# $L^{p}$ estimates for a singular integral operator motivated by Calderón's second commutator 

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Incompressible Fluids, Turbulence and Mixing In honor of Peter Constantin's 60th birthday

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## The Water Wave Problem

- Inviscid, incompressible, irrotational fluid in $\Omega(t), t \geq 0$, under influence of gravity.


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- Inviscid, incompressible, irrotational fluid in $\Omega(t), t \geq 0$, under influence of gravity.
- Air above fluid and a free interface $\sum(t), t \geq 0$, separates the two.
- Motion of fluid is described by

$$
\begin{aligned}
& \mathbf{v}_{t}+\mathbf{v} \cdot \nabla \mathbf{v}=-\nabla P-\mathbf{k} \text { on } \Omega(t), t \geq 0 \\
& \operatorname{div} \mathbf{v}=0, \text { curl } \mathbf{v}=0 \text { on } \Omega(t), t \geq 0 \\
& P=0 \text { on } \sum(t) \\
& (1, \mathbf{v}) \text { is tangent to the free surface }\left(t, \sum(t)\right)
\end{aligned}
$$

Theorem (Sijue Wu, 2009)
Let initial interface be a graph $z(\alpha, 0)=\alpha+i \epsilon f(\alpha)$, initial velocity $z_{t}(\alpha, 0)=\epsilon g(\alpha), \alpha \in \mathbb{R}$ where $f, g$ are smooth and decay fast at infinity.
There exist $\epsilon_{0}>0, T>0$, depending only on $f$ and $g$ such that for $0<\epsilon<\epsilon_{0}$, the initial value problem of the 2-D water wave system has a unique classical solution for a time period $\left[0, e^{T / \epsilon}\right]$.
During this time period, the solution has the same regularity as the initial data and remains small, and the interface is a graph.

- Variables related through the double layer potential operator, $K$.
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- The core problem is finding $L^{p}$ estimates for the commutator $[\Gamma, K]$.
- Sijue Wu faces integrals of the type

$$
\text { p.v. } \int_{\mathbb{R}} F\left(\frac{A(x)-A(y)}{x-y}\right) \frac{\prod_{i=1}^{n}\left(B_{i}(x)-B_{i}(y)\right)}{(x-y)^{n+1}} f(y) d y
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- $L^{p}$ estimates are known if $A^{\prime}, B_{i}^{\prime} \in L^{\infty}(\mathbb{R})$ for $i=1, \ldots, n$ and $f \in L^{2}(\mathbb{R})$.
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- Novelty in Sijue Wu's paper is that she faces $B_{1}^{\prime} \in L^{2}(\mathbb{R})$.
- Her setup is $A^{\prime}, B_{i}^{\prime} \in L^{\infty}(\mathbb{R})$ for $i=2, \ldots, n, B_{1}^{\prime} \in L^{2}(\mathbb{R})$ and $f \in L^{\infty}(\mathbb{R})$.
- Bounds can be obtained using $T(b)$ theorem.


## Calderón Commutators

## Definition

The $k$-th Calderón commutator, $k \in\{1,2,3, \ldots\}$, is given by

$$
\mathcal{C}_{A}^{(k)} f(x)=\int_{\mathbb{R}} \frac{1}{x-y}\left(\frac{A(x)-A(y)}{x-y}\right)^{k} f(y) d y
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where $A$ is Lipschitz and $A^{\prime} \in L^{\infty}(\mathbb{R})$.

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- Coifman and Meyer showed in 1975

$$
\mathcal{C}_{A}^{(k)}: L^{p} \rightarrow L^{p} \text { for } 1<p<\infty
$$

for $k=1,2, \ldots$

## Bilinear Hilbert Transform

$$
-\frac{A(x)-A(y)}{x-y}=\int_{0}^{1} A^{\prime}(x+\alpha(y-x)) d \alpha
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## Bilinear Hilbert Transform

- $\frac{A(x)-A(y)}{x-y}=\int_{0}^{1} A^{\prime}(x+\alpha(y-x)) d \alpha$
- Calderón wrote

$$
\begin{aligned}
\mathcal{C}_{A}^{(1)} f(x) & =\int_{\mathbb{R}}\left(\frac{A(x)-A(y)}{x-y}\right)(x-y)^{-1} f(y) d y \\
& =\int_{0}^{1} \int_{\mathbb{R}} A^{\prime}(x+\alpha(y-x))(x-y)^{-1} f(y) d y d \alpha \\
& =\int_{0}^{1} \int_{\mathbb{R}} A^{\prime}(x+\alpha t) f(x+t) \frac{1}{t} d t d \alpha
\end{aligned}
$$

