# How fast travelling waves can attract small initial data

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$$\frac{\partial_t v - d\Delta v = f(v)}{-\partial_y v = 0}$$
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- Enjoys a comparison principle.
- Motivation : robustness of the propagation enhancement discovered by BRR.

■ There exists a T.W. : (c, φ, ψ) with c > 0 unique and φ, ψ smooth connecting (0,0) and (1/μ, 1)

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$$0 \leftarrow u \qquad -u'' + c_{\infty}u' = v - \mu u \qquad u \to 1/\mu$$
$$d\partial_{y}v = \mu u - v$$
$$0 \leftarrow v \qquad c_{\infty}\partial_{x}v - d\partial_{yy}^{2}v = f(v) \qquad v \to 1$$
$$\partial_{y}v = 0$$

which is well posed.

(2)

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- c.c. initial data with a large enough support w.r.t D (expected, see below)

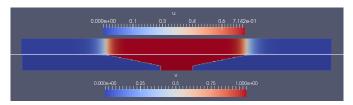
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How fast travelling waves can attract small initial data

Context : propagation enhancement

## Enhancement by diffusion : the homogeneous case

$$\begin{cases} \partial_t v - \partial_{xx}^2 v = f(v) & t > 0, x \in \mathbb{R} \\ v_0(x) = \mathbf{1}_{(-L,L)}(x) \end{cases}$$
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Rescaling  $x \leftarrow x\sqrt{d}, c \leftarrow c/\sqrt{d}$  gives :  $L_0(d) = \sqrt{d}L_0(1)$   $c(d) = \sqrt{d}c(1)$ 

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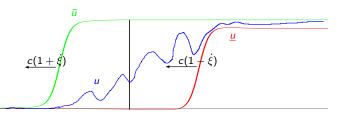
## Back to our system : what happens ?

#### Theorem 1

Let  $(u_0, v_0)$  be front-like. There exists  $\omega > 0$  indep. of D s.t. for  $\varepsilon > 0$  small there exists two shifts  $\xi_1^{\pm}$  s.t.

$$\begin{split} \phi(x+c\xi_1^-+ct) - C\varepsilon e^{-\omega t} &\leq \mu u(t,x) \leq \mu \phi(x+c\xi_1^++ct) + C\varepsilon e^{-\omega t} \\ \psi(x+c\xi_1^-+ct) - C\varepsilon e^{-\omega t} \leq v(t,x,y) \leq \psi(x+c\xi_1^++ct) + C\varepsilon e^{-\omega t} \end{split}$$

where C = C(d).



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## Consequence

#### Theorem 2

Let  $(u_0, v_0)$  be  $\geq 0$  smooth and compactly supported. There exists  $\delta > 0$  and M > 0 indep. of D such that if

$$\mu u_0, v_0 > 1 - \delta$$
 for  $x \in (-M\sqrt{D}, M\sqrt{D})$ 

then  $\mu u$ , v stays trapped (up to an exponentially decaying error) between two shifts of a pair of travelling waves evolving in both directions.

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#### Idea of proof.

Upper bound : (min(ū, ũ), min(v, v)) is a supersolution (ũ is like ū with reversed x). Can be put above (u<sub>0</sub>, v<sub>0</sub>) at inital time.

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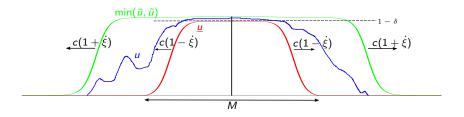
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- Upper bound : (min(ū, ũ), min(v, v)) is a supersolution (ũ is like ū with reversed x). Can be put above (u₀, v₀) at inital time.
- Lower bound (idea of FML) :

$$\begin{cases} \underline{u} = \max\left(0, \phi + \tilde{\phi} - 1/\mu - q_u(t)/\mu\min(\Gamma, \tilde{\Gamma})\right) \\ \underline{v} = \max\left(0, \psi + \tilde{\psi} - 1 - q_v(t, y)\min(\Gamma, \tilde{\Gamma})\right) \end{cases}$$

Subsolution provided initial shifts are large enough.



