

Aubry-Mather Theory for PDEs

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CNA Seminar
Carnegie Mellon University

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- 1 Background Material
- 2 Comparison for the Sobolev Gradient
- 3 Numerical Method
- 4 Asymptotic Analysis

Energy Functionals and Minimizers

- A function $u \in H^1(\mathbb{R}^d, \mathbb{R})$ is a minimizer for a formal energy

$$S(u) = \int_{\mathbb{R}^d} F(x, u, \nabla u) dx$$

if for all compactly supported $\varphi \in H^1(\mathbb{R}^d, \mathbb{R})$

$$\int_{\text{supp}(\varphi)} F(x, u + \varphi, \nabla(u + \varphi)) - F(x, u, \nabla u) dx \geq 0.$$

- Assumptions: F is smooth, $F(x + k, y + l, p) = F(x, y, p)$ for all $(k, l) \in \mathbb{Z}^{d+1}$, and satisfies growth and convexity requirements in p , so that the Euler-Lagrange equation for S is elliptic.

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Birkhoff Minimizers and Average Slope

- A continuous $u : \mathbb{R}^d \rightarrow \mathbb{R}$ is a *Birkhoff* function if

$$u(x - k) + j - u(x) \leq 0 \quad \text{or} \quad \geq 0$$

depending on $(k, j) \in \mathbb{Z}^{d+1}$ but independent of x .

- If u is a Birkhoff minimizer, then there is a $\omega \in \mathbb{R}^d$ such that

$$\sup_{x \in \mathbb{R}^d} |u(x) - \omega \cdot x| < \infty$$

Theorem (Moser, '86)

For each $\omega \in \mathbb{R}^d$ there is a Birkhoff minimizer u with slope ω .

$$\mathcal{M}_\omega = \{u \mid u \text{ is Birkhoff minimizer of } S \text{ with slope } \omega\} \neq \emptyset$$

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Minimal Average Energy and Crystal Shape

- The average energy of Birkhoff minimizers depends only on the slope:

$$E(\omega) = \lim_{r \rightarrow \infty} \frac{1}{|B_r|} \int_{B_r} F(x, u, \nabla u) dx, \quad u \in \mathcal{M}_\omega$$

- The differentiability of $E(\omega)$ depends on the structure of \mathcal{M}_ω .
- A crystal $W \subset \mathbb{R}^3$ can be modeled as a set that minimizes surface energy, ϕ , for a fixed volume:

$$\min_W \int_{\partial W} \phi(\nu(x)) dx, \quad \text{vol}(W) = \text{const},$$

where

$$\phi(\nu) = \frac{1}{|\nu|} E(\omega), \quad \nu = (\omega, -1).$$

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Specific Form of S

- $Au = -\operatorname{div}(a(x)\nabla u)$

$$S(u) = \int_{\mathbb{R}^d} \frac{1}{2}(Au)u + V(x, u) dx = \int_{\mathbb{R}^d} \frac{1}{2} (a(x)\nabla u) \cdot \nabla u + V(x, u) dx$$

V is \mathbb{Z}^{d+1} -periodic, and $a(x)$ is symmetric, positive definite and \mathbb{Z}^d -periodic.

- Minimizing surfaces satisfy the elliptic PDE

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The Reduced Functional

- Fix $\omega \in \frac{1}{N}\mathbb{Z}^d$ and look for N -periodic Birkhoff minimizers of S of the form $u(x) = \omega \cdot x + z(x)$.
- This reduces to minimizing

$$S_N(u) = \int_{[0,N]^d} \frac{1}{2}(Au)u + V(x, u(x)) dx$$

where $u(x) = \omega \cdot x + z(x)$ and $z(x+k) = z(x)$ for all $k \in N\mathbb{Z}^d$.

- S_N is called a *reduced functional*, and minimizers satisfy

$$\operatorname{div}(a(x)\nabla u) = V_u(x, u), \quad z(x+k) = z(x) \quad \forall k \in N\mathbb{Z}^d.$$

This is a cell problem for $z(x)$.

