

# Mean value properties: Old and New

Juan J. Manfredi  
University of Pittsburgh

Center for Nonlinear Analysis

CARNEGIE MELLON UNIVERSITY

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A. Oberman, M. Parviainen, J. Rossi, A. Sviridov

# Representative Classical Results

## Blasche Theorem (1916)

An upper-semicontinuous function  $u$  is subharmonic if and only if

$$\limsup_{\varepsilon \rightarrow 0} \frac{1}{\varepsilon^2} \left[ \int_{\partial B(x, \varepsilon)} u(y) d\sigma(y) - u(x) \right] \geq 0.$$

## Privaloff's Theorem (1925)

An upper-semicontinuous function  $u$  is subharmonic if and only if

$$\limsup_{\varepsilon \rightarrow 0} \frac{1}{\varepsilon^2} \left[ \int_{B(x, \varepsilon)} u(y) dy - u(x) \right] \geq 0.$$

Application: The sum of two subharmonic functions is subharmonic.

# Modern Linear results

## Case of constant coefficients

If we replace the Laplace equation  $\Delta u = 0$  by a linear elliptic equation with constant coefficients  $Lu = \sum_{i,j} a_{ij} u_{x_i x_j} = 0$  then mean value formulas now hold for appropriate ellipsoids instead of balls.

## Linear Subelliptic case

Bonfiglioli and Lanconelli (JEMS 2012) proved extensions of Blasche and Privalov Theorems to the subelliptic case.

They use a definition of W. Kozakiewicz, *Un théorème sur les opérateurs et son application à la théorie des Laplacians généralisés*, C.R. Soc. Varsovie 26 (1933), that is equivalent to the modern notion of viscosity solution.

# A view from 30,000 ft

$$\text{MVP} \iff \text{DPP} \iff \text{PDE}$$

For an appropriate real function  $u$  we have a meta-equivalence among

- 1  $u$  satisfies a Mean Value Property (in an appropriate asymptotic sense)
- 2  $u$  satisfies a Dynamic Programming Principle associated to a game or control problem
- 3  $u$  solves a (possibly nonlinear) PDE

## Flexibility of this approach

Euclidean spaces, Riemannian manifolds, Sub-Riemannian manifolds (Heisenberg group), graphs (trees), metric-measure spaces, parabolic versions.

But **limited** to scalar  $\mathbb{R}$ -valued functions.

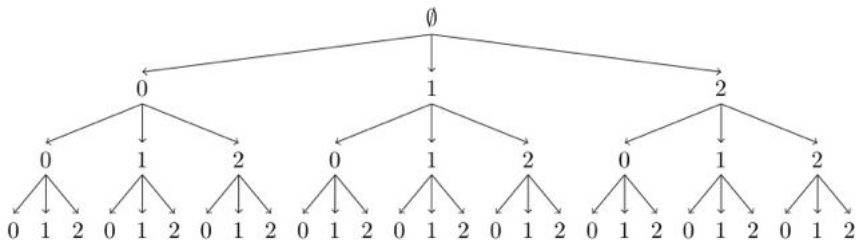
## Example: Trees

A directed tree with regular 3-branching  $T$  consists of

- the empty set  $\emptyset$ ,
- 3 sequences of length 1 with terms chosen from the set  $\{0, 1, 2\}$ ,
- 9 sequences of length 2 with terms chosen from the set  $\{0, 1, 2\}$ ,
- ...
- $3^r$  sequences of length  $r$  with terms chosen from the set  $\{0, 1, 2\}$

and so on. The elements of  $T$  are called *vertices*.

# Example: Trees



## Calculus on Trees

Each vertex  $v$  at level  $r$  has three children (successors)

$$v_0, v_1, v_2.$$

Let  $u: T \mapsto \mathbb{R}$  be a real valued function.

