GLOBAL DYNAMICS OF BOSE-EINSTEIN CONDENSATION FOR A MODEL OF THE KOMPANEETS EQUATION

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ABSTRACT. The Kompaneets equation describes a field of photons exchanging energy by Compton scattering with the free electrons of a homogeneous, isotropic, non-relativistic, thermal plasma. This paper strives to advance our understanding of how this equation captures the phenomenon of Bose-Einstein condensation through the study of a model equation. For this model we prove existence and uniqueness theorems for global weak solutions. In some cases a Bose-Einstein condensate will form in finite time, and we show that it will continue to gain photons forever afterwards. Moreover we show that every solution approaches a stationary solution for large time. Key tools include a universal super solution, a one-sided Oleinik type inequality, and an $L^1$ contraction.

1. Introduction

Photons can play a major role in the transport of energy in a fully ionized plasma through the processes of emission, absorption, and scattering. At high temperatures or low densities, the dominant process can be Compton scattering off free electrons. We make the simplification that the plasma is spatially uniform, isotropic, nonrelativistic, and thermal at temperature $T$. We also neglect the heat capacity of the photons and assume that $T$ is fixed. If the photon field is also spatially uniform and isotropic then it can be described by a nonnegative number density $f(x,t)$ over the unitless photon energy variable $x \in (0,\infty)$ given by

$$x = \frac{\hbar |k|c}{k_B T},$$

where $\hbar$ is Planck’s constant, $c$ is the speed of light, $k_B$ is Boltzmann’s constant, and $k$ is the photon wave vector. Because $x$ is a unitless radial variable, the total photon number and (unitless) total photon energy associated with $f(x,t)$ are then given by

$$N[f] = \int_0^\infty f x^2 \, dx, \quad E[f] = \int_0^\infty f x^3 \, dx.$$

When the only energy exchange mechanism is Compton scattering of the photons by the free electrons in the plasma then the evolution of $f$ is governed by the Kompaneets equation

$$\partial_t f = \frac{1}{x^2} \partial_x \left[ x^4 \left( \partial_x f + f^2 \right) \right]. \quad (1.1)$$
This Fokker-Planck approximation to a quantum Boltzmann equation is justified physically by arguing that little energy is exchanged by each photon-electron collision.

Because $x$ is a radial variable, the associated divergence operator has the form $x^{-2} \partial_x x^2$. Thereby we see from (1.1) that the diffusion coefficient in the Kompaneets equation is $x^2$, which vanishes at $x = 0$. This singular behavior allows the $f^2$ convection term to drive the creation of a photon concentration at $x = 0$. This hyperbolic mechanism models the phenomenon of Bose-Einstein condensation. Our goal is to better understand how the Kompaneets equation generally describes the process of relaxation to equilibrium over large time and how it captures the phenomenon of Bose-Einstein condensation in particular.

Rather than addressing these questions for the Kompaneets equation (1.1) we will consider the model Fokker-Planck equation

$$\frac{\partial f}{\partial t} = \frac{1}{x^2} \partial_x \left[ x^4 \left( \partial_x f + f^2 \right) \right],$$

posed over $x \in (0, 1)$ and subject to a zero flux boundary condition at $x = 1$. This model is obtained by simply dropping the $f$ term that appears in the flux of the Kompaneets equation (1.1) and reducing the $x$-domain to $(0, 1)$. As we will see, this model shares many structural features with the Kompaneets equation. In particular, it shares the $x^2$ diffusion coefficient and the $f^2$ convection term that allow the onset of Bose-Einstein condensation. The neglect of the $f$ term in the flux of the Kompaneets equation is a reasonable approximation during the onset of Bose-Einstein condensation when we expect $f$ to be large. The advantage of model (1.2) is that we know some estimates for it that have no known analogs for (1.1), and which facilitate the study of condensate dynamics and equilibration. A disadvantage of (1.2) is that its equilibrium solutions differ from those of (1.1), so we may expect the long-time behavior of its solutions to be similar to that of solutions of (1.1) only in a qualitative sense.

1.1. Structure of the Kompaneets Equation. Here we describe some structural features of the Kompaneets equation that will be shared by our model. First, solutions of (1.1) formally conserve total photon number $N[f]$. Indeed, we formally compute that

$$\frac{d}{dt} N[f] = x^4 \left( \partial_x f + f^2 \right) \bigg|^{\infty}_{0} = 0,$$

under the expectation that the flux vanishes as $x$ approaches 0 and $\infty$. Second, solutions of (1.1) formally dissipate quantum entropy $H[f]$ given by

$$H[f] = \int_{0}^{\infty} h(f, x) x^2 dx,$$

$$h(f, x) = f \log(f) - (1 + f) \log(1 + f) + x f.$$

Indeed, because

$$h_f(f, x) = \log(f) - \log(1 + f) + x = \log \left( \frac{e^x f}{1 + f} \right),$$

$$\partial_x h_f = h_f f \partial_x f + 1 = \frac{1}{f(1 + f)} (\partial_x f + f + f^2),$$

we formally compute that

$$\frac{d}{dt} H[f] = \int_{0}^{\infty} h_f(f, x) (\partial_t f) x^2 dx = - \int_{0}^{\infty} x^4 f(1 + f) (\partial_x h_f(f, x))^2 dx \leq 0.$$
By this “H theorem,” we expect solutions to approach an equilibrium for which
\[ \partial_x h_f(f, x) = 0. \] These equilibria have the Bose-Einstein form
\[ f = f_\mu(x) = \frac{1}{e^{x+\mu} - 1}, \quad \text{for some } \mu \geq 0. \]

At this point a paradox arises. The total photon number for the equilibrium \( f_\mu \) is
\[ N[f_\mu] = \int_0^\infty \frac{x^2}{e^{x+\mu} - 1} \, dx. \]
This is a decreasing function of \( \mu \) over \([0, \infty)\), and is thereby bounded above by \( N[f_0] \), which is finite. Because total number is supposed to be conserved, we expect any solution to relax to an equilibrium \( f_\mu \) with the same total number as the initial data, satisfying \( N[f_\mu] = N[f_{\text{in}}] \). But if the initial number \( N[f_{\text{in}}] > N[f_0] \) then no such equilibrium exists!

1.2. Bose-Einstein Condensation. The foregoing paradox indicates that there must be a breakdown in the expectations given above. Previous studies (in particular) have shown that a breakdown in the no-flux condition at \( x = 0 \) can occur. A physical interpretation of a nonzero photon flux at \( x = 0 \) is that the photon distribution forms a concentration of photons at zero energy (i.e., energy that is negligible on the scales described by the model). This Bose-Einstein condensate accounts for some of the total photon number. See especially the works \([27, 3, 6, 12]\), and the discussion of related literature in subsection 1.4 below. As massless, chargeless particles of integer spin, photons are the simplest bosons. Indeed, S. N. Bose had photons in mind in 1924 when he proposed his new way of counting indistinguishable particles, work soon followed by Einstein’s prediction of the existence of the condensate. Yet it was not until 2010 that the first observation of a photon condensate was reported by Martin Weitz and colleagues \([18]\).

In the present context, we can gain insight into this phenomenon by dropping the diffusion term in (1.1), as discussed by Levich and Zel’dovich \([27]\). In this case the Kompaneets equation simplifies to the first-order hyperbolic equation
\[ \partial_t f = \frac{1}{x^2} \partial_x \left[ x^4 (f + f^2) \right]. \]
Letting \( n = x^2 f \), this becomes
\[ \partial_t n = \partial_x \left[ x^2 n + n^2 \right], \quad \text{(1.3)} \]
whose characteristic equations are
\[ \dot{x} = -x^2 - 2n, \quad \dot{n} = 2xn. \]
Because \( n \geq 0 \), the origin \( x = 0 \) is an outflow boundary, and no boundary condition can be specified there. Clearly any nonzero entropy solution will develop a nonzero flux of photons into the origin in finite time, leading to the formation of a condensate.

The fact the \( f^2 \) convection term plays an essential role in the formation of Bose-Einstein condensates is illustrated by considering what happens when that term is dropped from the Kompaneets equation (1.1). This leads to the linear degenerate parabolic equation
\[ \partial_t f = \frac{1}{x^2} \partial_x \left[ x^4 (\partial_x f + f) \right]. \quad \text{(1.4)} \]
This equation is the analog of the Kompaneets equation for classical statistics. Its solutions formally conserve $N[f]$ and dissipate the associated entropy

$$H[f] = \int_0^\infty h(f,x) x^2 dx,$$

where $h(f,x) = f \log(f) - f + xf$.

Its family of equilibria is

$$f_\mu(x) = e^{-x- \mu}, \text{ for some } \mu \in \mathbb{R}.$$

The initial-value problem for (1.4) is well-posed in cones of nonnegative densities $f$ such that

$$\int_0^\infty (e^x f)^p e^{-x} x^2 dx < \infty, \text{ for some } p \in (1, \infty).$$

These solutions

- are smooth over $\mathbb{R}^+ \times \mathbb{R}^+$,
- are positive over $\mathbb{R}^+ \times \mathbb{R}^+$ provided that $f$ is nonzero,
- satisfy all the expected boundary conditions,
- conserve $N[f]$ and dissipate $H[f]$ as expected,
- approach $f_\mu$ as $t \to \infty$, where $N[f_\mu] = N[f]$.

In particular, the no-flux boundary condition is satisfied at $x = 0$ without being imposed! Therefore, no Bose-Einstein concentration happens!

1.3. Present Investigation. Of course, solutions of the hyperbolic model (1.3) may develop shocks at any location. However, the diffusion term in the Kompaneets equation (1.1) prevents shock formation for $x > 0$. The results of Escobedo et al. [6] prove that the degeneracy of its diffusion does not prevent shock formation at $x = 0$. These authors proved that there exist solutions of (1.1) that are regular and satisfy no-flux conditions for $t$ on a bounded interval $0 < t < T_c$ (which is solution-dependent), but at time $t = T_c$ the flux at $x = 0$ becomes nonzero. Such solutions exist for arbitrarily small initial photon number. Moreover, global existence and uniqueness of solutions of (1.1) was proved subject to a boundedness condition for $x^2 f$ for $x \in [0, 1]$.

A number of interesting questions about solutions to the Kompaneets equation remain unanswered by previous studies: What happens to a condensate once it forms? Can it lose photons as well as gain them? Are there any boundary conditions at all that we can impose near $x = 0$ that yield different condensate dynamics, allowing the condensate to interact with other photons? Can we identify the long-time limit of any initial density of photons?

In order to focus clearly on these questions, we have found it convenient to drop the linear term $x^2 f$ from the Kompaneets flux and consider the model equation (1.2), which retains the essential features of nonlinearity and degenerate diffusion. The equilibria of equation (1.2) are

$$f_\mu(x) = \frac{1}{x + \mu}, \text{ for some } \mu \geq 0. \quad (1.5)$$

We include these solutions in the class of functions considered by restricting our attention to the interval $0 < x < 1$ and imposing a no-flux boundary condition at $x = 1$. For these equilibria the maximal total photon number is $N[f_0] = \frac{1}{2}$.

For this model problem, we shall assemble a fairly detailed description of well-posedness and long-time dynamics. We establish existence and uniqueness in a
natural class of nonnegative weak solutions for initial data that simply has some finite moment
\[ \int_0^\infty x^p f^\text{in} \, dx, \quad p \geq 2. \]
These results are proved with essential use of estimates for hyperbolic (first-order) equations, and establish that while the model Kompaneets equation (1.4) is parabolic for \( x > 0 \), the point \( x = 0 \) remains an outflow boundary at which no boundary condition can be specified.

The solution map is nonexpansive in \( L^1 \)-norm with weight \( x^2 \). Therefore the total photon number \( N[f(t)] \) is nonincreasing in time. A condensate can gain photons but never lose them, and must form in finite time whenever \( N[f^\text{in}] > N[f_0] \). Moreover, once it starts growing it never stops. Every solution relaxes to some equilibrium state \( f_\mu \) in the long-time limit \( t \to \infty \). We cannot identify the limiting state in general, but the solution must approach the maximal steady state \( f_0 \) if the initial data \( f^\text{in} \geq f_0 \) everywhere.

The proofs of the results on long-time behavior are greatly facilitated by two features of the model problem (1.2). First, the problem admits a universal super-solution \( f^{\text{super}} \) determined by
\[ x^2 f^{\text{super}}(x,t) = x + \frac{1-x}{t} + \frac{2}{\sqrt{t}}. \] (1.6)
By consequence, for every solution, \( x^2 f \) is in fact bounded in \( x \) for each \( t > 0 \), and moreover one has \( \limsup_{t \to \infty} x^2 f(x,t) \leq x = x^2 f_0(x) \) for every solution, for example. Also, every solution satisfies
\[ \partial_x (x^2 f) \geq -\frac{4}{t}, \]
which is Oleinik’s inequality for admissible solutions of the conservation law (1.3) after dropping the linear flux term \( x^2 n \).

1.4. Literature on Related Problems. As indicated above, the Kompaneets equation is derived from a Boltzmann-Compton kinetic equation for photons interacting with a gas of electrons in thermal equilibrium—see [19], and especially [8] for a derivation and links to some of the physical literature. Regarding the analysis of the Boltzmann-Compton equation itself, when a simplified regular and bounded kernel is adopted, Escobedo and Mischler [7] studied the asymptotic behavior of the solutions, and showed that the photon distribution function may form a condensate at zero energy asymptotically in infinite time. Further, Escobedo et al. [9] showed that the asymptotic behavior of solutions is sensitive not only to the total mass of the initial data but also to its precise behavior near the origin. In some cases, solutions develop a Dirac mass at the origin for long times (in the limit \( t \to \infty \)) in a self-similar manner. For the Boltzmann-Compton equation with a physical kernel, some results concerning both global existence and non-existence, depending on the size of initial data, were obtained by Ferrari and Nouri [11].

A natural question is whether results analogous to those obtained in the present paper concerning the development of condensates may hold for other kinetic equations that govern boson gases, such as Boltzmann-Nordheim (aka Uehling-Uhlenbeck) quantum kinetic equations. Concerning these issues we refer to the work of H. Spohn [25], Xuguang Lu [21], the recent analysis of blowup and condensation formation
by Escobedo and Velazquez [10], and references cited therein. Higher-order Fokker-Planck-type approximations to the Boltzmann-Nordheim equation were derived formally by Josserand et al. [12], and an analysis of the behavior of solutions has been performed recently by Jüngel and Winkler [13, 14].

Bose-Einstein equilibria and condensation phenomena also appear in classical Fokker-Planck models that incorporate a quantum-type exclusion principle [15, 16]. Concerning mathematical results on blowup and condensates for these models, we refer to work of Toscani [26] and Carrillo et al. [4] and references therein.

1.5. Plan of the Paper. In Section 2 we introduce our notion of weak solutions for (1.2) together with relevant notations, followed by precise statements of the main results, and a discussion of related literature. In Section 3 we prove the uniqueness of weak solutions for initial data with some finite moment. Existence is proved in Section 4 by passing to the limit in a problem regularized by truncating the domain away from \( x = 0 \).

In Section 5 we establish that condensation must occur if the initial photon number \( N[f_{in}] > N[f_0] \), and we show that once a shock forms at \( x = 0 \) in finite time, it will persist and continue growing for all later time. Large-time convergence to equilibrium is proved for every solution in Section 6 using arguments related to LaSalle’s invariance principle.

The paper concludes with three appendices that deal with several technical but less central issues. A simple, self-contained treatment of some anisotropic Sobolev embedding estimates used in our analysis is contained in Appendix A. The truncated problem used in Section 4 requires a special treatment due to the fact that the zero-flux boundary condition at \( x = 1 \) is nonlinear — this treatment is carried out in Appendix B. A proof of interior regularity of the solution, sufficient to provide a classical solution away from \( x = 0 \) but up to the boundary \( x = 1 \), is established in Appendix C.

2. Main results

2.1. Model Initial-Value Problem. In light of the foregoing discussion, it is convenient to work with the densities

\[
n = x^2 f, \quad n^{in} = x^2 f^{in}.
\]

The flux in our model equation (1.2) can be expressed as

\[
J = x^2 \partial_x n + n^2 - 2xn.
\]

The initial-value problem for our model equation (1.2) that we will consider is

\[
\begin{align*}
\partial_t n - \partial_x J &= 0, & 0 < x < 1, \ t > 0, \\
J(1, t) &= 0, & t > 0, \\
n(x, 0) &= n^{in}(x), & 0 < x < 1.
\end{align*}
\]

Here we have imposed the no-flux boundary condition at \( x = 1 \), but do not impose any boundary condition at \( x = 0 \), where the diffusion coefficient \( x^2 \) vanishes.

We work with a weak formulation of the initial-value problem (2.3). We require the initial data \( n^{in} \) to satisfy

\[
n^{in} \geq 0, \quad x^p n^{in} \in L^1((0, 1]) \text{ for some } p \geq 0.
\]
Let \( Q = (0,1] \times (0,\infty) \). We say \( n \) is a weak solution of the initial-value problem (2.3) if

\[
\begin{align*}
  &n \geq 0, \quad n, \, \partial_x n \in L^2_{\text{loc}}(Q), \\
  &x^p n \in L^1((0,1] \times (0,T)) \quad \text{for every } T > 0, \\
  &n(\cdot, t) \to n^{\text{in}} \quad \text{in } L^1_{\text{loc}}((0,1]) \text{ as } t \to 0^+, \\
  &\int_Q (n \, \partial_t \psi - J \, \partial_x \psi) \, dX = 0 \quad (dX = dx \, dt),
\end{align*}
\]

for every \( C^1 \) test function \( \psi \) with compact support in \( Q \). Condition (2.5a) is needed to make sense of the weak formulation (2.5d). Condition (2.5b) is an admissibility condition we need to establish uniqueness. Condition (2.5c) gives the sense in which the initial data is recovered.

### 2.2. Uniqueness, Existence, and Regularity

The following results establish the basic uniqueness, existence, and regularity properties of weak solutions to (2.3). Henceforth we will use \( N[n] \) to denote the total photon number,

\[
N[n] = \int_0^1 n \, dx,
\]

replacing the earlier notation \( N[f] \). We will also denote the positive part of a number \( a \) by \( a_+ = \max\{a,0\} \).

