ; localization of the integral domain will be determined by the condition

$$\int_0^T \int_{B(0,2R_0+R_0^{\frac{2}{3}})} |\omega|^2 \, dx \, dt \le \frac{1}{C_2},$$

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the modulation assumption on the evolution of local enstrophy on (0,T) – consistent with the choice of the temporal cut-off  $\eta$  – reads

$$\int |\omega(x,T)|^2 \psi_0(x) \, dx \ge \frac{1}{2} \sup_{t \in (0,T)} \int |\omega(x,t)|^2 \psi_0(x) \, dx$$

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## Theorem

Let u be a Leray solution on  $\mathbb{R}^3 \times (0,T)$  satisfying (A1)-(A3) on the spatiotemporal integral domain  $B(0, 2R_0 + R_0^{\frac{2}{3}}) \times (0,T)$ , and suppose that  $\omega_0$  is in  $L^1(\mathbb{R}^3)$ . Then,

$$\frac{1}{4K_*}P_0 \le \langle \Phi \rangle_R \le 4K_* \ P_0$$

for all R,  $\frac{1}{\beta}\sigma_0 \leq R \leq R_0$ .

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denoting the time-averaged local fluxes associated to the cover element  $B(x_i,R)$  by  $\hat{\Psi}_{x_i,R},$ 

$$\hat{\Psi}_{x_i,R} = \frac{1}{T} \int_0^T \int \frac{1}{2} |\omega|^2 (u \cdot \nabla \phi_i) \, dx, \tag{15}$$

the (time and ensemble) averaged flux is given by

$$\langle \Psi \rangle_R = \frac{1}{n} \sum_{i=1}^n \hat{\Psi}_{x_i,R} = R^3 \langle \Phi \rangle_R \tag{16}$$

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the following locality result is a simple consequence of the universality of the cascade of the time and ensemble-averaged local fluxes *per unit mass*  $\langle \Phi \rangle_R$  presented in the previous theorem

#### Theorem

Let u be a Leray solution on  $\mathbb{R}^3 \times (0,T)$  satisfying (A1)-(A3) on the spatiotemporal integral domain  $B(0, 2R_0 + R_0^{\frac{2}{3}}) \times (0,T)$ , and suppose that  $\omega_0$  is in  $L^1(\mathbb{R}^3)$ . Let R and r be two scales within the inertial range delineated in the previous theorem. Then

$$\frac{1}{16K_*^2} \left(\frac{r}{R}\right)^3 \le \frac{\langle \Psi \rangle_r}{\langle \Psi \rangle_R} \le 16K_*^2 \left(\frac{r}{R}\right)^3.$$

In particular, if  $r = 2^k R$  for some integer k, i.e., through the dyadic scale,

$$\frac{1}{16K_*^2} \ 2^{3k} \le \frac{\langle \Psi \rangle_{2^k R}}{\langle \Psi \rangle_R} \le 16K_*^2 \ 2^{3k}.$$

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previous locality results include locality of the filtered flux – via coarse graining approach – presented in [Eyink, 2005] and [Eyink and Aluie, 2009], and locality of the flux in the Littlewood-Paley setting obtained in [Cheskidov, Constantin, Friedlander and Shvydkoy, 2008]

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(ii) let f be analytic in  $\Omega \setminus K$ ,  $|f| \leq M$ , and  $|f| \leq m$  on K. then

 $|f(z)| \le m^{\theta} M^{1-\theta}$ 

for any z in  $\Omega \setminus K$ , where  $\theta = \omega(z, \Omega, K)$  [this a refined form of the maximum modulus principle for analytic functions in  $\Omega \setminus K$  (the log-convexity of the modulus of f – sometimes referred to as "two-constants theorem")]

