# Convergence rates for graph-based learning featuring singular PDEs

Leon Bungert

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March 19, 2024

CNA seminar @ CMU Pittsburgh

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# Outline



2 Convergence Rates for Lipschitz Learning

- 3 Convergence Rates for Poisson Learning
- 4 Conclusion and Outlook

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Convergence Rates for Lipschitz Learning

3 Convergence Rates for Poisson Learning

Conclusion and Outlook

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### Given:

• a data set  $\Omega_n \subset \mathbb{R}^d$ ,

• with labels 
$$g: \mathcal{O}_n \subset \Omega_n \to \mathbb{R}$$
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Represent data as weighted graph

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### Extend labels solving a graph PDE

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# Laplacian Learning

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# Laplacian Learning

In Laplacian learning [ZGL03] one computes a harmonic extension of the labels via

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 $\min_{\mathbf{u}} \ \mathcal{E}_2^n(\mathbf{u}),$  subject to  $\mathbf{u} = g$  on  $\mathcal{O}_n.$ 

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$$\begin{array}{c} \min_{\mathbf{u}} \ \mathcal{E}_{2}^{n}(\mathbf{u}), \\ \text{subject to } \mathbf{u} = g \text{ on } \mathcal{O}_{n}. \end{array} \qquad \longleftrightarrow \qquad \mathcal{L}_{2}^{n}\mathbf{u} = 0 \text{ in } \Omega_{n} \setminus \mathcal{O}_{n}, \\ \mathbf{u} = g \text{ on } \mathcal{O}_{n}, \end{array}$$

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$$\min_{\mathbf{u}} \ \mathcal{E}_2^n(\mathbf{u}),$$
  
subject to  $\mathbf{u} = g$  on  $\mathcal{O}_n$ .

$$\mathcal{L}_2^n \mathbf{u} = 0 \text{ in } \Omega_n \setminus \mathcal{O}_n,$$
  
 $\mathbf{u} = g \text{ on } \mathcal{O}_n,$ 

$$\mathcal{E}_2^n(\mathbf{u}) := \sum_{x,y \in \Omega_n} \omega_n(x,y) |\mathbf{u}(x) - \mathbf{u}(y)|^2$$
$$\mathcal{L}_2^n \mathbf{u}(x) := \sum_{y \in \Omega_n} \omega_n(x,y) (\mathbf{u}(y) - \mathbf{u}(x))$$

denotes the graph Dirichlet-energy,

denotes the graph Laplacian.

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### What are the challenges in semi-supervised learning?

# Spiking in Laplacian Learning

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# Spiking in Laplacian Learning



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# Spiking in Laplacian Learning



### Graph-Based Semi-Supervised Learning

- Given: Weighted graph  $G_n = (\Omega_n, \omega_n)$  with labels  $g : \mathcal{O}_n \subset \Omega_n \to \mathbb{R}^k$ .
- Goal:  $\mathbf{u}_n : \Omega_n \to \mathbb{R}$  such that  $\mathbf{u}_n = g$  on  $\mathcal{O}_n$
- Tool: graph PDE

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### Driving question:

What happens with more and more data,  $|\Omega_n| \to \infty$  (and potentially  $|\mathcal{O}_n| \to \infty$ )?

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### Driving question:

What happens with more and more data,  $|\Omega_n| \to \infty$  (and potentially  $|\mathcal{O}_n| \to \infty$ )?



• sufficiently large labeling rates  $\frac{|O_n|}{|\Omega_n|}$  [CST23] or reweighting [CS20];

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- sufficiently large labeling rates  $\frac{|\mathcal{O}_n|}{|\Omega_n|}$  [CST23] or reweighting [CS20];
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- Lipschitz learning (i.e.,  $p = \infty$ ), well-posed continuum limit [Cal19; RB23] with rates [BCR23; BCR24];
- Poisson learning [Cal+20], little empirical degradation for small label rates, well-posed continuum limit [B+24]

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### 2 Convergence Rates for Lipschitz Learning

3 Convergence Rates for Poisson Learning

Conclusion and Outlook

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### What is Lipschitz learning?

