# Line of Sight Networks 

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## Modelling Wireless Networks



Sensors modelled as discs of a fixed size placed randomly in $[0,1]^{2}$. Two discs can "communicate" if they overlap.

## Suppose that there are obstacles.



Processors $A, B$ cannot communicate. Need another model.

## LINE OF SIGHT MODEL



Sensors are at centres of crosses and can communicate with sensors lying on their arms.
$A, B$ can communicate, but $A, C$ cannot.
$T=\{0,1, \ldots, n-1\}^{2}$ is a toroidal grid.

Distance:
$d\left((x, y),\left(x^{\prime}, y^{\prime}\right)\right)=\min \left(\left|x-x^{\prime}\right|, n-\left|x-x^{\prime}\right|\right)+\min \left(\left|y-y^{\prime}\right|, n-\left|y-y^{\prime}\right|\right)$.

Two points are mutually visible if they are in the same row or column and within distance $\omega$ of each other.
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We study the random graph $G$ that results if, for some placement probability $p>0$, we locate a node at each point of $T$ independently with probability $p$, and then connect those pairs of nodes that are mutually visible.
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If $\omega=1$ then $G$ is a site percolation model.
If $\omega=n$ then $G$ is the line graph of a random bipartite graph with edge probability $p$.

## Connectivity

## Theorem

Suppose that $\omega / \ln n \rightarrow \infty$ where $\omega=n^{\delta}, \delta \leq 6 /(8 k+7)$.

Let $k \geq 1$ be a fixed positive integer and let $p=\frac{\left(1-\frac{1}{2} \delta\right) \ln n+\frac{k}{2} \ln \ln n+c_{n}}{2 \omega}$. Then

$$
\lim _{n \rightarrow \infty} \operatorname{Pr}(G \text { is } k \text {-connected })= \begin{cases}0 & c_{n} \rightarrow-\infty \\ e^{-\lambda_{k}} & c_{n} \rightarrow c \\ 1 & c_{n} \rightarrow \infty\end{cases}
$$

where

$$
\lambda_{k}=\frac{2^{k-2}\left(1-\frac{1}{2} \delta\right)^{k} e^{-2 c}}{(k-1)!}
$$

Note that if $\omega=o(\ln n)$ and $p=x / \omega$ then the expected number of isolated vertices is

$$
n^{2} p\left(1-\frac{x}{\omega}\right)^{4 \omega}=n^{2} p \exp \left\{-4 x\left(1+\frac{x}{2 \omega}+\frac{x^{2}}{3 \omega^{2}}+\cdots\right)\right\}
$$

So unless $n^{2} p \rightarrow 0$ or $x / \omega$ is very close to one, this expectation tends to infinity. In which case a second moment calculation will show isolated vertices exist whp.
To summarize: We need to consider $\omega=\Omega(\ln n)$ to get any sensible results.

## Giant Component

$G$ will whp contain $\sim n^{2} p$ vertices. A giant component is therefore one with $\Omega\left(n^{2} p\right)$ vertices.

## Theorem

(a) If $p=\frac{c}{\omega}$ where $c>1$ and $\omega \rightarrow \infty$ then whp $G$ contains a unique component with $(1-o(1))\left(1-x_{c}^{2}\right) n^{2} / \omega$ vertices, where $x_{c}$ is the unique solution in $(0,1)$ of $x e^{-x}=c e^{-c}$.
(b) If $p=\frac{c}{\omega}$ where $c<1 /(4 e)$ and $\omega \rightarrow \infty$ then whp the largest component in $G$ has size $O(\ln n)$.

Since (a) is valid for arbitrary $\omega \rightarrow \infty$, we can get a result about the existence of a giant component assuming only that $\omega$ is sufficiently large.

## Finding Paths Between Nodes

## Theorem

Let $p=C \ln n / \omega$ for a constant $C \geq 3$. There is a decentralized algorithm that whp, given nodes $s$ and $t$, constructs an s-t path with $O(d(s, t) / \omega+\ln n)$ edges while involving $O(d(s, t) / \omega+\omega \ln n)$ nodes in the computation.

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This bound is nearly optimal, since $\Omega(d(s, t) / \omega)$ is a simple lower bound on the number of edges and the number of nodes involved in any $s-t$ path.

## Relay Placement: An Approximation Algorithm

Relay Placement Problem: Given a set of nodes on a grid, we would like to add a small number of additional nodes (Steiner Set) so that the full set becomes connected.