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### Theorem

Let K be a closed subset of [-1,1] such that  $|K| = 2\lambda$  for some  $\lambda$ ,  $0 < \lambda < 1$ , and suppose that  $0 \in \mathbb{D} \setminus K$ . Then

$$\omega(0, \mathbb{D}, K) \ge \omega(0, \mathbb{D}, K_{\lambda}) = \frac{2}{\pi} \arcsin \frac{1 - (1 - \lambda)^2}{1 + (1 - \lambda)^2}$$

where  $K_{\lambda} = [-1, -1 + \lambda] \cup [1 - \lambda, 1].$ 

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where  $K_{\lambda} = [-1, -1 + \lambda] \cup [1 - \lambda, 1].$ 

the above theorem provides a generalization of the classical Beurling's result from 1933 in which K is a finite union of intervals lying on one side of the origin. this was conjectured in [Segawa, 1988], and the symmetric version was previously resolved in [Essen and Haliste, 1989]

a general method for deriving explicit local-in-time lower bounds on the uniform radius of spatial analyticity of solutions to the NSE in  $L^p$  was introduced in [G. and Kukavica, 1998]

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## Theorem

Let  $u_0$  be in  $L^{\infty}(\mathbb{R}^3)$ . Then, there exists an absolute constant  $c_0 > 1$  such that setting  $T = \frac{1}{c_0^2 ||u_0||_{\infty}^2}$ , a unique mild solution u = u(t) on [0,T] has the analytic extension U = U(t) to the region

$$\mathcal{R}_t = \{x + iy \in \mathbb{C}^3 : |y| \le \frac{1}{c_0}\sqrt{t}\}$$

for any t in (0,T]. In addition,

$$||U(t)||_{L^{\infty}(\mathcal{R}_t)} \le c_0 ||u_0||_{\infty}$$

for all t in [0,T].

the vorticity version of the above theorem is as follows (the proof is analogous; utilizing the Biot-Savart law to close each iteration)

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### Theorem

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$$\|\Omega(t)\|_{L^{\infty}(\mathcal{R}_t)} \le d_0 \|\omega_0\|_{\infty}$$

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since our main tool in the proof is the harmonic measure maximum principle, the spatial regularity is recorded in  $L^{\infty} = L^{\infty}(\mathbb{R}^3)$ ; starting from an initial value in  $L^{\infty}$ , we consider the corresponding unique mild solution u on the maximal interval of regularity  $(0, T^*)$  (there is always 'the first singular time')

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note that – due to the local-in-time well-posedness of the equations in  $L^{\infty}$  – for an arbitrary large L, there exists an 'escape time'  $t_L$ ; i.e., for any L > 0, there exists a time  $t_L$  in  $(0, T^*)$ , such that  $||u(t)||_{\infty} > L$  for all t in  $(t_L, T^*)$ 

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for M > 0, denote by  $\Omega_M(t)$  the super-level set at time t; more precisely,

$$\Omega_M(t) = \{x \in \mathbb{R}^3 : |u(x,t)| > M\}$$

## Definition

Let  $x_0$  be a point in  $\mathbb{R}^3$ , r > 0, S an open subset of  $\mathbb{R}^3$  and  $\delta$  in (0,1).

The set S is linearly  $\delta$ -sparse around  $x_0$  at scale r in weak sense if there exists a unit vector d in  $S^2$  such that

$$\frac{S \cap (x_0 - rd, x_0 + rd)|}{2r} \le \delta.$$

the main result (for the velocity formulation) reads as follows

## Theorem

Let  $u_0$  be in  $L^{\infty}$ , and consider the corresponding unique mild solution u on the maximal interval of regularity  $[0, T^*)$ . Let  $\delta$  be in (0, 1),  $h = h(\delta) = \frac{2}{\pi} \arcsin \frac{1-\delta^2}{1+\delta^2}$ ,  $\alpha = \alpha(\delta) \ge \frac{1-h}{h}$ , and  $M = M(\delta) = \frac{1}{c_0^{\alpha}} \|u(t^e)\|_{\infty}$  where  $c_0$  is the constant in the local-in-time analyticity estimate. Assume that there exists an escape time  $t^e$  and a time t in  $\left[t^e + \frac{1}{4c_0^2 \|u(t^e)\|_{\infty}^2}, t^e + \frac{1}{c_0^2 \|u(t^e)\|_{\infty}^2}\right]$  such that for any spatial point  $x_0$ , there exists a scale  $r, 0 < r \le \frac{1}{2c_0^2 \|u(t^e)\|_{\infty}}$ , with the property that the super-level set  $\Omega_t(M)$  is linearly  $\delta$ -sparse around  $x_0$  at scale r in weak sense.