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### Lipschitz Learning

Find  $\mathbf{u}_n: \Omega_n \to \mathbb{R}$  such that

$$\begin{cases} \mathcal{L}_{\infty}^{n} \mathbf{u}_{n} = 0, & \text{ in } \Omega_{n} \setminus \mathcal{O}_{n}, \\ \mathbf{u}_{n} = g, & \text{ in } \mathcal{O}_{n}. \end{cases}$$
(LL)

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### Lipschitz Learning

Find  $\mathbf{u}_n: \Omega_n \to \mathbb{R}$  such that

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### Continuum Problem

Find  $u \in C(\Omega)$ , viscosity solution of

$$\begin{cases} \Delta_{\infty} u = 0, & \text{in } \Omega \setminus \mathcal{O}, \\ u = g, & \text{in } \mathcal{O}. \end{cases}$$
(IL)

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### Lipschitz Learning

Find  $\mathbf{u}_n: \Omega_n \to \mathbb{R}$  such that

$$\begin{cases} \mathcal{L}_{\infty}^{n} \mathbf{u}_{n} = 0, & \text{in } \Omega_{n} \setminus \mathcal{O}_{n}, \\ \mathbf{u}_{n} = g, & \text{in } \mathcal{O}_{n}. \end{cases}$$
(LL)

Continuum Problem

Find  $u \in C(\Omega)$ , viscosity solution of

$$\begin{cases} \Delta_{\infty} u = 0, & \text{in } \Omega \setminus \mathcal{O}, \\ u = g, & \text{in } \mathcal{O}. \end{cases}$$
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$$\mathcal{L}_{\infty}^{n}\mathbf{u}_{n}(x) := \max_{y \in \Omega_{n}} \omega_{n}(x, y)(\mathbf{u}_{n}(y) - \mathbf{u}_{n}(x)) + \min_{y \in \Omega_{n}} \omega_{n}(x, y)(\mathbf{u}_{n}(y) - \mathbf{u}_{n}(x))$$
$$\Delta_{\infty}u(x) := \langle \nabla u(x), D^{2}u(x)\nabla u(x) \rangle$$

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(IL)

### Previous work:

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### Lipschitz Learning

Find  $\mathbf{u}_n: \Omega_n \to \mathbb{R}$  such that

 $\begin{cases} \mathcal{L}_{\infty}^{n} \mathbf{u}_{n} = 0, & \text{ in } \Omega_{n} \setminus \mathcal{O}_{n}, \\ \mathbf{u}_{n} = g, & \text{ in } \mathcal{O}_{n}. \end{cases}$ (LL)

Continuum Problem Find  $u \in C(\Omega)$ , viscosity solution of  $\begin{cases} \Delta_{\infty} u = 0, & \text{in } \Omega \setminus \mathcal{O}, \\ u = g, & \text{in } \mathcal{O}. \end{cases}$ (IL)

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**Aims:** convergence rates for sparse graphs

# Graph Bandwidth and Resolution

Graph Bandwidth

For a bandwidth  $\varepsilon_n > 0$  and a function  $\eta : (0, \infty) \to [0, \infty)$  we define

 $\omega_n(x,y) := \eta(|x-y|/\varepsilon_n), \quad x,y \in \Omega_n, \ x \neq y.$ 

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Graph Resolution

We define the graph resolution as

$$\delta_n := d_H(\Omega_n, \Omega) \vee d_H(\mathcal{O}_n, \mathcal{O}),$$

where we use the Hausdorff distance

$$d_H(A,B) = \sup_{x \in A} \inf_{y \in B} |x-y| \lor \sup_{x \in B} \inf_{y \in A} |x-y|, \quad A, B \subset \mathbb{R}^d.$$

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#### Important relations:

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## Theorem ([BCR23])

Let  $\Omega \subset \mathbb{R}^d$  be a locally convex domain,  $\Omega_n \subset \Omega$  be an arbitrary set of points, let  $\mathbf{u}_n : \Omega_n \to \mathbb{R}$  solve (LL) and  $u : \Omega \to \mathbb{R}$  solve (IL), and let  $\tau > 0$  be arbitrary. If  $\delta_n \lesssim \varepsilon_n \lesssim \tau$  then it holds

$$\max_{\Omega_n} |\mathbf{u}_n - u| \lesssim \tau + \sqrt[3]{\frac{\delta_n}{\varepsilon_n \tau} + \frac{\varepsilon_n}{\tau^2}}.$$

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#### Corollary

Optimizing over  $\tau = \tau_n$  one gets:

• (Sparse regime): If 
$$\delta_n \lesssim \varepsilon_n \lesssim \delta_n^{rac{5}{9}}$$
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• (Dense regime): If  $\varepsilon_n \gtrsim \delta_n^{\frac{5}{9}}$  the rate is  $\varepsilon_n^{\frac{1}{5}}$ .