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The Sobolev Spaces $H_{\gamma,A}^\beta$

- For $\gamma > 0$, fractional powers of $\gamma I + A$ are defined as

$$(\gamma I + A)^{-\beta} = C_\beta \int_0^\infty t^{\beta-1} e^{-t(\gamma I + A)} dt$$

- $H_{\gamma,A}^\beta$ is defined as

$$H_{\gamma,A}^\beta(N\mathbb{T}^d) = \{u \in H^0(N\mathbb{T}^d) : \langle (\gamma I + A)^\beta u, u \rangle_0 < \infty\}$$

with the inner product

$$\langle u, v \rangle_\beta = \langle (\gamma I + A)^\beta u, v \rangle_0.$$

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$$\begin{aligned} DS_N(u)\eta &= \langle \nabla_0 S_N(u), \eta \rangle_0 \\ &= \langle Au + V_u(x, u), \eta \rangle_0 \\ &= \langle (\gamma I + A)^\beta (\gamma I + A)^{-\beta} (Au + V_u(x, u)), \eta \rangle_0 \\ &= \langle (\gamma I + A)^{-\beta} (\gamma u + Au - \gamma u + V_u(x, u)), \eta \rangle_\beta \\ &= \langle (\gamma I + A)^{1-\beta} u - (\gamma I + A)^{-\beta} (\gamma u - V_u(x, u)), \eta \rangle_\beta \\ &= \langle \nabla_\beta S_N(u), \eta \rangle_\beta \end{aligned}$$

The descent equation $\partial_t u = -\nabla_\beta S_N(u)$ is

$$\partial_t u = -(\gamma I + A)^{1-\beta} u + (\gamma I + A)^{-\beta} (\gamma u - V_u(x, u))$$

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The Descent Equation: $\partial_t u = -\nabla_\beta \mathcal{S}_N(u)$

Theorem (B., de la Llave, Valdinoci)

If $u(t, x)$ and $w(t, x)$ are solutions to the gradient descent equation

$$\partial_t u = -(\gamma + A)^{1-\beta} u + (\gamma + A)^{-\beta} (\gamma u - V_u(x, u))$$

for initial conditions $u_0, w_0 \in L^\infty(N\mathbb{T}^d)$, with $\beta \in [0, 1]$, $\gamma > \sup |V_{uu}|$, $V \in C^3$, $u_0(x) \geq w_0(x)$ for a.e. x , then $u(t, x) \geq w(t, x)$ for all $t > 0$ and a.e. $x \in N\mathbb{T}^d$. In particular, if $u_0(x) = \omega \cdot x + z_0(x)$ is a Birkhoff function, then $u(t, x) = \omega \cdot x + z(t, x)$ is Birkhoff for each $t > 0$.

Sketch of Proof: Semigroup Theory

We rewrite gradient as $-\nabla_{\beta}S(u) = Lu + X(u)$

$$L := -(\gamma I + A)^{1-\beta}, \quad X(u) := (\gamma I + A)^{-\beta} (\gamma u - V_u(x, u)).$$

Mild solutions of $\partial_t u = Lu + X(u)$ satisfy

$$u(t, x) = e^{tL}u_0(x) + \int_0^t e^{(t-\tau)L}X(u(\tau, x))d\tau.$$

Smoothing estimates for e^{tL} , X and Moser estimates show that solutions exist for bounded initial data and gain regularity.

$$\|e^{tL}\|_{\mathcal{L}(H^s, H^{s+2\alpha(1-\beta)})} \leq c_{\alpha}t^{-\alpha}, \quad \|V(x, u)\|_{H^r} \leq c_r|V|_{C^r}(1 + \|u\|_{H^r}).$$

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Sketch of Proof: Comparison

If $u \geq w$ and $\gamma > \sup |V_{uu}|$ then $\gamma u - V_u(x, u) \geq \gamma w - V_u(x, w)$.

$$(\gamma I + A)^{-\beta} = C_\beta \int_0^\infty \tau^{\beta-1} e^{-\tau(\gamma I + A)} d\tau$$

implies $(\gamma I + A)^{-\beta} u \geq (\gamma I + A)^{-\beta} w$ when $u \geq w$, and $X(u) \geq X(w)$ follows.