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*M* and  $\delta$  arise when one wants to put  $(\underline{u}, \underline{v})(0)$  below  $(u_0, v_0)$ .

## What about small initial data when D is large ?

#### Theorem 3

There exists  $M', \delta' > 0$  independent of D > d such that if

$$v_0 > 1 - \delta'$$
 for  $x \in (-M', M')$ 

then after a time  $t_D = D^{1/2} \ln D + O(1)$  one has  $\mu u$  and v satisfying the assumptions of Theorem 2.

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 $d\partial_{y}\underline{v} + \underline{v} = 0$  $\partial_{t}\underline{v} - d\Delta\underline{v} = f(\underline{v})$  $\partial_{y}\underline{v} = 0$ 

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• (4) has a steady state  $p(y) > 1 - \delta$  (provided *L* is not too small). Berestycki–Nirenberg '92 :  $\exists$  T.W. connecting 0 and p(y) with speed  $c_p$  indep. of *D*. This gives :

Under the assumptions of Theorem 3, there holds

$$v(t,x,-L) \geq (1-\delta'')\varphi_t(x) - Ce^{-bt}$$

where C, b > 0 do not depend on D and  $\varphi_t$  is a regularisation of  $\mathbf{1}_{\left(-\frac{c_p}{2}t, \frac{c_p}{2}t\right)}$ .

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End of the proof of Theorem 3. Rescale by  $x \leftarrow x/\sqrt{D}$ . Goal :

 $\liminf_{t \to +\infty} \inf_{D>d} \min_{(x,y) \in \overline{\Omega_{L,M}}} \{ \mu u^D(T_D + t, x), v^D(T_D + t, x, y) \} \ge p(-L) > 1 - \delta$ (5)

where  $T_D = \sqrt{D} \ln D$  and  $\Omega_{L,M} = (-M, M) \times (-L, 0)$ , i.e. we want to connect with Theorem 2.

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where  $T_D = \sqrt{D} \ln D$  and  $\Omega_{L,M} = (-M, M) \times (-L, 0)$ , i.e. we want to connect with Theorem 2.

• Easy but tedious : LHS of (5) can be characterised as lim of  $\mu u^{D_n}(T_{D_n} + t_n, x_n)$  or  $v^{D_n}(T_{D_n} + t_n, x_n, y_n)$  where  $t_n \to +\infty$ ,  $D_n > d$ ,  $(x_n, y_n) \in \overline{\Omega_{L,M}}$ . Extract so that  $(D_n)$  has a limit in  $[d, +\infty]$ .

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Idea :  $\underline{v}_n(t, x, -L) \xrightarrow[n \to +\infty]{} p(-L) > 1 - \delta$  loc. unif. in  $\mathbb{R} \times \mathbb{R}$  (either  $(D_n)$ ) bounded and it is immediate, or since  $\ln(D_n) \to +\infty$ )

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Issue if  $D_n$  unbounded : uniform in time regularity ?

- Regularity in y is OK by rescaling.
- Regularity in x falls but : (6) is linear and (φ<sub>t</sub>) bounded in C<sup>3</sup>, so use the maximum principle.

Now extract :  $(u_{\infty}, v_{\infty})$  global in time (since  $t_n \to +\infty$ ) :

$$\frac{\partial_t u_{\infty} - \partial_{xx}^2 u_{\infty} = v_{\infty} - \mu u_{\infty}}{d\partial_y v_{\infty} = \mu u_{\infty} - v_{\infty}}$$
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The maximum principle applies in the standard way for u and on every y-slice for  $v : \mu u_{\infty}, v_{\infty} \equiv p(-L)$  and this proves (5) and thus Theorem 3.

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# Additional information

Initial datum supported on the road :  $v_0 \equiv 0, \mu u_0 = \mathbf{1}_{(-L,L)}(x)$ 

#### Theorem 5

There exists  $a_0, a_1$  and  $\mu^{\pm}$  indep. of D such that

- If  $L < a_0 \sqrt{D}$ , extinction occurs.
- If  $L > a_1 \sqrt{D}$ , invasion occurs if  $\mu < \mu and$  extinction if  $\mu > \mu^+$ .

Results

Merci pour votre attention !