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# Improved Convergence on Random Graphs

## Theorem ([BCR24])

Assume that  $\Omega_n$  is a uniform i.i.d. sample or a homogeneous Poisson point process, let  $\eta(t) = \frac{1}{t} \mathbb{1}_{t \leq 1}$ , et ceteris paribus.

If  $(\log n/n)^{1/d} \lesssim \varepsilon_n \lesssim \tau$  then it holds with high probability:

$$\max_{x \in \Omega_n} |\mathbf{u}_n - u| \lesssim \tau + \sqrt[3]{\log n \frac{(\log n/n)^{1/d}}{\sqrt{\tau^3 \varepsilon_n}}} + \frac{\varepsilon_n}{\tau^2}$$

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#### Corollary

Optimizing over  $\tau = \tau_n$  and choosing  $\varepsilon_n \sim (\log n/n)^{1/d}$  yields almost surely:

$$\max_{x \in \Omega_n} |\mathbf{u}_n - u| \lesssim (\log n)^{\frac{2}{9}} \left(\frac{\log n}{n}\right)^{\frac{1}{9q}}$$

Introduce non-local operator with larger bandwidth  $\tau \gg \varepsilon_n$ 

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Introduce non-local operator with larger bandwidth  $\tau \gg \varepsilon_n$ 

$$\varDelta^\tau_\infty u(x) := \frac{1}{\tau^2} \left( \sup_{y \in B(x;\tau)} (u(y) - u(x)) + \inf_{y \in B(x;\tau)} (u(y) - u(x)) \right),$$

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and define the infimal convolution

$$u_{\tau}(x) := \min_{y \in B(x;\tau)} u(y),$$

Using comparison with cones [AS10] proved

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$$u_\tau(x) := \min_{y \in B(x;\tau)} u(y), \qquad u_n^\tau(x) := \max_{y \in B(x;\tau) \cap \varOmega_n} \mathbf{u}_n(y).$$

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$$-\Delta_{\infty} u \ge 0 \implies -\Delta_{\infty}^{\tau} u_{\tau} \ge 0, -\mathcal{L}_{\infty}^{n} \mathbf{u}_{n} \le 0 \implies -\Delta_{\infty}^{\tau} u_{n}^{\tau} \lesssim \frac{r_{\tau}}{\tau} + \frac{\varepsilon_{n}}{\tau^{2}},$$

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$$\varDelta_{\infty}^{\tau}u(x):=\frac{1}{\tau^2}\left(\sup_{y\in B(x;\tau)}(u(y)-u(x))+\inf_{y\in B(x;\tau)}(u(y)-u(x))\right),$$

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where we define the ratio of graph distances as

$$r_{\tau}(x) := \frac{\sup_{y \in \overline{B}(x,\tau) \cap \Omega_n} d_n(x,y)}{\inf_{y \in \Omega_n \setminus \overline{B}(x,2\tau-\varepsilon_n)} d_n(x,y)} - \frac{1}{2}.$$

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Use perturbation and comparison principle for  $-\Delta_{\infty}^{\tau}$  to show

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$$|x-y| \le d_n(x,y) \le \left(1 + C\frac{\delta_n}{\varepsilon_n}\right)|x-y| + \tau_\eta \varepsilon_n$$

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$$|x-y| \le d_n(x,y) \le \left(1 + C\frac{\delta_n}{\varepsilon_n}\right)|x-y| + \tau_\eta \varepsilon_n$$

or the percolation estimate [BCR24], valid for  $\varepsilon_n \sim \delta_n$ ,

$$r_{ au} \lesssim \left(\frac{\log n}{n}\right)^{rac{1}{d}} rac{\log n}{\sqrt{ auarepsilon}}$$

which is based on homogenization of the graph distance.

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## Numerical Results



Figure: Experimental rates for constant weights on star domain.

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# Numerical Results



Figure: Experimental rates for singular weights on star domain.