### Gradient

The gradient of  $u$  at the vertex  $v$  is the vector in  $\mathbb{R}^3$

$$\nabla u(v) = \{u(v_0) - u(v), u(v_1) - u(v), u(v_2) - u(v)\}.$$

### Divergence

The averaging operator or *divergence* of a vector

$X = (x, y, z) \in \mathbb{R}^3$  as

$$\operatorname{div}(X) = \frac{x + y + z}{3}.$$

# Harmonic Functions on Trees

## Harmonic functions

A function  $u$  is harmonic if satisfies the Laplace equation

$$\operatorname{div}(\nabla u) = 0.$$

## The Mean Value Property

A function  $u$  is harmonic if and only if it satisfies the mean value property

$$u(v) = \frac{u(v_0) + u(v_1) + u(v_2)}{3}.$$

Thus the values of harmonic function at level  $r$  determine its values at all levels smaller than  $r$ .



# The boundary of the tree

## Branches and boundary

A **branch** of  $T$  is an infinite sequence of vertices, each followed by one of its immediate successors (this corresponds to the level  $r = \infty$ .) The collection of all branches forms the boundary of the tree  $T$  is denoted by  $\partial T$ .

The mapping  $g: \partial T \mapsto [0, 1]$  given by

$$g(b) = \sum_{r=1}^{\infty} \frac{b_r}{3^r} \quad (\text{also denoted by } b)$$

is (almost) a bijection (think of an expansion in base 3 of the numbers in  $[0, 1]$ ).

# The Dirichlet problem

- We have a natural metric and natural measure in  $\partial T$  inherited from the interval  $[0, 1]$ .
- The **classical Cantor set**  $C$  is the subset of  $\partial T$  formed by branches that don't go through any vertex labeled 1.

## The Dirichlet problem

Given a (continuous) function  $f: \partial T \mapsto \mathbb{R}$  find a harmonic function  $u: T \mapsto \mathbb{R}$  such that

$$\lim_{r \rightarrow \infty} u(b_r) = f(b)$$

for every branch  $b = (b_r) \in \partial T$ .

## Dirichlet problem, II

Given a vertex  $v \in T$  consider the subset of  $\partial T$  consisting of all branches that start at  $v$ . This is always an interval that we denote by  $I_v$ .

### Solution to the Dirichlet problem, $p = 2$

The we have

$$u(v) = \frac{1}{|I_v|} \int_{I_v} f(b) db.$$

Note that  $u$  is a *martingale*.

We see that we can in fact solve the Dirichlet problem for  $f \in L^1([0, 1])$ .

# Where are the nonlinear PDEs?

Setting

$$\operatorname{div}_{\infty}(X) = \frac{1}{2} (\max\{x, y, z\} + \min\{x, y, z\})$$

we obtain the  $\infty$ -Laplacian

$$\operatorname{div}_{\infty}(\nabla u) = 0$$

Choose  $\alpha, \beta \in (0, 1)$  such at  $\alpha + \beta = 1$  and set

$$\operatorname{div}_{\alpha, \beta}(X) = \frac{\alpha}{2} (\max\{x, y, z\} + \min\{x, y, z\}) + \beta \left( \frac{x + y + z}{3} \right).$$

We obtain the  $(\alpha, \beta)$ -Laplacian

$$\operatorname{div}_{\alpha, \beta}(\nabla u) = 0.$$

This operator is **the homogeneous  $(\alpha, \beta)$ -Laplacian.**

# The (homogeneous) $p$ -Laplacian

## The equations

$$\operatorname{div}_2(\nabla u) = 0, \quad \operatorname{div}_p(\nabla u) = 0, \quad \operatorname{div}_\infty(\nabla u) = 0$$

## MVP

$$u(v) = \frac{\alpha}{2} \left( \max_i \{u(v_i)\} + \min_i \{u(v_i)\} \right) + \beta \left( \frac{u(v_0) + u(v_1) + u(v_2)}{3} \right).$$

In general we have  $p = p(\alpha, \beta, \text{geometry})$

- 1 The case  $p = 2$  corresponds to  $\alpha = 0, \beta = 1$ .
- 2 The case  $p = \infty$  corresponds to  $\alpha = 1, \beta = 0$ .
- 3 In general, there is no explicit solution formulas for  $p \neq 2$

