Centroidal Voronoi Tessellations And Gersho's Conjecture In 3D And On The Sphere

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(Joint work with Rustum Choksi)

Question: given a continuous distribution of mass, which we want to approximate with only N points, how to place them so to minimize the approximation error?

Voronoi diagrams, Euclidean distance:



Given a collection if points $\{y_k\}$ (the black dots), the Voronoi cell of a point y_k is the set

$$V := \{x \in Q : |x - y_k| \le |x - y_j| \text{ for all } j \ne k\}.$$

We associate to $\{y_k\}_{k=1}^n$ the second moment energy:

$$E(Y) := \int_Q \operatorname{dist}^2(x, Y) dx = \sum_{k=1}^n E(V_k),$$
$$E(V_k) := \int_{V_k} |x - y_k|^2 dx, \qquad k = 1, \cdots, n$$

where $Q = [0, 1]^d$ and V_k denotes the Voronoi cell of y_k .

Centroid of a set: given a set Ω , a centroid is a point $y \in \Omega$ such that

$$\int_{\Omega} (x-y) dx = 0 \Longrightarrow y = rac{1}{|\Omega|} \int_{\Omega} x dx.$$

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Voronoi tessellations:





Left: a Voronoi diagram

Right: a centroidal Voronoi tessellation (CVT)

Voronoi tessellations are all around us: some examples and applications

Centroidal Voronoi tessellation (CVT) in nature:



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[b]0.4 Left: SEM of the corneal endothelium of a dog.

Right: Honeycomb



Giant's causeway

Voronoi tessellations are useful in a wide array of applications:



Figure: London's tube network, with Voronoi cells of its stations.

The Voronoi cells of a stations represents the region closest to that particular station.

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Figure: Driving path (red), and obstacles detected (white).

By driving on edges of Voronoi cells of the obstacles, the car keeps a maximal distance from these...

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The idea of Voronoi tessellations is quite not new...



Figure: "Boundary of equal distance between Broad Street Pump and other Pumps", J. Snow's report on the cholera outbreak in the Parish of St. James, Westminster 1854.

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Gersho's conjecture (1979)

There exists a polytope V with |V| = 1 which tiles the space with congruent copies such that the following holds: let $(Y_n)_n$ be a sequence of minimizers, with Y_n minimizer with n points, then the Voronoi cells of points Y_n are asymptotically congruent to $n^{\alpha(d)}V$ as $n \to +\infty$.

Note:

- the polytope V can depend on the dimension d.
- **2** Nothing is said about the geometry of V.
- Solution This conjecture is for n → +∞. Nothing is said, or expected, for finite n.

So Gersho's conjecture is a crystallization problem.

Crystallization problems are notoriously easy-looking, but relatively hard:

- Seems *obviously* true in simulations...
- 2 It is *never* easy when it comes to proofs...

An example from Ohta-Kawasaki:



Figure: Image courtesy of Chong Wang et al.

Minimizers seems to distribute along a triangular lattice, with all double bubbles being parallel...

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Even "simpler" crystallization problems are highly nontrivial:Heitmann and Radin (1980): interaction energy

$$V(r) := \begin{cases} +\infty & \text{if } 0 \le r < 1, \\ -1 & \text{if } r = 1, \\ 0 & \text{if } r > 1, \end{cases}$$

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Gersho's conjecture: State of art

Known results:

Gersho's conjecture is fully proven in 2D (Fejes Tóth, Gruber, etc.): the optimal Voronoi tessellation is the triangular lattice ("honeycomb").



2 Open for higher dimensions.

Gruber's arguments for 2D:

- optimal with k edges are regular k-gons.
- 2 The function $(k, A) \mapsto g(k, A)$ is convex.

g(k, A) := energy of optimal convex k-gon with area A.

The average number of sides in a Voronoi tessellation is 6 (by Euler's polytope formula). Then, for any arbitrary tessellation Y_n (with $\sharp Y_n = n$), of Q, let $\{V_k\}$ be the collection of Voronoi cells, and let α_k be the number of faces of V_k . Thus it follows

$$E(Y_n) = \sum_{k=1}^n \int_{V_k} |x - y|^2 dx \ge \sum_{k=1}^n g(\alpha_k, |V_k|)$$
$$\ge ng(6, 1/n) + \text{error due to boundary effects.}$$

Since the error due to boundary effects is a higher order term compared to ng(6, 1/n), it follows that the optimal tessellation (as $n \to +\infty$) consists of congruent copies of a space tiling polyhedron realizing g(6, 1/n).

Conjecture

The optimal lattice in 3D is the body centered cubic (BCC) lattice.



Numerical results seem to support this (Du et al. 2005).

Main difficulties in 3D:

- No regular *k*-hedra.
- Very difficult to compute the energy of a generic *k*-hedron. Moreover:
 - **()** Gersho's conjecture is **nonlocal** and **infinite dimensional**.
 - On a priori bounds on the geometric complexity of Voronoi cells.

Even deeper difficulties in 3D

Deeper causes: existence of universally optimal lattices.