Leon Bungert (J	м	U)
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## 3 Convergence Rates for Poisson Learning

Conclusion and Outlook

Leon Bungert (JMU)

Convergence rates for graph-based learning

March 19, 2024

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## What is Poisson learning?

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#### Poisson Learning

Find  $\mathbf{u}_n: \Omega_n \to \mathbb{R}$  such that

$$-\mathcal{L}_2^n \mathbf{u}_n = \sum_{x \in \mathcal{O}} (g(x) - \overline{g}) \delta_x,$$

subject to  $\sum_{x \in \Omega_n} d_n(x)u(x) = 0.$ 

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### Continuum Problem

Find  $u \in W^{1,1}(\Omega)$ , distributional solution of

$$-\operatorname{div}(\rho^2 \nabla u) = \sum_{x \in \mathcal{O}} (g(x) - \overline{g}) \delta_x,$$

subject to 
$$\frac{\partial u}{\partial \nu} = 0$$
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Here,

$$d_n(x) := \sum_{y \in \Omega_n} \omega_n(x, y), \qquad \overline{g} := \frac{1}{|\mathcal{O}|} \sum_{x \in \mathcal{O}} g(x),$$

and we assume that  $\Omega_n = \{x_i\}_{i=1}^n$  with *i.i.d.* samples  $x_i$  with  $Law(x_i) = \rho$  and that  $\mathcal{O}$  is a finite set.

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### Remark:

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#### Poisson Learning

Find  $\mathbf{u}_n:\Omega_n\to\mathbb{R}$  such that

$$-\mathcal{L}_2^n \mathbf{u}_n = \sum_{x \in \mathcal{O}} (g(x) - \overline{g}) \delta_x,$$

subject to  $\sum_{x\in \varOmega_n} d_n(x) u(x) = 0.$ 

### Continuum Problem

Find  $u \in W^{1,1}(\Omega)$ , distributional solution of

$$-\operatorname{div}(\rho^2 \nabla u) = \sum_{x \in \mathcal{O}} (g(x) - \overline{g}) \delta_x,$$

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### Remark:

• Proposed in [Cal+20], superior experimental results

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### Aims: convergence rates

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# Formal Main Result

## Theorem (Formal, [B+24] (forthcoming))

Under reasonable assumptions and for

$$1 \gg \varepsilon_n \gg \begin{cases} \left(\frac{\log n}{n}\right)^{\frac{1}{3d-2}} & \text{if } d \ge 4\\ \left(\frac{\log n}{n}\right)^{\frac{1}{2d+2}} & \text{if } d < 4 \end{cases}$$

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Under reasonable assumptions and for

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it holds with high probability that

$$\|\mathbf{u}_n - u\|_{\ell^1(\Omega_n)} \lesssim \varepsilon_n^{\frac{1}{d+2}}.$$

If  $\rho \equiv const$  and  $\varepsilon_n \gg \left(\frac{\log n}{n}\right)^{\frac{1}{3d-2(d+2)/(d+4)}}$  this can be improved to

$$\|\mathbf{u}_n - u\|_{\ell^1(\Omega_n)} \lesssim \varepsilon_n^{\frac{2}{d+4}}.$$

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# Numerical Results

We consider the problem  $\Delta u = \Delta_z - \delta_{-z}$  for  $z \in \Omega = B(0,1) \subset \mathbb{R}^2$  which has an explicit solution.

We choose  $\varepsilon = 2\left(\frac{\log n}{n}\right)^{\frac{1}{d+2}}$  for  $n = 2^{10}, \ldots, 2^{16}$  and get the following rates<sup>1</sup>:



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Convergence rates for graph-based learning

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### Continuum mollification

Replace continuum data  $\sum_{x \in \mathcal{O}} (g(x) - \overline{g}) \delta_x$  by  $\sum_{x \in \mathcal{O}} (g(x) - \overline{g}) \varphi_x$  with  $\operatorname{supp} \varphi_x \subset B(x, R)$  obtain quantitative  $L^1$ -estimates in R.

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#### Discrete mollification

Mollify discrete data  $\sum_{x \in \mathcal{O}} (g(x) - \overline{g}) \delta_x$  with k steps of the graph heat equation and obtain quantitative estimates in k and  $\varepsilon$ .