**Theorem 2.1** (Stability and comparison). Let \( n^{\text{in}} \) and \( \bar{n}^{\text{in}} \) satisfy (2.4) for some \( p \geq 0 \). Let \( n \) and \( \bar{n} \) be weak solutions of (2.3) associated with the initial data \( n^{\text{in}} \) and \( \bar{n}^{\text{in}} \) respectively as defined by (2.5). Set \( c_p = p(p + 3) \). Then

\[
\int_0^1 x^p (n - \bar{n})_+(x,t) \, dx \leq e^{c_p t} \int_0^1 x^p (n^{\text{in}} - \bar{n}^{\text{in}})_+ \, dx, \quad \text{a.e. } t > 0. \tag{2.6}
\]

Furthermore, if \( n^{\text{in}} \geq \bar{n}^{\text{in}} \) a.e. on \((0,1)\), then \( n \geq \bar{n} \) a.e. on \( Q \). In particular, if \( n^{\text{in}} = \bar{n}^{\text{in}} \) a.e. on \((0,1)\) then \( n = \bar{n} \) a.e. on \( Q \).

From (2.6) we draw immediately the following conclusion on uniqueness.

**Corollary 2.2** (Uniqueness). Let \( n \) and \( \bar{n} \) be two weak solutions to (2.3), subject to initial data \( n^{\text{in}}, \bar{n}^{\text{in}} \) respectively, with \( x^p n^{\text{in}}, x^p \bar{n}^{\text{in}} \in L^1((0,1]) \). Then

\[
\int_0^1 x^p \left| n(x,t) - \bar{n}(x,t) \right| \, dx \leq e^{c_p t} \int_0^1 x^p \left| n^{\text{in}} - \bar{n}^{\text{in}} \right| \, dx, \quad \text{a.e. } t > 0. \tag{2.7}
\]

For each initial data \( n^{\text{in}} \) satisfying \( x^p n^{\text{in}} \in L^1(0,1) \) for some \( p \geq 0 \), there exists at most one weak solution of (2.3).

**Remark 2.1.** Because \( c_0 = 0 \), if (2.4) holds with \( p = 0 \) then (2.7) is the \( L^1 \)-contraction property

\[
\| (n - \bar{n})(t) \|_{L^1(0,1)} \leq \| n^{\text{in}} - \bar{n}^{\text{in}} \|_{L^1(0,1)}. \tag{2.8}
\]

In particular, the total photon number \( N[n] \) is nonincreasing in time.

**Theorem 2.3** (Existence and global bounds). Let \( n^{\text{in}} \) satisfy (2.4) for some \( p \geq 0 \). Then there exists a unique global weak solution \( n \) of (2.3) as defined by (2.5). Moreover \( x^p n \in C([0,\infty); L^1(0,1)) \) and we have the following bounds:
(i) (A universal upper bound) For every $t > 0$,
\[ n \leq x + \frac{1-x}{t} + \frac{2}{\sqrt{t}} \quad \text{for a.e. } x \in (0, 1), \]

(ii) (Oleinik-type inequality) For a.e. $(x, t) \in Q$,
\[ \partial_x n \geq -\frac{4}{t}. \]

(iii) (Energy estimate) $n \in C((0, \infty), L^2(0, 1))$, and whenever $0 < s < t$,
\[ \int_0^1 n^2(x, t) dx + \int_s^t \int_0^1 [n^2 + x^2(\partial_x n)^2] dx d\tau \leq \int_0^1 n^2(x, s) dx + \frac{8}{3}(t-s). \quad (2.9) \]

Note that the Oleinik-type inequality allows for the formation of ‘shock waves’ in $n$ at $x = 0$, but rules out oscillations.

**Theorem 2.4** (Regularity away from $x = 0$). For the global weak solution $n$ from Theorem 2.3, the quantities $n$, $\partial_x n$, $\partial_t n$ and $\partial_x^2 n$ are locally H"older-continuous on $Q$. Furthermore, $n$ is smooth in the interior of $Q$.

2.3. Dynamics of solutions. Next we state our main results concerning the formation of condensates and the large-time behavior of solutions. Observe that the bounds in (i) and (ii) of Theorem 2.3 imply the existence of the right limit $n(0^+, t)$, for each $t > 0$.

**Theorem 2.5** (Formation and growth of condensates). Let $n^{in}$ satisfy (2.4) for some $p \geq 0$. Let $n$ be the unique global weak solution to (2.3) associated with $n^{in}$. Then

(i) (Conservation of photons.) For every $t > s > 0$ we have
\[ \int_0^1 n(x, t) dx = \int_0^1 n(x, s) dx - \int_s^t n(0^+, \tau)^2 d\tau. \]

(ii) (Persistence.) There exists $t_* \in [0, \infty]$ such that $n(0^+, t) > 0$ whenever $t > t^*$, and $n(0^+, t) = 0$ whenever $0 \leq t < t_*$. 

(iii) (Formation.) If $N[n^{in}] > \frac{1}{2}$ then $n(0^+, t) > 0$ whenever
\[ \frac{1}{2\sqrt{t}} \leq \sqrt{1 + \delta} - 1, \quad \text{where} \quad 2\delta = N[n^{in}] - \frac{1}{2}. \]

(iv) (Absence.) If $n^{in} \leq x$, then $t_* = \infty$. I.e., for every $t > 0$ we have $n(0^+, t) = 0$ and $N[n(\cdot, t)] = N[n^{in}]$.

The formula in part (i) justifies a physical description of the photon energy distribution that contains a Dirac delta mass at $x = 0$, corresponding to a condensate of photons at zero energy that keeps total photon number conserved. By the formula in part (i), the quantity
\[ \int_s^t n(0^+, \tau)^2 d\tau \]
is the number of photons that have entered the condensate between times $s$ and $t$. This quantity is nonnegative, meaning the condensate behaves like a ‘black hole’—photons go in but do not come out. Part (ii) shows that a condensate never stops growing once it starts. Part (iii) states that a condensate must develop in finite time for any initial data $n^{in}$ with more photons than the maximal equilibrium $n_0 = x$. 

Part (iv) means that for initial data bounded above by $n_0$, a condensate does not form.

According to Theorems 2.1 and 2.2, however, we see that the notion of a condensate is not strictly required for mathematically discussing existence and uniqueness. The solution is determined by the conditions imposed for $x \in (0, 1]$, and it so happens that the total photon number can decrease due to an outward flux at $x = 0^+$. Theorem 2.6 (Large-time convergence). Let $n^{in}$ satisfy (2.4) for some $p \geq 0$. Let $n$ be the unique global weak solution to (2.3) associated with $n^{in}$. Then there exists $\mu \geq 0$ such that

$$\lim_{t \to \infty} \|n(\cdot, t) - n_\mu\|_1 = 0, \quad \text{where} \quad n_\mu(x) = \frac{x^2}{x + \mu}.$$  

The equilibrium $n_\mu$ to which a solution converges depends not only on $N[n^{in}]$, but also on details of $n^{in}$. In some special cases, $\mu$ can be explicitly determined.

Corollary 2.7. Let $n$ be the global solution to (2.3), subject to initial data satisfying $n^{in}(x) \geq x$ for $x \in (0, 1]$. Then

$$\lim_{t \to \infty} n(x, t) = n_0(x) = x.$$  

Moreover,

$$|n(x, t) - x| \leq \frac{1}{t} + \frac{2}{\sqrt{t}}, \quad \text{for every } t > 0. \quad (2.10)$$

If $n^{in}(x) \leq x$ for $x \in (0, 1]$, then

$$\lim_{t \to \infty} n(x, t) = n_\mu(x) = \frac{x^2}{x + \mu},$$

with $\mu$ uniquely determined by the relation

$$N[n^{in}] = N[n_\mu] = \frac{1}{2} - \mu + \mu^2 \log \left(1 + \frac{1}{\mu}\right). \quad (2.11)$$

Remark 2.2. For the model equation (1.2), these results provide a definite answer to the main issues of concern. The main assertions are expected to hold true for the full Kompaneets equation (1.1), and may be partially true for some extensions of the Kompaneets equation. Theorems 2.1 and 2.2 improve upon Theorems 1 and 2 of [6] p. 3839 for the Kompaneets equation, in the sense that we impose no growth condition near $x = 0$. Though for a model equation, Theorems 2.4 and 2.5 provide a theoretical justification of observations made previously, including the detailed singularity analysis given in [6], the self-similar blow-up of the Kompaneets equation’s solution in finite time [12], as well as the classical result of Levich and Zel’dovich [27] on shock waves in photon spectra.

Remark 2.3. We remark that the quantum entropy defined by

$$H[n] = \int_0^1 [xn - x^2 \log(n)] \, dx$$

satisfies

$$H[n(t)] + \int_0^t \int_0^1 n^2 \left(1 - \partial_x \left(\frac{x^2}{n}\right)\right)^2 \, dx \, dt \leq H[n^{in}], \quad \forall t > 0,$$
provided $H[n^{in}] < \infty$. As we have no need for this entropy dissipation inequality in this paper, we omit the proof. We mention, however, that the entropy $H[n]$ is not sensitive to the presence of the Bose-Einstein condensate.

3. Uniqueness of weak solutions

This section is primarily devoted to the proof of Theorem 2.1. At the end of this section we include an additional result, a strict $L^1$ contraction property, which will be used in section 6.

3.1. Proof of Theorem 2.1

Let $w = n - \bar{n}$ and $\bar{n} = n + \bar{n} - 2x$. Then from (2.5d) for both $n$ and $\bar{n}$ it follows that

$$\int_Q (w \partial_t \psi - (x^2 \partial_x w + \bar{n}w) \partial_x \psi) = 0. \tag{3.1}$$

The estimate (2.6) can be derived formally by using a test function of form $\psi = x^p \mathbb{1}_{[0,t]}(w)$, where $H(w)$ is the usual Heaviside function and $\mathbb{1}_E$ is the characteristic function of a set $E$. This is not an admissible test function, however, and instead we need several approximation steps.

For use below, we fix a smooth, nondecreasing cutoff function $\chi : \mathbb{R} \to [0,1]$ with the property $\chi(x) = 0$ for $x \leq 1$, $\chi(x) = 1$ for $x \geq 2$, and set $\chi_\epsilon(x) = \chi(x/\epsilon)$ for $\epsilon > 0$. For any interval $I \subset [0,\infty)$ we define the space-time domains

$$Q_I = (0,1] \times I, \quad \text{so} \quad Q = Q_{(0,\infty)} = (0,1] \times (0,\infty). \tag{3.2}$$

1. (Steklov average in $t$.) For $h \not= 0$, the Steklov average $u_h$ of a continuous function $u$ on $Q$ is defined by extending $u(x,t)$ to be zero for $t < 0$, and setting

$$u_h(x,t) = \frac{1}{h} \int_{t-h}^{t+h} u(x,s) \, ds, \quad (x,t) \in Q.$$

By density arguments, the Steklov average extends to an operator with the following properties: First, for $1 \leq p < \infty$, if $u \in L^p_{loc}(Q)$ then $u_h \in L^p_{loc}(Q)$ with weak derivative

$$\partial_t u_h = \frac{u(\cdot, t+h) - u(\cdot, t-h)}{h} \in L^p_{loc}(Q).$$

Moreover, one has $u_h \to u$ in $L^p_{loc}(Q)$ as $h \to 0$.

Since

$$n, \bar{n} \in B_+ := \{ n \mid n, \partial_n n \in L^2_{loc}(Q) \text{ with } n \geq 0 \},$$

it follows $\partial_j \partial_k \bar{n} w \in L^2_{loc}(Q)$ for $j, k = 0, 1$, whence $w_h$ is continuous on $Q$. If $\psi$ is a $C^1$ test function with compact support in $Q$, the same is true for $\psi_{-h}$ if $|h|$ is sufficiently small, and a simple calculation with integration by parts and justified by density of smooth functions shows that

$$\int_Q w \partial_t (\psi_{-h}) = \int_Q w (\partial_t \psi)_{-h} = \int_Q w_h \partial_t \psi = -\int_Q (\partial_t w_h) \psi.$$

Substitution of this into (3.1) and treating the other term similarly, one finds

$$\int_Q \left( (\partial_t w_h \psi + (x^2 \partial_x w + \bar{n}w) \partial_x \psi \right) = 0. \tag{3.3}$$

Recall $n, \bar{n} \in B_+$, hence $\bar{n}w$ and $\partial_x (\bar{n}w)$ are in $L^1_{loc}(Q)$, whence $(\bar{n}w)_h$ is continuous in $Q$. By replacing $\psi(x,t)$ by $\psi(x,t)\chi_\epsilon(t-\sigma)\chi_\epsilon(\tau-t)$ and taking $\epsilon \to 0$ using
dominated convergence, we find that for any $C^1$ function $\psi$ with compact support in $Q_{[0,\infty]}$,
\[
\int_{Q_{[\sigma,\tau]}} \left( (\partial_t w_h)\psi + (x^2 \partial_x w + \hat{n} w) \partial_x \psi \right) = 0, \quad \text{whenever } [\sigma, \tau] \subset (0, \infty). \tag{3.4}
\]
By approximation, (3.4) holds for any $\psi \in W^{1,2}(Q)$ supported in $Q_{[0,\infty]}$.

2. (Integrate in $t$) Define $\zeta(a) = \int_0^a \chi_\varepsilon(u) \, du$ as a smooth, convex approximation to the function $a \mapsto a_+$. Since $\zeta$ is Lipschitz with $\zeta'(a) = 1$ for $a > 2\varepsilon$, the composition $\zeta(w_h) \in W^{1,2}_{\text{loc}}(Q)$, with the weak derivatives
\[
\partial_t \zeta(w_h) = \zeta'(w_h) \partial_t w_h, \quad \partial_x \zeta(w_h) = \zeta'(w_h) \partial_x w_h.
\]
We may now set $\psi(x,t) = \eta(x)(\zeta' \circ w_h)(x,t)$ in (3.4), where $\eta$ is any $C^2$ function with compact support in $(0, 1)$. In what follows, we assume also that $\eta \geq 0$ and $\eta' \geq 0$ on $(0, 1)$. The function $t \mapsto \int_0^1 \eta(x)\zeta(w_h(x,t)) \, dx$ is absolutely continuous for $t > 0$, with
\[
\int_0^1 \eta(x)\zeta(w_h(x,t)) \, dx \bigg|_{t=\sigma}^{t=\tau} = \int_{Q_{[\sigma,\tau]}} \eta\zeta'(w_h) \partial_t w_h = -\int_{Q_{[\sigma,\tau]}} (x^2 \partial_x w + \hat{n} w) \partial_x (\eta\zeta'(w_h)) \tag{3.5}
\]
whenever $[\sigma, \tau] \subset (0, \infty)$.

3. (Take $h \to 0$) As $h \to 0$, the hypotheses for weak solutions imply that $n, \bar{n} \in L^1_{\text{loc}}(Q_{[0,\infty]})$. By consequence, in $L^1_{\text{loc}}((0, \infty))$ we have
\[
\int_0^1 \eta(x)\zeta(w_h(x,\cdot)) \, dx \to \int_0^1 \eta(x)\zeta(w(x,\cdot)) \, dx. \tag{3.6}
\]
In fact, we will show that the right-hand side here is absolutely continuous for $t > 0$, from studying the terms on the right-hand side of (3.5): First, as $h \to 0$, in $L^2_{\text{loc}}(Q)$ we have
\[
x^2 \partial_x w_h \to x^2 \partial_x w. \tag{3.7}
\]
And along a subsequence $h_j \to 0$, $\zeta'(w_h) \to \zeta'(w)$ and $\zeta''(w_h) \to \zeta''(w)$ boundedly a.e. on compact subsets of $Q$. Hence in $L^2_{\text{loc}}(Q)$ we have
\[
\partial_x (\eta \zeta'(w_h)) = \eta' \zeta'(w_h) + \eta \zeta''(w_h) \partial_x w_h \to \eta' \zeta'(w) + \eta \zeta''(w) \partial_x w. \tag{3.8}
\]
Since $\zeta'(w) \partial_x w = \partial_x \zeta(w)$, we find
\[
\int_{Q_{[\sigma,\tau]}} (x^2 \partial_x w_h) \partial_x (\eta \zeta'(w_h)) \to \int_{Q_{[\sigma,\tau]}} \left( x^2 \eta' \partial_x \zeta(w) + x^2 \eta \zeta''(w)(x^2 \partial_x w)^2 \right). \tag{3.9}
\]
Next we deal with the nonlinear term in (3.5). Observe
\[
\int_{Q_{[\sigma,\tau]}} (\hat{n} w) \partial_x (\eta \zeta'(w_h)) = \int_0^\tau \eta \zeta'(w_h) (\hat{n} w)(1,t) \, dt - \int_{Q_{[\sigma,\tau]}} \eta \zeta'(w_h)(\partial_x (\hat{n} w)) \tag{3.9}
\]
Since $n, \bar{n} \in B_+$ we have $\hat{n} w, \partial_x (\hat{n} w) \in L^1_{\text{loc}}(Q)$, and it follows that $(\hat{n} w)_h(1,\cdot) \to \hat{n} w(1,\cdot)$ in $L^1_{\text{loc}}((0, \infty))$. Moreover, $w(1, \cdot) \in L^2_{\text{loc}}((0, \infty))$ and $\zeta'(w_h(1,\cdot)) \to \zeta'(w(1,\cdot))$ boundedly a.e. on compact subsets of $(0, \infty)$ along a sub-subsequence of $h \to 0$. 

GLOBAL DYNAMICS OF BOSE-EINSTEIN CONDENSATION 11
Thus we may pass to the limit on the right-hand side of (3.9), integrate back by parts, and infer that the limit is

\[
\int_{Q_{[\sigma,T]}} \eta' \zeta'(w) (\dot{\eta}w)(1,t) \ dt - \int_{Q_{[\sigma,T]}} \eta' \zeta'(w) \partial_x (\dot{\eta}w) = \int_{Q_{[\sigma,T]}} (\dot{\eta}w)(\eta' \zeta'(w) + \eta \zeta''(w) \partial_x) \ dx. 
\]

(3.10)

One can justify this equality using an additional argument approximating \( \mathcal{I} \) does make sense, however, since \( \mathcal{I} \) does not make sense with only the regularity assumed for \( w \), due to insufficient integrability in time \( (L^1 \) for one factor, \( L^2 \) for the other). The right-hand side of (3.10) does make sense, however, since \( \zeta'(w) \) and \( w \zeta''(w) \) are bounded on the support of the integrand.