- The Bilinear Hilbert Transform is defined as

$$
B H T_{\alpha}\left(f_{1}, f_{2}\right)(x)=p . v . \int_{\mathbb{R}} f_{1}(x+\alpha t) f_{2}(x+t) \frac{1}{t} d t
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Theorem (Lacey and Thiele from 1997 and 1999)
Let $\alpha \notin\{0,1\}, 1<p_{1}, p_{2} \leq \infty$ and $\frac{2}{3}<p:=\frac{p_{1} p_{2}}{p_{1}+p_{2}}<\infty$. Then there exists a constant $C_{\alpha, p_{1}, p_{2}}$ such that

$$
\left\|B H T_{\alpha}\left(f_{1}, f_{2}\right)\right\|_{p} \leq C_{\alpha, p_{1}, p_{2}}\left\|f_{1}\right\|_{p_{1}}\left\|f_{2}\right\|_{p_{2}}
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for all $f_{1}$ and $f_{2}$ in $\mathcal{S}(\mathbb{R})$.

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for all $f_{1}$ and $f_{2}$ in $\mathcal{S}(\mathbb{R})$.

- Applications to AKNS systems.


## Trilinear Hilbert Transform

$$
\begin{aligned}
\mathcal{C}_{A}^{(2)} f(x) & =\int_{\mathbb{R}}\left(\frac{A(x)-A(y)}{x-y}\right)^{2}(x-y)^{-1} f(y) d y \\
& =\int_{0}^{1} \int_{0}^{1} \int_{\mathbb{R}} A^{\prime}\left(x+\alpha_{1} t\right) A^{\prime}\left(x+\alpha_{2} t\right) f(x+t) \frac{1}{t} d t d \alpha_{1} d \alpha_{2}
\end{aligned}
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$$

- The Trilinear Hilbert Transform is defined as

$$
T H T_{\vec{\alpha}}\left(f_{1}, f_{2}, f_{3}\right)(x)=p . v . \int_{\mathbb{R}} f_{1}\left(x+\alpha_{1} t\right) f_{2}\left(x+\alpha_{2} t\right) f_{3}(x+t) \frac{1}{t} d t
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- Open question: Find $L^{p}$ estimates for $T H T_{\vec{\alpha}}$.


## Main Theorem

Define

$$
\begin{aligned}
& T_{\beta}\left(f_{1}, f_{2}, f_{3}\right)(x)= \\
& \text { p.v. } \int_{\mathbb{R}}\left(\int_{0}^{1} f_{1}(x+\alpha t) d \alpha\right) f_{2}(x+\beta t) f_{3}(x+t) \frac{1}{t} d t
\end{aligned}
$$

Theorem (P.)
Let $\beta \notin\{0,1\}, 1<p_{1}, p_{2}, p_{3} \leq \infty$,

$$
\frac{1}{2}<p:=\frac{p_{1} p_{2} p_{3}}{p_{1} p_{2}+p_{1} p_{3}+p_{2} p_{3}}<\infty \quad \text { and } \quad \frac{2}{3}<\frac{p_{2} p_{3}}{p_{2}+p_{3}} \leq \infty
$$

Then there exists a constant $C_{\beta, p_{1}, p_{2}, p_{3}}$ such that

$$
\left\|T_{\beta}\left(f_{1}, f_{2}, f_{3}\right)\right\|_{p} \leq C_{\beta, p_{1}, p_{2}, p_{3}}\left\|f_{1}\right\|_{p_{1}}\left\|f_{2}\right\|_{p_{2}}\left\|f_{3}\right\|_{p_{3}}
$$

for all $f_{1}, f_{2}$ and $f_{3}$ in $\mathcal{S}(\mathbb{R})$.

## Future Applications?

- Motivated by Sijue Wu's operator it would be interesting to obtain $L^{p}$ estimates for

$$
\text { p.v. } \int_{\mathbb{R}} F\left(\frac{A(x+t)-A(x)}{t}\right) b(x+\beta t) f(x+t) \frac{1}{t} d t
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- First need $L^{p}$ estimates for

$$
p . v . \int_{\mathbb{R}}\left(\frac{A(x+t)-A(x)}{t}\right)^{m} b(x+\beta t) f(x+t) \frac{1}{t} d t
$$

with polynomial bounds in $m$.

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- Result on operator on previous slide is the first step, showing a wide range of $L^{p}$ estimates for the case $m=1$.