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Prove discrete-to-continuum convergence rates for bounded right hand sides using variational methods (strong convexity).

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Prove discrete-to-continuum convergence rates for bounded right hand sides using variational methods (strong convexity).

**NB:** Keeping track of all constants (which blow up) and optimizing over all parameters we obtain the final rate.

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## Continuum Mollification

We regularize the continuum equation by approximating the Dirac deltas:

$$-\operatorname{div}(\rho^2 \nabla u) = \sum_{x \in \Gamma} a_x \delta_x \quad \text{and} \quad -\operatorname{div}(\rho^2 \nabla u_R) = \sum_{x \in \Gamma} a_x \varphi_x,$$

where  $\operatorname{supp} \varphi_x \subset B(x, R)$ ,  $\varphi_x \ge 0$ , and  $\int_{B(x, R)} \varphi_x(y) \, dy = 1$ .

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Theorem ([B+24])

If  $dist(\Gamma, \partial \Omega) > R$  then

$$\|u - u_R\|_{L^1(\Omega)} \lesssim \sum_{x \in \Gamma} |a_x| R.$$

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If in addition  $ho\equiv const$  and  $arphi_{x}(y)=R^{-d}\psi\left(\left|y-x\right|/R
ight)$ , then

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#### Discrete Mollification

We define the random walk graph Laplacian:

$$\mathcal{L}_{rw}\mathbf{u}_n(x) := \frac{1}{\varepsilon_n^2 d_n(x)} \mathcal{L}_2^n \mathbf{u}_n(x) = \frac{1}{\varepsilon_n^2} \left( \frac{1}{d_n(x)} \sum_{y \in \Omega_n} \omega_n(x, y) \mathbf{u}_n(y) - \mathbf{u}_n(x) \right)$$

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The graph heat kernel  $\mathcal{H}_k^x$  is the solution of the heat equation, starting with  $\delta_x$ :

$$\mathcal{H}_{k+1}^x = \mathcal{H}_k^x - \varepsilon_n^2 \mathcal{L}_{rw}^T \mathcal{H}_k^x, \qquad \mathcal{H}_0^x = n\delta_x.$$

We define the convolution  $\mathcal{H}_k * \mathbf{u}_n(x) := \frac{1}{n} \sum_{y \in \Omega_n} \mathcal{H}_k^x(y) \mathbf{u}_n(y).$ 

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Theorem ([B+24])It holds  $\mathcal{H}_k * (\mathcal{L}_{rw} \mathbf{u}_n) = \mathcal{L}_{rw} (\mathcal{H}_k * \mathbf{u}_n).$ 

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#### Estimates on Mollified Problem

Let  $\mathbf{u}_n$  and  $\mathbf{u}_n^{(k)} := \mathcal{H}_k^{\cdot} * \mathbf{u}_n$  solve

$$-\mathcal{L}\mathbf{u}_n = \sum_{x \in \mathcal{O}} a_x \delta_x$$
 and  $-\mathcal{L}\mathbf{u}_n^{(k)} = \sum_{x \in \mathcal{O}} a_x \mathcal{H}_k^x.$ 

Then it holds

$$\mathbf{u}_n - \mathbf{u}_n^{(k)} = \frac{n\varepsilon_n^2}{d_n} \sum_{x \in \mathcal{O}} a_x \sum_{j=0}^{k-1} \mathcal{H}_j^x.$$

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Using that  $d_n \sim n$  and  $\left\|\mathcal{H}_j^x\right\|_{\ell^1(\Omega_n)} = 1$  we get the estimate

$$\left\|\mathbf{u}_n - \mathbf{u}_n^{(k)}\right\|_{\ell^1(\Omega_n)} \lesssim k\varepsilon_n^2 \sum_{x \in \mathcal{O}} |a_x|$$

and will need to choose  $1 \ll k \ll \frac{1}{\varepsilon_n^2}$ .