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In a general graph, there is an $\Omega(\log n)$ hardness of approximation result for this problem and this is matched by a corresponding upper bound, Klein and Ravi.


FINDING PATAS bETWEEN VERTICES $-x \& y$.


Since now $p=K \log n / w$
(i) Each $H_{i}$ is connected; (ii) Each $H_{i}$ has diamder o(logn).
(iii) Each vertex $v$ of $G$ has 4 mighty arms.

## No Giant Component

We note that an $r$-regular, $N$-vertex graph contains at most $N(e r)^{k-1}$ trees with $k$ vertices.

Thus the expected number of $k$-vertex trees in $G$ is bounded by

$$
n^{2}(4 e \omega p)^{k-1}=n^{2}(4 e c)^{k-1}=o(1)
$$

if $c<1 /(4 e)$ and $k \geq A \ln n$ and $A$ is sufficiently large.

Partition torus into $\frac{n^{2}}{\omega^{2}} \omega \times \omega$ subsquares.

|  |  |  |  |  |
| :--- | :--- | :--- | :--- | :--- |
|  |  | $\omega$ |  |  |
|  |  |  |  |  |
|  |  |  |  |  |
|  |  |  |  |  |
|  |  |  |  |  |

Subsquare $S_{i}$ induces a subgraph $H_{i}$ of $G$.

$\Gamma_{i}$ one edge for each point.

Defines a random bipartite graph $\Gamma_{i}$ with $\omega+\omega$ vertices and edge density $c / \omega, c>1$.
Fact 1: why $\Gamma$ contains a giant component $K$

$$
\begin{aligned}
& \text { Fact 1: } \\
& x_{c} e^{-x_{c}}=c e^{-c} .
\end{aligned}
$$

Fact 2: whip $k$ contains $\geqslant(1-0(1)) x_{c} \omega$ vertices on each side of the partition.


Facts imply whip
(i) $H_{i}$ contains a connected component $K_{i}$ with $\geqslant(1-0(1))\left(1-x_{0}^{2}\right) w^{2}$ vertices.
(ii) $K_{\text {: }}$ contains a vertex in $\geqslant(1-0(1)) x_{0} w$ rows and columns.

why $\exists u_{J} v$ connecting the two giants together.
Can argue that these connections bet ween $\omega \times \omega$ squares are indepen dent.

|  |  |  |  |  |
| :--- | :--- | :--- | :--- | :--- |
|  |  |  |  |  |
|  | $e$ |  |  |  |
|  |  |  |  |  |
|  |  |  |  |  |

Consider mixed percolation on now $\times$ 罂 lat bice where

$$
\begin{aligned}
& P_{v}=\operatorname{Pr}(\text { site open })=\operatorname{Pr}\left(H_{v} \text { has giant }\right)=1-010 . \\
& P_{e}=\operatorname{Pr} \text { (edge e open }=\operatorname{Pr}\left(K_{v}, K_{w} \text { conneotod by edge }\right)=1-0(0) .
\end{aligned}
$$

Why there is a cluster of size $(1-0(1)) n^{2} / w^{2}$
$\Rightarrow$ whip $G$ contains component of size $\geq(1-0(x)) n^{2} / w^{2} x$ $(1-0(1)) x_{c} n$ ．

## Connectivity

Assume that

$$
p=\frac{\left(1-\frac{1}{2} \delta\right) \ln n+\frac{k}{2} \ln \ln n+c}{2 \omega}
$$

Let $X_{I}$ denote the number of vertices of degree $0 \leq I<k$.

$$
\mathbf{E}\left(X_{l}\right) \sim \begin{cases}0 & l \leq k-2 \\ \lambda_{k} & l=k-1\end{cases}
$$

For $t=O(1)$.

$$
\mathbf{E}\left(\left(X_{k-1}\right)_{t}\right) \sim \lambda_{k}^{t}
$$

$$
\left((a)_{t}=a(a-1) \cdots(a-t+1)\right)
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$\left((a)_{t}=a(a-1) \cdots(a-t+1)\right)$.
So whp there are no vertices of degree $\leq k-2$ and

$$
\operatorname{Pr}(\delta(G)=k-1) \sim 1-e^{-\lambda_{k}}
$$

## We condition on $\delta(G) \geq k$.

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We write $G=G_{1} \cup G_{2}$ where $G_{i}$ is defined using $p_{i}$ where $p_{1}=p-\frac{1}{2 \omega \ln n}=(1-o(1)) p$ and $1-p=\left(1-p_{1}\right)\left(1-p_{2}\right)$.