In sum, we find that in \( \mathcal{I} \) and for a.e. \( \tau > \sigma > 0 \),

\[
\int_{Q_{[\sigma,T]}} \eta(x) \zeta(w(x,t)) \ dx \mid_{t=\tau}^{t=\sigma} = - \int_{Q_{[\sigma,T]}} \left( x \eta' \zeta'(w) + x^2 \eta \zeta''(w) \partial_x \right) \ dx + \int_{Q_{[\sigma,T]}} \eta \zeta''(w) \partial_x (x^2 \eta') \ dx.
\]

(3.11)

4. (Take \( \bar{v} \to 0 \).) Note that since \( \zeta(w) \), \( \partial_x \zeta(w) \in L^2(Q) \), we have \( \zeta(w(1,\cdot)) \in L^2(\bar{v},0,\infty) \) and

\[
- \int_{Q_{[\sigma,T]}} x \eta' \zeta'(w) \ dx = - \int_{Q_{[\sigma,T]}} \eta' \zeta'(w) (\partial_x \zeta(w)) \ dz + \int_{Q_{[\sigma,T]}} \zeta(w) \partial_x (x^2 \eta') \ dx \leq \int_{Q_{[\sigma,T]}} \zeta(w) \partial_x (x^2 \eta').
\]

Since \( \eta, \eta' \geq 0 \), \( \dot{\eta} \geq -2x \), and \( w \zeta' \geq 0 \), therefore

\[
\int_{Q_{[\sigma,T]}} \eta(x) \zeta(w(x,t)) \ dx \mid_{t=\tau}^{t=\sigma} \leq \int_{Q_{[\sigma,T]}} \left( \zeta(w) \partial_x (x^2 \eta') + 2x \eta w \zeta'(w) - \dot{\eta}w \eta \zeta''(w) \partial_x \right) \ dx.
\]

(3.12)

Now we take the limit \( \bar{v} \to 0 \), for which we have \( \zeta \circ \dot{w} \to \dot{w} \) and \( w(\zeta \circ \omega) \to \dot{w} \) pointwise. Moreover, \( w \zeta'' \circ \omega = (w/\bar{v}) \chi'(w/\bar{v}) \) is bounded and converges to zero a.e. Since \( \partial_x \partial_x w \in L^1(Q) \), by dominated convergence the last term in (3.12) tends to zero, and we derive

\[
\int_{Q_{[\sigma,T]}} \eta(x) \zeta''(w(x,t)) \ dx \mid_{t=\tau}^{t=\sigma} \leq \int_{Q_{[\sigma,T]}} \left( \zeta(w) \partial_x (x^2 \eta') + 4x \eta \eta \zeta''(w) \partial_x \right) \ dx.
\]

(3.13)

for a.e. \( \tau > \sigma > 0 \). Due to assumption (2.5c) on weak solutions, now we can take \( \sigma \to 0 \) and conclude that this inequality holds also with \( \sigma = 0 \).

5. (Make Gronwall estimate.) Finally, we take \( \eta \) of the form \( \eta(x) = x^p \chi(x) \), where \( p \geq 0 \) is the exponent for which we assume \( x^p \partial_x^\infty \in L^1(0,1) \). Observe that

\[
x \eta' = x^p (p \chi + (x/\epsilon) \chi'), \quad x^2 \eta'' = x^p (p(p-1) \chi + 2p(x/\epsilon) \chi' + (x/\epsilon)^2 \chi''),
\]

(3.14)

where the arguments of \( \chi \), \( \chi' \) and \( \chi'' \) are \( x/\epsilon \). As \( \epsilon \to 0 \), since we assume \( x^p \partial_x^\infty \) and \( x^p \partial_x^\bar{n} \) are in \( L^1(Q_{[0,T]}) \) for any \( T > 0 \), we infer by monotone and dominated convergence that

\[
\int_{Q_{[\sigma,T]}} x^p \zeta''(w(x,t)) \ dx \mid_{t=\tau}^{t=\sigma} \leq \int_{Q_{[\sigma,T]}} x^p \zeta''(w(x,t)) \ dx + c_p \int_{Q_{[\sigma,T]}} x^p \zeta''(w(x,t)) \ dx dt,
\]

(3.15)
for a.e. $\tau > 0$, with $c_p = p(p - 1) + 4p = p(p + 3)$. Denoting the (absolutely continuous) right hand side of (3.15) by $U(\tau)$, we have

$$U(\tau) = U(0) + \int_0^\tau U'(s) \, ds \leq U(0) + c_p \int_0^\tau U(s) \, ds,$$

and Gronwall’s inequality implies that

$$U(\tau) \leq e^{c_p \tau} \int_0^1 x^p w_{\infty}^n(x) \, dx,$$

for all $\tau > 0$. This proves (2.6). Clearly, $\bar{n}_{\infty} \leq \bar{n}_{\infty}$ implies $n \leq \bar{n}$, by virtue of (2.6).

3.2. **Strict $L^1$-contraction.** From Corollary 2.2 it easily follows that weak solutions of (2.3) enjoy the $L^1$ contraction property mentioned in (2.8). For use in section 4 below, we strengthen this to the following *strict* $L^1$ contraction property for $C^1$ solutions that cross transversely.

**Lemma 3.1.** Let $n, \bar{n}$ be nonnegative solutions to (2.3) with respect to initial data $n_{\infty}, \bar{n}_{\infty}$ that are in $L^1(0,1) \cap L^\infty(0,1)$, then for a.e. $t > 0$,

$$\|n(\cdot,t) - \bar{n}(\cdot,t)\|_{L^1(0,1)} \leq \|n_{\infty} - \bar{n}_{\infty}\|_{L^1(0,1)}.$$  \hspace{1cm} (3.16)

Moreover, assuming the solutions $n$ and $\bar{n}$ are $C^1$ in $(0,1) \times [0,\infty)$, and that for some $t_0 \geq 0$, $n(\cdot,t_0)$ and $\bar{n}(\cdot,t_0)$ cross transversely at least once on $(0,1)$, then for all $t > t_0$ we have

$$\|n(\cdot,t) - \bar{n}(\cdot,t)\|_{L^1(0,1)} < \|n(\cdot,t_0) - \bar{n}(\cdot,t_0)\|_{L^1(0,1)}. \hspace{1cm} (3.17)$$

**Proof.** The $L^1$-contraction estimate (3.16) follows directly from Corollary 2.2 with $p = 2$. In order to prove (3.17), it suffices to treat the case $t_0 = 0$ for $t > 0$ sufficiently small, and assume the right-hand side is finite. Let $w = n - \bar{n}$ and $\hat{n} = n + \bar{n} - 2x$. If $n$ crosses $\bar{n}$ transversely at $(x_0,0)$, then the regularity of the solution implies that there exists a nondegenerate rectangle $\Sigma_0 = [x_0 - \delta, x_0 + \delta] \times [0,\delta]$ such that $w(x_0,0) = 0$ and $\partial_x w \neq 0$ in $\Sigma_0$. We suppose $\partial_x w(x_0,0) > 0$ (relabeling $n$ and $\bar{n}$ if necessary), whence $\partial_x w \geq c_1 > 0$ in $\Sigma_0$, so $w(x_0 + \delta, t) > c_1 \delta > 0$ and $w(x_0 - \delta, t) < -c_1 \delta < 0$.

We follow the proof of Theorem 2.1 up to (3.12), finding that for $0 < \sigma < \tau < \delta$,

$$\int_0^1 \eta(x) \zeta(w(x,t)) \, dx \bigg|_{t=\tau} \leq \int_{Q[\sigma,\tau]} \left( -x^2 \eta \zeta''(w)(\partial_x w)^2 + \zeta(w)\partial_x(x^2 \eta') + 2x \eta' w \zeta'(w) - \bar{n} \eta \zeta''(w)(\partial_x w) \right). \hspace{1cm} (3.18)$$

Here we include a term $-x^2 \eta \zeta''(w)(\partial_x w)^2$ from (3.11) that was dropped in (3.12). This identity is valid for any $C^2$ function $\eta \geq 0$ with compact support in $(0,1)$ and with $\eta' \geq 0$. We may require $x^2 \eta \geq c_2 > 0$ in $\Sigma_0$. Therefore, taking $\xi \downarrow 0$, we find

$$\int_{Q[\sigma,\tau]} x^2 \eta \zeta''(w)(\partial_x w)^2 \geq \int_{\Sigma_0 \cap Q[\sigma,\tau]} c_1 c_2 \zeta''(w) \partial_x w$$

$$= \int_{\tau}^{\sigma} c_1 c_2 \zeta'(w) \bigg|_{x_0 - \delta}^{x_0 + \delta} \, dt \to c_1 c_2 (\tau - \sigma) > 0.$$

When taking the limit $\xi \downarrow 0$, we also have $\zeta \circ w \uparrow w_+$ and $\zeta'(\zeta \circ w) \uparrow w_+$ pointwise. Moreover, $w \zeta'' \circ w = (w/\xi)'(w/\xi)$ is bounded and converges to zero a.e. Since
\( \eta \hat{n} \partial_x w \in L^1(Q) \), by dominated convergence the last term in (3.18) tends to zero, and we derive
\[
\int_0^1 \eta w_+(x, \tau) \, dx \leq \int_0^1 \eta w_+(x, \sigma) \, dx + \int_{Q;[\sigma, \tau]} (x^2 \eta'' + 4x \eta') w_+ - c_1 c_2 (\tau - \sigma). \tag{3.19}
\]

Finally, we take \( \eta \) of the form \( \eta(x) = \chi_\theta(x) \) with \( \theta < x_0 - \hat{\delta} \). Observe that
\[
x \eta' = (x/\theta) \chi', \quad x^2 \eta'' = (x/\theta)^2 \chi'',
\]
where the arguments of \( \chi, \chi' \) and \( \chi'' \) are \( x/\theta \). As \( \theta \to 0 \), since we assume \( n \) and \( \bar{n} \) are in \( L^1(Q) \), we infer by monotone and dominated convergence that
\[
\int_0^1 w_+(x, \tau) \, dx \leq \int_0^1 w_+(x, \sigma) \, dx - c_1 c_2 (\tau - \sigma) < \int_0^1 w_+(x) \, dx,
\]
where the last inequality follows by applying Theorem 2.1 with \( t = \sigma \) and \( p = 0 \). Adding this result together with (2.6) with \( p = 0 \) and \( n \) interchanged with \( \bar{n} \), we obtain (3.17).

4. Existence of weak solutions

The existence result in Theorem 2.3 is proved through three main approximation steps:

(i) Approximate the rough initial data \( n \in L^1(\mathbb{R}) \) by smooth data \( n_\kappa \) that is strictly positive and bounded.

(ii) Truncate the problem (2.3) to \( x \in [\epsilon, 1] \) with \( \epsilon > 0 \), resulting in a strictly parabolic problem at the cost of needing to impose an additional boundary condition at \( x = \epsilon \).

(iii) Further approximate by cutting off the nonlinearity in the flux near the boundary \( x = 1 \), resulting in a problem with linear boundary conditions.

Passing to the limit in the various approximations involves compactness arguments and uniform estimates that are based on energy estimates and Gronwall inequalities. Step (iii) is comparatively straightforward and its analysis is relegated to Appendix B. We deal with steps (i) and (ii) in the remainder of this section.

4.1. Smoothing the initial data. Consider fixed initial data \( n^{in} \in L^1(\mathbb{R}) \). We regularize the given initial data to obtain a family of functions \( n^{in}_\kappa \) for small \( \kappa > 0 \), which are smooth on \([0,1]\) and positive on \((0,1]\), with the following properties:
\[
\int_0^1 x^p |n^{in}_\kappa - n^{in}| \, dx \to 0 \quad \text{as} \quad \kappa \to 0, \tag{4.1}
\]
\[
n^{in}_\kappa(x) = \kappa x^2, \quad 0 < x < \kappa, \tag{4.2}
\]
\[
n^{in}_\kappa(x) = \frac{\kappa x^2}{\kappa x + 1}, \quad 1 - \kappa < x < 1. \tag{4.3}
\]
(The properties in (4.2) and (4.3) are conveniences so that we get compatible initial data in the approximation steps to follow below.) The desired regularization can be achieved through mollification: Let \( \rho \) be a smooth, nonnegative function on \( \mathbb{R} \) with support contained in \((-1,1)\) and total mass one. Define
\[
\rho_\kappa(x) = \kappa^{-1} \rho(x/\kappa), \quad \chi(x) = \int_{-\infty}^x \rho(z) \, dz \tag{4.4}
\]
(note $\chi(x) = 0$ for $x < -1$ and $\chi(x) = 1$ for $x > 1$), and require that
\[
x^p n_{\kappa}^\in(x) = \int_{-2}^{1-2\kappa} \rho_\kappa(x-y) y^p n_{\kappa}^\in(y) \, dy + \frac{\kappa x^{2+p}}{1 + \kappa x \chi(4x-2)}.
\]
The integral term vanishes when $x < \kappa$ or $x > 1 - \kappa$, and there is no singularity near $x = 0$.

For this regularized initial data, our goal is to prove the following result.

**Proposition 4.1.** For every small enough $\kappa > 0$, there exists a weak solution $n_{\kappa}$ of (2.3) with initial data $n_{\kappa}^\in = n_{\kappa}^\in$, having $n_{\kappa} \in C([0, \infty), L^1((0, 1]))$.

4.2. **Truncation.** To obtain $n_{\kappa}$, we regularize by truncating the domain away from the origin, thus removing the degenerate parabolic nature of the problem. In other words, we will study classical solutions of the following problem for small $\epsilon > 0$: In terms of the (left-oriented) flux
\[
J_\epsilon = x^2 \partial_x n_\epsilon - 2x n_\epsilon + n_\epsilon^2,
\]
we seek a solution to the problem
\[
\begin{align*}
\partial_t n_\epsilon &= \partial_x J_\epsilon, & x \in (\epsilon, 1), \ t \in (0, \infty), \\
n_\epsilon &= n_{\kappa}^\in, & x \in (\epsilon, 1), \ t = 0, \\
0 &= J_\epsilon, & x = 1, \ t \in [0, \infty), \\
0 &= \epsilon^2 \partial_x n_\epsilon - 2n_\epsilon, & x = \epsilon, \ t \in [0, \infty).
\end{align*}
\]
The boundary condition (4.6d) says $J_\epsilon = n_\epsilon^2$ at $x = \epsilon$. As will be seen in section 5 below, this boundary condition is well-adapted to proving the conservation identity for photon number in Theorem 2.5. An important point to note, however, is that the uniqueness result of Theorem 2.1 shows that the solution of (2.3) does not depend on the choice of this boundary condition in (4.6d).

For fixed small $\epsilon > 0$, the following global existence result for classical solutions of (4.6) is proved in Appendix B. Note that due to (4.2) and (4.3), the boundary conditions (4.6c)–(4.6d) hold at $t = 0$ whenever $0 < \epsilon < \kappa$.

**Proposition 4.2.** Let $n_{\kappa}^\in$ be smooth and positive on $(0, 1)$ and satisfy (4.2)–(4.3). Then for any sufficiently small $\epsilon > 0$, there is a global classical solution $n_\epsilon$ of (4.6), smooth in the domain
\[
Q^\epsilon := (\epsilon, 1) \times (0, \infty),
\]
with $n_\epsilon$, $J_\epsilon$ and $\partial_x n_\epsilon$ globally bounded and continuous on $\bar{Q}^\epsilon = [\epsilon, 1] \times [0, \infty)$.

From this result, we will derive Proposition 4.1 by taking $\epsilon \downarrow 0$ after establishing a number of uniform bounds on the solution $n_\epsilon$ of (4.6). The global bounds stated in Theorem 2.3 will follow directly from corresponding uniform bounds on $n_\epsilon$, which are proved in Lemmas 4.4 and 4.5 and are inherited by $n_{\kappa}$.

4.3. **Uniform estimates for the truncation.** The first few uniform estimates that we establish on the solution $n_\epsilon$ of (4.6) are pointwise estimates that arise from comparison principles.

**Lemma 4.3.** We have $n_\epsilon(x,t) > 0$ for every $(x,t) \in [\epsilon, 1] \times [0, \infty)$.
Proof. Recall \( \min_{[\epsilon,1]} n_{\kappa}^{in} > 0 \). If we suppose the claim fails, then \( 0 < t^* < \infty \), where

\[
 t^* = \sup \{ t \mid n_\epsilon(x,t) > 0 \text{ for all } x \in [\epsilon,1] \}.
\]

By continuity, there exists \( X^* = (x^*,t^*) \) with \( x^* \in [\epsilon,1] \) such that \( n_\epsilon(X^*) = 0 \). We claim first that \( x^* \neq \epsilon \) or \( 1 \). If \( x^* = \epsilon \) or \( 1 \), by the strong maximum principle \cite{23}, we must have \( 0 \neq \partial_x n_\epsilon(X^*) \), but this violates the boundary conditions \eqref{4.6c}–\eqref{4.6d}.