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#### Continuum Limit for Bounded Data

We consider Poisson equations with bounded right hand side:

$$-\operatorname{div}(\rho^2 \nabla u) = f$$
 and  $-\mathcal{L}_2^n \mathbf{u}_n = f_n$ 

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Theorem ([B+24]) For all  $R, \lambda_1, \lambda_2, \varepsilon_n, \delta > 0$  sufficiently small, and  $q > \frac{d}{2}$  we have with high probability:  $\|u - \mathbf{u}_n\|_{H^1(\mathcal{X}_n)}^2 \lesssim \left(\|f_n - f\|_{\ell^1(\Omega_n)} + \|\operatorname{osc}_{\Omega \cap B(\cdot,\delta)} f\|_{L^1(\Omega)}\right) \left(\|f\|_{L^q(\Omega)} + \|f_n\|_{\ell^q(\Omega_n)}\right)$   $+ \|f\|_{L^{\infty}(\Omega)}^2 \lambda_1 + \|f\|_{L^{\infty}(\partial_{4\varepsilon_n}\Omega)}^2 \varepsilon_n + \|f_n\|_{\ell^2(\Omega_n)} \|f_n\|_{\ell^2(\Omega_n \cap \partial_{2R}\Omega)}$  $+ \left(\|f_n\|_{\ell^2(\Omega_n)}^2 + \|f\|_{L^2(\Omega)}^2\right) \left(\frac{\delta}{\varepsilon_n} + \varepsilon_n + \lambda_1^2 + \lambda_2\right).$ 

## Continuum Limit for Bounded Data

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Theorem ([B+24]) For all  $R, \lambda_1, \lambda_2, \varepsilon_n, \delta > 0$  sufficiently small, and  $q > \frac{d}{2}$  we have with high probability:  $\|u - \mathbf{u}_n\|_{H^1(\mathcal{X}_n)}^2 \lesssim \left(\|f_n - f\|_{\ell^1(\Omega_n)} + \|\operatorname{osc}_{\Omega \cap B(\cdot,\delta)} f\|_{L^1(\Omega)}\right) \left(\|f\|_{L^q(\Omega)} + \|f_n\|_{\ell^q(\Omega_n)}\right)$   $+ \|f\|_{L^{\infty}(\Omega)}^2 \lambda_1 + \|f\|_{L^{\infty}(\partial_{4\varepsilon_n}\Omega)}^2 \varepsilon_n + \|f_n\|_{\ell^2(\Omega_n)} \|f_n\|_{\ell^2(\Omega_n \cap \partial_{2R}\Omega)}$  $+ \left(\|f_n\|_{\ell^2(\Omega_n)}^2 + \|f\|_{L^2(\Omega)}^2\right) \left(\frac{\delta}{\varepsilon_n} + \varepsilon_n + \lambda_1^2 + \lambda_2\right).$ 

We choose  $f_n = \sum_{x \in \mathcal{O}} a_x \mathcal{H}_k^x$  and prove discrete-to-continuum convergence rates towards a k-fold convolution  $f := \sum_{x \in \mathcal{O}} a_x \rho(x)^{-1} \mathcal{M}_{\varepsilon}^k(\delta_x)$ .

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#### Motivation

2 Convergence Rates for Lipschitz Learning

3 Convergence Rates for Poisson Learning



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Convergence rates for graph-based learning

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What we discussed today:

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#### Part 1 (Lipschitz Learning):

- Lipschitz learning is asymptotically well-posed
- Uniform discrete-to-continuum convergence rates down to smallest length scales
- Novel "homogenized" proof technique

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What we discussed today:

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#### Part 2 (Poisson Learning):

- Poisson learning is asymptotically well-posed
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- Three-scale proof technique

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#### Future work:

- Convergence rates for Lipschitz Learning with density-drift
- Percolation rates for less rigid assumptions
- Sharpness of Poisson learning rates

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Convergence rates for graph-based learning

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# Thank you for your attention! Questions?

L. B, J. Calder, and T. Roith. "Uniform convergence rates for Lipschitz learning on graphs". In: IMA Journal of Numerical Analysis 43.4 (2023), pp. 2445–2495

L. B, J. Calder, and T. Roith. "Ratio convergence rates for Euclidean first-passage percolation: Applications to the graph infinity Laplacian". In: Annals of Applied Probability (2024). In press

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Sparse graph: bandwidth  $\gg$  connectivity threshold, Lipschitz learning (today, [BCR23])

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Sparse graph: bandwidth  $\gg$  connectivity threshold, Lipschitz learning (today, [BCR23])



Medium graph: bandwidth  $\gg$  (connectivity threshold)<sup> $\frac{2}{3}$ </sup>, Lipschitz learning (best so far, [Cal19])

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Sparse graph: bandwidth  $\gg$  connectivity threshold, Lipschitz learning (today, [BCR23])



Medium graph: bandwidth  $\gg$  (connectivity threshold)<sup> $\frac{2}{3}$ </sup>, Lipschitz learning (best so far, [Cal19])



Dense graph: bandwidth  $\gg$  (connectivity threshold)  $^{\frac{1}{4}}$  , Laplacian learning [Cal18]

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Figure: Experimental rates for constant weights on star domain.