Then,  $T^*$  is in fact not a singular time, and the solution u can be smoothly continued past  $T^*$ .

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#### Lemma

Let  $x_0$  be a point in  $\mathbb{R}^3$ ,  $\rho > 0$ , S an open subset of  $\mathbb{R}^3$  and  $\delta$  in (0,1).

Suppose that

$$\frac{|S \cap B(x_0, \rho)|}{|B(x_0, \rho)|} \le (1 - \delta)^3.$$
(17)

Then, there exists a scale r,  $0 < r \le \rho$ , such that S is linearly  $\delta$ -sparse around  $x_0$  at scale r in weak sense.

recall that the distribution function of a function f – encoding virtually all information on the size of f – is given by

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an *amorphous* regularity criterion – obtained from the previous theorem via the lemma as a geometrically worst case scenario – is a requirement on the decrease of the distribution function of the solution, uniformly in  $(T^* - \epsilon, T^*)$ 

### Theorem

Let  $u_0$  be in  $L^{\infty}$ , and consider the corresponding unique mild solution u on the maximal interval of regularity  $[0, T^*)$ .

Assume that there exists  $\epsilon$ ,  $0 < \epsilon < T^*$ , such that

$$\lambda_{u(s)}(\beta) = o\left(\frac{1}{\beta^3}\right), \quad \beta \to \infty,$$

uniformly in  $(T^* - \epsilon, T^*)$  (the same rate for all s in the interval).

Then,  $T^*$  is in fact not a singular time, and the solution u can be smoothly continued past  $T^*$ .

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it is instructive to compare this result with the well-known uniform-in-time boundedness of the  $L^3$ -norm of u-regularity criterion given in [Escauriaza, Seregin and Sverak, 2003]

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however, since the inclusion is not continuous, i.e., the size of the  $L^3$  norm provides no information on the rate at which  $\alpha^3\lambda_f(\alpha)$  decreases to 0, as  $\alpha\to\infty$ , the two regularity criteria are in fact not directly comparable

the vorticity version is completely analogous

### Theorem

Let  $\omega_0$  be in  $L^{\infty}$ , and consider the corresponding unique mild solution  $\omega$  on the maximal interval of regularity  $[0, T^*)$ . Let  $\delta$  be in (0, 1),  $h = h(\delta) = \frac{2}{\pi} \arcsin \frac{1-\delta^2}{1+\delta^2}$ ,  $\alpha = \alpha(\delta) \ge \frac{1-h}{h}$ , and  $M = M(\delta) = \frac{1}{d_0^{\alpha}} \|\omega(t^e)\|_{\infty}$  where  $d_0$  is the constant in the local-in-time analyticity estimate. Assume that there exists an escape time  $t^e$  and a time t in  $\left[t^e + \frac{1}{4d_0^2}\|\omega(t^e)\|_{\infty}, t^e + \frac{1}{d_0^2}\|\omega(t^e)\|_{\infty}\right]$  such that for any spatial point  $x_0$ , there exists a scale  $r, 0 < r \le \frac{1}{2d_0^2}\|\omega(t^e)\|_{\infty}^2$ , with the property that the super-level set  $\Omega_t(M)$  is linearly  $\delta$ -sparse around  $x_0$  at scale r in weak sense.