Thus \( \epsilon < x^* < 1 \), but this is also not possible due to rather standard comparison arguments: There exists \( \delta > 0 \) such that \( \delta \) is less than the minimum of \( n_\epsilon(\epsilon,t) \), \( n_\epsilon(1,t) \) and \( n_\epsilon(x,0) \) whenever \( 0 \leq t \leq t^* \) and \( x \in [\epsilon,1] \). Setting \( w = e^{nt}n_\epsilon \), we find that \( w > \delta \) at \( t = 0 \), and there is some first time \( \hat{t} \in (0,t^*) \) when \( w(\hat{X}) = \delta \) for some \( \hat{X} = (\hat{x},\hat{t}) \) with \( \hat{x} \in (\epsilon,1) \). Then \( \partial_\hat{t}w \leq 0 \), \( \partial_{\hat{x}}w = 0 \) and \( \partial_{\hat{x}}^2w \geq 0 \) at \( \hat{X} \), but computation then shows \( \partial_\hat{t}w \geq w = \delta > 0 \). This finishes the proof. \( \square \)

Next we establish a universal upper bound on our solution of \eqref{4.6}. We do this by establishing that the function defined by

\[
 S(x,t) = x + \frac{1-x}{t} + \frac{2}{\sqrt{t}}
\]

is a universal super-solution. This fact depends essentially on the hyperbolic nature of our problem at large amplitude—Note that the middle term \((1-x)/t\) is a centered rarefaction wave solution of the equation \( \partial_t n - 2n\partial_x n = 0 \).

**Lemma 4.4.** We have

\[
 n_\epsilon(x,t) < S(x,t) \quad \text{for all } (x,t) \in \bar{Q}^\epsilon.
\]

Furthermore, there exists \( \tau_1 > 0 \), depending only on \( \sup n_{\kappa}^{in} \), such that

\[
 n_\epsilon(x,t) < S(x,t + \tau_1) \quad \text{for all } (x,t) \in \bar{Q}^\epsilon.
\]

**Proof.** Let us write \( L[n] := \partial_t n - x^2\partial_x^2 n - 2n(\partial_x n - 1) \). Then a simple calculation gives

\[
 L[S] = \frac{1-x}{t^2} + \frac{2x}{t} + 3t^{-3/2} > 0.
\]

Hence with \( v = S - n_\epsilon \), we have

\[
 L[S] - L[n_\epsilon] = \partial_\epsilon v - x^2\partial_x^2 v - \partial_x((n_\epsilon + S)v) + 2v > 0.
\]

By continuity we have \( \min_\epsilon v(x,t) > 0 \) for small \( t > 0 \), and we claim that this continues to hold for all \( t > 0 \). If not, there is a first time \( \hat{t} \) when it fails, and some \( \hat{X} = (\hat{x},\hat{t}) \) with \( \hat{x} \in [\epsilon,1] \) where \( v(\hat{X}) = 0 \). By \eqref{4.9} it is impossible that \( \hat{x} \in (\epsilon,1) \).

If \( \hat{x} = \epsilon \), then \( v = 0 \) and \( \partial_\hat{x}v \geq 0 \) at \( \hat{X} \). But due to the boundary condition \eqref{4.6d} we find that at \( (x,t) = (\epsilon,\hat{t}) \),

\[
 0 \leq \epsilon \partial_\epsilon v = \epsilon \partial_\epsilon S - 2S = \epsilon \left( 1 - \frac{1}{\hat{t}} \right) - 2 \left( \epsilon + 1 - \frac{\epsilon}{\hat{t}} + \frac{2}{\sqrt{\hat{t}}} \right) < 0.
\]

So \( \hat{x} \neq \epsilon \). On the other hand, if \( \hat{x} = 1 \), we would have \( v = 0 \) and \( \partial_\hat{x}v \leq 0 \) at \( \hat{X} \). But then, at \( (x,t) = (1,\hat{t}) \) we find by \eqref{4.6c} that

\[
 0 \geq \partial_\hat{x}v = \partial_\hat{x}S + S^2 - 2S = 1 - \frac{1}{\hat{t}} + \left( 1 + \frac{2}{\sqrt{\hat{t}}} \right)^2 - 2 \left( 1 + \frac{2}{\sqrt{\hat{t}}} \right) = \frac{3}{\hat{t}} > 0.
\]
Thus \( \dot{x} \neq 1 \), and the result \( S - n_{\epsilon} > 0 \) follows. Furthermore, if \( \sup n_{\epsilon}^{in} \leq 2/\sqrt{\tau_1} \) then
\[
\min_x (S(x, \tau_1) - n_{\epsilon}^{in}(x)) > \frac{2}{\sqrt{\tau_1}} - \|n_{\epsilon}^{in}\|_{L^\infty} \geq 0.
\]
Then the above procedure shows that \( S(x, t + \tau_1) \) is also a super-solution. \( \square \)

The next result bounds \( \partial_x n_{\epsilon} \) from below. This is again a typical kind of estimate for the hyperbolic equation \( \partial_t n - 2\alpha \partial_x n = 0 \).

**Lemma 4.5.** (Oleinik-type inequality) We have
\[
\partial_x n_{\epsilon}(x,t) \geq -\frac{4}{t} \quad \text{for all } (x,t) \in Q^\epsilon.
\]
Furthermore, there exists \( \tau_2 > 0 \), depending only on \( \inf \partial_x n_{\epsilon}^{in} \), such that
\[
\partial_x n_{\epsilon}(x,t) \geq -\frac{4}{t + \tau_2} \quad \text{for all } (x,t) \in Q^\epsilon.
\]

**Proof.** Let \( w = \partial_x n_{\epsilon} \) with \( n_{\epsilon} \) being the solution of (4.6). Differentiation of (4.6) shows that \( w \) satisfies
\[
\partial_t w = x^2 \partial_x^2 w + 2(n_{\epsilon} + x)\partial_x w + 2w(w - 1), \quad (x,t) \in Q^\epsilon, \quad (4.10a)
\]
\[
eq w(\epsilon, t) = 2\epsilon n_{\epsilon}(\epsilon, t), \quad t > 0, \quad (4.10b)
\]
\[
w(1, t) = 2n_{\epsilon}(1, t) - n_{\epsilon}(1, t)^2, \quad t > 0. \quad (4.10c)
\]

We claim that \( z = -4/t \) is a sub-solution of this problem. Set \( U = w - z = w + 4/t \). A direct calculation gives
\[
\partial_t U - x^2 \partial_x^2 U - 2(n_{\epsilon} + x)\partial_x U - 2(w - 4/t)U + 2U = \frac{4}{t^2}(7 + 2t) > 0.
\]

Note that \( U(x, t) > 0 \) for \( t > 0 \) small, because \( \partial_x n_{\epsilon} \) is continuous on \( Q^\epsilon \). Then \( U(x, t) > 0 \) for all \( x \) and \( t \) as long as it is so at \( x = \epsilon \) and \( x = 1 \). At \( x = \epsilon \), we have
\[
U(\epsilon, t) = w(\epsilon, t) + \frac{4}{t} = \frac{2}{\epsilon} n_{\epsilon}(\epsilon, t) + \frac{4}{t} > 0.
\]

On the other hand, at \( x = 1 \), we have
\[
U(1, t) = w(1, t) + \frac{4}{t} = 2n_{\epsilon}(1, t) - n_{\epsilon}(1, t)^2 + \frac{4}{t}.
\]

If \( 0 \leq n_{\epsilon}(1, t) \leq 2 \) then \( U(1, t) \geq 4/t \), and otherwise, \( 2 < n_{\epsilon}(1, t) \leq S(1, t) = 1 + 2t^{-1/2} \), hence
\[
U(1, t) \geq 2S(1, t) - S(1, t)^2 + \frac{4}{t} = 1.
\]

Therefore \( U(1, t) > 0 \). Provided \( \tau_2 > 0 \) is sufficiently small so that \( \partial_x n_{\epsilon}^{in} > -4/\tau_2 \), we have
\[
\min_x \left\{ w(x, 0) + \frac{4}{\tau_2} \right\} > 0,
\]
hence the above procedure shows that \( w(x, t) \geq -4/(t + \tau_2) \) for all \( (x, t) \) under consideration. This concludes the proof. \( \square \)

We now turn to obtain some compactness estimates that will be needed to establish convergence as \( \epsilon \downarrow 0 \). First we establish equicontinuity in the mean for solutions of (4.6).
Lemma 4.6. For each \( t > 0 \), we have
\[
\int_{\epsilon}^{1} |\partial_x n_\epsilon| \, dx \leq K_1(t), \quad K_1(t) = 1 + \frac{2}{\sqrt{t + \tau_1}} + \frac{8}{t + \tau_2}, \tag{4.11}
\]
and for all \( t > 0 \) and all small \( h > 0 \),
\[
\int_{\epsilon}^{1} |n_\epsilon(x, t + h) - n_\epsilon(x, t)| \, dx \leq K_2(t)h^{1/2}, \tag{4.12}
\]
where \( K_2(t) \) is a decreasing function of \( t \) with \( K_2(0) \) bounded by a constant depending only on \( \sup n_\infty^\rho \) and \( \inf \partial_x n_\infty^\rho \).

Proof. With \( \tau_1 \) and \( \tau_2 \) determined by the previous two lemmas, set
\[
u(x, t) = n_\epsilon(x, t) + \frac{4x}{t + \tau_2},
\]
Then by Lemma 4.5, \( u \) is a non-decreasing function of \( x \), satisfying \( \partial_x u > 0 \). We have
\[
\int_{\epsilon}^{1} |\partial_x n_\epsilon| \, dx = \int_{\epsilon}^{1} \left| \partial_x u - \frac{4}{t + \tau_2} \right| \, dx \leq \frac{4}{t + \tau_2} + \int_{\epsilon}^{1} \partial_x u \, dx \leq \frac{8}{t + \tau_2} + n_\epsilon(1, t) \leq \frac{8}{t + \tau_2} + S(1, t + \tau_1) = K_1(t).
\]
This proves the first estimate of the lemma.

We next prove the bound (4.12). Fix any \( t > 0 \) and consider \( h > 0 \) small. Suppressing the dependence on \( t \) and \( h \), we set
\[
v(x) = n_\epsilon(x, t + h) - n_\epsilon(x, t), \quad x \in [\epsilon, 1],
\]
and observe that
\[
\|v\|_\infty \leq 2\|S(\cdot, t + \tau_1)\|_\infty, \quad \int_{\epsilon}^{1} |\partial_x v| \, dx \leq 2K_1(t). \tag{4.14}
\]
We proceed by approximating \( |v(x)| \) by \( \phi(x)v(x) \), where \( \phi \) is obtained by mollifying \( \text{sgn} \, v(x) \). Let \( \rho \) be a smooth, nonnegative function on \( \mathbb{R} \) with support contained in \((-1, 1)\) and total mass one, and \( \alpha > 0 \) be a parameter. (We will take \( \alpha = \frac{1}{2} \) below.) We define \( \rho_h(x) = h^{-\alpha}\rho(x/h^\alpha) \), and set
\[
\phi(x) = \int_{\epsilon}^{1} \rho_h(x - z) \text{sgn} \, v(z) \, dz. \tag{4.15}
\]
To bound the integral of \( |v(x)| \) over \([\epsilon, 1]\), we bound integrals over the sets
\[
I_h = [\epsilon + h^\alpha, 1 - h^\alpha], \quad \hat{I}_h = [\epsilon, \epsilon + h^\alpha] \cup [1 - h^\alpha, 1],
\]
writing
\[
\int_{\epsilon}^{1} |v(x)| \, dx = \int_{\epsilon}^{1} \phi(x)v(x) \, dx + \int_{I_h} \left( |v(x)| - \phi(x)v(x) \right) \, dx + \int_{\hat{I}_h} \left( |v(x)| - \phi(x)v(x) \right) \, dx. \tag{4.16}
\]
Since \( |\phi| \leq 1 \), the third term is bounded using the first estimate in (4.14) as
\[
\int_{\hat{I}_h} \left| |v(x)| - \phi(x)v(x) \right| \, dx \leq 8h^\alpha\|S(\cdot, t)\|_\infty. \tag{4.17}
\]
We next estimate the middle term in \((4.16)\). For \(x \in I_h\), we compute
\[
|v(x)| - \phi(x)v(x) = \int_{\mathbb{R}} \rho_h(x - z) \left( |v(x)| - v(x) \text{sgn} v(z) \right) dz.
\]
Noting that \(|a - a \text{sgn} b| \leq 2|a - b|\) for any real \(a, b\), we have
\[
|v(x)| - v(x) \text{sgn} v(z) | \leq 2|v(x) - v(z)|.
\]
Integrating over \(I_h\), we find
\[
\int_{I_h} |v(x)| - \phi(x)v(x) | dx \leq 2 \int_{I_h} \int_{|y| \leq h^\alpha} \rho(y)|v(x) - v(y)| dy dx
\]
\[
\leq 2 \int_{I_h} \int_{|y| \leq h^\alpha} \rho(y)|\int_0^1 |\partial y v(x - ys)| ds | dy dx.
\]
Now we integrate first over \(x\), note \(x - ys \in [\epsilon, 1]\) and use \((4.14)\), and note that \(|y| \leq h^\alpha\) and \(\rho_h\) has unit integral. We infer that
\[
\int_{I_h} |v(x)| - \phi(x)v(x) | dx \leq 2h^\alpha \int_{\epsilon}^1 |\partial x v| dx \leq 4h^\alpha K_1(t). \tag{4.18}
\]
Finally, we bound the first term in \((4.16)\). Multiply equation \((4.6a)\) by \(\phi\) and integrate over \((\epsilon, 1) \times (t, t + h)\). Integration by parts yields
\[
\int_\epsilon^1 \phi v(x) dx = \int_t^{t+h} \int_\epsilon^1 \left( \partial_x \phi \right) \left( -x^2 \partial_x n - n^2 + 2xn \right) dx d\tau - \int_t^{t+h} \phi(\epsilon)n^2(\epsilon, \tau) d\tau. \tag{4.19}
\]
Note that \(|\phi| \leq 1\) and \(|\partial_x \phi| \leq h^{-\alpha} \|\rho\|_1\). By virtue of \(0 \leq n \leq S\), we have
\[
\int_\epsilon^1 \phi v dx \leq h^{-\alpha} \|\rho\|_1 \int_t^{t+h} \int_\epsilon^1 (|\partial_x n| + S^2 + 2S) dx d\tau + \int_t^{t+h} S(\epsilon, \tau)^2 d\tau \leq h^{1-\alpha} \|\rho\|_1 (K_1(t) + 3S(\epsilon, t + \tau_1)^2) + hS(\epsilon, t + \tau_1)^2.
\]
Assembling all the bounds on the terms in \((4.16)\) above, we obtain
\[
\int_\epsilon^1 |v(x)| dx \leq \|S(\epsilon, t + \tau_1)^2 + 8h^\alpha + h + 3h^{1-\alpha} \|\rho\|_1 \right) + K_1(t) (4h^\alpha + h^{1-\alpha} \|\rho\|_1).
\]
Choosing \(\alpha = \frac{1}{2}\) and determining \(K_2(t)\) to correspond, the result in the lemma follows. \(\square\)

Finally, we have the following energy estimate.

**Lemma 4.7.** For any \(t > s > 0\),
\[
\int_\epsilon^1 n^2(\epsilon, t) dx + \int_s^t \int_\epsilon^1 [n^2 + x^2(\partial_x n)^2] dx d\tau \leq \int_\epsilon^1 n^2(\epsilon, s) dx + \frac{8}{3}(t - s). \tag{4.20}
\]

**Proof.** From equation \((4.6a)\) and the boundary conditions \((4.6c) - (4.6d)\), it follows
\[
\frac{d}{dt} \int_\epsilon^1 n^2(\epsilon) dx = -2 \int_\epsilon^1 (\partial_x n) J \epsilon dx - 2n^3(\epsilon, t) = -2 \int_\epsilon^1 [n^2 + x^2(\partial_x n)] dx + \Gamma(t),
\]
with
\[
\Gamma(t) = -\frac{2}{3} n^3(1, t) - \frac{4}{3} n^2(1, t) + 2n^2(1, t) - 2en^2(\epsilon, t) \leq \max_{a \geq 0} \left( -\frac{2}{3} a^3 + 2a^2 \right) = \frac{8}{3}.
\]
Hence, the claimed estimate follows by integration in time. \(\square\)
4.4. Proof of Proposition 4.1. We now show a solution of (2.3) does exist for initial data \( n^\epsilon \) as prepared in subsection 4.1. Let \( n^\epsilon \) be our solution of (4.6), for small \( \epsilon > 0 \).

Recalling the uniform estimates \( 0 < n^\epsilon \leq S(x, t + \tau_1) \) from Lemmas 4.3 and 4.4 and using Lemma 4.6 we see the family \( \{ n^\epsilon \} \) is uniformly bounded and equicontinuous in the mean on any compact subset of \( (0, 1] \times [0, \infty) \). Consequently, we may extract a sequence \( \epsilon_k \downarrow 0 \) as \( k \to \infty \), such that for each \( a \in (0, 1) \) and \( T > 0 \), \( n_{\epsilon_k} \) converges to some function \( n \), boundedly almost everywhere in \( [a, 1] \times [0, \infty) \) and in \( C([0, T]; L^1([a, 1])) \), with

\[
\int_a^1 |n(x, t + h) - n(x, t)| dx \leq Ch^{1/2}.
\]

Actually, this \( C \) is independent of \( a \), so (4.21) holds also with \( a = 0 \). Moreover, due to (4.20) we can ensure that

\( x \partial_x n_{\epsilon_k} \to x \partial_x n \) weakly in \( L^2_{\text{loc}}(Q) \).

We claim that \( n \) is a weak solution of (2.3). Multiply (4.6a) by a smooth test function \( \psi \) with compact support in \( (0, 1] \times (0, \infty) \), and integrate over \( (\epsilon, 1) \times (0, \infty) \) with integration by parts to obtain, for small enough \( \epsilon \),

\[
\int_0^1 \int_0^1 \left( n_{\epsilon_k} \partial_t \psi - (x^2 \partial_x n_{\epsilon_k} + n_{\epsilon_k}^2 - 2 xn_{\epsilon_k}) \partial_x \psi \right) = 0.
\]

Setting \( \epsilon = \epsilon_k \) and letting \( k \to \infty \), we conclude that

\[
\int_0^\infty \int_0^1 \left( n \partial_t \psi - (x^2 \partial_x n + n^2 - 2 xn) \partial_x \psi \right) = 0
\]

for all smooth test functions \( \psi \). By completion, we infer that (4.23) holds for all \( \psi \) merely in \( H^1 \) with compact support in \( Q \). Hence \( n \) is a weak solution as claimed.

Since there may exist at most one such solution of (2.3), we conclude that the whole family \( \{ n_{\epsilon_k} \} \) converges to \( n \), as \( \epsilon \to 0 \). This ends the proof of Proposition 4.1.