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Figure: Experimental rates for singular weights on star domain.

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Figure: Experimental rates for constant weights on square domain.

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Figure: Experimental rates for weights on domain.



# Graph Functional

Graph Lipschitz Learning Find  $u : \Omega_n \to \mathbb{R}$  such that  $u \in \arg \min \max_{x,y \in \Omega_n} \omega_n(x,y) |u(x) - u(y)|,$ and u = g on  $\mathcal{O}_n$ . Lipschitz Learning Find  $u \in W^{1,\infty}(\Omega)$  such that  $u \in \arg\min \operatorname{ess\,sup}_{x \in \Omega} |\nabla u(x)|,$ and u = g in  $\mathcal{O}$ .

• The graph functional has the form

$$E_n(u) = \frac{1}{\varepsilon_n} \max_{x, y \in \Omega_n} \eta_{\varepsilon_n}(|x - y|) |u(x) - u(y)|$$

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• The respective continuum functional for  $u\in W^{1,\infty}(\varOmega)$  reads

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 We want to prove Γ-convergence and compactness for convergence of minimizers.

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## Domain Regularity

The key estimate in our arguments is

$$|u(x) - u(y)| \le \|\nabla u\|_{L^{\infty}} d_{\Omega}(x, y),$$

where  $u: W^{1,\infty}(\Omega) \to \mathbb{R}$  and

 $d_{\varOmega}(x,y):=\inf\left\{\operatorname{len}(\gamma)\ :\ \gamma:[0,1]\to\varOmega\text{ is a curve with }\gamma(0)=x,\,\gamma(1)=y\right\}$ 

denotes the geodesic distance in  $\Omega$ .

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denotes the geodesic distance in  $\Omega$ .

Our results only hold true for "locally convex" domains  $\Omega$  which satisfy

Local Convexity Condition

$$\lim_{\delta \searrow 0} \sup \left\{ \frac{d_{\Omega}(x,y)}{|x-y|} : x, y \in \Omega, |x-y| < \delta \right\} = 1.$$

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## Non-Local Auxiliary Functional

Similar to the proof in [GS15] it is convenient to first establish a convergence result for a non-local continuum functional.

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#### Non-Local Auxiliary Functional

Similar to the proof in [GS15] it is convenient to first establish a convergence result for a non-local continuum functional.

#### Non-Local to Local Convergence [RB23]

Let  $\Omega$  be locally convex. For  $u \in L^{\infty}(\Omega)$  and h > 0 we define

$$\mathcal{E}_h(u) := \frac{1}{h} \operatorname{ess\,sup}_{x,y \in \Omega} \left\{ \eta_s(|x-y|) \left| u(x) - u(y) \right| \right\}.$$

For any null sequence  $\varepsilon_n$  we have that

$$\mathcal{E}_{\varepsilon_n} \xrightarrow{\Gamma} \sigma_{\eta} \mathcal{E}.$$

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• The limit functional is defined as

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For any null sequence  $\varepsilon_n$  we have that

$$\mathcal{E}_{\varepsilon_n} \xrightarrow{\Gamma} \sigma_{\eta} \mathcal{E}.$$

• The limit functional is defined as

$$\mathcal{E}(u) := \operatorname{ess\,sup}_{\Omega} |\nabla u|.$$

• The value  $\sigma_{\eta}$  is defined as

$$\sigma_{\eta} := \operatorname{ess\,sup}_{x>0} \left\{ \eta(x) \, |x| \right\}.$$

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Convergence rates for graph-based learning

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How do we establish  $\Gamma$ -convergence for a sequence of discrete functionals with varying domain, namely the space of functions on the graph  $\Omega_n$ ?

### Extension of the Discrete Functional

 $\bullet\,$  In our case we associate graph functions with piecewise constant  $L^\infty$  functions.