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$G_{1}$ defines the red nodes and $G_{2}$ defines the blue nodes.

The following hold whp:

- No red node has an arm $\alpha$ on which we can find 1000 red vertices each having an arm orthogonal to $\alpha$ which is not mighty.

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- There is no blue node with fewer than $k$ red neighbours.

Assume that the previous properties hold.

Let $L$ be the set of points in $T$ with coordinates $(i, j)$, where each of $i$ and $j$ is a multiple of $\omega$.

Suppose $S$ is a set of $k-1$ red nodes and let $G_{S}=G_{1}-S$.

For each connected component $K$ of $H_{S}$, and for each point $x \in L$, let $v_{K x}$ denote the node in $K$ that is closest to $x$ in $L_{1}$ distance. We claim

## Lemma

$v_{K x}$ lies within the $\omega \times \omega$ box $B_{x}$ centered at $x$.

Simplest Case


It follows from the lemma that there are at most $n^{2} / \omega^{2}$ components in $G_{1}$.

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The probability that there is no blue node at $z(J, K, x)$ is $\left(1-p_{2}\right)^{n^{2} / \omega^{2}}$ and so the probability that $J, K$ do not get merged into one component is at most $n^{2} e^{-n^{2} p_{2} / \omega^{2}} \leq n^{2} e^{-\Omega\left(n^{2} /\left(\omega^{3} \ln n\right)\right)}$ which is small enough to handle all the $\leq n^{k}$ choices for $S$.

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So, if we remove any set of $k-1$ vertices $S$ then there is a component of $G-S$ containing all of the red vertices.

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So, if we remove any set of $k-1$ vertices $S$ then there is a component of $G-S$ containing all of the red vertices.

Each blue node has at least $k$ red neighbours and so if we remove any set $S$ of $k-1$ vertices the remaining graph $G-S$ is connected.

## Relay Placement

Problem: Given $c_{v} \geq 0$ for $v \in T$ and a set $X \subseteq T$ find $Y$ such that $X \cup Y$ is connected and $c(Y)$ is small.

Define $c_{v}^{X}=\left\{\begin{array}{ll}0 & v \in X \\ c_{v} & v \notin X\end{array}\right.$ and for an edge $e=\{v, w\}$ let
its weight be $w(e)=\max \left\{c_{v}^{X}, c_{w}^{X}\right\}$.
Let $Y^{*}$ be a Steiner set for $X$ of minimum cost, and let $\wedge^{*}$ be a Steiner tree for $X$ of minimum total edge weight.

A Steiner tree $\Lambda^{\prime}$ whose edge weight is within a constant factor $\gamma \leq 1.55$ of optimal can be computed in polynomial time Robins and Zelikovsky.

RELAY REPLACEMENT

$$
X=\{\bullet\} \quad Y=\{\bullet\}
$$



$$
\begin{aligned}
& : c_{v}= \begin{cases}0: v \in X \\
c_{v}: v \in X\end{cases} \\
& v_{0}, \\
& \omega(e): \max \left\{c_{v}, c_{w}\right\}
\end{aligned}
$$

(i) $Y^{*}=\min . \cos t Y$.
(iv) $Y^{\prime}$ : \{Steiner notes
(ii) $\bigwedge^{*}=$ min. weight
$\left.6 \wedge^{\prime}\right\}$
(iii) $\Lambda^{\prime}=1.55$ approx. to $\Lambda^{*}$
(a) $\Lambda^{*}$ has max. degree 4 .

リ
(b) $\omega\left(\Lambda^{*}\right) \leqslant 4 c\left(Y^{*}\right)$
(c) $c\left(y^{\prime}\right) \leqslant w\left(\Lambda^{\prime}\right) \leqslant 1.55 w\left(\Lambda^{*}\right) \leqslant 6.2 c\left(y^{*}\right)$.

Let $Y^{\prime}$ be the Steiner nodes of $\Lambda^{\prime}$.

$$
c\left(Y^{\prime}\right) \leq w\left(\Lambda^{\prime}\right) \leq \gamma w\left(\Lambda^{*}\right) \leq 4 \gamma c\left(Y^{*}\right)
$$

## Open Questions

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- Find the exact threshold for the existence of a giant component.
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- Study problems associated with the points of $G$ moving (randomly).


## THANK YOU