The Bochner identity

$$e^{tL} = \int_0^\infty \phi(t, \beta, \tau) e^{-\tau(\gamma I + A)} d\tau, \quad \phi(t, \beta, \tau) > 0 \quad \forall \tau > 0$$

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Sketch of Proof: Iteration and Extension

If $u \geq w$ then $e^{(t-\tau)L}X(u(\tau, x)) \geq e^{(t-\tau)L}X(w(\tau, x))$.

If $u_0(x) \geq w_0(x)$ then $u^j(t, x) \geq w^j(t, x)$, where

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$u^{j+1}(t, x)$ converges to solution of $\partial_t u = Lu + X(u)$.

The method generalizes to energies of the form

$$S(u) = \int_{\mathbb{R}^d} \frac{1}{2}(A^\alpha u)u + V(x, u) dx, \quad \alpha \in (0, 1)$$

where equilibrium solutions solve

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The Numerical Method, $d = 2$

Constant coefficients case: $u(x) = \omega \cdot x + z(x)$

$$\partial_t z = -(\gamma I - \Delta)^{1-\beta} z + (\gamma I - \Delta)^{-\beta} (\gamma z - V(x, \omega \cdot x + z))$$

In Fourier space the descent equation is

$$\partial_t \widehat{z} = - \left(\gamma + \frac{4\pi^2}{N^2} |k|^2 \right)^{1-\beta} \widehat{z} + \left(\gamma + \frac{4\pi^2}{N^2} |k|^2 \right)^{-\beta} (\gamma \widehat{z} - \mathcal{F}[V_u(x, \omega \cdot x + z)])$$

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- If $\beta \approx 1$, the stiffness of the equation is greatly reduced.

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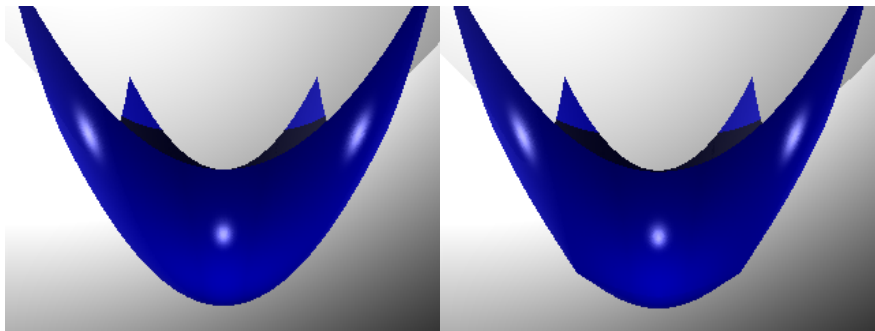
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- If n^2 Fourier modes are used, the number of operations for one step is on the order of $n^2 \log(n)$.
- If $\beta \approx 1$, the stiffness of the equation is greatly reduced.

Example: $\varepsilon = 0$ compared with $\varepsilon > 0$

$$E_\varepsilon(\omega) = \frac{1}{N^2} \int_{[0,N]^2} \frac{1}{2} |\nabla u|^2 + \varepsilon \sin(2\pi k_1 x_1) \sin(2\pi k_2 x_2) \cos(2\pi u) dx$$



(a) $\varepsilon = 0$

(b) $\varepsilon > 0$

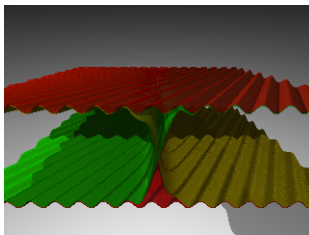
Computed from $u(x) = \omega \cdot x + z(x)$ for $\omega \in [-2, 2]^2$ and $k = (1, 1)$

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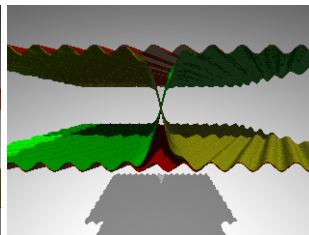
Senn's Formula