\( \square \)

4.5. Proof of Theorem 2.3. Our next task is to complete the proof of Theorem 2.3 by studying the solutions \( n^\kappa \) from Proposition 4.1 in the limit \( \kappa \to 0 \).

By the Gronwall inequality from (2.6), for any fixed \( T > 0 \), and small \( \kappa_1, \kappa_2 > 0 \),

\[
\sup_{t \in [0, T]} \int_0^1 x^p |(n_{\kappa_1} - n_{\kappa_2})(x, t)| dx \leq C e^{\kappa_2 T} \int_0^1 x^p |(n_{\kappa_1}^0 - n_{\kappa_2}^0)(x)| dx.
\]

This with (4.4) implies that \( n^\kappa \) is a Cauchy sequence in \( C([0, T]; L^1(x^p dx)) \), and therefore there is a function \( n \in C([0, T]; L^1(x^p dx)) \) such that \( \lim_{\kappa \to 0} n_{\kappa} = n \). From the local-in-time energy estimate (4.20) we have

\[
\int_0^1 n_{\kappa}^2(x, t) dx + \int_0^t \int_0^1 \left[ n_{\kappa}^2 + x^2 \partial_x n_{\kappa} \right] dx d\tau \leq \int_0^1 n_{\kappa}^2(x, s) dx + \frac{8}{3} (t - s).
\]

The right hand side, by virtue of \( 0 \leq n_{\kappa}(x, t) \leq S(x, t) \), is bounded for any \( s > 0 \) by

\[
\int_0^1 S(x, s)^2 dx + \frac{8}{3} (t - s) < \infty.
\]

Taking the limit \( \kappa \to 0 \), we deduce that \( n \) and \( \partial_x n \) lie in \( L^2_{\text{loc}}(Q(0, T)) \), and the limit \( n \) is non-negative and satisfies (2.5d). This proves that \( n \) is indeed a weak
solution of (2.3), as claimed. Moreover, from Lemma 4.4 it follows that the limit \( n \) has the universal upper bound that for every \( t > 0 \),
\[
n \leq S(x, t) = x + \frac{1 - x}{t} + \frac{2}{\sqrt{t}} \quad \text{for a.e. } x \in (0, 1),
\]
and Lemma 4.5 implies that for almost every \( (x, t) \in Q(0, T) \), its slope has the one-sided bound
\[
\partial_x n \geq -\frac{4}{t}.
\]
Finally, the limit function \( n \in C((0, T], L^2) \), due to the following estimate. With
\[
\omega(h) = \sup_{s \leq t \leq s + h} \int_0^1 x^p |n(x, t) - n(x, s)| \, dx,
\]
whenever \( 0 < t - s < h \) is so small that \( \alpha = \omega(h)^{1/(p + 1)} < 1 \) we have
\[
\int_0^1 |n(x, t) - n(x, s)|^2 \, dx \leq C_s^2 \alpha + C_s \alpha^{-p} \int_0^1 x^p |n(x, t) - n(x, s)| \, dx \leq (C_s^2 + C_s) \alpha.
\]
By consequence, the energy estimate (2.9) follows from the one for \( n_{\kappa} \). This finishes the proof of Theorem 2.3.

5. Finite time condensation

The results of this section establish Theorem 2.5, demonstrating that loss of photons is due to the generation of a nonzero flux at \( x = 0^+ \), that such a flux persists if ever formed, and that photon loss does occur if the initial photon number exceeds the maximum attained in steady state.

Throughout this section, we let \( n \) be any global weak solution of (2.3).

5.1. Formula for loss of photon number. First, we show how any possible decrease of photon number in time is related to the nonvanishing of \( n(0, t)^2 = n(0^+, t)^2 \), which is the formal limit of the flux \( J \) at the origin \( x = 0 \). The following result implies part (i) of Theorem 2.5 in particular.

Lemma 5.1. For any fixed \( t > s > 0 \),
\[
\int_0^1 n(x, t) \, dx = \int_0^1 n(x, s) \, dx - \int_s^t n^2(0, \tau) \, d\tau.
\]
Moreover, for any \( t > 0 \)
\[
\int_0^1 n(x, t) \, dx \leq \frac{1}{2} + \frac{1}{2t} + \frac{2}{\sqrt{t}}.
\]

Proof. Integration of equation (4.6a) over \( (x, 1) \times (s, t) \), using \( J_e(1, t) = 0 \), gives
\[
\int_x^1 n_\epsilon(y, \tau) \, dy \bigg|_{\tau = s}^{\tau = t} = -\int_s^t (x^2 \partial_x n_\epsilon(x, \tau) + n_\epsilon^2(x, \tau) - 2x n_\epsilon(x, \tau)) \, d\tau.
\]
Taking an average in \( x \) over \( (\epsilon, a) \), we find
\[
\int_\epsilon^a \int_x^1 n_\epsilon(y, \tau) \, dy \, d\tau \bigg|_s^t + \int_s^t \int_\epsilon^a n_\epsilon^2 \, dx \, d\tau = \int_s^t \int_\epsilon^a (2x n_\epsilon - x^2 \partial_x n_\epsilon) \, dx \, d\tau.
\]
where, because $\epsilon \leq x$,
\[
R = \int_\epsilon^a \int_x^a n_x(y, \tau) \, dy \leq \left( \int_\epsilon^a \int_x^a n_x(y, \tau)^2 \, dy \, dx \right)^{1/2} \left( \int_\epsilon^a \int_x^a 1 \, dy \, dx \right)^{1/2} \\
\leq \left( \int_\epsilon^a n_x^2 \, dy \right)^{1/2} (a - \epsilon)^{1/2} \\
\leq C_s a^{1/2},
\]
due to the energy estimate in Theorem 2.4. The right-hand side in (5.3) is bounded above by
\[
\left( \int_s^t \int_\epsilon^a (2n_\epsilon - x\partial_x n_\epsilon)^2 \, dx \, d\tau \right)^{1/2} \left( \int_s^t \int_\epsilon^a x^2 \, dx \, d\tau \right)^{1/2} \\
\leq \left( \int_s^t \int_\epsilon^a 8n_\epsilon^2 + 2x^2(\partial_x n_\epsilon)^2 \, dx \, d\tau \right)^{1/2} ((t - s)a^2)^{1/2} \\
\leq \left( \int_s^t \int_\epsilon^1 n_\epsilon^2 + x^2(\partial_x n_\epsilon)^2 \, dx \, d\tau \right)^{1/2} \left( \frac{8(t - s)a^2}{a - \epsilon} \right)^{1/2} \\
\leq C_{t,s} \left( \frac{a^2}{a - \epsilon} \right)^{1/2}.
\]
Passing to the limit $\epsilon \downarrow 0$ first, we have
\[
\left. \int_a^1 n(x, \tau) \, dx \right|_s^t + \int_s^t \int_\epsilon^a n^2(x, \tau) \, dx \, d\tau = O(1) a^{1/2}.
\]
The desired equality follows from further taking $a \downarrow 0$. Moreover, by virtue of $n \leq S$, we have
\[
\int_0^1 n(x, t) \, dx \leq \int_0^1 S(x, t) \, dx = \frac{1}{2} + \frac{1}{2t} + 2t^{-1/2},
\]
for any $t > 0$. The proof is complete. \hfill \Box

Because $n$ is a classical solution of $\partial_t n = \partial_x J$ for $x, t > 0$, by integration over $x \in [a, 1]$, $\tau \in [s, t]$ we can infer that the loss term in (5.1) arises from the exit flux from the interval $[a, 1]$ in the limit $a \to 0$. Thus the following result provides a precise sense in which the flux $J(a, t)$ converges to $n_\epsilon^2(0, t)$ as $a \to 0$.

**Corollary 5.2.** Whenever $t > s > 0$ we have
\[
\lim_{a \to 0^+} \int_s^t J(a, \tau) \, d\tau = \int_s^t n_\epsilon^2(0, \tau) \, d\tau.
\]

### 5.2. Persistence of condensate growth.

Next we prove part (ii) of Theorem 2.5, showing that $n(0, t)$ once positive will remain positive for all time. More precisely:

**Lemma 5.3.** If $n(0, t^*) > 0$ for some $t^* > 0$, then $n(0, t) \geq b(t) \hat{x}$ for all $t > t^*$, where
\[
b(t) = \left( (1 + t^*/4)e^{2(t-t^*)} - 1 \right)^{-1}, \quad \hat{x} = \min \left\{ \frac{t^*n(0, t^*)}{4}, 1 \right\}.
\]
Proof. From $\partial_x n(x,t^*) \geq -4/t^*$ we have

$$n(x,t^*) \geq \left( n(0,t^*) - \frac{4x}{t^*} \right)_+ \geq \frac{4}{t^*}(\hat{x} - x)_+ = b(t^*)(\hat{x} - x)_+.$$ 

Hence $n(x,t^*) \geq \hat{n}(x,t^*)$ with

$$\hat{n}(x,t) = b(t)(\hat{x} - x)_+.$$ 

Note that $\hat{n}(1,t) = 0$, and for $0 < x < \hat{x}$ we have

$$L[\hat{n}] := \partial_t \hat{n} - x^2 \partial_x^2 \hat{n} + 2 \hat{n} - 2 \hat{n} \partial_x \hat{n} = (\hat{x} - x)(b'(t) + 2b(t) + 2b(t)^2) = 0.$$ 

We claim $n \geq \hat{n}$ on $(0,\hat{x}]$ for $t > t^*$. Let $\epsilon > 0$. Substitution of $n = \hat{n} + v + \epsilon \Psi$ into the equation $L[n] = 0$ gives

$$\hat{L}[v] := \partial_t v - x^2 \partial_x^2 v + 2v - 2v \partial_x \hat{n} - 2n \partial_x v = -\epsilon \hat{L}[\Psi].$$

Choosing $\Psi = -t + \log x$, we have $\Psi < 0$ and

$$\hat{L}[\Psi] = 2 \Psi + 2 \Psi \epsilon - \frac{2n}{x} < 0,$$

hence $\hat{L}[v] > 0$ for $0 < x < \hat{x}$, $t \geq t^*$. For $0 < x \leq \sigma$ for $\sigma$ sufficiently small (depending on $\epsilon$),

$$v = n - \hat{n} - \epsilon \Psi \geq -\hat{n} + \epsilon(t - \log \sigma) > 0, \quad \forall t > t^*.$$ 

Moreover, at $x = \hat{x}$ we have

$$v(\hat{x},t) = n(\hat{x},t) + \epsilon(t - \log \hat{x}) > 0.$$ 

These facts, together with the fact $v(x,t^*) \geq \epsilon(t - \log x) > 0$, ensure that

$$v(x,t) > 0, \quad \forall t > t^*, \ x \in (0,\hat{x}].$$

Since $\epsilon > 0$ is arbitrary, we infer

$$n(x,t) \geq \hat{n}(x,t), \quad \forall t \geq t^*, \ x \in (0,1].$$

This gives the desired estimate upon taking $x \to 0$. \hfill $\square$

5.3. **Formation of condensates.** The next result shows that photon loss will occur—meaning a condensate will form—in finite time if the initial photon number $N[n^\text{in}] > \frac{1}{2}$. This proves part (iii) of Theorem 2.5. Note that $\frac{1}{2} = N[x]$ is the maximum photon number for any steady state.

**Proposition 5.4.** If $N[n^\text{in}] > \frac{1}{2}$, then photon loss begins in finite time. More precisely, we have $n(0,t) > 0$ whenever

$$\frac{1}{2\sqrt{t}} < \sqrt{1+\delta - 1}, \quad \text{where} \quad 2\delta = N[n^\text{in}] - \frac{1}{2}. \quad (5.5)$$

**Proof.** From the supersolution obtained in Lemma 3.2 it follows that

$$n(x,t) \leq x + \frac{1-x}{t} + 2t^{-1/2}.$$ 

Integration in $x$ over $(0,1)$ leads to

$$N[n(\cdot,t)] \leq \frac{1}{2} + \frac{1}{2t} + \frac{2}{\sqrt{t}}.$$
Using Lemma 5.1 we have
\[
\int_0^t n(0, \tau)^2 d\tau \geq N[n^{\text{in}}] - \frac{1}{2} - \frac{2}{\sqrt{t}} - \frac{1}{2t} = 2\delta + 2 - 2\left(1 + \frac{1}{2\sqrt{t}}\right)^2.
\]
The right-hand side becomes positive when (5.5) holds. The conclusion then follows from Lemma 5.3.

5.4. Absence of condensates. Part (iv) of Theorem 2.5 follows from a simple comparison: If \(n^{\text{in}}(x) \leq x\), then since \(x = n_0(x)\) is a steady weak solution, the comparison property from Theorem 2.1 implies \(n(x, t) \leq x\) for all \(t \geq 0\). Then \(n(0^+, t) = 0\), so by part (a), no condensate is formed and we have \(N[n(\cdot, t)] = N[n^{\text{in}}]\) for all \(t > 0\).

6. LARGE TIME CONVERGENCE

We now investigate the large time behavior of solutions with non-trivial initial data. In the system (2.3), the flux vanishes for any equilibrium:
\[
0 = J = n^2 \partial_x \left( x - \frac{x^2}{n} \right).
\]
Consequently \(n = n_\mu\) for some constant \(\mu \geq 0\), where
\[
n_\mu(x) = \frac{x^2}{x + \mu}.
\]
Our main goal in this section is to prove Theorem 2.6, which means that for every solution of (2.3) provided by Theorem 2.3 with nonzero initial data \(n^{\text{in}}\), there exists \(\mu \geq 0\) such that
\[
\|n(\cdot, t) - n_\mu\|_1 = \int_0^1 |n(x, t) - n_\mu(x)| \, dx \to 0 \quad \text{as } t \to \infty.
\]

It will be convenient to denote by
\[
n(\cdot, t) = U(t)a
\]
the solution of (2.3) with initial data \(n^{\text{in}}(x) = a(x), x \in (0, 1)\). Due to the bound \(n(x, t) \leq S(x, t)\) that holds by Theorem 2.3(i), for \(t \geq 1\) any solution \(U(t)n^{\text{in}}\) will lie in the set
\[
A := \{a \in L^\infty(0, 1) : 0 \leq a(x) \leq 3 \text{ for a.e. } x \in (0, 1)\},
\]
since \(S(x, 1) \equiv 3\). The set \(A\) is positively invariant under the semi-flow induced by the solution operator:
\[
U(t)A \subset A, \quad t \geq 0.
\]
With the metric induced by the \(L^1\) norm,
\[
\rho(n_1, n_2) = \|n_1 - n_2\|_1,
\]
the set \(A\) is a complete metric space, and by Lemma 3.1, \(U(t)\) is a contraction: We have
\[
\|U(t)a - U(t)b\|_1 \leq \|a - b\|_1.
\]
whenever \(t \geq 0\) and \(a, b \in A\).

For present purposes it is important that a stronger contractivity property also holds, as shown in Lemma 3.1. Namely, if the functions \(a\) and \(b\) are \(C^1\) and cross transversely, then for \(t > 0\), \(U(t)\) strictly contracts the \(L^1\) distance between \(a\)
and $b$. Based on these contraction properties and the one-sided Oleinik bound in Theorem 2.3(ii), we proceed to establish the large time convergence (6.2).

We introduce the usual $\omega$-limit set of any element $a \in A$ as

$$\omega(a) = \cap_{s>0} \{ U(t)a \mid t \geq s \}.$$  

We have $b \in \omega(a)$ if and only if there is a sequence $\{t_j\} \to \infty$ such that $\|U(t_j)a - b\|_1 \to 0$.

**Lemma 6.1.** (The $\omega$-limit set) Let $a \in A$. Then $\omega(a)$ is not empty, and is invariant under $U(t)$, with

$$U(t)\omega(a) = \omega(a), \quad t > 0.$$  

Moreover, for any $b \in \omega(a)$, $b$ is smooth (at least $C^2$ on $(0,1]$) and satisfies

$$\partial_x b(x) \geq 0, \quad 0 \leq b(x) \leq x, \quad 0 < x < 1.$$  

**Proof.** To show $\omega(A)$ is not empty, note that for any sequence $t_j \to \infty$, the estimates from Lemma 4.6 show that $\{U(t_j)a\}$ is bounded in $BV$. By virtue of the Helley compactness theorem, some subsequence converges in $L^1$, and this limit belongs to $\omega(a)$.

Next we prove (6.3). Given $b \in \omega(a)$, there exists $t_j$ such that

$$\|U(t_j)a - b\|_1 \to 0, \quad j \to \infty.$$  

From $L^1$ contractivity and the semigroup property it follows that $\|(U(t + t_j)a - U(t)b)\|_1 \to 0$, hence $U(t)b \in \omega(a)$. On the other hand, if $b \in U(t)\omega(a)$, we have $b = U(t)b^*$ with $b^* \in \omega(a)$. Then for some sequence $t_j \to \infty$,

$$\|U(t + t_j)a - b\|_1 = \|U(t)U(t_j)a - U(t)b^*\|_1 \leq \|U(t_j)a - b\|_1 \to 0$$  

as $j \to \infty$, hence $b \in \omega(a)$.

By relation (6.3), for each $b \in \omega(a)$ and $t > 0$, $b = U(t)b^*$ for some $b^* \in \omega(a)$. From this it follows $b$ is smooth and that $\partial_x b \geq -4/t$ and $0 \leq b(x) \leq S(x,t)$ by Theorem 2.3. Taking $t \to \infty$, since $S(x,t) \to x$ we infer (6.4).

**Lemma 6.2.** (Equilibria and $\omega(a)$) (i) If $n_\mu \in \omega(a)$ for some $\mu \geq 0$, then

$$\lim_{t \to \infty} \|U(t)a - n_\mu\|_1 = 0.$$  

(ii) Let $b \in \omega(A)$. Then for any $\mu \geq 0$,

$$\|b - n_\mu\|_1 = \|U(t)b - n_\mu\|_1.$$  

(iii) If $a \not\equiv 0$, then $0 \not\in \omega(a)$.