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assuming that the length of a tube is comparable with the macro scale, this implies the decrease of the tubes' diameters of at least  $C_3 \frac{1}{\|\omega(t)\|_{\infty}^{\frac{1}{2}}}$ , which is exactly the scale

needed for the application of the theorem

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back to  $(K_1, K_2)$ -covers and ensemble averages

$$\int_0^t \int (\omega \cdot \nabla) u \cdot \phi_i \, \omega \, dx \, ds = \int \frac{1}{2} |\omega(x,t)|^2 \psi_i(x) \, dx + \int_0^t \int |\nabla \omega|^2 \phi_i \, dx \, ds$$
$$- \int_0^t \int \frac{1}{2} |\omega|^2 ((\phi_i)_s + \Delta \phi_i) \, dx \, ds$$
$$- \int_0^t \int \frac{1}{2} |\omega|^2 (u \cdot \nabla \phi_i) \, dx \, ds, \tag{18}$$

for any t in (2T/3,T), and  $1\leq i\leq n$ 

denote the time-averaged local vortex-stretching terms per unit mass associated to the cover element  $B(x_i,R)$  by  $VST_{x_i,R,t},$ 

$$VST_{x_i,R,t} = \frac{1}{t} \int_0^t \frac{1}{R^3} \int (\omega \cdot \nabla) u \cdot \phi_i \, \omega \, dx \, ds \tag{19}$$

,

denote the time-averaged local vortex-stretching terms per unit mass associated to the cover element  $B(x_i,R)$  by  $VST_{x_i,R,t}$ ,

$$VST_{x_i,R,t} = \frac{1}{t} \int_0^t \frac{1}{R^3} \int (\omega \cdot \nabla) u \cdot \phi_i \, \omega \, dx \, ds \tag{19}$$

the quantity of interest is the ensemble average of  $\{VST_{x_i,R,t}\}_{i=1}^n$ ; namely,

$$\langle VST \rangle_{R,t} = \frac{1}{n} \sum_{i=1}^{n} VST_{x_i,R,t}$$
<sup>(20)</sup>

denote by  $E_{0,t}$  time-averaged enstrophy per unit mass associated with the integral domain  $B(0,2R_0) \times (0,t)$ ,

$$E_{0,t} = \frac{1}{t} \int_0^t \frac{1}{R_0^3} \int \frac{1}{2} |\omega|^2 \phi_0^{2\rho-1} \, dx \, ds,$$

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by  $P_{0,t}$  a modified time-averaged palinstrophy per unit mass,

$$P_{0,t} = \frac{1}{t} \int_0^t \frac{1}{R_0^3} \int |\nabla \omega|^2 \phi_0 \, dx \, ds + \frac{1}{t} \frac{1}{R_0^3} \int \frac{1}{2} |\omega(x,t)|^2 \psi_0(x) \, dx$$

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and by  $\sigma_{0,t}$  a corresponding modified Kraichnan scale,

$$\sigma_{0,t} = \left(\frac{E_{0,t}}{P_{0,t}}\right)^{\frac{1}{2}}$$

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## A DYNAMIC ESTIMATE ON VST ACROSS A RANGE OF SCALES

let u be a Leray-Hopf solution on a global spatiotemporal domain  $\Omega \times (0, T)$ , smooth on  $B(0, 2R_0) \times (0, T)$ , and let  $0 < \gamma < 1$ . assume that  $\frac{1}{c_*\gamma} \sigma_{0,t} < R_0$  for a suitable constant  $c_*$ . then, there exist  $c_1(\gamma)$  and  $c_2(\gamma)$  such that  $c_1(\gamma) \to 1^-$ , as  $\gamma \to 0^+$  and  $c_2(\gamma) \to 1^+$ , as  $\gamma \to 0^+$ , and

$$c_1(\gamma) \frac{1}{K_1} P_{0,t} \le \langle VST \rangle_{R,t} \le c_2(\gamma) K_2 P_{0,t}$$
(21)

for all R within the range  $\frac{1}{c_*\gamma}\sigma_{0,t} \leq R \leq R_0$