- Minimizing surfaces define a set of gaps G .
- Senn's Formula for the derivative:

$$D_{e_j}A_\varepsilon(\omega) + D_{-e_j}A_\varepsilon(\omega) = \sum_G \int_0^\infty \int_0^1 F_\varepsilon(x, u_T, \nabla u_T) - F_\varepsilon(x, u_B, \nabla u_B) dx_i dx_j$$



(c)

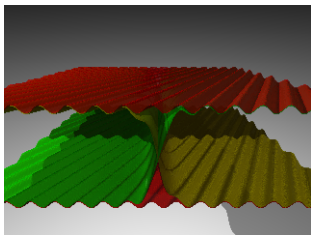


(d)

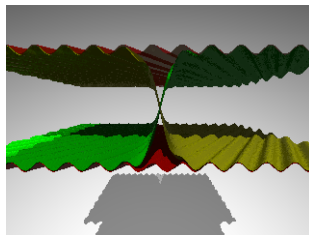
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(e)



(f)

Lindstedt Series

- Take $F_\varepsilon(x, u, \nabla u) = \frac{1}{2}|\nabla u|^2 + \varepsilon V(x, u)$
- For fixed $\omega \in \frac{1}{N}\mathbb{Z}^d$, find an expression for $u_\varepsilon(x)$ as a series in ε

$$u_\varepsilon(x) = \sum_{j=0}^{\infty} u_j(x)\varepsilon^j$$

with u_j N -periodic, and solving

$$-\Delta u_\varepsilon + \varepsilon V_u(x, u_\varepsilon) = 0, \quad \sup_x |u_\varepsilon(x) - \omega \cdot x| < \infty.$$

- Also find expression for the heteroclinic connections between the gaps.

- Take $F_\varepsilon(x, u, \nabla u) = \frac{1}{2}|\nabla u|^2 + \varepsilon V(x, u)$
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$$-\Delta u_\varepsilon + \varepsilon V_u(x, u_\varepsilon) = 0, \quad \sup_x |u_\varepsilon(x) - \omega \cdot x| < \infty.$$

- Also find expression for the heteroclinic connections between the gaps.

Lindstedt Series

- Take $F_\varepsilon(x, u, \nabla u) = \frac{1}{2}|\nabla u|^2 + \varepsilon V(x, u)$
- For fixed $\omega \in \frac{1}{N}\mathbb{Z}^d$, find an expression for $u_\varepsilon(x)$ as a series in ε

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Lindstedt Series

To solve $\Delta(u_0 + \varepsilon u_1 + \dots) = \varepsilon V_u(x, u_0 + \varepsilon u_1 + \dots)$ collect powers of ε :

$$\Delta u_0 = 0 \quad \implies \quad u_0 = \omega \cdot x + \alpha$$

$$\Delta u_1 = V_u(x, u_0)$$

$$\Delta u_2 = V_{uu}(x, u_0)u_1$$

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Theorem (B., de la Llave)

Let $u_0(x) = \omega \cdot x + \alpha$, $\omega \in \frac{1}{N}\mathbb{Z}^d$, and $\alpha \in [0, 1)$. If

$$\int_{N\mathbb{T}^d} V_{uu}(x, u_0) dx \neq 0$$

then there are at least two choices of α such that $\Delta u_j = [V_u(x, u^{<j})]_{j-1}$ has a periodic solution for all $j \geq 1$.

Proof of Theorem

If $\Phi(\alpha) = \int_{N\mathbb{T}^d} V_u(x, \omega \cdot x + \alpha) dx$, then

$$\begin{aligned}\int_0^1 \Phi(\alpha) d\alpha &= \int_0^1 \int_{N\mathbb{T}^d} V_u(x, \omega \cdot x + \alpha) dx d\alpha \\ &= \int_0^1 \int_{N\mathbb{T}^d} \frac{\partial}{\partial \alpha} V(x, \omega \cdot x + \alpha) dx d\alpha \\ &= \int_{N\mathbb{T}^d} V(x, \omega \cdot x + 1) - V(x, \omega \cdot x) dx = 0. \\ &\implies \Phi \text{ has a zero in } [0, 1)\end{aligned}$$

- $\Phi(\alpha) = \Phi(\alpha + 1) \implies \Phi$ has at least two zeros.
- $\Delta u_1 = V_u(x, u_0)$ can be solved for $u_1 = u_1^* + \lambda_1$.

