

**Department of Mathematical Sciences**  
**Carnegie Mellon University**  
21-393 Operations Research II  
Test 1

Name: \_\_\_\_\_

Problem	Points	Score
1	40	
2	40	
3	20	
Total	100	

**Q1: (40pts)**

(a) Solve the following knapsack problem, writing the results of the dynamic programming recursion in a table. You will not score any points for just writing down the answer:

$$\begin{aligned} &\text{maximise} && 3x_1 + 7x_2 + 17x_3 \\ &\text{subject to} && \\ &&& 2x_1 + 3x_2 + 7x_3 \leq 10 \\ &&& x_1, x_2, x_3 \geq 0 \text{ and integer.} \end{aligned}$$

Your answer should consist of a table.

(b) Using the answer to part (a), solve the following problem:

$$\begin{aligned} &\text{minimise} && 2x_1 + 3x_2 + 7x_3 \\ &\text{subject to} && \\ &&& 3x_1 + 7x_2 + 17x_3 \geq 20 \\ &&& x_1, x_2, x_3 \geq 0 \text{ and integer.} \end{aligned}$$

(This does not require any new computations!)

**Q2: (40pts)** A system can be in 3 states 1,2,3 and the cost of moving from state  $i$  to state  $j$  in one period is  $c(i, j)$ , where the  $c(i, j)$  are given in the matrix below. The one period discount factor  $\alpha$  is  $1/2$ .

The aim is to find a policy which simultaneously minimises the discounted cost of operating from any starting state. Start with the policy

$$\pi(1) = 2, \pi(2) = 1, \pi(3) = 2.$$

Evaluate this policy. Is it optimal? If not find an improved policy.

**YOU DO NOT NEED TO EVALUATE THIS NEW POLICY OR FIND AN OPTIMAL STRATEGY.**

The matrix of costs is

$$\begin{bmatrix} 5 & 10 & 1 \\ 8 & 2 & 2 \\ 1 & 10 & 2 \end{bmatrix}$$

**Q3: (20pts)**  $I, J$  are intervals of length  $n$ . Every pair of sub-intervals  $I' \subseteq I, J' \subseteq J$  is given a value  $v(I', J')$ . Here we are restricting our attention to intervals that have integer endpoints. Give a Dynamic Programming algorithm for partitioning  $I$  into consecutive intervals  $I_1, I_2, \dots, I_m$  and  $J$  into consecutive intervals  $J_1, J_2, \dots, J_m$  in order to maximise the total value  $v(I_1, J_1) + v(I_2, J_2) + \dots + v(I_m, J_m)$ . The intervals chosen must be such that  $I_t \cap J_t \neq \emptyset$  for  $t = 1, 2, \dots, m$ . There is no restriction on  $m$ .