## Formulas for $f$ monotone, $p = \infty$

Suppose that  $f$  is monotonically increasing. Let us play tug-of-war in the tree with pay-off function  $f$ . Starting at the vertex  $v_k$  at level  $k$

$$v_k = 0.b_1 b_2 \dots b_k, \quad b_j \in \{0, 1, 2\}$$

players always move either left (adding a 0) or right (adding a 1). In this case  $I_v$  is a Cantor-like set

$$I_v = \{0.b_1 b_2 \dots b_k d_1 d_2 \dots\}, \quad d_j \in \{0, 2\}$$

**Formula for  $p = \infty$**

$$u(v) = \sup_{S_I} \inf_{S_{II}} \mathbb{E}_{S_I, S_{II}}^v[f(b)] = E_{S_I^*, S_{II}^*}^v[f(b)] = \int_{I_v} f(b) d\mathcal{C}_v(b)$$

## Mean Value Properties in $\mathbb{R}^n$ , I

We start by observing that in order to characterize continuous harmonic functions it is enough to ask that the mean value property holds in an asymptotic sense

$$u(x) = \int_{B(x,\varepsilon)} u(y) dy + o(\varepsilon^2) \text{ as } \varepsilon \rightarrow 0. \quad (1)$$

In fact, even a weaker *viscosity* notion suffices.

### Lemma

An upper semicontinuous function  $u: \Omega \subset \mathbb{R}^n \rightarrow \mathbb{R}$  is *subharmonic* in  $\Omega$  if for every  $x \in \Omega$  and test function  $\phi \in C^2(\Omega)$  that touches  $u$  from above at  $x$  we have that

$$\phi(x) \leq \int_{B(x,\varepsilon)} \phi(y) dy + o(\varepsilon^2) \text{ as } \varepsilon \rightarrow 0. \quad (2)$$

Notice that the characterization (2) gives a simple proof of Privaloff's characterization.

## Mean Value Properties, II

### Lemma (M-Parviainen-Rossi)

Solutions to the  $p$ -Laplace equation are characterized by

$$u(x) = \frac{p-2}{2(p+n)} \left\{ \max_{\bar{B}(x,\varepsilon)} u + \min_{\bar{B}(x,\varepsilon)} u \right\} + \frac{n+2}{n+p} \int_{B(x,\varepsilon)} u(y) dy + o(\varepsilon^2) \quad (3)$$

in the viscosity sense, for  $p$  in the range  $1 < p \leq \infty$ .

That is, we have the analogue of Privaloff's characterization for  $p$ -subharmonic functions by replacing the regular solid average with the nonlinear average in (3) and using expansions in the viscosity sense.

### Ferrari-Liu-M.

Similar characterization in the Heisenberg group for  $1 < p < \infty$ .



## Calculus in the Heisenberg group

- $\mathcal{H}$ : the Heisenberg group is just  $\mathbb{R}^3$  with the group operation for  $p = (x, y, z)$  and  $p' = (x', y', z')$  given by

$$p \star p' = (x + x', y + y', z + z' + \frac{1}{2}(xy' - x'y)).$$

- $X = \partial_x - (y/2)\partial_z$ ,  $Y = \partial_y + (x/2)\partial_z$ , and  $Z = \partial_z$  are a basis for left-invariant vector fields.
- $[X, Y] = Z$
- For  $u: \mathcal{H} \mapsto \mathbb{R}$ , the horizontal gradient of  $u$  is the vector field

$$\nabla_H u = (Xu)X + (Yu)Y = (Xu, Yu).$$

- For  $F: \mathcal{H} \mapsto \mathbb{R}^2$ , the horizontal divergence of  $F = F^1 X + F^2 Y + F^3 Z$  is the scalar

$$\operatorname{div}_H(F) = XF^1 + YF^2.$$

# Level-sets and Horizontal Mean Curvature Flow

Take  $u : \mathcal{H} \times [0, \infty) \rightarrow \mathbb{R}$  such that

$$\Gamma_t = \{p \in \mathcal{H} : u(p, t) = 0\} \quad \text{for all } t \geq 0.$$