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Proof of Theorem

Assuming we have solved $\Delta u_j = [V_u(x, u^{<j})]_{j-1}$ for $u_j = u_j^* + \lambda_j$. Write $[V_u(x, u^{<j+1})]_j = V_{uu}(x, u_0)(u_j^* + \lambda_j) + R(u^{<j})$.

$$\text{Set } \lambda_j = -\frac{\int V_{uu}(x, u_0)u_j^* + R(u^{<j}) dx}{\int V_{uu}(x, u_0) dx}.$$

Then

$$\int_{N\mathbb{T}^d} [V_u(x, u^{<j+1})]_j dx = \int_{N\mathbb{T}^d} V_{uu}(x, u_0)(u_j^* + \lambda_j) + R(u^{<j}) dx = 0$$

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Convergence via Newton Method

- Set $G_\varepsilon(u) = -\Delta u + \varepsilon V_u(x, u)$, find u_ε with $G_\varepsilon(u_\varepsilon) = 0$.
- Find a zero of G_ε via Newton Method:

$$U_\varepsilon^{n+1} = U_\varepsilon^n - DG_\varepsilon(U_\varepsilon^n)^{-1} G_\varepsilon(U_\varepsilon^n)$$

with initial guess

$$U_\varepsilon^0 = \omega \cdot x + \alpha + \varepsilon u_1 + \dots + \varepsilon^M u_M.$$

Theorem (B., de la Llave)

Under non-degeneracy conditions on V , and if ε is small, and M is large, then $U_\varepsilon^n \rightarrow U_\varepsilon^\infty$, analytic in ε in a neighborhood of zero, and $G_\varepsilon(U_\varepsilon^\infty) = 0$.

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Connecting Surfaces in the Gaps

- If $\int V_{uu}(x, \omega \cdot x + \alpha) dx \neq 0$ then to solve $\Delta u_1 = V_u(x, \omega \cdot x + \alpha)$ we must make a choice of α .
- If we look for $u(x) = \omega \cdot x + \alpha(\sqrt{\varepsilon}x) + \varepsilon u_1(x) + \dots$, we get a PDE of the form

$$\Delta \alpha = g_\omega(x, \alpha), \quad \alpha(x) \rightarrow \alpha_\pm \text{ as } x \cdot v \rightarrow \pm\infty.$$

- Example: $V(x, u) = \sin(2\pi kx) \cos(2\pi u)$, and $\omega = k \in \mathbb{Z}^2$

$$\Delta \alpha = -\pi \cos(2\pi \alpha), \quad \alpha_+ = \frac{1}{4}, \quad \alpha_- = -\frac{3}{4}$$

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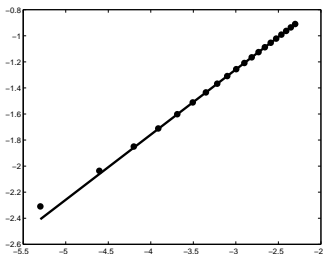
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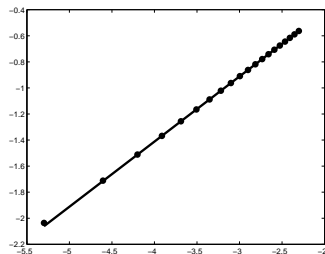
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Log-Log Plots of $J(\omega, \varepsilon) = D_{e_1}A_\varepsilon(\omega) + D_{-e_1}A_\varepsilon(\omega)$



$$(g) \quad J(\omega, \varepsilon) \approx \frac{4}{\pi} \sqrt{\varepsilon}$$



$$(h) \quad J(\omega, \varepsilon) \approx \frac{4\sqrt{2}}{\pi} \sqrt{\varepsilon}$$

Figure: In 1(g) $V(x, u) = \sin(2\pi k_1 x_1) \sin(2\pi k_2 x_2) \cos(2\pi u)$, and in 1(h) $V(x, u) = \sin(2\pi k \cdot x) \cos(2\pi u)$. Both plots are for $\omega = k$.