- (Cohn, Viazovska et al.) \mathbb{R}^8 does have a universally optimal lattice (\mathbb{E}_8), and so does \mathbb{R}^{24} (Leech lattice).
- (unproven, but likely to be true) ℝ² should have a universally optimal lattice (triangular lattice). This lattice is optimal for several problems:
 - sphere packing
 - optimal foam
 - crystallization of two-body interaction potentials
 - total first eigenvalues of $-\Delta$
- R³ is hugely unlikely to have a universally optimal lattice... BCC (Body Centered Cubic), FCC (Face Centered Cubic), HCP (Hexagonal Close Packing), and even non lattice structures (e.g. Weaire-Phelan structure) are potentially optimal configurations...

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Figure: The Weaire-Phelan structure.

The Weaire-Phelan structure disproved the century old Kelvin conjecture that the "optimal foam" (i.e. packing with smallest surface area) was given by the bitruncated cubic honeycomb structure.

The Weaire-Phelan structure uses **two** polyhedra, and shows little regularity when sectioned along planes...



Figure: If you take sections of the Wearie-Phelan structure...

Geometric complexity of optimal CVTs

Main result:

Upper bound on the number of faces (Choksi and L.)

There exists a computable $N \approx 10^{20}$ such that Voronoi cells in optimal CVTs have at most N faces.

The constant N is quite large, but **finite**.

Domain $Q = [0, 1]^3$, *n* generators. Expected averages.

- Average diameter of each Voronoi cell $O(n^{-1/3})$.
- **2** Average volume of each Voronoi cell $O(n^{-1})$.
- Average energy of each Voronoi cell $O(n^{-5/3})$.

Since the second moment is "convex", an optimal tessellation should be made of cells whose properties should not differ too much from the averages...

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Prove that all the above quantities differ from the average by a uniform multiplicative constant. But, there is far too little regularity to use anything "powerful".

Main idea (quite simple one...)

- remove a point from some cell: this increases the energy
- \bullet add such point elsewhere: this $\ensuremath{\textit{decreases}}$ the energy

Then we estimate the energy difference...

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- add such point elsewhere: this **decreases** the energy Then we estimate the energy difference...

Key ingredients.

- Crucial: reduction when adding another point.
- 2 Lower bound on the distance to a closest neighbor.
- Solution Lower/upper bound on the diameter of Voronoi cells.
- 4 Lower bound on the volume of Voronoi cells.
- **9** Boundary cells can be ignored.

Maximum geometric complexity of Voronoi cells (Choksi, L.)

For any $y \in Y_n$, its Voronoi cell V is a convex polyhedron with at most

$$N = \frac{9\pi\Gamma_4^2}{16\Gamma_1}$$

faces.

- All faces of any Voronoi cell belong to axial plane of the line segment between 2 generators, whose Voronoi cells share a boundary.
- Can't be too far away: if two atoms $y', y'' \in Y_n$ satisfy

 $|y'-y''| > 2\Gamma_4 n^{-1/3} \ge 2$ maximum diameter

then their Voronoi cells do not share boundaries.

• **Upper bound on diameter**: ... so if *y*, *y*' share boundary, then the *entire* Voronoi cell of *y*' is in the ball

$$B(y, 3\Gamma_4 n^{-1/3})...$$

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• ... Volume argument $B(y, 3\Gamma_4 n^{-1/3})$ can contain only

$$N := \frac{\frac{4}{3}\pi (3\Gamma_4 n^{-1/3})^3}{\Gamma_1 \Gamma_4^{-2} n^{-1}} = \frac{9\pi\Gamma_4^2}{16\Gamma_1} \approx 10^{20}$$

entire Voronoi cells. Thus V can share boundaries with at most N other Voronoi regions.

Voronoi tessellations on the sphere

Voronoi tessellations are not exclusive to the plane:



Figure: What is your closest airport?

The same question can be posed with the domain being S^2 instead of $[0,1]^3$: as the number of generators diverge, are "almost all" (i.e. all except o(n) many) the Voronoi cells going to be asymptotically congruent to some fixed polytope?

Idea: the sphere S^2 is "really like" the plane \mathbb{R}^2 , at least locally... So "almost all" the Voronoi cells going to be asymptotically congruent to a (rescaled) regular hexagon... The same question can be posed with the domain being S^2 instead of $[0, 1]^3$: as the number of generators diverge, are "almost all" (i.e. all except o(n) many) the Voronoi cells going to be asymptotically congruent to some fixed polytope?

Idea: the sphere S^2 is "really like" the plane \mathbb{R}^2 , at least locally... So "almost all" the Voronoi cells going to be asymptotically congruent to a (rescaled) regular hexagon... Key difference: S^2 is geometrically more rigid, mainly due to the Euler polytope formula

#vertices - #edges + #faces = 2.

The number of *defects* (i.e. non hexagonal cells) should be controlled, with something much tighter than o(n).

Main result:

Only finitely many non hexagonal cells (Choksi, L.)

There exist computable constants M, N such that, whenever the number of generators n > N, the optimal configuration satisfies the following geometric properties:

- the number k = k(n) of hexagonal cells is at least n M;
- denote by $\{V_i\}$ the hexagonal cells, $i = 1, \cdots, k$ and let $A_n := \sum_i |V_i|$. Denote by H the regular hexagon of area A_n/k . Then

$$\lim_{n\to+\infty}\sum_{i}\inf_{x\in S^2}|V_i\triangle(H+x)|=0.$$

That is, the **total** mismatch between the Voronoi cells and regular hexagons is vanishing.

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Thank you for your attention!