The horizontal mean curvature of  $\Gamma_t$  is given by

$$\kappa_H = \operatorname{div}_H \left( \frac{\nabla_H u}{|\nabla_H u|} \right).$$

The horizontal normal velocity is

$$V_H = \frac{u_t}{|\nabla_H u|} \text{ and } .$$

## Horizontal mean curvature flow equation

$$V_H = \kappa_H$$

# Mean Curvature Flow in the Heisenberg group

We obtain the level set equation

$$u_t = \operatorname{tr} \left[ \left( I - \frac{\nabla_H u \otimes \nabla_H u}{|\nabla_H u|^2} \right) (\nabla_H^2 u)^* \right].$$

cf. [Evans-Spruck, '91] and [Chen-Giga-Goto, '91] for well-posedness in  $\mathbb{R}^n$ .

# Wellposedness of the Level set Equation

**Problem:** Existence and uniqueness of viscosity solutions of

$$\text{(MCF)} \quad \begin{cases} u_t - \operatorname{tr} \left[ \left( I - \frac{\nabla_H u \otimes \nabla_H u}{|\nabla_H u|^2} \right) (\nabla_H^2 u)^* \right] = 0 & \text{in } \mathcal{H} \times (0, \infty) \\ u(p, 0) = u_0(p) \in BC(\mathcal{H}) & \text{in } \mathcal{H}. \end{cases}$$

Main difficulty lies at the *characteristic set* (always  $\neq \emptyset$ ):

$$\{(p, t) \in \mathcal{H} \times (0, \infty) : \nabla_H u(p, t) = 0\}.$$

Known Results:

[Capogna-Citti, '09]: Uniqueness and existence for a special class of solutions vertically separated at the boundary. [Dirr-Dragoni-Renesse, '10]: Existence via a stochastic control

## Vertical Axial Symmetry

The function  $u$  is *spatially symmetry about the vertical axis* if

$$u(x, y, z, t) = u(x', y', z, t) \text{ when } (x')^2 + (y')^2 = x^2 + y^2.$$

Examples include spheres, tori and other compact surfaces.

### Example (A solution initiated from the gauge sphere)

For  $p = (x, y, z) \in \mathcal{H}$ ,  $R > 0$

$$u(p, t) = (x^2 + y^2)^2 + 12t(x^2 + y^2) + 16z^2 + 12t^2 - R^4$$

is a solution of (MCF) with

$$u_0(p) = G(p) = |p|_H^4 - R^4 = (x^2 + y^2)^2 + 16z^2 - R^4.$$

The zero level set of  $u(\cdot, t)$  shrinks and disappears in finite time.

**Question: Is this solution unique?**

# Definition of Viscosity Solutions

$$F(\eta, Y) = -\operatorname{tr} \left( \left( I - \frac{\eta \otimes \eta}{|\eta|^2} \right) Y \right), \quad \eta \in \mathbb{R}^2, \quad Y \in \mathbb{R}^{2 \times 2} \text{ symmetric}$$

## Definition (Definition of subsolutions)

A bounded upper semicontinuous function  $u$  is a *subsolution* in  $\mathcal{O} \subset \mathcal{H} \times (0, \infty)$  if for any smooth function  $\phi$  and  $(\hat{p}, \hat{t}) \in \mathcal{O}$  s.t.

$$\max_{\mathcal{O}}(u - \phi) = (u - \phi)(\hat{p}, \hat{t}),$$

the function  $\phi$  satisfies at  $(\hat{p}, \hat{t})$

$$\begin{cases} \phi_t + F(\nabla_H \phi, (\nabla_H^2 \phi)^*) \leq 0 & \text{if } \nabla_H \phi(\hat{p}, \hat{t}) \neq 0, \\ \phi_t \leq 0 & \text{if } \nabla_H \phi(\hat{p}, \hat{t}) = 0, (\nabla_H^2 \phi)^*(\hat{p}, \hat{t}) = 0. \end{cases}$$