**Proof.** (i) By definition, for any $\epsilon > 0$, $\|U(t_j)a - n_\mu\|_1 < \epsilon$ for large $t_j$. This ensures that for any $t > t_j$,

$$\|U(t)a - n_\mu\|_1 = \|U(t - t_j)U(t_j)a - U(t - t_j)n_\mu\| \leq \|U(t_j)a - n_\mu\|_1 < \epsilon,$$

hence (6.5).

(ii) Since $b \in \omega(A)$, there exists $a \in A$ and a sequence $\{t_j\}$ such that $t_j \to \infty$ as $j \to \infty$ and

$$\lim_{t \to \infty} \|U(t_j)a - b\|_1 = 0.$$  

Given any $\mu \geq 0$, by contraction of $U(t)$ we know that

$$\|U(t)a - n_\mu\|_1 = \|U(t)a - U(t)n_\mu\|_1$$
is decreasing in time and thus admits a limit $c_\mu \geq 0$ as $t \to \infty$, i.e.,

$$\lim_{t \to \infty} \| U(t)a - n_\mu \|_1 = c_\mu, \quad t \to \infty.$$ 

Letting $t = t_j$ in the above equation and passing to the limit, we have

$$\| b - n_\mu \|_1 = c_\mu.$$ 

Note that if $b \in \omega(a)$, then $U(t)b \in \omega(a)$; thereby

$$\| U(t)b - n_\mu \|_1 = c_\mu.$$ 

Therefore (6.6) holds for $\forall t > 0, \quad \mu \geq 0$.

(iii) Suppose $a \not\equiv 0$, so that $N[a] > 0$. We claim $0 \notin \omega(a)$. Supposing $0 \in \omega(a)$ instead, we write $n(\cdot, t) = U(t)a$. Then $N[n(\cdot, t)] = \| U(t)a - 0 \|_1$ is non-increasing and approaches zero as $t \to \infty$. By Lemmas 5.1 and 5.3 then, a condensate forms and $n(0^+, t) > 0$ for all large $t$.

From the Oleinik-type lower bound of Theorem 2.3(ii), $x < z < 1$ entails $n(x,t) - 4t \leq n(z,t)$. After integration from $1 - x$ to $1$ we find

$$(1 - x) \left( n(x,t) - \frac{4}{t} \right) \leq N[n(\cdot, t)].$$

For $t$ large enough we have $N[n(\cdot, t)] < \frac{1}{16}$ and $t > 32$, and this ensures that

for all $x \in \left[ \frac{1}{4}, \frac{1}{2} \right]$, \quad $n(x,t) \leq 2N[n(\cdot, t)] + \frac{4}{t} < \frac{1}{4} \leq x$.

Then, because $n(0^+, t) > 0$, the last crossing point defined by

$$x_1 = \max\{ x \in (0, \frac{1}{4}] : n(x,t) = x \}$$\hspace{1cm} (6.7)

is well defined. Using again Theorem 2.3(ii), it now follows

$$0 \leq n(x,t) \leq x_1 + \frac{4}{t}x_1 \quad \text{for } 0 < x < x_1,$$

$$x \geq n(x,t) \geq x_1 - \frac{4}{t}x_1 \quad \text{for } x_1 < x < 2x_1.$$ 

From these inequalities, we deduce respectively that

$$\int_0^{x_1} | x - n(x,t) | \, dx \leq x_1^2 \left( 1 + \frac{4}{t} \right),$$

$$\int_{x_1}^{2x_1} | x - n(x,t) | \, dx \leq \int_{x_1}^{2x_1} x \, dx - x_1^2 \left( 1 - \frac{4}{t} \right).$$

We may also assume $t$ is so large that $S(x,t) < 2x$ for $\frac{1}{2} \leq x \leq 1$. Then since $0 \leq n(x,t) \leq S(x,t)$, it follows

$$\int_{2x_1}^1 | x - n(x,t) | \, dx \leq \int_{2x_1}^1 x \, dx.$$ 

Because $\int_0^{x_1} x \, dx$, after adding the last three inequalities we find $\| x - U(t)a \|_1 < \| x - 0 \|_1$. But then since $\| x - U(t)a \|_1$ is nonincreasing in $t$, it is impossible that $\| U(t)a - 0 \|_1 \to 0$ as $t \to \infty$. This proves $0 \notin \omega(a)$. \hfill \Box

The following restatement of the result in Lemma 3.1 plays a critical role in proving (6.2).
Lemma 6.3. If \( a, b \in A \cap C^1((0,1)) \) and \( a \) and \( b \) cross transversely at least once on \((0,1)\), then
\[
\|U(t)a - U(t)b\|_1 < \|a - b\|_1, \quad t > 0.
\]

We are now ready to prove (6.2). Let \( a \in A \) with \( a \not\equiv 0 \). By Lemma 6.1 we know that \( \omega(a) \) is not empty. Let \( b \in \omega(a) \). We need to show there exists a \( \mu \geq 0 \) such that
\[
b = n_\mu. \tag{6.8}
\]
Since \( b \not\equiv 0 \) and \( b \) is non-decreasing, the quantity
\[
g(x) = x - \frac{x^2}{b(x)},
\]
which is the first variation \( \delta H/\delta n \) of entropy, is well defined in some non-empty interval \((x_0,1)\). If \( g \) is not a constant, there exists some \( x^* \in (x_0,1) \) such that
\[
g'(x^*) \neq 0.
\]
Then it follows that at \( x = x^* \), with \( \mu^* = -g(x^*) \) we have
\[
b = \frac{x^2}{x - g(x)} = n_{\mu^*}, \quad \partial_x b = \partial_x n_{\mu^*} + \frac{x^2g'}{(x - g(x))^2} \neq \partial_x n_{\mu^*}.
\]
In other words, \( b \) and \( n_{\mu^*} \) cross transversely at \( x^* \). Therefore by Lemma 6.3 we have
\[
\|U(t)b - U(t)n_{\mu^*}\|_1 < \|b - n_{\mu^*}\|_1.
\]
This contradicts (6.6). We conclude that \( g \) must be a constant, i.e., \( g(x) = -\mu \), which gives (6.8). From \( b \not\equiv 0 \) and \( b \leq x \) we see that \( \mu \geq 0 \).

Remark 6.1. Due to loss of mass, determining \( \mu \) quantitively for each given initial data is not straightforward, except for some special cases as treated in Corollary 2.7.

Proof of Corollary 2.7 If \( n^{\text{in}} \geq x \), by the comparison result in Theorem 2.1, we have
\[
x \leq n(x,t), \quad t > 0.
\]
On the other hand, the supersolution bound from Theorem 2.3(i) ensures that
\[
n(x,t) \leq x + \frac{1 - x}{t} + 2t^{-1/2}.
\]
These together lead to (2.10), hence \( \lim_{t \to \infty} n(x,t) = x \).

In the case of \( n^{\text{in}} \leq x \), we have \( n(x,t) \leq x \) for all \( t \). Then there is no mass loss, hence the limiting equilibrium state \( n_\mu \) satisfies
\[
\int_0^1 n_\mu \, dx = \int_0^1 n^{\text{in}} \, dx = N[n^{\text{in}}].
\]
Integration of the left-hand side yields (2.11). \( \square \)

Appendix A. Anisotropic Sobolev estimates.

For use in section 4 and Appendices B and C we need some basic anisotropic Sobolev estimates that are not easy to find in the extensive literature on the subject. The results that we need appear to be related to embedding results for anisotropic Besov spaces contained in the books [2]. For the reader’s convenience, however, we provide a self-contained treatment based on simple estimates for Fourier transforms.

If \( \Omega \subset \mathbb{R}^2 \), the typical anisotropic Sobolev space is
\[
u \in W^{2k,k}_2(\Omega) = \{ u \mid D^s_r D^t_r u \in L^2(\Omega), \ 0 \leq 2r + s \leq 2k \}.\]
As usual, if a function \( u \in W^{2k,k}_2(\Omega) \), it will automatically belong to certain other spaces, which depend on \( k \) and the dimension. One such space is \( C^{\gamma,\gamma/2}(\Omega) \). We say \( u \in C^{\gamma,\gamma/2}(\Omega) \) if there is a constant \( K \) such that
\[
|u(x,t) - u(y,\tau)| \leq K((x-y)^2 + |t-\tau|)^{\gamma/2}, \quad \forall (x,t), (y,\tau) \in \Omega.
\]
The space \( C^{\gamma,\gamma/2}(\Omega) \) is a Banach space with norm given by
\[
\|u\|_{C^{\gamma,\gamma/2}(\Omega)} = \max_{(x,t) \in \Omega} |u(x,t)| + \sup_{(x,t), (y,\tau) \in \Omega} \frac{|u(x,t) - u(y,\tau)|}{((x-y)^2 + |t-\tau|)^{\gamma/2}}.
\]
The results we need are contained in the following result.

**Theorem A.2.** Let \( u \in W^{2k,k}_2(\Omega) \), then
\[
W^{2k,k}_2 \rightarrow \begin{cases} 
C^{\gamma,\gamma/2}, & \gamma = 2k - \frac{n+2}{2}, \quad k > \frac{n+2}{2}, \\
L^s, & 2 \leq s < \infty, \quad k = \frac{n+2}{2}, \\
L^s, & 2 \leq s < \frac{2(n+2)}{n+4}, \quad k < \frac{n+2}{2}.
\end{cases}
\]

(a) \( C\|u\|_{W^{2k,k}_2} \geq \begin{cases} 
\|\partial_x u\|_{L^\infty}, & k > \frac{n}{2} + 1, \\
\|\partial_x u\|_{L^s(\Omega)}, & 2 \leq s < \infty, \quad k = \frac{n}{2} + 1, \\
\|\partial_x u\|_{L^s(\Omega)}, & 2 \leq s < \frac{2(n+2)}{n+4}, \quad k < \frac{n}{2} + 1.
\end{cases}
\]

The results in Theorem B.1 correspond to \( n = 1, k = 1 \) and the cases \( \gamma = 1/2 \) in part (i) and \( s \in [2, 6) \) in part (ii).

**A.1. Fourier estimates in \( \mathbb{R}^2 \).** The Fourier transform for \( u \in L^1(\mathbb{R}^2) \) is
\[
\hat{u}(\xi, \ell) = \int_{\mathbb{R}^2} u(x,t)e^{-2\pi i(x\xi + \ell t)}dx\,dt,
\]
which extends to a bounded linear map \( u \rightarrow \hat{u} \) from \( L^p \) to \( L^{p'} \), for \( 1 \leq p \leq 2 \) and \( 1/p + 1/p' = 1 \). Moreover, the Hausdorff-Young inequality holds:
\[
\|\hat{u}\|_{p'} \leq \|u\|_p
\]
for \( u \in L^p \). This simply interpolates \( \|u\|_{\infty} \leq \|u\|_1 \) and the Plancherel theorem, \( \|\hat{u}\|_2 = \|u\|_2 \). The continuity of \( \hat{u} \) follows from the dominated convergence theorem.

In case \( \hat{u} \) is integrable, one may recover \( u \) from \( \hat{u} \) by
\[
u(x,t) = \int_{\mathbb{R}^2} \hat{u}(\xi, \ell)e^{2\pi i(x\xi + \ell t)}d\xi\,d\ell.
\]
We will deduce Theorem A.1 from the corresponding result on all of \( \mathbb{R}^2 \):

**Theorem A.3.** Suppose \( u \in W^{2,1}_2(\mathbb{R}^2) \). Then \( u \in C^{1,1/4}(\mathbb{R}^2) \). Moreover, \( \partial_x u \in L^s(\mathbb{R}^2) \) for \( 2 \leq s < 6 \), with
\[
\|\partial_x u\|_{L^s(\mathbb{R}^2)} \leq C\|u\|_{W^{2,1}_2(\mathbb{R}^2)}.
\]
Lemma A.4. (Characterization of $W_2^{2k,k}(\mathbb{R}^2)$ by Fourier transform). Let $k$ be a nonnegative integer, and set

$$m(\xi, l) = (1 + l^2 + |\xi|^4)^{1/2}.$$  

Then $u \in W_2^{2k,k}(\mathbb{R}^2)$ if and only if $m^k \hat{u} \in L^2(\mathbb{R}^2)$. In addition, there exists a constant $C$ such that

$$C^{-1} \|u\|_{W_2^{24,k}} \leq \|m^k \hat{u}\|_{L^2} \leq C \|u\|_{W_2^{2k,k}}.$$  

The following two technical lemmas will be used as well.

Lemma A.5. For $0 \leq \alpha < 2\beta$ and $\beta \geq 1$, we have

$$A_{\alpha,\beta} := \|\xi|^\alpha / m^\beta \in L^4(\mathbb{R}^2) \quad \text{if any only if} \quad s > \max \left\{ \frac{3}{2\beta - \alpha}, \frac{1}{\beta} \right\}.$$  

Proof. A direct calculation using the substitution $l = y(1 + |\xi|^4)^{1/2}$ gives

$$\|A_{\alpha,\beta}\|^4_s = \frac{|\xi|^\alpha}{(1 + l^2 + |\xi|^4)^{3/2}} d\xi dl = \int_{\mathbb{R}^2} \frac{|\xi|^\alpha (1 + |\xi|^4)^{1/2}}{(1 + y^2)^{3/2}} d\xi dy = \int_{\mathbb{R}} \frac{dy}{(1 + y^2)^{3/2}} \int_{\mathbb{R}} \frac{|\xi|^\alpha (1 + |\xi|^4)^{1/2}}{(1 + y^4)^{3/2}} d\xi.$$  

This is bounded if and only if $\beta s > 1$ and $2\beta s - 2 - \alpha s > 1$. That is, $s \beta > 1$ and $s(2\beta - \alpha) > 3$. \hfill \qed

Lemma A.6. Let $V(x) = |x| \wedge 1 := \min\{|x|, 1\}$. Then for some constant $C > 0$,

$$\|m^{-1} V(r \xi)\|_2 + \|m^{-1} V(r^2 l)\|_2 \leq C r^{1/2} \quad \text{for all} \ r > 0.$$  

(A.4)

Proof. For the first term, substituting $l = y(1 + |\xi|^4)^{1/2}$ again, we find

$$\|m^{-1} V(r \xi)\|_2^2 = \frac{(|r \xi| \wedge 1)}{(1 + l^2 + |\xi|^4)} d\xi dl = \int_{\mathbb{R}^2} \frac{(|r \xi| \wedge 1)^2}{(1 + l^2)} d\xi dy \leq \int_{\mathbb{R}^2} \frac{(|r \xi| \wedge 1)^2}{(1 + y^2)} d\xi dy = \int_{\mathbb{R}} \frac{dy}{(1 + y^2)} \int_{\mathbb{R}} \frac{(|r \xi| \wedge 1)^2}{(1 + |\xi|^4)^{1/2}} d\xi.$$  

The first factor is finite. We proceed to decompose the last integral into two parts, one over $\{\xi : |\xi| < r^{-1}\}$ and the other over $\{\xi : |\xi| > r^{-1}\}$: The integrand is even, and

$$\int_0^\infty \frac{(|r \xi| \wedge 1)^2}{(1 + |\xi|^4)^{1/2}} d\xi = \int_0^{r^{-1}} \frac{(r^2 \xi)^2}{(1 + |\xi|^4)^{1/2}} d\xi + \int_{r^{-1}}^\infty \frac{1}{(1 + |\xi|^4)^{1/2}} d\xi \leq r^2 \int_0^{r^{-1}} d\xi + \int_{r^{-1}}^{\infty} |\xi|^{-2} d\xi = 2r.$$  

To proceed, we first recall a characterization of $W_2^{2k,k}$.  

Lemma A.6. Let $s \beta > 1$ and $s(2\beta - \alpha) > 3$. \hfill \qed
In a similar fashion, we estimate, using $\xi = (1 + l^2)^{1/4}\eta$,

$$
\|m^{-1}V(r^2l)\|_2^2 = \int_{\mathbb{R}^2} \frac{||r^2l| \wedge 1|^2}{1 + l^2 + |\xi|^4} d\xi dl \\
\leq \int_{\mathbb{R}^2} \frac{(r^2l)^2}{(1 + l^2)^{3/4}(1 + |\eta|^4)} d\eta dl \\
= \int_{\mathbb{R}} \frac{d\eta}{(1 + |\eta|^4)} \int_{\mathbb{R}} (r^2l)^2 \frac{1}{(1 + l^2)^{3/4}} dl.
$$

The first integral is bounded; the second integral is further estimated by

$$
\int_0^\infty \frac{(r^2l)^2}{(1 + l^2)^{3/4}} dl \leq \int_0^{r^2} \frac{(r^2l)^2}{(1 + l^2)^{3/4}} dl + \int_{r^2}^\infty \frac{1}{(1 + l^2)^{3/4}} dl \\
\leq r^4 \int_0^{r^2} l^{1/2} dl + \int_{r^2}^\infty l^{-3/2} dl \\
= \left(\frac{2}{3} + 2\right) r = \frac{8}{3} r.
$$

These estimates together yield the bound (A.4) as claimed. \hfill \Box

Proof of Theorem A.3. From the inversion formula (A.3) it follows that

$$
\|u\|_\infty \leq \|u\|_1 \leq \|m\hat{u}\|_2 \|m^{-1}\|_2 \leq C\|u\|_{W^{2,1}_2},
$$

where the bound on $\|m^{-1}\|_2 = \|A_{0,1}\|_2$ is ensured by Lemma A.5.

(i) Fix $(x, t) \neq (y, \tau)$ so that $r = \sqrt{(y-x)^2 + (\tau-t)^2} > 0$. Using the inequalities

$$
|e^{2ia} - e^{2ib}| \leq 2|a-b| \wedge 2 = 2V(a-b), \\
|(y-x) \cdot \xi + (\tau-t)l| \leq r|\xi| + r^2|l|,
$$

we obtain from the inversion formula and Lemma A.6 that

$$
|u(x, t) - u(y, \tau)| \leq 2\pi \int (V(\tau \xi) + V(r^2l))|u(\xi, l)|d\xi dl \\
\leq 2\pi(\|m^{-1}V(\tau \xi)\|_2 + \|m^{-1}V(r^2l)\|_2)\|m\hat{u}\|_2 \\
\leq Cr^{1/2}\|u\|_{W^{2,1}_2}.
$$

This proves the embedding $W^{2,1}_2(\mathbb{R}^2) \to C^{1/2,1/4}(\mathbb{R}^2)$.