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### Extension of the Discrete Functional

- $\bullet\,$  In our case we associate graph functions with piecewise constant  $L^\infty$  functions.
- Consider a closest-point projection  $p_n: \Omega \to \Omega_n$  such that

$$p_n(x) \in \arg\min_{y \in \Omega_n} |x - y|.$$

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$$p_n(x) \in \arg\min_{y \in \Omega_n} |x - y|.$$

• We extend the functional  $E_n$  onto  $L^{\infty}$  by defining for  $u \in L^{\infty}(\Omega)$ :

$$E_n(u) = \begin{cases} \frac{1}{\varepsilon_n} \max_{x, y \in \Omega_n} \eta_{\varepsilon_n}(|x - y|) |\bar{u}(x) - \bar{u}(y)|, & \text{if } u = \bar{u} \circ p_n, \\ +\infty, & \text{else.} \end{cases}$$

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# Discrete to Continuum Convergence

We can also define the constrained functionals

$$E_{n,\mathrm{cons}}(u) = \begin{cases} E_n(u), & \text{if } u = g \text{ on } \mathcal{O}_n, \\ \infty, & \text{else}, \end{cases} \qquad \qquad \mathcal{E}_{\mathrm{cons}}(u) = \begin{cases} \mathcal{E}(u), & \text{if } u = g \text{ on } \mathcal{O}, \\ \infty, & \text{else} \end{cases}$$

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# Discrete to Continuum Convergence

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#### and obtain

#### Discrete to Continuum Convergence [RB23]

Let  $\varOmega$  be locally convex. For any null sequence  $\varepsilon_n$  such that

 $d_H(\Omega_n, \Omega) \ll \varepsilon_n,$  $d_H(\mathcal{O}_n, \mathcal{O}) \ll \varepsilon_n.$ 

we have that

$$E_{n, \text{cons}} \xrightarrow{\Gamma} \sigma_{\eta} \mathcal{E}_{\text{cons}}.$$

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# Discrete to Continuum Convergence

We can also define the constrained functionals

$$E_{n,\mathrm{cons}}(u) = \begin{cases} E_n(u), & \text{if } u = g \text{ on } \mathcal{O}_n, \\ \infty, & \text{else}, \end{cases} \qquad \qquad \mathcal{E}_{\mathrm{cons}}(u) = \begin{cases} \mathcal{E}(u), & \text{if } u = g \text{ on } \mathcal{O}, \\ \infty, & \text{else} \end{cases}$$

and obtain

#### Discrete to Continuum Convergence [RB23]

Let  $\varOmega$  be locally convex. For any null sequence  $\varepsilon_n$  such that

 $d_H(\Omega_n, \Omega) \ll \varepsilon_n,$  $d_H(\mathcal{O}_n, \mathcal{O}) \ll \varepsilon_n.$ 

we have that

$$E_{n, \operatorname{cons}} \xrightarrow{\Gamma} \sigma_{\eta} \mathcal{E}_{\operatorname{cons}}.$$

# Convergence of minimizers?

Leon Bungert (JMU)

Convergence rates for graph-based learning

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# Compactness

A sequence of functionals  $F_n:X\to\mathbb{R}$  is called compact if for any sequence  $(x_n)_{n\in\mathbb{N}}$  the property

 $\sup_{n\in\mathbb{N}}F_n(x_n)<\infty$ 

implies that  $(x_n)_{n \in \mathbb{N}}$  is relatively compact.

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# Compactness

A sequence of functionals  $F_n: X \to \mathbb{R}$  is called compact if for any sequence  $(x_n)_{n \in \mathbb{N}}$  the property

> $\sup F_n(x_n) < \infty$  $n \in \mathbb{N}$

implies that  $(x_n)_{n \in \mathbb{N}}$  is relatively compact.

Compactness Result [RB23]

Let  $\varepsilon_n$  be a null sequence such that

 $d_H(\Omega_n, \Omega) \ll \varepsilon_n,$  $d_H(\mathcal{O}_n, \mathcal{O}) \ll \varepsilon_n.$ 

then  $E_{n,cons}$  is a compact sequence of functionals. Therefore, every sequence of minimizers for  $E_{n,cons}$  has a cluster point which is a minimizer of  $\mathcal{E}_{cons}$ .