# Definition of Viscosity Solutions

$$F(\eta, Y) = -\operatorname{tr} \left( \left( I - \frac{\eta \otimes \eta}{|\eta|^2} \right) Y \right), \quad \eta \in \mathbb{R}^2, \quad Y \in \mathbb{R}^{2 \times 2} \text{ symmetric}$$

## Definition (Definition of supersolutions)

A bounded **lower semicontinuous** function  $u$  is a *supersolution* in  $\mathcal{O} \subset \mathcal{H} \times (0, \infty)$  if for any smooth function  $\phi$  and  $(\hat{p}, \hat{t}) \in \mathcal{O}$  s.t.

$$\min_{\mathcal{O}} (u - \phi) = (u - \phi)(\hat{p}, \hat{t}),$$

the function  $\phi$  satisfies at  $(\hat{p}, \hat{t})$

$$\begin{cases} \phi_t + F(\nabla_H \phi, (\nabla_H^2 \phi)^*) \geq 0 & \text{if } \nabla_H \phi(\hat{p}, \hat{t}) \neq 0, \\ \phi_t \geq 0 & \text{if } \nabla_H \phi(\hat{p}, \hat{t}) = 0, (\nabla_H^2 \phi)^*(\hat{p}, \hat{t}) = 0. \end{cases}$$

# Uniqueness for Axisymmetric Solutions

## Theorem (Comparison Theorem)

Let  $u$  and  $v$  be respectively a subsolution and a supersolution of

$$u_t - \operatorname{tr} \left[ \left( I - \frac{\nabla_H u \otimes \nabla_H u}{|\nabla_H u|^2} \right) (\nabla_H^2 u)^* \right] = 0$$

in  $\mathcal{H} \times (0, T)$  for any  $T > 0$ .

★ Assume that  $u - a$  and  $v - b$  are compactly supported for some  $a, b \in \mathbb{R}$  with  $a \leq b$ .

★★ Assume that **one of**  $u$  or  $v$  is spatially axisymmetric about the vertical axis.

Then, we have that

$$u(p, 0) \leq v(p, 0) \text{ for all } p \in \mathcal{H} \implies u \leq v \text{ in } \mathcal{H} \times [0, T).$$



## Strategy for the proof

- Double the variables for  $u - v$  and take the auxiliary function:

$$u(p, t) - \left( v(q_\alpha, s_\alpha) + \alpha w(p, q_\alpha) + \alpha(t - s_\alpha)^2 + \frac{\sigma}{T - t} \right),$$

where  $\alpha > 0$  large,  $\sigma > 0$  small and  $w$  is of class  $C^2$ .

- Consider the maximizer  $(p_\alpha, t_\alpha, q_\alpha, s_\alpha)$  and get test functions of  $(p, t)$ .
- Compare the viscosity inequalities and derive a contradiction.

It is helpful if we have  $w$  satisfying

$$(1) \quad \nabla_p w(p, q) = -\nabla_q w(p, q);$$

$$(2) \quad \nabla_p w(p, q) = 0 \Rightarrow \nabla_p^2 w(p, q) = 0.$$

The Euclidean choice is  $w(p, q) = |p - q|^4$ .

Neither  $|p \cdot q^{-1}|^4$  nor  $|q^{-1} \cdot p|^4$  works in the Heisenberg group.