(ii) For $2 \leq s < 6$ we have $s' = \frac{s}{s-2} \leq 2$ and $r > 3$ where

$$
\frac{1}{r} = \frac{1}{2} - \frac{1}{s}.
$$

We may then use the Hausdorff-Young inequality (A.2) and Lemma A.5 to obtain

$$
\|\partial_x u\|_s \leq C_s\|\xi\hat{u}\|_{s'} \leq \|m\hat{u}\|_2\|A_{1,1}\|_r, \leq C\|u\|_{W^{2,1}_2}.
$$

\hfill \Box

Proof of Theorem A.7. Let $D$ be the given closed rectangle in $\mathbb{R}^2$. For functions $u$ defined a.e. on $D$, we extend $u$ from $D$ to a larger rectangle $\hat{D}$ containing $D$ in its interior, in two steps, using linear combinations of dilated reflections as shown in Adams [11, Theorem 4.26]. The extension is to be made so that the weak derivatives are preserved across $\partial D$. 


For instance, we reflect across the faces of $D$ sequentially: First, from $x$ faces $\{a, b\}$ with $c < t < d$, writing $\hat{a} = a - (b - a)$, $\hat{b} = b + (b - a)$, let

$$E_x u(x,t) = \begin{cases} 
-3u(2a - x, t) + 4u(-x/2 + 3a/2), & \hat{a} \leq x \leq a, \\
u(x, t), & a \leq x \leq b, \\
-3u(2b - x, t) + 4u(-x/2 + 3b/2), & b \leq x \leq \hat{b}.
\end{cases}$$

and then from the $t$ faces $\{c, d\}$ in an entirely similar manner, such that

$$\tilde{u} = E_t E_x u(x,t)$$

is an $C^1$ extension when crossing $\partial D$ and well-defined in $\hat{D} = [\hat{a}, \hat{b}] \times [\hat{c}, \hat{d}]$. Then multiply by a fixed smooth cutoff function $\phi(x,t)$ that is 1 on $D$ and 0 near the boundary of $\hat{D}$ to obtain

$$Eu = \phi(x,t) E_t E_x u(x,t).$$

In this way, given $u$ such that $\partial_t u$ and $\partial_j^2 u$ are in $L^2(D)$ for $j = 0, 1, 2$, we obtain $Eu$ such that $\partial_t Eu$ and $\partial_j^2 Eu$ are in $L^2(\mathbb{R}^2)$ for $j = 0, 1, 2$. The extension $E$ is thus a bounded linear operator from $\in W^{2,1}_2(D)$ to $W^{2,1}_2(\mathbb{R}^2)$. Moreover,

$$Eu = u \quad \text{a.e. in } D,$$

$Eu$ has support in $\hat{D}$, and

$$\|Eu\|_{W^{2,1}_2(\mathbb{R}^2)} \leq C\|u\|_{W^{2,1}_2(D)}.$$

This combined with Theorem A.3 when applied to $Eu$ proves Theorem A.1. □

**Appendix B. Existence for the truncated problem**

In this appendix, we establish the existence of a classical solution to the truncated problem (4.6). We aim to prove Proposition 4.2. This global existence result does not appear to follow easily from stated results in standard parabolic theories, due to the fact that the boundary condition $J = 0$ at $x = 1$ is nonlinear. For the convenience of the reader, we indicate how to establish Theorem 4.2 by use of an approximation method that involves cutting off the nonlinear term in the flux $J$ together with interior regularity theory. This will result in a problem with standard linear Robin-type boundary conditions, that still respects a maximum principle which keeps the solution uniformly bounded.

**B.1. Approximation by flux cut-off.** We consider, then, the following problem. Let $\chi(x)$ be a smooth, nondecreasing function with $\chi(x) = 0$ for $x <-1$, $\chi(x) = 1$ for $x > 1$ as in (4.4). For small $h > 0$ define $\chi_h(x) = \chi(1 + (x - 1)/h)$, so that

$$\chi_h(x) = \begin{cases} 
0, & x < 1 - 2h, \\
1, & x = 1.
\end{cases} \quad (B.1)$$

Writing

$$J_h = x^2 \partial_x n_h - 2x n_h + n_h^2 + (3n_h - n_h^2) \chi_h, \quad (B.2)$$

$$E_x u(x,t) = \begin{cases} 
-3u(2a - x, t) + 4u(-x/2 + 3a/2), & \hat{a} \leq x \leq a, \\
u(x, t), & a \leq x \leq b, \\
-3u(2b - x, t) + 4u(-x/2 + 3b/2), & b \leq x \leq \hat{b}.
\end{cases}$$

and then from the $t$ faces $\{c, d\}$ in an entirely similar manner, such that

$$\tilde{u} = E_t E_x u(x,t)$$

is an $C^1$ extension when crossing $\partial D$ and well-defined in $\hat{D} = [\hat{a}, \hat{b}] \times [\hat{c}, \hat{d}]$. Then multiply by a fixed smooth cutoff function $\phi(x,t)$ that is 1 on $D$ and 0 near the boundary of $\hat{D}$ to obtain

$$Eu = \phi(x,t) E_t E_x u(x,t).$$

In this way, given $u$ such that $\partial_t u$ and $\partial_j^2 u$ are in $L^2(D)$ for $j = 0, 1, 2$, we obtain $Eu$ such that $\partial_t Eu$ and $\partial_j^2 Eu$ are in $L^2(\mathbb{R}^2)$ for $j = 0, 1, 2$. The extension $E$ is thus a bounded linear operator from $\in W^{2,1}_2(D)$ to $W^{2,1}_2(\mathbb{R}^2)$. Moreover,

$$Eu = u \quad \text{a.e. in } D,$$

$Eu$ has support in $\hat{D}$, and

$$\|Eu\|_{W^{2,1}_2(\mathbb{R}^2)} \leq C\|u\|_{W^{2,1}_2(D)}.$$

This combined with Theorem A.3 when applied to $Eu$ proves Theorem A.1. □

**Appendix B. Existence for the truncated problem**

In this appendix, we establish the existence of a classical solution to the truncated problem (4.6). We aim to prove Proposition 4.2. This global existence result does not appear to follow easily from stated results in standard parabolic theories, due to the fact that the boundary condition $J = 0$ at $x = 1$ is nonlinear. For the convenience of the reader, we indicate how to establish Theorem 4.2 by use of an approximation method that involves cutting off the nonlinear term in the flux $J$ together with interior regularity theory. This will result in a problem with standard linear Robin-type boundary conditions, that still respects a maximum principle which keeps the solution uniformly bounded.

**B.1. Approximation by flux cut-off.** We consider, then, the following problem. Let $\chi(x)$ be a smooth, nondecreasing function with $\chi(x) = 0$ for $x < -1$, $\chi(x) = 1$ for $x > 1$ as in (4.4). For small $h > 0$ define $\chi_h(x) = \chi(1 + (x - 1)/h)$, so that

$$\chi_h(x) = \begin{cases} 
0, & x < 1 - 2h, \\
1, & x = 1.
\end{cases} \quad (B.1)$$

Writing

$$J_h = x^2 \partial_x n_h - 2x n_h + n_h^2 + (3n_h - n_h^2) \chi_h, \quad (B.2)$$
we consider the problem
\[\begin{align*}
    \partial_t n_h &= \partial_x J_h, \\
    n_h &= n_{h}^{\text{in}}, \\
    0 &= J_h, \\
    0 &= \epsilon^2 \partial_x n_h - 2\epsilon n_h,
\end{align*}\]
where
\[\begin{align*}
    x &\in (\epsilon, 1), \\
    t &\in (0, \infty),
\end{align*}\]
and
\[\begin{align*}
    n_h &= n_{h}^{\text{in}}, \\
    0 &= J_h, \\
    0 &= \epsilon^2 \partial_x n_h - 2\epsilon n_h,
\end{align*}\]
with
\[\begin{align*}
    x &\in (\epsilon, 1), \\
    t &\in (0, \infty),
\end{align*}\]
We construct the initial data \(n_{h}^{\text{in}}\) from the given \(n_{\text{in}}\) so that at \(t = 0\), the cut-off flux \(J_h\) is the original \(J\). Namely, we require that at \(t = 0\),
\[J_h = x^2 \partial_x n_{h}^{\text{in}} - 2\epsilon n_{h}^{\text{in}} + (n_{h}^{\text{in}})^2.\]
We make the boundary condition in (B.3c) is linear in \(n\) by this theorem agrees with that given by Proposition 7.3.6. (B.3c)–(B.3d). Clearly in the limit \(x \rightarrow 0\), we have \(n_{h}^{\text{in}} \rightarrow n_{\text{in}}\) uniformly on \([\epsilon, 1]\).

B.2. Uniform bounds on the cut-off problem. Because \(\chi_{h}(1) = 1\), the boundary condition in (B.3c) is linear in \(n_h\), taking the form
\[\partial_x n_h = -n_h, \quad x = 1, \quad t \in [0, \infty),\]
Moreover, note that (B.3a) takes the explicit form
\[\partial_t n_h = x^2 \partial_x^2 n_h - 2n_h + (\partial_x n_h)(2n_h + (3 - 2n_h)\chi_h) + (3n_h - n_h^2)\chi_h'.\]
For this problem, comparison principles hold, whence we obtain positivity and uniform sup-norm bounds on solutions.

**Lemma B.1.** Suppose \(\min_{[\epsilon,1]} n_{h}^{\text{in}} > 0\) and \(\max_{[\epsilon,1]} n_{h}^{\text{in}} < M_1\) where \(M_1 \geq 3\). Suppose \(n_h\) is a classical solution of (B.3) in \([\epsilon, 1] \times (0, T]\), with \(n_h\) continuous on \([\epsilon, 1] \times [0, T]\). Then \(0 < n_h(x, t) < M_1\) for all \((x, t) \in [\epsilon, 1] \times [0, T]\).

**Proof.** The proof of strict positivity is similar to Lemma 4.2. To prove the upper bound, suppose \(n_h(X^*) = M\) with \(X^* = (x^*, t^*)\), where \(t^* > 0\) is minimal. Because \(\partial_x n_h = -n_h < 0\) holds at \(x = 1\), and holds at \(x = \epsilon\), \(x^*\) must lie strictly between \(\epsilon\) and \(1\). But because (B.6) holds and \(\chi_h' \geq 0\), this is impossible. □

We may obtain global existence of a classical solution to problem (B.3) with cut-off from the proof of Proposition 7.3.6 of [22], due to the time-uniform bounds on \(n_h\) in this Lemma, and the fact that the nonlinear terms in (B.3a) appear in the divergence form \(N_h(n_h) := \partial_x (n_h^2 (1 - \chi_h))\), which enjoys a local Lipschitz bound in the \(L^\infty\) norm of the form
\[\|N_h(u) - N_h(v)\| \leq K \left(\|u - v\|_\infty \|u\|_{C^1} + \|v\|_\infty \|u - v\|_{C^1}\right),\]
with \(K = 1 + \|\chi_h'\|_\infty\).

From the proof of Prop. 7.3.6 of [22], this solution \(n_h\) is continuous on \([\epsilon, 1] \times [0, \infty) = Q^\epsilon\), and the quantities \(\partial_x n_h, \partial_x^2 n_h, \partial_t n_h\) and \(\partial_x^2 n_h\) are continuous on \([\epsilon, 1] \times (0, \infty)\). However, these quantities are actually all continuous on \(Q^\epsilon\) by the local-time existence theorem 8.5.4 of [22], due to the fact that the initial data are \(C^3\) and satisfy the compatibility conditions. (A simple energy estimate for the difference, along the lines of step 1 in subsection B.3 below, shows that the local solution given by this theorem agrees with that given by Prop. 7.3.6.)

Additionally, these quantities are also locally Hölder-continuous on \([\epsilon, 1] \times (0, \infty)\), due to the regularity results stated in [22] Prop. 7.3.3(iii)]. From standard interior
regularity theory for parabolic problems (e.g., based on Theorem 8.12.1 of [20] and bootstrapping), we infer that \( n_h \) is smooth in \( Q^\epsilon \). In particular, the flux \( J_h \) is a classical solution in \( Q^\epsilon \) of the equation

\[
\partial_t J_h = x^2 \partial_x^2 J_h + (\partial_x J_h)(-2x + 2n_h + (3 - 2n_h)\chi_h) .
\]

Since \( J_h \) is continuous on \( Q^\epsilon \), by the maximum principle it is bounded in terms of its initial and boundary values—recall \( J_h = n_h^2 \) at \( x = \epsilon \). From this and the sup-norm bound in the previous Lemma, we obtain (\( \epsilon \)-dependent) uniform bounds on \( \partial_x n_h \).

**Lemma B.2.** There is a constant \( M_2 \) depending on \( n_h^\text{in} \) and independent of \( h \) and \( \epsilon \), such that \( |J_h| + \epsilon^2 |\partial_x n_h| \leq M_2 \) for all \((x,t) \in Q^\epsilon\).

**B.3. Energy estimates.** These are simpler than the corresponding ones in section 5, because here \( \epsilon > 0 \) is fixed, and the initial data is smooth.

1. The basic energy estimate is (using that \( n_h \) is positive and bounded)

\[
\frac{d}{dt} \int_\epsilon^1 \frac{1}{2} n_h^2 \, dx = \int_\epsilon^1 n_h \partial_x J_h \, dx = n_h J_h \bigg|_\epsilon^1 - \int_\epsilon^1 (\partial_x n_h) J_h \, dx \\
= -n_h(\epsilon,t)^3 - \int_\epsilon^1 (\partial_x n_h)(x^2 \partial_x n_h - 2xn_h + n_h^2 + (3n_h - n_h^2)\chi_h) \, dx \\
\leq -\frac{\epsilon^2}{2} \int_\epsilon^1 (\partial_x n_h)^2 \, dx + C \int_\epsilon^1 n_h^2 \, dx
\]

Here \( C \) is independent of \( h \) and \( t \), and after integration we conclude that \( \partial_x n_h \) (and also \( J_h \)) is uniformly bounded independent of \( h \) in \( L^2 \) on \([\epsilon, 1] \times [0, T] \), for any \( T \).

2. For \((x,t) \in Q^\epsilon\), the flux \( J_h \) satisfies (B.8), and we find

\[
\frac{d}{dt} \int_\epsilon^1 \frac{1}{2} J_h^2 \, dx = J_h(x^2 \partial_x J_h) \bigg|_\epsilon^1 - \int_\epsilon^1 (x\partial_x J_h)^2 \, dx \\
+ \int_\epsilon^1 J_h(\partial_x J_h)(-4x + 2n_h + (3 - 2n_h)\chi_h) \, dx \\
\leq -\frac{\epsilon^2}{3} \partial_t(n_h(\epsilon,t)^3) - \frac{\epsilon^2}{2} \int_\epsilon^1 (\partial_x J_h)^2 \, dx + C \int_\epsilon^1 J_h^2 \, dx .
\]

Upon integration in time, we conclude \( \partial_x J_h = \partial_t n_h \) is uniformly bounded independent of \( h \) in \( L^2 \) on \([\epsilon, 1] \times [0, T] \), for any given \( T \). And further, using (B.2) for \( x < 1 - 2h \), we deduce that \( \partial_x^2 n_h \) is uniformly bounded independent of \( h \) in \( L^2 \) on any compact set

\[
[\epsilon, 1 - \epsilon] \times [0, T] \subset [\epsilon, 1] \times [0, \infty)
\]

fixed independent of \( h \). (This does not work for \( \epsilon = 0 \) because \( \chi_h' \) is not uniformly bounded.)

3. Next, we have

\[
\frac{d}{dt} \int_\epsilon^1 \frac{1}{2} (\partial_x J_h)^2 \, dx = (\partial_x J_h)(\partial_t J_h) \bigg|_\epsilon^1 - \int_\epsilon^1 (\partial_x^2 J_h)(\partial_t J_h) \, dx \\
\leq -2n_h(\epsilon,t)(\partial_x n_h(\epsilon,t))^2 - \frac{\epsilon^2}{2} \int_\epsilon^1 (\partial_x^2 J_h)^2 \, dx + C \int_\epsilon^1 (\partial_x J_h)^2 \, dx .
\]

Because \( \partial_x J_h \) is continuous on \( Q^\epsilon \), we may integrate this inequality over \( t \in [0, T] \), and use the bound on \( \partial_x J_h \) from the previous step, to conclude that \( \partial_x^2 J_h \) and \( \partial_t J_h \)
are uniformly bounded independent of $h$ in $L^2$ on $[\epsilon, 1] \times [0, T]$. By the anisotropic Sobolev estimates in Appendix A, we deduce that $\partial_x J_h$ is uniformly bounded independent of $h$ in $L^4$ on $[\epsilon, 1] \times [0, T]$, as well.

4. Lastly we derive an interior estimate on $\partial_x^3 J_h$. We define

$$
\beta(x, t) = -2x + 2n_h + (3 - 2n_h)\chi_h, \quad \text{so} \quad \partial_t \beta = 2(1 - \chi_h)\partial_x J_h.
$$

Then

$$
\partial_t^2 J_h = x^2 \partial_x^2 \partial_t J_h + \beta \partial_x \partial_t J_h + 2(1 - \chi_h)(\partial_x J_h)^2, \quad \text{(B.10)}
$$

and we let $\eta(x)$ be $x - \epsilon$ so that $\eta(\epsilon) = 0$ and $\eta' = 1$,

$$
\frac{d}{dt} \int_\epsilon^1 \frac{1}{2} \eta^2 (\partial_t J_h)^2 dx = \int_\epsilon^1 \eta^2 (\partial_t J_h)(\partial_t^2 J_h) dx
$$

$$
= \int_\epsilon^1 \eta^2 (\partial_t J_h)(\beta \partial_x \partial_t J_h + 2(1 - \chi_h)(\partial_x J_h)^2) dx
$$

$$
- \int_\epsilon^1 \eta^2 x^2(\partial_x \partial_t J_h)^2 dx - \int_\epsilon^1 (\partial_t J_h)(\partial_x \partial_t J_h)(\partial_x (\eta^2 x^2)) dx
$$

$$
\leq -\frac{\epsilon^2}{2} \int_\epsilon^1 \eta^2 (\partial_x \partial_t J_h)^2 dx + C \int_\epsilon^1 (\partial_t J_h)^2 + (\partial_x J_h)^4 dx
$$

Because only know $\partial_t J_h$ is continuous for $t > 0$, we integrate this over $t \in [s, T]$, then over $s \in [0, \tau]$, and use the bounds from the previous step. We infer that $\eta \partial_x \partial_t J_h$ is uniformly bounded independent of $h$ in $L^2$ on $[\epsilon, 1] \times [\tau, T]$. Due to (B.8) and (B.1), we infer that $\partial_t (\partial_x J_h)$ and $\partial_x^2 (\partial_x J_h)$ are uniformly bounded independent of $h$ in $[\epsilon + \hat{\epsilon}, 1 - \hat{\epsilon}] \times [\tau, T]$, for any small fixed $\hat{\epsilon} > 0$ and compact $[\tau, T] \subset (0, \infty)$.

**B.4. Compactness argument.** By the anisotropic Sobolev estimates in Appendix A, from the bounds on $\partial_t J_h$ and $\partial_x^2 J_h$ in step 3 above, we have that $J_h$ is uniformly Hölder-continuous (independent of $h$) on any compact set

$$
[\epsilon, 1] \times [0, T] \subset [\epsilon, 1] \times [0, T] = Q^c.
$$

Also, by the bounds on $\partial_t n_h$ and $\partial_x^2 n_h$ in step 2, $n_h$ is uniformly Hölder-continuous on any compact set of the form in (B.9). From this we infer by (B.2) for $x < 1 - 2h$ the same for $\partial_x n_h$. By step 4, $\partial_t n_h = \partial_x J_h$ and $\partial_x^2 n_h$ are uniformly Hölder-continuous on any compact set

$$
[\epsilon + \hat{\epsilon}, 1 - \hat{\epsilon}] \times [\tau, T] \subset (\epsilon, 1) \times (0, \infty) .
$$

From the Arzela-Ascoli theorem and a diagonalization argument, along a subsequence of $h \to 0$ we get uniform convergence of: $J_h$ to $J_\epsilon$ in sets of form (B.11), $n_h$ and $\partial_x n_h$ to respective limits $n_\epsilon$ and $\partial_x n_\epsilon$ in sets of form (B.9) and $\partial_t n_h$ to $\partial_t n_\epsilon$ and $\partial_x^2 n_h$ to $\partial_x^2 n_\epsilon$ in sets of form (B.12), with all limits Hölder-continuous on the indicated sets.

In the limit, the PDE $\partial_t n_\epsilon = \partial_x J_\epsilon$ holds for $(x, t) \in Q^c$, and

$$
J_\epsilon = x^2 \partial_x n_\epsilon - 2x n_\epsilon + n_\epsilon^2, \quad (x, t) \in [\epsilon, 1] \times [0, \infty) .
$$

Because of the continuity of $J_\epsilon$ on the sets in (B.11) and $n_\epsilon$ on the sets in (B.9), by regarding (B.13) as an ODE for $n_\epsilon$ we deduce that $n_\epsilon$ and $\partial_x n_\epsilon$ are continuous on the sets in (B.11) also (i.e., up to the boundary $x = 1$), and both boundary conditions in (4.6c)–(4.6d) hold.

From standard parabolic theory as before, we find that $n_\epsilon$ is smooth in $Q^c$. This concludes the proof of Proposition 4.2.
Appendix C. Regularity away from the origin

What we seek to do in this section is to prove Theorem 2.4 providing sufficient local regularity in the domain \( Q = (0,1) \times (0,\infty) \) to infer that the solutions \( n \) in Theorem 2.3 are classical, with at least the regularity needed for the strict contraction estimate in Lemma 3.1. For higher regularity in the interior of \( Q \) we will rely on standard parabolic theory via bootstrap arguments.

The idea is to obtain uniform local bounds on \( L^2 \) norms of the solutions \( n^h \) of the flux-cutoff problem, the associated fluxes \( J^h \) in (B.2), and certain space-time derivatives \( \partial^\alpha n^h, \partial^\beta J^h \). These bounds will be independent of \( h, \epsilon \) and the smoothing parameter \( \kappa \). The local \( L^2 \) bounds on these derivatives are inherited by \( \partial^\alpha n, \partial^\beta J \) in the limit \( h \to 0 \), then by \( \partial^\alpha n, \partial^\beta J \) after taking \( \epsilon \to 0 \), and then by \( \partial^\alpha n, \partial^\beta J \) after taking \( \kappa \to 0 \). Local Hölder-norm bounds for each quantity \( v \in \{n, \partial_x n, \partial_t n, \partial_t^2 n\} \) in \( Q \) will follow from the local \( L^2 \) bounds on \( \partial_t v \) and \( \partial_t^2 v \), due to Theorem A.1.

In order to achieve this, we proceed to first obtain the needed estimates for \( n^h \) and \( J^h \), independent of \( h, \epsilon \) and \( \kappa \), and then pass to the limits. Select a smooth function \( \bar{\eta} : \mathbb{R} \to [0,\infty) \), convex and nondecreasing with \( 0 = \bar{\eta}(0) < \bar{\eta}(x) \leq x \) for \( x > 0 \). Weighted energy estimates with weight \( \eta(x) = \bar{\eta}(x - ma) \) will yield uniform estimates in \( L^2(W_m) \), where the sets \( W_m \subset [\epsilon,1] \times [s,T] \) have the form

\[
W_m = [(m+1)a,1] \times [ms,T], \quad m = 1,2,\ldots,
\]

for \( a, s > 0 \) arbitrary but fixed independent of \( h, \epsilon \), and \( \kappa \).

0. As a preliminary step, we seek a uniform pointwise bound on \( n^h \) independent of \( h, \epsilon \), and \( \kappa \), in domains of the form

\[
[\epsilon,1] \times [\tau,\infty), \quad \tau > 0.
\]

From the form of \( J^h \) and \( J^s \) it follows that

\[
n^h(x,t) - n^s(x,t) = n^h(1/2,t) - n^s(1/2,t) + \int_{1/2}^{x} \frac{1}{y^2} (J^h - J^s) \, dy \\
+ \int_{1/2}^{x} \left[ \frac{2}{y} (n^h - n^s) - \frac{1}{y^2} (n^h_1 - n^s_1) \right] \, dy \\
+ \int_{1/2}^{x} \frac{1}{y^2} (n^h_2 - 3n^h) \chi_h \, dy.
\]

Using the uniform convergence of \( n^h \) to \( n^s \) in \([\epsilon,1-\epsilon] \times [0,T]\) (proven previously), and of \( J^h \) to \( J^s \) in \([\epsilon,1] \times [0,T]\), as well as the bounds on \( n^h \) in Lemma B.1 and on \( n^s \leq S(x,t) \) in Lemma 4.4, we obtain the uniform convergence of \( n^h \) toward \( n^s \), as \( h \to 0 \). Therefore, we get the following uniform pointwise bound independent of \( h, \epsilon, \) and \( \kappa \): For any \( \tau > 0 \), for sufficiently small \( h > 0 \) we have

\[
0 < n^h(x,t) \leq M_\tau = \max_{x \in [0,1]} S(x,\tau) + 1, \quad (x,t) \in [\epsilon,1] \times [\tau,\infty).
\]

(Here and below, the required smallness of \( h \) depends on \( \kappa \), because the bound in Lemma 4.4 depends on \( \kappa \). But we will not mention this further.)
1. Next we proceed to obtain bounds using weighted energy estimates. The weighted energy estimate with \( \eta(x) = \bar{\eta}(x - a) \) is

\[
\frac{d}{dt} \int_a^1 \frac{1}{2} \eta^2 n_h^2(x) \, dx = \int_a^1 \eta^2 n_h \frac{\partial_x J_h}{\partial x} \, dx = - \int_a^1 (\eta^2 \partial_x n_h + 2 \eta \eta_n h) J_h \, dx = - \int_a^1 (\eta^2 \partial_x n_h + 2 \eta \eta_n h)(x^2 \partial_x n_h - 2 x n_h + n_h^2 + (3n_h - n_h^2) \chi_h) \, dx \leq - \frac{1}{2} \int_a^1 (x \eta \partial_x n_h)^2 \, dx + C \int_a^1 (n_h + n_h^2)^2 \, dx.
\]

By integration over \( t \in [s, T] \) and using (C.3), we infer that

\[
\int_s^T \int_a^1 \eta^2 n_h^2(x, t) \, dt \leq \int_a^1 \eta^2 n_h^2(x, s) \, dx + C \int_s^T \int_a^1 (n_h + n_h^2)^2 \, dx \, dt \leq C_s,
\]

where \( C_s \) may depend on \( s \) (and \( T \), but we suppress this dependence), but is independent of \( h, \epsilon, \kappa \). Because \( \eta(2a) > 0 \), we conclude that \( \partial_x n_h \), hence also \( J_h \), is uniformly bounded independent of \( h, \epsilon \) and \( \kappa \) in \( L^2(W_1) \) (with a bound that depends on \( a \) and \( s \)).

2. The cut-off flux \( J_h \) satisfies

\[
\partial_t J_h = x^2 \partial_x J_h + \beta \partial_x J_h,
\]

with boundary condition \( J_h(1, t) = 0 \) for \( t > 0 \), where

\[
\beta(x, t) = -2x + 2n_h + (3 - 2n_h) \chi_h.
\]

Multiply by \( \eta^2 J_h \) with \( \eta(x) = \bar{\eta}(x - 2a) \), integrate by parts, and use the inequality \( uv \leq \frac{1}{4} u^2 + v^2 \) to obtain

\[
\frac{d}{dt} \int_a^1 \frac{1}{2} \eta^2 J_h^2 \, dx = - \int_a^1 (x \eta \partial_x J_h)^2 \, dx + \int_a^1 J_h(\partial_x J_h)(\eta^2 \beta - \partial_x (x^2 \eta^2)) \, dx \leq - \int_a^1 (x \eta \partial_x J_h)^2 \, dx + \int_a^1 |J_h \partial_x J_h| \cdot 2x \eta C_s \, dx \leq - \frac{1}{2} \int_a^1 (x \eta \partial_x J_h)^2 \, dx + C_s \int_{2a}^1 J_h^2 \, dx.
\]

Integrating over \( t \in [\tau, T] \) first, then averaging over \( \tau \in [s, 2s] \), we obtain

\[
\int_{2s}^T \int_{3a}^1 (x \eta \partial_x J_h)^2 \, dx \, dt = \frac{1}{8} \int_s^{2s} \int_{2a}^1 \eta^2 J_h^2 (x, \tau) \, dx \, d\tau + \int_s^T \int_{2a}^1 J_h^2 \, dx \, dt \leq C(a, s).
\]
Here we have used $|J_h|^2 \leq C(x^2|\partial_x n_h|^2 + n_h^2 + n_h^4)$. We conclude that $\partial_x J_h$ is uniformly bounded in $L^2(W_2)$, independent of $h, \epsilon, \kappa$. Thus $\partial_t n_h$ (but not $\partial^2 n_h$) is uniformly bounded in the same $L^2$ sense.

3. Let us write $n_1 = \partial_t n_h = \partial_x J_h$. Then for $t > 0$,

$$
\partial_t n_1 = \partial_x J_1, \quad J_1(1, t) = 0, \quad (C.7)
$$

where

$$
J_1 = \partial_t J_h = x^2 \partial_x n_1 + \beta n_1. \quad (C.8)
$$

Note that the validity of the zero-flux condition $J_1(1, t) = 0$ is implied by the H"older continuity of $J_1$. To see this is valid, set $v = J_h - n_h^2(1 - \chi_h)$. From (B.8) it follows that $v$ solves

$$
\partial_t v - x^2 \partial_x^2 v = F,
$$

subject to homogeneous boundary conditions, where the source term

$$
F = \partial_x J_h(\rho - 3\chi_h) + x^2 \partial_x^2 (n_h^2(1 - \chi_h)).
$$

From the results in Appendix B, $F$ is locally Hölder-continuous on $[\epsilon, 1] \times (0, \infty)$. Hence, $J_1 = \partial_t v + 2n_h \partial_n n_h (1 - \chi_h)$ is continuous up to $x = 1$.

Multiply (C.7) by $\eta^2 n_1$ with $\eta(x) = \bar{\eta}(x - 3a)$, and integrate in $x$ over $[\epsilon, 1]$ to obtain

$$
\frac{d}{dt} \int_\epsilon^1 \frac{1}{2} \eta^2 n_1^2 dx = - \int_\epsilon^1 (\eta^2 \partial_x n_1 + 2\eta \eta' n_1)(x^2 \partial_x n_1 + \beta n_1) dx
$$

$$
\leq - \int_\epsilon^1 (x \eta \partial_x n_1)^2 dx + \int_\epsilon^1 \left(2x^2 \eta' n_1^2 + |\beta n_1|^2 \right) dx
$$

$$
\leq - \frac{1}{2} \int_\epsilon^1 (x \eta \partial_x n_1)^2 dx + C_s \int_{3a}^1 n_1^2 dx.
$$

Integrating over $t \in [\tau, T]$ first, then over $\tau \in [2s, 3s]$, we obtain

$$
\int_{3a}^T \int_{4a}^1 (x \eta \partial_x n_1)^2 dx d\tau
$$

$$
\leq \frac{1}{s} \int_{2s}^{3s} \int_{3a}^1 \eta^2 n_1^2(x, \tau) dx d\tau + C_s \int_{2s}^T \int_{3a}^1 n_1^2 dx d\tau
$$

$$
\leq C(a, s), \quad (C.9)
$$

where the bound on $n_1 = \partial_x J_h$ in (C.6) from step 2 has been used. We conclude that $\partial_x^2 J_h$ and $\partial_n J_h$ (by (C.5)) are uniformly bounded independent of $h, \epsilon, \kappa$ in $L^2$ on $W_3$, hence $J_h$ is uniformly Hölder continuous on $W_3$.

4. Next we compute $\partial_t J_1$ to complete the estimates for classical solutions. Differentiating (C.8) with respect to $t$ we find that for $t > 0$,

$$
\partial_t J_1 = x^2 \partial_x^2 J_1 + \beta \partial_x J_1 + \partial_t \beta n_1, \quad J_1(1, t) = 0. \quad (C.10)
$$
Recall that \(|\beta| \leq C_s\) and note \(\partial_t \beta = 2(1 - \chi_h)\partial_x J_h\), hence \(|\partial_t \beta| \leq 2|n_1|\). Multiply by \(\eta^2 J_1\) with \(\eta(x) = \bar{\eta}(x - 4a)\), and integrate by parts to find

\[
\frac{d}{dt} \int_{\mathbb{R}^2} \frac{1}{2} \eta^2 J_1^2 \, dx + \int_{\mathbb{R}^2} (x \eta \partial_x J_1)^2 \, dx
= \int_{\mathbb{R}^2} (\beta \eta^2 - \partial_x (x^2 \eta^2)) J_1 (\partial_x J_1) + \eta^2 J_1 \partial_t \beta n_1 \, dx
\leq \frac{1}{2} \int_{\mathbb{R}^2} (x \eta \partial_x J_1)^2 \, dx + C_s \left( \int_{4a}^1 J_1^2 \, dx + \int_{4a}^1 n_1^4 \, dx \right).
\]

Integrating over \(t \in [\tau, T]\) first, then averaging over \(\tau \in [3s, 4s]\), we obtain

\[
\int_{4s}^T \int_{5a}^1 (x \eta \partial_x J_1)^2 \, dx \, dt \leq \frac{1}{8} \int_{3s}^{4s} \int_{4a}^1 \eta^2 J_1^2 (x, \tau) \, dx \, d\tau
+ C_s \int_{3s}^T \left( \int_{4a}^1 J_1^2 \, dx + \int_{4a}^1 n_1^4 \, dx \right) \, dt
\leq C_s \int_{3s}^T \int_{4a}^1 (|\partial_x n_1|^2 + |\partial_x J_h|^2 + |n_1|^4) \, dx \, dt.
\]

The first two terms are bounded using the bounds from the previous steps, \((C.6)\) and \((C.9)\). Note also that \(n_1 = \partial_x J_h\) is in \(L^4(W_3)\) due to an anisotropic embedding theorem. Hence

\[
\int_{4s}^T \int_{5a}^1 (x \eta \partial_x J_1)^2 \, dx \, d\tau \leq C(a, s). \quad (C.11)
\]

We can conclude that \(\partial_x J_1 (= \partial_x \partial_t J_h = \partial_t \partial_x J_h = \partial_t^2 n_h)\) is bounded in \(L^2(W_4)\) independent of \(h, \epsilon, \) and \(\kappa\).

5. After taking the limit \(h \to 0\) along a suitable subsequence, we conclude from steps 1 and 2 that \(\partial_t n_e = \partial_x J_e\) is uniformly bounded in \(L^2(W_2)\), hence the same is true of \(\partial_x^2 n_e\) due to the form of \(J_e\) in \((4.5)\). By Theorem \(A.1\) \(n_e\) is uniformly Hölder-continuous on \(W_2\), independent of \(\epsilon\) and \(\kappa\).

Next we conclude from step 3 that \(J_e\) is uniformly Hölder-continuous on \(W_3\), and the same is true of \(\partial_x n_e\) by \((4.5)\).

From step 4 we then conclude \(\partial_t \partial_x J_e\) is uniformly bounded in \(L^2(W_4)\) and by differentiating \((4.5)\) we conclude the same for \(\partial_x^2 J_e\). Therefore \(\partial_x J_e = \partial_t n_e\) is uniformly Hölder-continuous on \(W_4\), and the same holds for \(\partial_x^2 n_e\).

After taking the limits \(\epsilon \to 0\), and finally \(\kappa \to 0\), these estimates ensure that the weak solution \(n\) of Theorem \(2.3\) is a classical solution in \(Q = (0, 1] \times (0, \infty)\), with the local Hölder regularity indicated in Theorem \(2.4\).

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