# Axial Symmetry

## Lemma (Tests for axisymmetric solutions)

Let  $u$  be a axisymmetric subsolution. Suppose that there exists  $(\hat{p}, \hat{t}) \in \mathcal{O} \subset \mathcal{H} \times (0, \infty)$  and  $\phi \in C^2(\mathcal{O})$  such that

$$\max_{\mathcal{O}}(u - \phi) = (u - \phi)(\hat{p}, \hat{t})$$

If  $\hat{p} = (\hat{x}, \hat{y}, \hat{z})$  satisfies  $\hat{x}^2 + \hat{y}^2 \neq 0$ , then there exists  $k \in \mathbb{R}$  such that

$$\frac{\partial}{\partial x}\phi(\hat{p}, \hat{t}) = \hat{x}k \quad \text{and} \quad \frac{\partial}{\partial y}\phi(\hat{p}, \hat{t}) = \hat{y}k.$$

The choice  $w(p, q) = |p \cdot q^{-1}|^4$  now works for the proof.

# Existence by Discrete Games

- $p$ : starting position
- $\varepsilon > 0$ : step size
- $u_0$ : objective function
- $t$ : duration of the game
- $N(= \lceil t/\varepsilon^2 \rceil)$ : total steps

Player I and Player II follow the repeated rules below.

- (1) Player I chooses in  $\mathcal{H}$  a unit horizontal vector  $v$ , i.e.,  $v = (x, y, 0)$  satisfying  $|v|^2 = 1$ .
- (2) Player II chooses  $b = \pm 1$ ;
- (3) The marker is moved from

$$p \mapsto p \cdot e^{\sqrt{2}\varepsilon bv},$$

which is denoted simply by  $p \cdot (\sqrt{2}\varepsilon bv)$ .

## Existence by Discrete Games, II

- The *game states* are  $p = y^0, y^1, \dots, y^N$ .
- The *game value* is

$$u^\varepsilon(p, t) := \min_{v^1} \max_{b^1} \min_{v^2} \max_{b^2} \dots \min_{v^N} \max_{b^N} u_0(y^N).$$

$$u^\varepsilon(p, t) = \min_{v^1} \max_{b^1} u^\varepsilon \left( p \cdot (\sqrt{2}\varepsilon b^1 v^1), t - \varepsilon^2 \right).$$

- Dynamic Programming Principle

$$u^\varepsilon(p, t) = \min_{v \in S_H^1} \max_{b=\pm 1} u^\varepsilon \left( p \cdot (\sqrt{2}\varepsilon b v), t - \varepsilon^2 \right)$$

# Existence by Discrete Games, III

## Theorem (Existence theorem by games)

Assume that  $u_0$  is uniformly continuous function in  $\mathcal{H}$  and is constant  $c \in \mathbb{R}$  outside a compact set. Assume also that  $u_0$  is spatially axisymmetric about the vertical axis. Let  $u^\varepsilon$  be the associated game value. Then  $u^\varepsilon$  converges, as  $\varepsilon \rightarrow 0$ , to the unique axisymmetric viscosity solution of (MCF) uniformly on compacta of  $\mathcal{H} \times [0, \infty)$ .

# Finite-time Extinction

## Theorem

Suppose that  $\{\Gamma_t\}_{t \geq 0}$  denotes an axisymmetric surface evolving by the horizontal mean curvature flow. If  $\Gamma_0 \subset B_r$  for some  $r > 0$ , then we have that  $\Gamma_t = \emptyset$  for  $t > r^2/\sqrt{12}$ .

Here  $B_r$  is the so-called Korány ball

$$B_r = \{p = (x, y, z) : (x^2 + y^2)^2 + z^2 < r^4\}.$$

The proof is based on the comparison with evolution from  $\partial B_r$ .

# Asymptotic Profile

## Theorem

If  $\Gamma_t \subset \mathcal{H}$  ( $t \geq 0$ ) is the horizontal mean curvature flow with initial condition a Korány sphere  $\Gamma_0 = \{p \in \mathcal{H} : |p| = r\}$ . Then the the normalized flow

$$\frac{\Gamma_t}{\sqrt{r^4 - 12t^2}} \rightarrow E_T$$

as  $t \rightarrow T$ , where  $E_T$  is given by

$$E_T := \{p \in \mathcal{H} : 12T(x^2 + y^2) + 16z^2 = 1\}.$$

and the extinction time  $T = \frac{r^2}{\sqrt{12}}$ .